#### LEARNING AS OPTIMIZATION: MOTIVATION

### Learning as optimization: general procedure

- Goal: Learn parameter  $\theta$  (or weight vector  $\mathbf{w}$ )
- Dataset:  $D = \{(x_1, y_1), ..., (x_n, y_n)\}$
- Write down loss function: how well w fits the data D as a function of w
  - -Common choice:  $\log Pr(D|\mathbf{w})$
- Maximize by differentiating
  - -Then **gradient descent**: repeatedly take a small step in the direction of the gradient

#### Learning as optimization: general procedure for SGD (stochastic gradient descent)

- Big-data problem: we don't want to load all the data D into memory, and the gradient depends on all the data
- Solution:
  - pick a small subset of examples B<<D</li>
  - approximate the gradient using them
    - "on average" this is the right direction
  - take a step in that direction
  - repeat....
- Math: find gradient of w for a single example, not a dataset

B = one example is a very popular choice

#### SGD vs streaming

- Streaming:
  - pass through the data once
  - hold model + one example in memory
  - update model for each example
- Stochastic gradient:
  - pass through the data multiple times
    - stream through a disk file repeatedly
  - hold model + B examples in memory
  - update model via gradient step

B = **one** example is a very popular choice

its simple ©

sometimes its cheaper to evaluate 100 examples at once than one example 100 times





# Efficient Logistic Regression with Stochastic Gradient Descent

William Cohen

#### Learning as optimization for logistic regression

• Goal: Learn the parameter **w** of the classifier

$$P(Y = y|X = \mathbf{x}, \mathbf{w}) = \frac{1}{1 + e^{-\mathbf{x} \cdot \mathbf{w}}}$$

Probability of a single example P(y|x,w) would be

$$P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \frac{1}{1 + e^{-\mathbf{x} \cdot \mathbf{w}}} & \text{if } y = 1\\ 1 - \frac{1}{1 + e^{-\mathbf{x} \cdot \mathbf{w}}} & \text{if } y = 0 \end{cases}$$

• Or with logs:

$$\log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \log p & \text{if } y = 1\\ \log(1 - p) & \text{if } y = 0 \end{cases}$$

$$p \equiv \frac{1}{1 + e^{-\mathbf{x} \cdot \mathbf{w}}} = \frac{1}{1 + \exp(-\sum_{i} x^{j} w^{j})}$$

$$\log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \log p & \text{if } y = 1\\ \log(1 - p) & \text{if } y = 0 \end{cases}$$

$$\frac{\partial}{\partial w^j} \log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \frac{1}{p} \frac{\partial}{\partial w^j} p & \text{if } y = 1\\ \frac{1}{1 - p} (-\frac{\partial}{\partial w^j} p) & \text{if } y = 0 \end{cases}$$

$$(\log f)' = \frac{1}{f} f'$$

$$p \equiv \frac{1}{1 + e^{-\mathbf{x} \cdot \mathbf{w}}} = \frac{1}{1 + \exp(-\sum_{j} x^{j} w^{j})}$$

$$p \equiv \frac{1}{1 + e^{-\mathbf{x} \cdot \mathbf{w}}} = \frac{1}{1 + \exp(-\sum_{j} x^{j} w^{j})}$$

$$1 - p = \frac{1 + \exp(-\sum_{j} x^{j} w^{j})}{1 + \exp(-\sum_{j} x^{j} w^{j})} - \frac{1}{1 + \exp(-\sum_{j} x^{j} w^{j})} = \underbrace{\begin{bmatrix} \exp(-\sum_{j} x^{j} w^{j}) \\ 1 + \exp(-\sum_{j} x^{j} w^{j}) \end{bmatrix}}_{1 + \exp(-\sum_{j} x^{j} w^{j})}$$

$$= \frac{\partial}{\partial w^{j}} (1 + \exp(-\sum_{j} x^{j} w^{j}))^{-1} \qquad (e^{f})' = e^{f}$$

$$= (-1)(1 + \exp(-\sum_{j} x^{j} w^{j}))^{-2} \frac{\partial}{\partial w^{j}} \exp(-\sum_{j} x^{j} w^{j})$$

$$= (-1)(1 + \exp(-\sum_{j} x^{j} w^{j}))^{-2} \exp(-\sum_{j} x^{j} w^{j})(-x^{j})$$

$$= \underbrace{\frac{1}{1 + \exp(-\sum_{j} x^{j} w^{j})}}_{1 + \exp(-\sum_{j} x^{j} w^{j})} \underbrace{\frac{\exp(-\sum_{j} x^{j} w^{j})}{1 + \exp(-\sum_{j} x^{j} w^{j})}}_{x^{j}}$$

$$\frac{\partial}{\partial w^j} p = p(1-p)x^j$$

$$\log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \log p & \text{if } y = 1\\ \log(1 - p) & \text{if } y = 0 \end{cases}$$

