

Homework 3

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Exercise 2

Consider the use of Gibbs sampling to generate samples from a bivariate normal distribution. Let the means be 0, the variances be 1, and the correlation be ρ .

Answer: The Gibbs sampler yields more reliable results when the correlation ρ is low, as the conditional distributions are less dependent and mix faster. Variance estimates are accurate across settings, and higher burn-in proportions improve the estimation of the correlation. The estimated means remain close to zero (error < 0.02), indicating good convergence. Overall, Gibbs sampling is effective for this problem due to the tractability of the conditional distributions.

```
library(phonTools)
```

```
## Warning: package 'phonTools' was built under R version 4.2.3
```

```
ps <- c(0.1, 0.2, 0.3, 0.4, 0.5)
burn_in_props <- c(0.3, 0.4, 0.5)
total_samples <- 13000
results <- data.frame(
  p = numeric(),
  burn_in_prop = numeric(),
  mean_x1 = numeric(),
  mean_x2 = numeric(),
  var_x1 = numeric(),
  var_x2 = numeric(),
  cov_x1x2 = numeric()
)

set.seed(123)

for (p in ps) {
  for (burn_in_prop in burn_in_props) {
    burn_in <- as.integer(total_samples * burn_in_prop)
    keep_draws <- total_samples - burn_in
    mu <- c(0, 0)
    sigma <- matrix(c(1, p, p, 1), nrow = 2)
    x_1 <- rep(0, total_samples)
    x_2 <- rep(0, total_samples)
    for (i in 2:total_samples) {
      x_2[i] <- sqrt(1 - p^2) * rnorm(1) + p * x_1[i - 1]
      x_1[i] <- sqrt(1 - p^2) * rnorm(1) + p * x_2[i]
    }
    ygs <- cbind(x_1, x_2)
    ygs <- ygs[(burn_in + 1):total_samples, ]
```

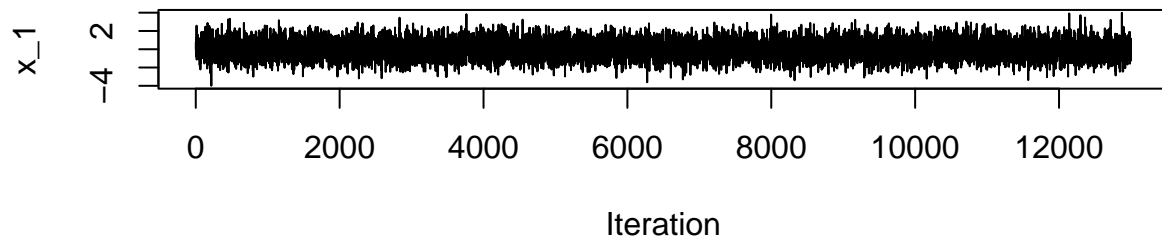
```

m <- colMeans(ygs)
v <- cov(ygs)
results <- rbind(
  results,
  data.frame(
    p = p,
    burn_in_prop = burn_in_prop,
    mean_x1 = m[1],
    mean_x2 = m[2],
    var_x1 = v[1, 1],
    var_x2 = v[2, 2],
    cov_x1x2 = v[1, 2]
  )
)
}

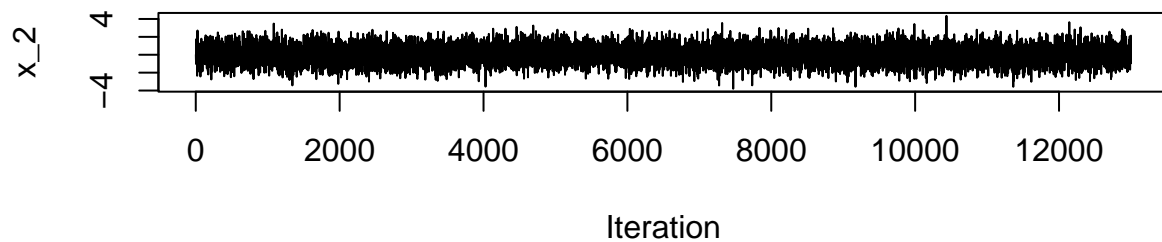
par(mfrow = c(2, 1))
plot(x_1, type = "l", main = "Trace plot of x_1", xlab = "Iteration", ylab = "x_1")
plot(x_2, type = "l", main = "Trace plot of x_2", xlab = "Iteration", ylab = "x_2")

```

Trace plot of x₁



Trace plot of x₂



```

par(mfrow = c(1, 1))

```

```

knitr::kable(results, digits = 4, caption = "Comparison of Gibbs Sampling Results for Different p and B")

