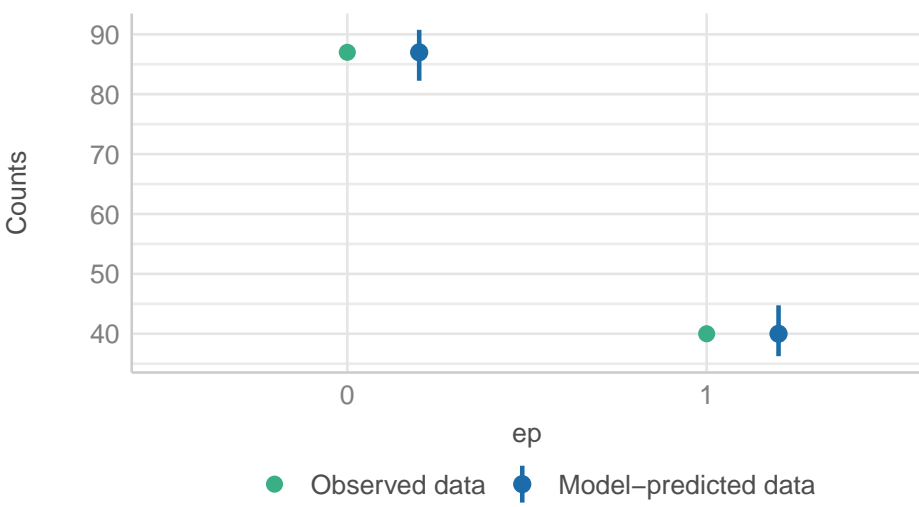
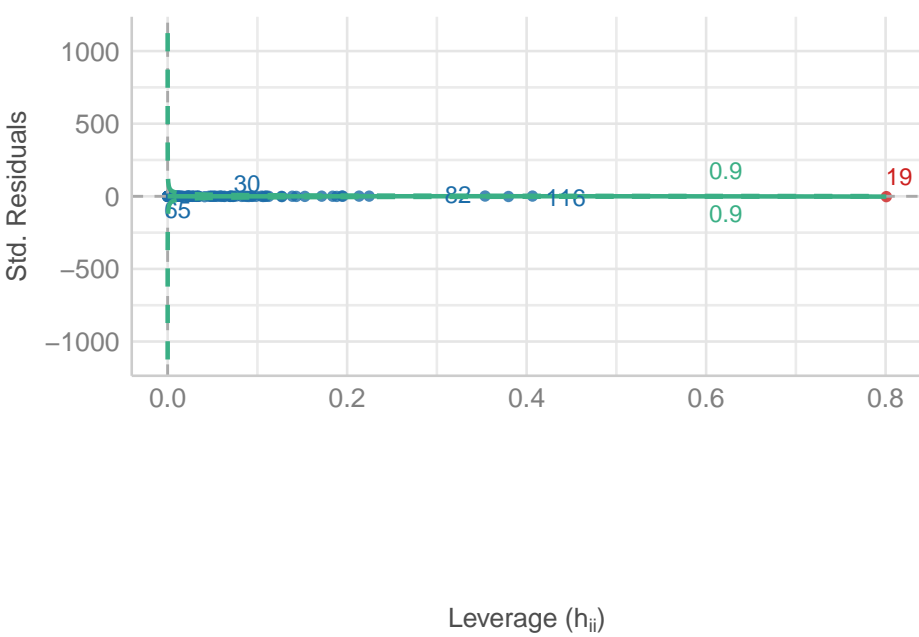


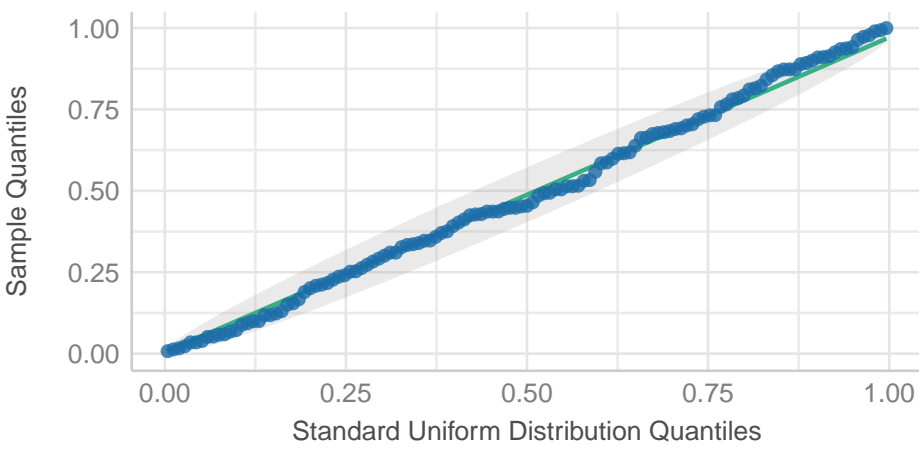
Posterior Predictive Check  
Model-predicted intervals should include observed data points



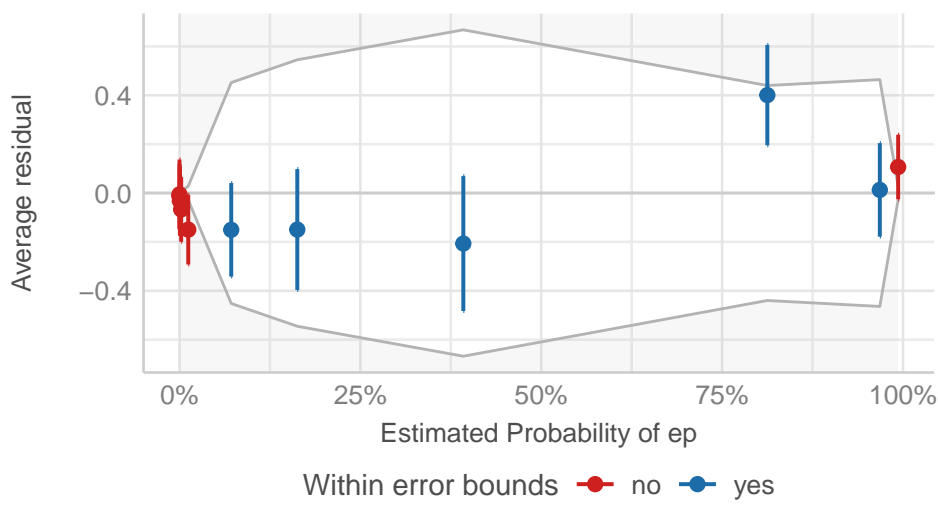
Influential Observations  
Points should be inside the contour lines



Uniformity of Residuals  
Dots should fall along the line



Binned Residuals  
Points should be within error bounds



Collinearity  
High collinearity (VIF) may inflate parameter uncertainty

