

1. El sistema tiene dos grados de libertad: el ángulo θ que forma la varilla de longitud l con la vertical y el ángulo ϕ que forma la varilla de longitud a con la horizontal.

Para la masa 1.

$$x_1 = l \sin \theta - \frac{a}{2} \cos(\phi) \quad y_1 = -l \cos(\theta) - \frac{a}{2} \sin(\phi)$$

Para la masa 2.

$$x_2 = l \sin(\theta) + \frac{a}{2} \cos(\phi) \quad y_2 = -l \cos(\theta) + \frac{a}{2} \sin(\phi)$$

La energía cinética (T) será igual a:

$$T = \frac{1}{2} m_1 (\dot{x}_1^2 + \dot{y}_1^2) + \frac{1}{2} m_2 (\dot{x}_2^2 + \dot{y}_2^2)$$

$$T = \frac{1}{2} m_1 \left[(l \dot{\theta} \cos(\theta) + \frac{a}{2} \sin(\phi) \dot{\phi})^2 + (l \dot{\theta} \sin(\theta) - \frac{a}{2} \cos(\phi) \dot{\phi})^2 \right] \\ + \frac{1}{2} m_2 \left[(l \dot{\theta} \cos(\theta) + \frac{a}{2} \sin(\phi) \dot{\phi})^2 + (l \dot{\theta} \sin(\theta) + \frac{a}{2} \cos(\phi) \dot{\phi})^2 \right]$$

$$T = \frac{1}{2} m_1 \left[l^2 \dot{\theta}^2 \cos^2(\theta) + l \dot{\theta} \cos(\theta) a \sin(\phi) \dot{\phi} + \frac{a^2}{4} \sin^2(\phi) \dot{\phi}^2 \right. \\ \left. + l^2 \dot{\theta}^2 \sin^2(\theta) - l \dot{\theta} \sin(\theta) a \cos(\phi) \dot{\phi} + \frac{a^2}{4} \cos^2(\phi) \dot{\phi}^2 \right] \\ + \frac{1}{2} m_2 \left[l^2 \dot{\theta}^2 \cos^2(\theta) + l \dot{\theta} \cos(\theta) a \sin(\phi) \dot{\phi} + \frac{a^2}{4} \sin^2(\phi) \dot{\phi}^2 \right. \\ \left. + l^2 \dot{\theta}^2 \sin^2(\theta) + l \dot{\theta} \sin(\theta) a \cos(\phi) \dot{\phi} + \frac{a^2}{4} \cos^2(\phi) \dot{\phi}^2 \right]$$

$$T = \frac{1}{2} (m_1 + m_2) l^2 \dot{\theta}^2 + \frac{1}{8} (m_1 + m_2) a^2 \dot{\phi}^2 + \frac{1}{2} l a \dot{\theta} \dot{\phi} [(\rightarrow$$

$$\rightarrow m_2 - m_1) \cos \theta \sin \phi + (m_1 - m_2) \sin \theta \cos \phi]$$

La Energía Potencial será

$$U = m_1 g y_1 + m_2 g y_2 = -g l (m_1 + m_2) \cos \theta + \frac{g a}{2} (m_1 - m_2) \sin \phi$$

$$L = T - U$$

Para θ

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0$$

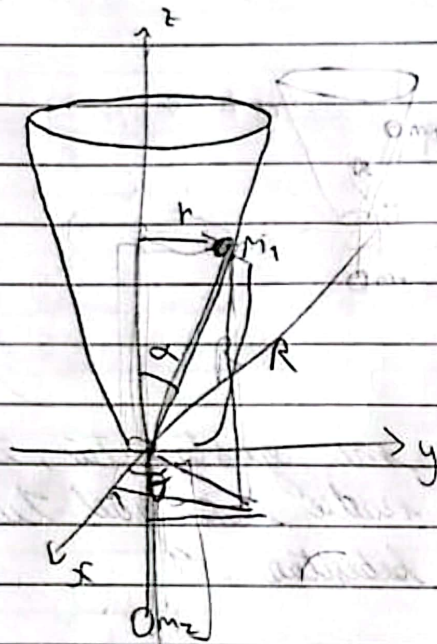
Resolviendo queda:

$$1) (m_1 + m_2) l^2 \ddot{\theta} + \frac{1}{2} l a [\ddot{\phi} ((m_2 - m_1) \cos \theta \sin \phi + (m_1 - m_2) \sin \theta \cos \phi) + \dot{\phi} (-\dot{\theta} (m_2 - m_1) \sin \theta \sin \phi + \dot{\theta} (m_1 - m_2) \cos \theta \cos \phi)] + g l (m_1 + m_2) \sin \theta = 0$$

