FaceNet

A Unified Embedding for Face Recognition and Clustering

The mean squares

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Problem Statement

Despite significant recent advances in the field of face recognition, implementing face verification and recognition efficiently at scale presents serious challenges to current approaches.

Solution Approach

- A system is described which converts an image to a fixed size embedding.
- Distances between any two embeddings is a measure of the similarity of the faces.
- The embedding is produced by training a siamese network with triplet loss.

Introduction to FaceNet

- A unified system for face verification (is this the same person), recognition (who is this person) and clustering (find common people among these faces).
- The embedding generated is an Euclidean embedding per image using a deep convolutional network.
- The network is trained such that the squared L2 distances in the embedding space directly correspond to face similarity.
- Faces of the same person have small distances and faces of distinct people have large distances.
- Face verification simply involves thresholding the distance between the two embeddings, recognition becomes a k-NN classification problem; and clustering can be achieved using off-the-shelf techniques such as k-means or agglomerative clustering.
- Dataset to be used for training:- Labeled Faces in the Wild (LFW).

Dataset Description

- Database of face photographs designed for studying the problem of unconstrained face recognition.
- For training, we are considering a subset of classes with 3 images each. That comes up to be 610 labels.
- All the images from LFW dataset are split into 2 sets -
 - For validation, to find appropriate threshold for distances of similar faces and different faces.
 - For testing, the images we are taking all labels in the LFW dataset and performing verification/recognition tasks.

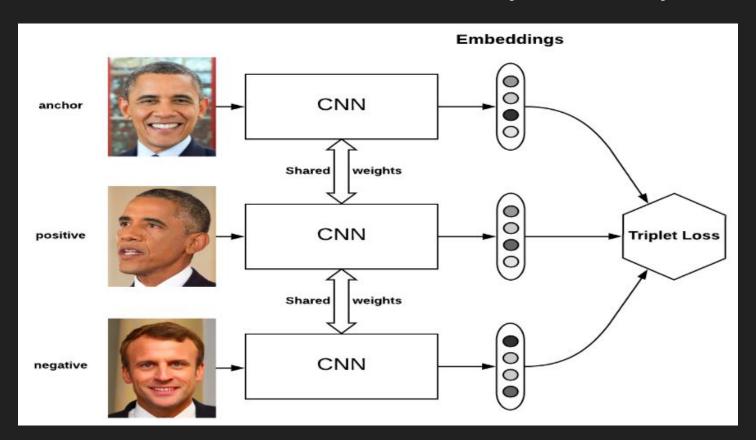
Expected Results

- The model will produce a fixed size embedding for a test data.
- If the test data belongs to a particular label then the distance between the embedding generated and stored embedding for that class should be less than a threshold.

Siamese Networks

- Siamese Networks are basically two same neural networks, the output of which are passed through the a function that calculates the distance between the inputs.
- For inputs belonging to same class, the outputs are close (i.e., distance is less) and for inputs belonging to different classes, the distance between outputs should be large.
- Triplet loss can be used to train a siamese network.

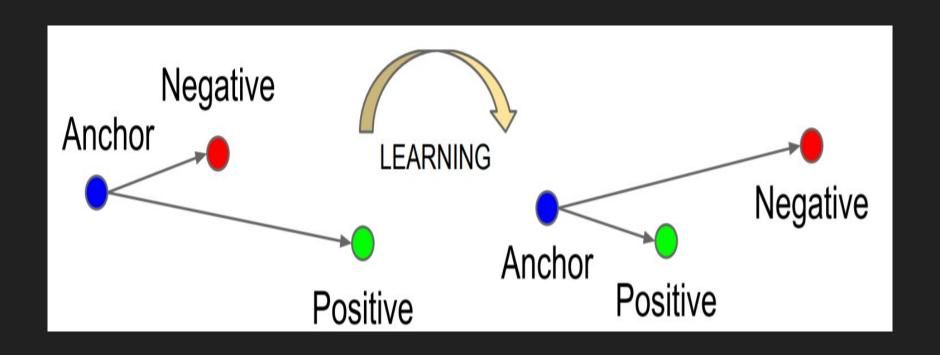
Siamese Network(Cont..)