```

Table 1: Comparison of Gibbs Sampling Results for Different p and Burn-in Proportions

	p	burn_in_prop	mean_x1	mean_x2	var_x1	var_x2	cov_x1x2
x_1	0.1	0.3	-0.0108	-0.0136	1.0047	1.0180	0.1130
x_11	0.1	0.4	0.0126	0.0117	1.0303	0.9869	0.0880
x_12	0.1	0.5	0.0116	0.0014	0.9805	0.9915	0.0990
x_13	0.2	0.3	-0.0046	-0.0091	0.9884	0.9794	0.1876
x_14	0.2	0.4	-0.0024	0.0001	0.9873	0.9996	0.1914
x_15	0.2	0.5	-0.0107	0.0152	1.0111	1.0065	0.2094
x_16	0.3	0.3	0.0115	0.0099	1.0023	1.0099	0.3171
x_17	0.3	0.4	0.0137	0.0113	1.0127	1.0133	0.3139
x_18	0.3	0.5	-0.0137	-0.0031	1.0083	0.9824	0.3099
x_19	0.4	0.3	-0.0211	-0.0126	1.0027	1.0170	0.4091
x_110	0.4	0.4	0.0165	0.0042	1.0097	1.0069	0.4127
x_111	0.4	0.5	-0.0188	-0.0114	1.0044	1.0291	0.4009
x_112	0.5	0.3	-0.0024	-0.0183	1.0003	1.0005	0.5038
x_113	0.5	0.4	0.0143	0.0070	1.0263	1.0252	0.5155
x_114	0.5	0.5	-0.0230	-0.0268	0.9697	1.0040	0.4794

Exercise 3

It is assumed that the lifetime of light bulbs follows an exponential distribution with parameter λ . To estimate λ , n light bulbs were tested until they all failed. Their failure times were recorded as u_1, \dots, u_n . In a separate experiment, m bulbs were tested, but the individual failure times were not recorded. Only the number of bulbs, r , that had failed at time t was recorded. The missing data are the failure times of the bulbs in the second experiment, v_1, \dots, v_m .

Let us define the auxiliary variable: $v_1, \dots, v_m \sim \text{Exponential}(\lambda)$: partially observed, with only r failures before time t ; r are right-censored at time t .

We assume a conjugate Gamma prior:

$$\lambda \sim \text{Gamma}(\alpha, \beta), \quad \text{with density } p(\lambda) \propto \lambda^{\alpha-1} e^{-\beta\lambda}$$

The exponential likelihood for fully observed data is:

$$L_{\text{obs}}(\lambda) = \prod_{i=1}^n \lambda e^{-\lambda u_i} = \lambda^n e^{-\lambda \sum_{i=1}^n u_i}$$

The observed failures in the second group (before time t) contribute:

$$L_{\text{fail}}(\lambda) = \prod_{j=1}^r \lambda e^{-\lambda v_j} = \lambda^r e^{-\lambda \sum_{j=1}^r v_j}$$

$$L_{\text{cens}}(\lambda) = \prod_{k=1}^{m-r} P(v_k > t \mid \lambda) = (e^{-\lambda t})^{m-r} = e^{-\lambda t(m-r)}$$

Combining all:

$$L(\lambda \mid \mathbf{u}, \mathbf{v}) = \lambda^{n+r} e^{-\lambda(\sum u_i + \sum v_j + t(m-r))}$$

Multiplying by the Gamma prior:

$$p(\lambda \mid \text{data}) \propto L(\lambda) \cdot p(\lambda)$$

$$\begin{aligned} &\propto \lambda^{n+r} e^{-\lambda(\sum u_i + \sum v_j + t(m-r))} \cdot \lambda^{\alpha-1} e^{-\beta\lambda} \\ &= \lambda^{\alpha+n+r-1} e^{-\lambda(\beta + \sum u_i + \sum v_j + t(m-r))} \end{aligned}$$

This is the kernel of a Gamma distribution:

$$\lambda \mid \text{data} \sim \text{Gamma}\left(\alpha + n + r, \beta + \sum u_i + \sum v_j + t(m-r)\right)$$

Step 1: Sample λ

Given $\mathbf{u}, \mathbf{v}_{1:r}, \mathbf{v}_{r+1:m}$, the conditional posterior is:

$$\lambda \mid \mathbf{u}, \mathbf{v} \sim \text{Gamma}\left(\alpha + n + m, \beta + \sum_{i=1}^n u_i + \sum_{j=1}^m v_j\right)$$

(Note: this includes both observed and imputed v_j 's)