Para ϕ

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\phi}} \right) - \frac{\partial L}{\partial \phi} = 0$$

$$2) \frac{1}{4} (m_1 + m_2) a^2 \ddot{\phi} + \frac{1}{2} l a [\ddot{\theta} ((m_2 - m_1) \cos \theta \sin \phi + (m_1 - m_2) \sin \theta \cos \phi) + \dot{\theta} (-\dot{\theta} (m_2 - m_1) \sin \theta \sin \phi + \dot{\theta} (m_1 - m_2) \cos \theta \cos \phi)] - \frac{g a}{2} (m_1 - m_2) \cos \phi = 0$$



$$q_1 = \theta \quad q_2 = r$$

$$q_3 = z_2$$

m_1

m_2

$$x_1 = r \cos \theta$$

$$x_2 = 0$$

$$y_1 = r \sin \theta$$

$$y_2 = 0$$

$$z_1 = r \cot \alpha$$

$$z_2 = l - r \sec \alpha$$

$$z_2 = l - r \sec \alpha$$

$$z_2 = l - r \sec \alpha$$

$$T_1 = \frac{1}{2} m_1 (\dot{x}^2 + \dot{y}^2 + \dot{z}^2) = \frac{1}{2} m_1 (\dot{r}^2 \csc^2 \alpha + r^2 \dot{\theta}^2)$$

$$T_2 = \frac{1}{2} m_2 \dot{z}_2^2$$

$$V_1 = m_1 g r \cot \alpha$$

$$V_2 = m_2 g z_2$$

$$\tan^2 \alpha + 1 = \sec^2 \alpha$$

$$\cot^2 \alpha + 1 = \csc^2 \alpha$$

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right) - \frac{\partial \mathcal{L}}{\partial q} = 0$$

$$\mathcal{L} = \frac{1}{2} m_1 \dot{r}^2 \csc^2 \alpha + \frac{1}{2} m_1 r^2 \dot{\theta}^2 + \frac{1}{2} m_2 \dot{z}_2^2 - m_1 g r \cot \alpha + m_2 g z_2$$

$$\frac{\partial \mathcal{L}}{\partial \theta} = 0$$

$$\frac{\partial \mathcal{L}}{\partial r} = m_1 \dot{\theta}^2 r - m_1 g \cot \alpha = m_1 (r \dot{\theta}^2 - g \cot \alpha)$$

$$\frac{\partial \mathcal{L}}{\partial z_2} = m_2 g$$

$$m_1 \ddot{r} \csc^2 \alpha - m_1 r \dot{\theta}^2 + m_2 g \cot \alpha = 0 \quad m_1 r^2 \dot{\theta} = c$$

$$\ddot{r} = -r \dot{\theta}^2 \sin^2 \alpha - g \cos \alpha \sin \alpha =$$

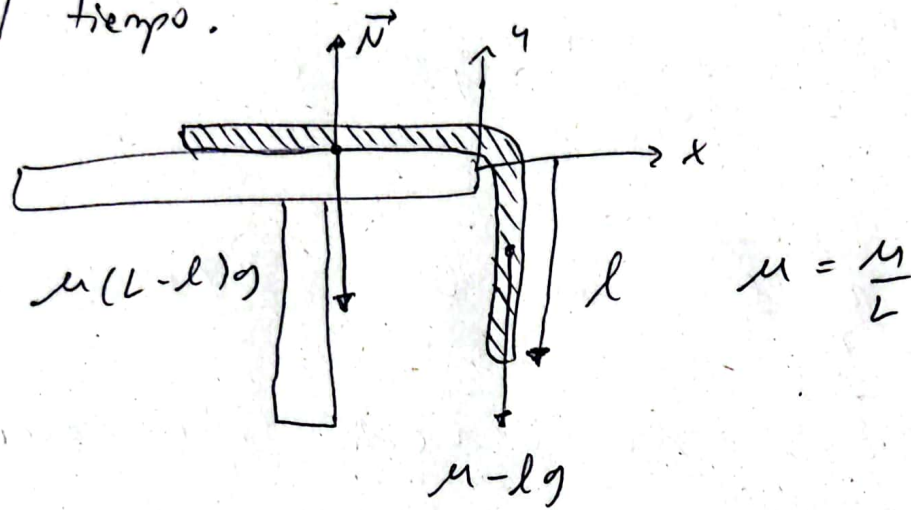
$$m_2 \ddot{z}_2 - m_2 g = 0$$

$$\ddot{z}_2 = g \quad m_1 r^2 \dot{\theta} = c = \int \tau(t) dt$$

$$\dot{\theta} = \frac{c}{m_1 r^2}$$

$$\theta = \frac{c_1 t}{m_1 r^2} + c_2 \quad \frac{1}{\cos^2 \alpha \sin \alpha}$$