Triplet loss

- It is a distance based loss function that operates on three inputs:
 - 1. anchor (a): is any arbitrary data point,
 - 2. positive (p): which is the same class as the anchor
 - 3. and negative (n): which is a different class from the anchor
- Mathematically, it is defined as: L=max(d(a,p)-d(a,n)+margin,0).
- We minimize this loss, which pushes d(a,p) to 0 and d(a,n) to be greater than d(a,p)+margin.
- After the training, the positive examples will be closer to the anchor while the negative examples will be farther from it.

Triplet Loss(Cont..)



Triplet loss - loss function

$$\sum_{i}^{N} \left[\|f(x_{i}^{a}) - f(x_{i}^{p})\|_{2}^{2} - \|f(x_{i}^{a}) - f(x_{i}^{n})\|_{2}^{2} + \alpha \right]_{+}$$

Model Summary

Layer (type)	Output	Shape	Param #
conv2d (Conv2D)	(None,	30, 30, 64)	1792
conv2d_1 (Conv2D)	(None,	15, 15, 128)	73856
conv2d_2 (Conv2D)	(None,	8, 8, 64)	73792
conv2d_3 (Conv2D)	(None,	4, 4, 64)	4160
flatten (Flatten)	(None,	1024)	0
dense (Dense)	(None,	512)	524800
dropout (Dropout)	(None,	512)	0
dense_1 (Dense)	(None,	256)	131328
dropout_1 (Dropout)	(None,	256)	0
dense_2 (Dense)	(None,	128)	32896
Total params: 842,624 Trainable params: 842,624 Non-trainable params: 0			=======
Model: "functional_1"			

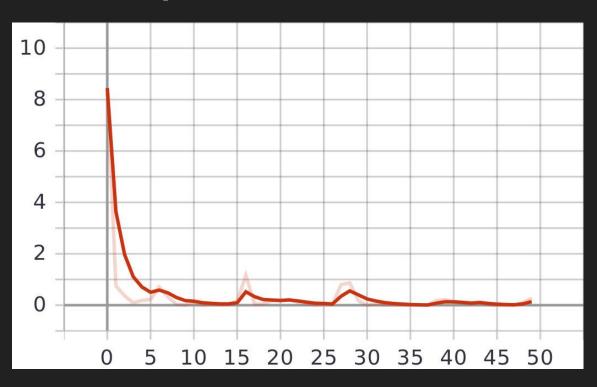
Non-trainable params: 0

```
Output Shape
                                                                  Connected to
anchor input (InputLayer)
                                [(None, 60, 60, 3)] 0
positive input (InputLayer)
                                [(None, 60, 60, 3)] 0
negative input (InputLayer)
                                [(None, 60, 60, 3)] 0
sequential (Sequential)
                                                                 anchor_input[0][0]
                                (None, 128)
                                                     842624
                                                                 positive_input[0][0]
                                                                 negative_input[0][0]
merged layer (Concatenate)
                                                                 sequential[0][0]
                                (None, 384)
                                                     0
                                                                 sequential[1][0]
                                                                  sequential[2][0]
Total params: 842,624
Trainable params: 842,624
```

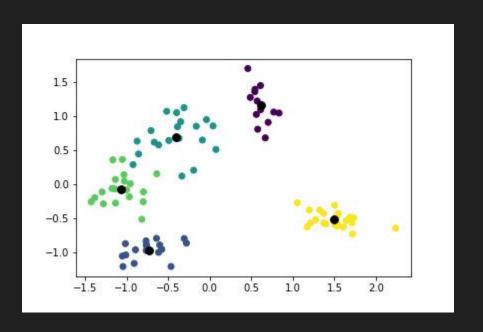
Training and Validation

- For training and validation, we have considered a small subset of the original dataset.
- For validation accuracy, we have used K-NN for better accuracy.

