# ETF3231/5231 Week 5 - Exponential smoothing, Part 1

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1 What we will cover this week (Chapters 5.9, 8.1 - 8.4)

Understanding equations of exponential smoothing

### Intuitively

Intuitively, exponential smoothing allows us to represent time series  $y_t$  and predictions  $\hat{y}_{t+1|t}$ ,  $\hat{y}_{t+2|t}$ , ... as a **weighted average** of past time series, these can be:

- Past time series of itself,  $y_t, y_{t-1}, ...$
- Or past time series of latent, unobservable components we need to derive from  $y_t$ . These include:
  - Smoothed values of  $y_t$ , which we refer to as  $I_t$
  - Trend values of  $y_t$ , which we refer to as  $b_t$
  - Seasonal values of  $y_t$ , which we refer to as  $s_t$
- We need to note that  $l_t$ ,  $b_t$  and  $s_t$ , are all components that depend on  $y_t$  and their past values. They are all functions of  $y_t$
- Essentially, the exponential smoothing method just takes weighted averages of the past to predict the future! though how the weighted averages are constructed is complex and clever

### Exponential smoothing in component form

We first begin with writing out the component form of a simple exponential smoothing method (no trend, no seasonality):

Forecast equation 
$$\hat{y}_{t+h|t} = I_t$$
  
Smoothing equation  $I_t = \alpha y_t + (1-\alpha)I_{t-1}$ 

Notice how the smoothing equation is a weighted average of past time series  $y_t$  and unobservable components  $b_t$ 

### Exponential smoothing in component form

$$\hat{y}_{t+h|t} = I_t$$

$$I_t = \underbrace{\alpha y_t}_{\text{weighted average of past value}} + \underbrace{(1-\alpha)I_{t-1}}_{\text{weighted average of unobservable component}}$$

$$= \alpha y_t + (1-\alpha)[\alpha y_{t-1} + (1-\alpha)I_{t-2}]$$

$$= \alpha y_t + (1-\alpha)\alpha y_{t-1} + (1-\alpha)^2I_{t-2}$$

$$= \alpha y_t + (1-\alpha)\alpha y_{t-1} + (1-\alpha)^2[\alpha y_{t-2} + (1-\alpha)I_{t-3}]$$

$$\dots$$

$$I_t = \underbrace{f(y_t, y_{t-1}, y_{t-2}, ... | \alpha, I_0)}_{\text{weighted average of past values}}$$

$$\therefore \hat{y}_{t+h|t} = f(y_t, y_{t-1}, y_{t-2}, ... | \alpha, I_0)$$

 $I_0$  and  $\alpha$  needs to be estimated, e.g., using the maximum-likelihood estimation, or Bayesian methods (more on this next week).

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# Adding seasonality and trend

If we add a trends and seasonality components (assuming undamped, and with additive seasonality):

Forecast equation 
$$\begin{aligned} \hat{y}_{t+h|t} &= l_t + hb_t + s_{t+h-m(k+1)} \\ \text{Level equation} & l_t &= \alpha(y_t - s_{t-m}) + (1-\alpha)(l_{t-1} + b_{t-1}) \\ \text{Trend equation} & b_t &= \beta(l_t - l_{t-1}) + (1-\beta)b_{t-1} \\ \text{Season equation} & s_t &= \gamma(y_t - l_{t-1} - b_{t-1}) + (1-\gamma)s_{t-m} \end{aligned}$$

Notice how these equations are similar to the simple method before? They are weighted averages of **past values** and **unobservable components**.

# Adding seasonality and trend

$$\begin{array}{lll} \hat{y}_{t+h|t} & = & l_t + hb_t + s_{t+h-m(k+1)} \\ l_t & = & \underbrace{\alpha(y_t - s_{t-m})}_{\text{past and unobservable component}} & + \underbrace{(1-\alpha)(l_{t-1} + b_{t-1})}_{\text{unobservable component}} \\ b_t & = & \underbrace{\beta(l_t - l_{t-1})}_{\text{unobservable component}} & + \underbrace{(1-\beta)b_{t-1}}_{\text{unobservable component}} \\ s_t & = & \underbrace{\gamma(y_t - l_{t-1} - b_{t-1})}_{\text{unobservable component}} & \underbrace{(1-\gamma)s_{t-m}}_{\text{unobservable component}} \end{array}$$

Notice how every equation is essentially a weighted average?

# Adding seasonality and trend

$$\hat{y}_{t+h|t} = l_t + hb_t + s_{t+h-m(k+1)} 
l_t = g(y_t, y_{t-1}, y_{t-2}, ... | \alpha, l_0, s_0, b_0) 
b_t = h(y_t, y_{t-1}, y_{t-2}, ... | \beta, l_0, b_0) 
s_t = k(y_t, y_{t-1}, y_{t-2}, ... | \gamma, l_0, b_0, s_0)$$

And in a nutshell:

$$\hat{y}_{t+h|t} = f(\underbrace{y_t, y_{t-1}, y_{t-2}, \dots}_{\text{past observations}} | \underbrace{\alpha, \beta, \gamma, I_0, b_0, s_0}_{\text{parameters to estimate}})$$

With the damped trend method though:

$$\hat{y}_{t+h|t} = f(\underbrace{y_t, y_{t-1}, y_{t-2}, \dots}_{\text{past observations}} | \underbrace{\alpha, \beta, \phi, \gamma, l_0, b_0, s_0}_{\text{parameters to estimate}})$$

#### Revisit intuition from before

- Exponential smoothing allows us to represent  $y_t$  and predictions  $\hat{y}_{t+1|t}, \hat{y}_{t+2|t}, ...$  as a weighted average of past time series.
- These weights come in the form of up to 7 parameters  $\alpha, \beta, \phi, \gamma, l_0, s_0, b_0$
- These parameters help capture the trend-cycle component and seasonal component of our time series
- All of our forecasts would then just be a function of past values and these parameters:

$$\hat{y}_{t+h|t} = f(y_t, y_{t-1}, y_{t-2}, ... | \alpha, \beta, \phi, \gamma, l_0, b_0, s_0)$$

#### Weeks 6 and 7 will teach

- We have learnt about the component form equations of exponential smoothing
- We are going to learn about representing exponential smoothing equations in state-space form (it's the same intuition, but just represented a bit differently)
- We are also going to learn about using the ETS() model in modelling and forecasting, also revise and remember:
  - The benchmark models (e.g., naive), because we can compare these simple models to the more complex, ETS model.
  - How to model(), forecast() and autoplot() forecasts.
  - How do we assess residual diagnostics (gg\_tsresiduals()).
  - How do we evaluate our forecasts using train-test split and time series cross validation