4. Una cuerda uniforme de masa M y longitud L se encuentra sobre una mesa sin fricción. La cuerda se suelta desde el reposo cuando una sección de longitud l está colgando. Encuentre la trayectoria de la cuerda en función del tiempo.



$$\begin{aligned} x=0 &\rightarrow s=1 \rightarrow y = -l(t) \\ z=0 &\rightarrow \dot{y} = -\dot{l} \end{aligned}$$

$$dT = \frac{1}{2} \mu dl \dot{l}^2 \rightarrow T = \int_0^l \frac{1}{2} \mu \dot{l}^2 dl$$

$$T = \frac{1}{2} \mu l \dot{l}^2$$

$$dU = \mu l g dl \rightarrow U = \mu g \int_0^l l dl = \frac{1}{2} \mu g l^2$$

$$L = T - U = \frac{1}{2} \mu l \dot{l}^2 - \frac{1}{2} \mu g l^2$$

Ecuaciones Euler-Lagrange:

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{l}} \right) - \frac{\partial L}{\partial l} = 0$$

$$\frac{d}{dt} \left(\frac{m}{l} \dot{l} \right) - \frac{1}{2} \frac{m}{l} \dot{l}^2 - \frac{m}{l} g l = 0$$

$$\frac{m}{l} \dot{l}^2 + \frac{m}{l} l \ddot{l} - \frac{1}{2} \frac{m}{l} \dot{l}^2 - \frac{m}{l} g l = 0$$

$$l \ddot{l} + \dot{l}^2 - \frac{1}{2} \dot{l}^2 - g l = 0$$

Entonces:

$$\ddot{l} + \frac{1}{2} \frac{\dot{l}^2}{l} - g = 0, \quad l \neq 0$$

Es una E.D. NO LINEAL por tener un exponente mayor a 1, por ser de Taylor:

$$\text{sea } l(0) = l, \quad \dot{l}(0) = 0,$$

$$\ddot{l} = g - \frac{1}{2} \frac{\dot{l}^2}{l} \rightarrow \ddot{l}(0) = g$$

$$\ddot{\ddot{l}} = -\frac{1}{2} \left(\frac{2 \dot{l} \ddot{l} l - \dot{l}^2}{l^2} \right) \rightarrow \ddot{\ddot{l}}(0) = -\frac{1}{2} \left(\frac{0 - 0}{l^2} \right) = 0$$

$$l^{(4)} = -\frac{1}{2} \left[\frac{(2 \ddot{l}^2 l^3 + 2 \dot{l} \ddot{\ddot{l}} l^3 + 2 \dot{l}^2 \ddot{\ddot{l}} l^2 - 4 \dot{l}^2 \ddot{l})}{l^4} + \frac{(2 \ddot{l} \ddot{\ddot{l}} l^3 + \ddot{l}^3 l^2 - 2 \dot{l}^3 l^2)}{l^4} \right]$$

$$l^{(4)}(0) = -\frac{1}{2} \left[\frac{2 \cancel{g^2} l^3 + 2(0) + 2(0) - 4(0)}{l^4} \right] - \left(\frac{2(0) + 0 - 0}{l^4} \right) = -g^2 \frac{l^3}{l^4} = -\frac{g^2}{l}$$

Por el binomio:

$$\begin{aligned} l(t) &= l + t \dot{l}(0) + \frac{t^2}{2} \ddot{l}(0) + \dots + \frac{t^n}{n!} l^{(n)}(0) \\ &= l + \frac{g}{2} t^2 - \frac{g^2}{6l} t^4 + \dots + \frac{t^n}{n!} l^{(n)}(0) \end{aligned}$$

Que es la expansión de Taylor de $l(t)$ al orden de $t=0$.

Considerando solo $t=0$ y $t=2$

$$l(t) = l + \frac{g}{2} t^2$$