Epoch vs Loss



Scatter Plot for validation data and clusters



Validation Accuracy

к	Accuracy
1	83.33%
3	83.33%
5	79.16%
7	70.83%

Code Snippets

Triplet Generation

```
def generate triplets(x, y, num same = 4, num diff = 4):
        anchor images = np.array([]).reshape((-1,)+ x.shape[1:])
        same_images = np.array([]).reshape((-1,)+ x.shape[1:])
       diff_images = np.array([]).reshape((-1,)+ x.shape[1:])
 6
       for i in range(len(y)):
           point = v[i]
 8
           anchor = x[i]
 9
10
           same pairs = np.where(y == point)[0]
           same pairs = np.delete(same pairs , np.where(same pairs == i))
11
12
           diff pairs = np.where(y != point)[0]
13
14
           same = x[np.random.choice(same_pairs,num_same)]
15
           diff = x[np.random.choice(diff pairs,num diff)]
16
17
           anchor images = np.concatenate((anchor images, np.tile(anchor, (num same * num diff, 1, 1, 1) )), axis = 0)
18
19
           for s in same:
20
                same images = np.concatenate((same images, np.tile(s, (num same, 1, 1, 1))), axis = \theta)
21
22
           diff images = np.concatenate((diff images, np.tile(diff, (num diff, 1, 1, 1) )), axis = 0)
23
24
       return anchor images, same images, diff images
```

Code Snippets

Triplet Loss Function

```
def triplet_loss(y_true, y_pred, alpha = 0.2):
    total_length = y_pred.shape.as_list()[-1]
    anchor, positive, negative = y_pred[:,:int(1/3*total_length)], \
        y_pred[:,int(1/3*total_length):int(2/3*total_length)], y_pred[:,int(2/3*total_length):]

pos_dist = tf.reduce_sum(tf.square(anchor - positive), axis=-1)
    neg_dist = tf.reduce_sum(tf.square(anchor - negative), axis=-1)
    basic_loss = pos_dist - neg_dist + alpha
    loss = tf.reduce_sum(tf.maximum(basic_loss,0.0))
    return loss
```

Models and experiments

- We have tried different deep learning structures and experimented with them.
 - Experiments on Batch Normalisation
 - Max/Min/Avg pooling
 - Dropout
 - optimizers
 - epochs and different batch sizes
- We tried different values of K in KNN classification.
- We trained our model to different numbers of triplets.
- We tried different subsets of LFW dataset for training model.

Accuracy on LFW

Model	Accuracy
Margin: 0.4, K=7, w/o dropout	52.70%
Margin: 0.4, K=9, with dropout	51.45%
Margin: 0.5, k = 1, w/o dropout	55.96%
Margin: 1, k = 7, w/o dropout, Batch normalization	52.74%

Final Model & Accuracy

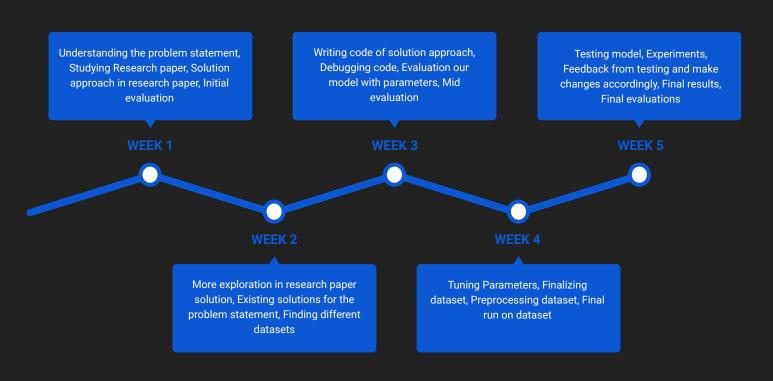
Margin: 0.6, k=9, w/o dropout

Accuracy = 61.32%

Layer (type)	Output Shap	e	Param #
	. <mark></mark>		
conv2d (Conv2D)	(None, 30,	30, 64)	1792
max_pooling2d (MaxPooling2D)	(None, 30,	30, 64)	0
conv2d_1 (Conv2D)	(None, 15,	15, 128)	73856
max_pooling2d_1 (MaxPooling2	(None, 15,	15, 128)	0
conv2d_2 (Conv2D)	(None, 8, 8	, 64)	73792
conv2d_3 (Conv2D)	(None, 4, 4	, 64)	4160
max_pooling2d_2 (MaxPooling2	(None, 4, 4	, 64)	0
flatten (Flatten)	(None, 1024	-)	0
dense (Dense)	(None, 512)		524800
dense_1 (Dense)	(None, 256)	1	131328
	(None, 128)		32896

Trainable params: 842,624 Non-trainable params: 0

Timeline



Individual contribution

- Data Preprocessing & face detection Param and Sanyam
- Generating triplets Shubham and Sanyam
- Siamese Network and Triplet Loss function Param and Shubham
- Experimenting with Different parameters All

References

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