Definition 1.1

The \mathbf{mean} of a sample of n measured responses $\boldsymbol{y}_1\boldsymbol{y}_2\ldots\boldsymbol{y}_n$ is given by

$$\overline{y} = \frac{1}{n} \sum_{i=1}^{n} (y_1)$$

The corresponding population mean is denoted μ .

Definition 1.2

The **variance** of a sample of measurements $y_1 y_2 \dots y_n$ is the sum of the square of the differences between the measurements and their mean, divided by n-1. Symbolically, the sample variance is

$$s^{2} = \frac{1}{n-1} \sum_{i=1}^{n} \left(y_{1} - \overline{y} \right)^{2}$$

The corresponding population variance is denoted by the symbol σ^2 .

Definition 1.3

The standard deviation of a sample of measurements is the positive square root of the variance; that is,

$$s = \sqrt{(s)^2}$$

The corresponding population standard deviation is denoted by $\sigma = \sqrt{\left(\sigma\right)^2}$

Definition 2.7

An ordered arrangement of r distinct objects is called a **permutation**. The number of ways of ordering n distinct objects taken r at a time will be designated by the symbol P_n^r

$$P_n^r = n (n-1) (n-2) \cdots (n-r+1) = \frac{n!}{(n-r)}$$

Definition 2.8

The number of combinations of n objects taken r at a time is the number of subsets, each of size r, that can be formed from the n objects. This number will be denoted by C_r^n or $\binom{r}{n}$.

$$P_n^r = n (n-1) 0(n-2) \cdots (n-r+1) = \frac{n!}{(n-r)}$$

Definition 2.9

The conditional probability of an event A, given that an event B has occurred, is equal to

 $P(A|B) = \frac{P(A \cap B)}{P(B)}$, provided P(B) > 0. [The symbol P(A|B) is read "probability of A given B."]

Definition 3.7

A random variable Y is said to have a **binomial distribution** based on n trials with success probability p if and only if $P(y) = \binom{n}{y} P^y Q^{n-y}$, y = 0, 1, 2,..., n and $0 \le p \le 1$.

Definition 3.8

A random variable Y is said to have a geometric probability distribution if and only if

$$P(y) = Q^{y-1}, y = 0, 1, 2,..., 0 \le p \le 1.$$

Definition 3.10

A random variable Y is said to have a hypergeometric probability distribution if and only if

$$P(y) = \frac{\binom{r}{y}\binom{N-r}{n-y}}{\binom{N}{n}}$$

where y is an integer 0, 1, 2, ... n, subject to the restrictions $y \le r$ and $n - y \le N - r$.

Definition 3.11

A random variable Y is said to have a **Poisson probability distribution** if and only if $P(y) = \frac{\lambda^y}{y!}e^{-\lambda}$, y = 0, 1, 2... $\lambda > 0$.

Definition 3.14

Tchebysheff's Theorem Let Y be a random variable with mean μ and finite variance μ^2 . Then, for any constant K>0, $P(|Y - \mu| < k\sigma) > 1 - \frac{1}{k^2}$ or $P(|Y - \mu| \ge k\sigma) \le \frac{1}{k^2}$

Definition 4.1

Let Y denote any random variable. **The distribution function** of Y, denoted by F(y). Is such that F(y) = P(Y < y) for $-\infty < y < \infty$.

Definition 4.2

A random variable Y with distribution function F(y) is aid to be continuous if F(y) is continuous, for

$$-\infty < y < \infty^2$$

Definition 4.3

Let F(y) be the distribution for a continuous random variable Y. Then f(y), given by

$$f(y) - \frac{dF(y)}{dy} = F'(y)$$

Wherever the derivative exists, is called the **probability function** for the random variable y.

Theorem 4.2

Property of Density Function If f(y) is a density function for a continuous random variable, then

1.
$$f(y) \ge 0$$
 for all y , $-\infty < \infty$.

$$2. \int_{-\infty}^{\infty} f(y) \, dy = 1.$$

Definition 4.6

If $_1 < _2$ a random variable Y is said to have a continuous **uniform probability distribution** on the interval $(_1,_2)$ if and only if density function Y is

$$f(y) = {\frac{1}{1-2}, \quad ^{1} < y < \quad ^{2} 0. \quad elsewhere}$$

Theorem 4.6 (Uniform Distribution)

If $_1$ < $_2$ and Y is a random variable uniformly distributed on the interval ($_1$ < $_2$), then

$$\mu = E(Y) = \frac{1+2}{2}$$
 and $\sigma^2 = V(Y) = \frac{(2-1)^2}{12}$