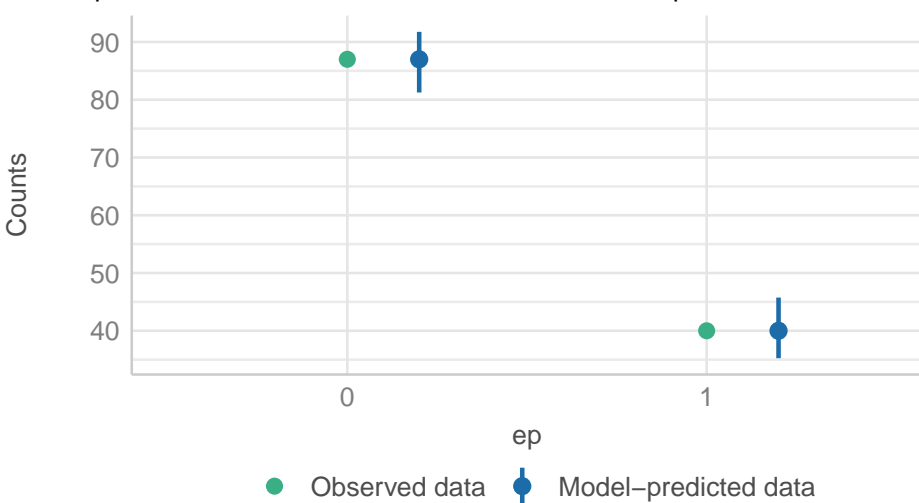
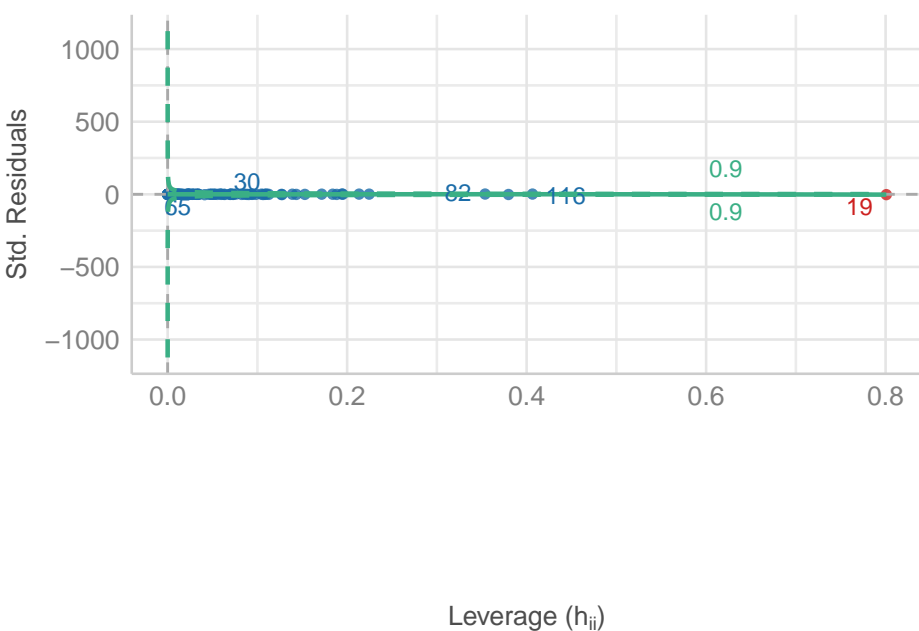


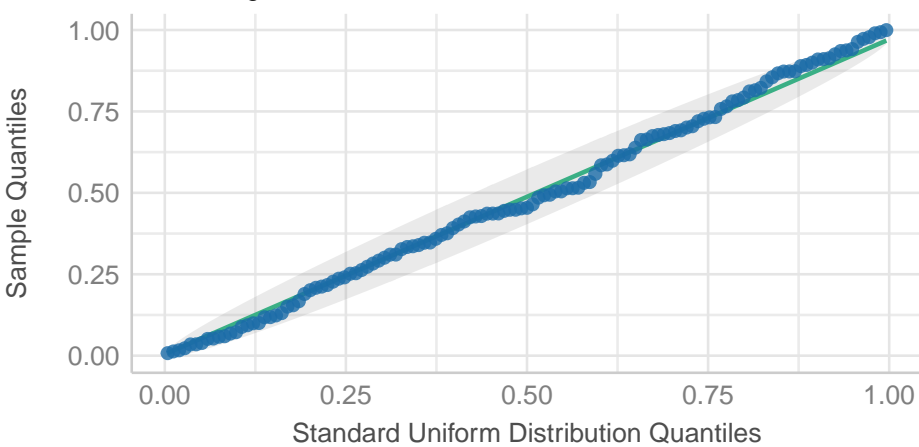
Posterior Predictive Check
Model-predicted intervals should include observed data points



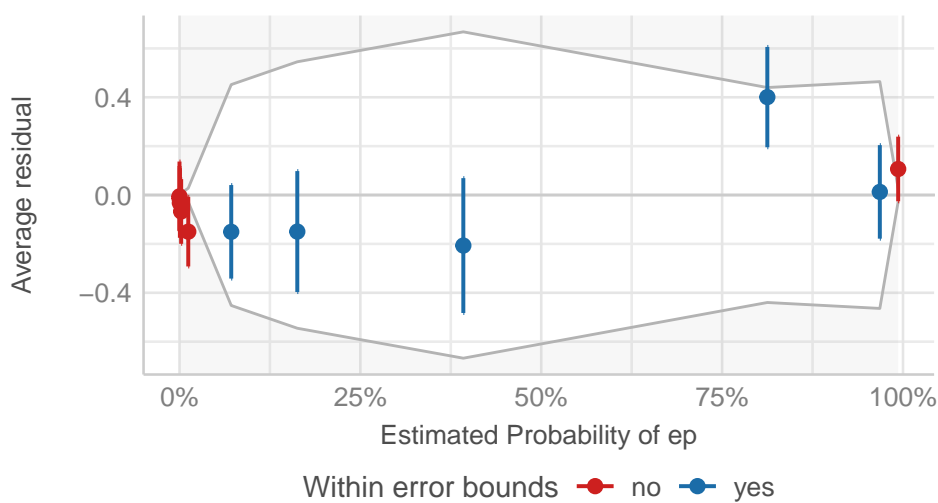
Influential Observations
Points should be inside the contour lines



Uniformity of Residuals
Dots should fall along the line



Binned Residuals
Points should be within error bounds



Collinearity
High collinearity (VIF) may inflate parameter uncertainty