Step 2: Sample each missing v_j , for $j = r + 1, \dots, m$

Each right-censored $v_j \sim \text{Exponential}(\lambda)$, truncated to the interval (t, ∞) :

$$v_j \mid \lambda \sim \text{TruncatedExponential}(\lambda; v_j > t)$$

This can be sampled via (This is because the exponential distribution is memoryless):

or equivalently:

$$v_j = t + \text{Exponential}(\lambda)$$

For sampling the truncated exponential, and the values from u_i we don't need to use the Gibbs sampler, as the distribution is known and can be sampled directly.

```
# Data generation
set.seed(123)
n <- 100; m <- 20; t <- 1
lambda_true <- 2

u <- rexp(n, rate = lambda_true)
v <- rexp(m, rate = lambda_true)
r <- sum(v <= t)

# Censored data, meaning those that did not fail before time t, but that we did not observe until they
v_obs <- v[v <= t]
v_censored_count <- r

# Gibbs parameters
alpha <- 1
beta <- 1
n_iter <- 10000
burn_in <- 5000

# Initialization
lambda <- 1
lambda_samples <- numeric(n_iter)
```

```

# Step 0 : Initial imputation. It is greater than t, because if they had been shorted
# failure times, we would have include them into the v_obs vector.
v_missing <- rep(t + 0.1, v_censored_count)

for (iter in 1:n_iter) {

# Step 1: Sample missing failure times (truncated exponential)

  v_missing <- t + rexp(v_censored_count, rate = lambda)

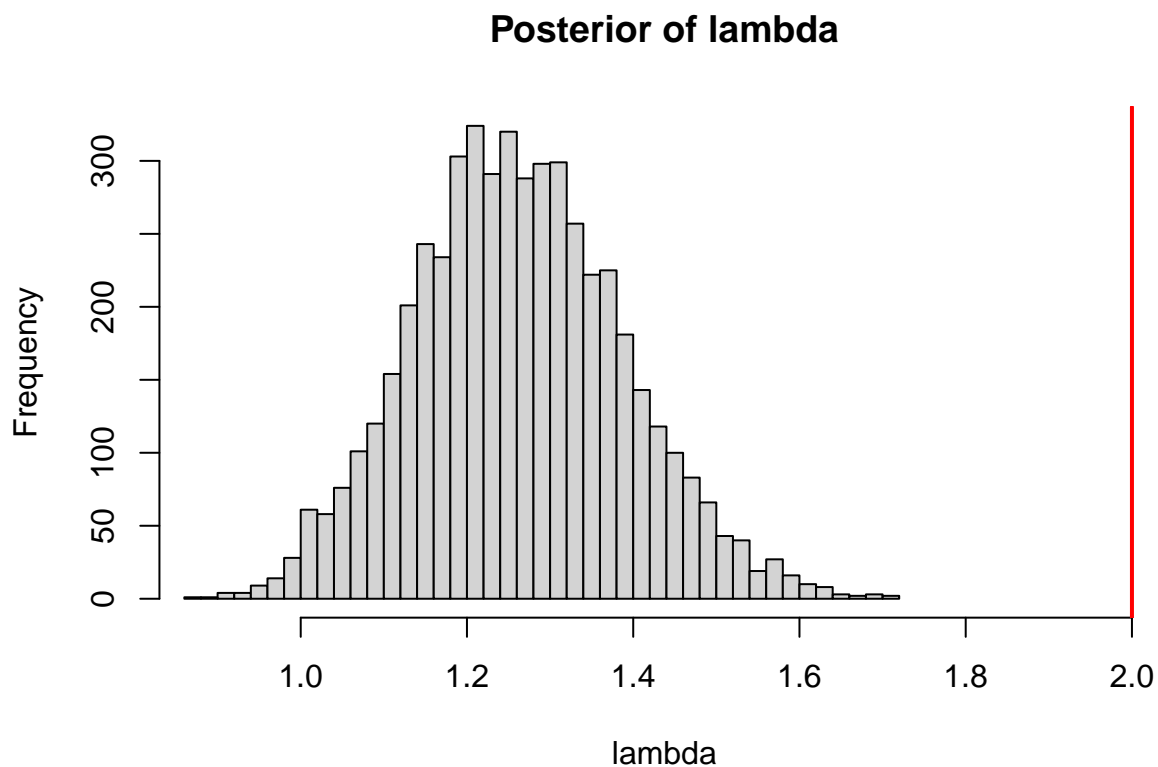
# Step 2: Update lambda from Gamma posterior
  total_time <- sum(u) + sum(v_obs) + sum(v_missing)*t
  lambda <- rgamma(1, shape = alpha + n + m, rate = beta + total_time)

  lambda_samples[iter] <- lambda
}

# Discard burn-in
lambda_samples_post <- lambda_samples[(burn_in + 1):n_iter]

# Results
hist(lambda_samples_post, breaks = 30, main = "Posterior of lambda", xlab = "lambda", xlim = range(c(la
abline(v = lambda_true, col = "red", lwd = 2)

```



As it is possible to observe in the histogram, the posterior distribution of λ is not centered around the true value. It seems that the MCMC algorithm is not converging properly. This could be due to the fact that

the initial values of the missing data are not representative of the true distribution, or that the number of iterations is not sufficient for convergence. Another possibility is that the prior distribution is not informative enough, leading to a posterior distribution that is not centered around the true value. We also consider that the