

Math 3322 Hw4

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1. $x, y \in \mathbb{R}^n$ s.t. $\|x\|_2 = \|y\|_2$

a) Since Householder matrix is of form $H = I - 2vv^T$
 $= I - 2 \frac{uv^T}{v^T v}$ ($v = \frac{y}{\|y\|}$)

Let's assume v is equal to $x - y$

Then, $Hx = x - \frac{2(x-y)(x-y)^T x}{(x-y)^T (x-y)}$
 $= \frac{x(x-y)^T (x-y) - 2(x-y)(x-y)^T x}{(x-y)^T (x-y)} \dots (1)$

$$x(x-y)^T (x-y) = (xx^T - xy^T)(x-y) = xx^T x - xy^T x - xxy^T + xy^T y$$

$$(x-y)(x-y)^T x = xx^T x - xy^T x - yx^T x + yy^T x$$

(1) : $\frac{2xx^T x - 2xy^T x}{(x-y)^T (x-y)} = \frac{y(x-y)^T (x-y)}{(x-y)^T (x-y)} = y$

In other words, when $\|x\|_2 = \|y\|_2$, $x - y$ passes the origin.

$$\therefore H = I - \frac{2(x-y)(x-y)^T}{(x-y)^T (x-y)}$$

b) $Hy = y - \frac{2(x-y)(x-y)^T y}{(x-y)^T (x-y)}$
 $= \frac{y(x-y)^T (x-y) - 2(x-y)(x-y)^T y}{(x-y)^T (x-y)} \dots (2)$

$$(y(x-y)^T (x-y)) = yx^T x - yx^T y - yx^T y + yy^T y$$

$$-2(x-y)(x-y)^T y = -2yx^T y - 2yx^T y + 2yx^T y + 2yy^T y$$

(2) : $\frac{yx^T x - 2yx^T y}{(x-y)^T (x-y)} = \frac{x(x-y)^T (x-y)}{(x-y)^T (x-y)} = x \quad \therefore Hy = x$

2. The entries of q_1 are all non-zero.

Let's denote H as
$$\begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$$

and G as
$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$
 which G is just a Givens Rotation.

To check whether matrix H is a householder matrix, we need to verify that it can be rewritten into $H = I - 2VV^T$.

By choosing $V = \left[\sqrt{\frac{1-\cos \theta}{2}}, \sqrt{\frac{1+\cos \theta}{2}} \right]^T$,

$H = I - 2VV^T = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$. Therefore, H is indeed a householder matrix.

Now, $H \cdot \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

and $G \cdot \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

With nonzero entries $q_1 = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$, $H(q_1) \neq G(q_1)$ is shown although the output $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is same.

3.

$$\begin{bmatrix} I & A \\ A^T & 0 \end{bmatrix} \begin{bmatrix} r \\ x \end{bmatrix} = \begin{bmatrix} b \\ 0 \end{bmatrix}$$

minimize $\|Ax - b\|^2 = \left\| \sum_{j=1}^n a_j x_j - b \right\|^2$

\downarrow
 $r = Ax - b$ is orthogonal to $\text{range}(A)$
 $A_{\hat{x}}$

Since $A \in \mathbb{R}^{m \times n}$ with $m \geq n$, $\text{rank}(A) = n$, there exists a decomposition $A = QR$.

We get $\begin{cases} r + Ax = b \\ A^T r = 0 \end{cases}$ from the above matrix.

Multiply A^T to the first equation : $A^T r + A^T A x = A^T b$
 \Downarrow
 0

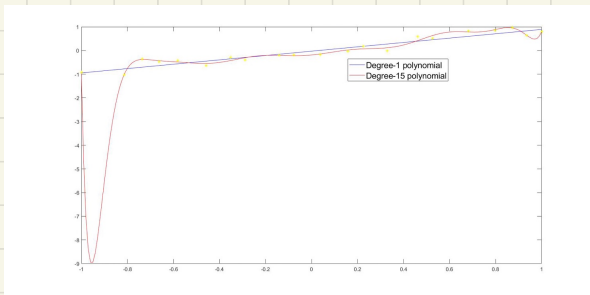
$\Rightarrow A^T A x = A^T b$

$\Rightarrow x = (A^T A)^{-1} A^T b$

which is exactly the closed form solution of $\min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2$, meaning the

same solution \hat{x} for the given matrix and $\min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2$.

4.



Overfitting observed when degree = 15.