$$\frac{\partial}{\partial w^{j}} \log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \frac{1}{p} \frac{\partial}{\partial w^{j}} p & \text{if } y = 1\\ \frac{1}{1 - p} (-\frac{\partial}{\partial w^{j}} p) & \text{if } y = 0 \end{cases}$$

$$\frac{\partial}{\partial w^{j}} p = p(1 - p)x^{j}$$

$$\frac{\partial}{\partial w^j} \log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \frac{1}{p} p(1 - p) x^j = (1 - p) x^j & \text{if } y = 1\\ \frac{1}{1 - p} (-1) p(1 - p) x^j = -p x^j & \text{if } y = 0 \end{cases}$$

$$\frac{\partial}{\partial w^j} \log P(Y = y | X = \mathbf{x}, \mathbf{w}) = (y - p)x^j$$

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \lambda(y - p)\mathbf{x}$$

$$\log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \log p & \text{if } y = 1\\ \log(1 - p) & \text{if } y = 0 \end{cases}$$
$$p = \sigma(\mathbf{x} \cdot \mathbf{w})$$

Magically, when we differentiate, we end up with something very simple and elegant.....

$$\frac{\partial}{\partial \mathbf{w}} L(\mathbf{w} \mid y, \mathbf{x}) = (y - p)\mathbf{x}$$
$$\frac{\partial}{\partial w^{j}} L(\mathbf{w} \mid y, \mathbf{x}) = (y - p)x^{j}$$

The update for gradient descent is just:

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \lambda(y - p)\mathbf{x}$$

## Logistic regression has a sparse update

#### An observation: sparsity!

$$\frac{\partial}{\partial w^j} \log P(Y = y | X = \mathbf{x}, \mathbf{w}) = (y - p)x^j$$

#### Key computational point:

- if  $x^{j}=0$  then the gradient of  $w^{j}$  is zero
- so when processing an example you only need to update weights for the non-zero features of an example.

### Learning as optimization for logistic regression

• The algorithm:

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \lambda(y - p)\mathbf{x}$$

- 1. Initialize a hashtable W
- 2. For t = 1, ..., T
  - For each example  $\mathbf{x}_i, y_i$ :

- do this in random order
- Compute the prediction for  $\mathbf{x}_i$ :

$$p_i = \frac{1}{1 + \exp(-\sum_{j:x_i^j > 0} x_i^j w^j)}$$

- For each non-zero feature of  $\mathbf{x_i}$  with index j and value  $x^j$ :
  - \* If j is not in W, set W[j] = 0.
  - \* Set  $W[j] = W[j] + \lambda(y_i p_i)x^j$
- 3. Output the hash table W.

#### REGULARIZED LOGISTIC REGRESSION

#### Regularized logistic regression

Replace LCL

$$\log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \log p & \text{if } y = 1\\ \log(1 - p) & \text{if } y = 0 \end{cases}$$

 with LCL + penalty for large weights, eg

$$LCL - \mu \sum_{j=1}^{d} (w^j)^2$$

So:

$$\frac{\partial}{\partial w^j} \log P(Y = y | X = \mathbf{x}, \mathbf{w}) = (y - p)x^j$$

becomes:

$$\frac{\partial}{\partial w^j} \log P(Y = y | X = \mathbf{x}, \mathbf{w}) - \mu \sum_{j=1}^d (w^j)^2 = (y - p)x^j - 2\mu w^j$$

#### Regularized logistic regression

Replace LCL

$$\log P(Y = y | X = \mathbf{x}, \mathbf{w}) = \begin{cases} \log p & \text{if } y = 1\\ \log(1 - p) & \text{if } y = 0 \end{cases}$$

 with LCL + penalty for large weights, eg

$$LCL - \mu \sum_{j=1}^{d} (w^j)^2$$

So the update for wj becomes:

$$w^j = w^j + \lambda((y-p)x^j - 2\mu w^j)$$

Or

$$w^j = w^j + \lambda(y - p)x^j - \lambda 2\mu w^j$$

### Learning as optimization for logistic regression

• Algorithm:

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \lambda(y - p)\mathbf{x}$$

- 1. Initialize a hashtable W
- 2. For t = 1, ..., T
  - For each example  $\mathbf{x}_i, y_i$ :

- do this in random order
- Compute the prediction for  $\mathbf{x}_i$ :

$$p_i = \frac{1}{1 + \exp(-\sum_{j:x_i^j > 0} x_i^j w^j)}$$

- For each non-zero feature of  $\mathbf{x_i}$  with index j and value  $x^j$ :
  - \* If j is not in W, set W[j] = 0.
  - \* Set  $W[j] = W[j] + \lambda(y_i p_i)x^j$
- 3. Output the hash table W.

• Algorithm:

$$w^j = w^j + \lambda(y - p)x^j - \lambda 2\mu w^j$$

- 1. Initialize a hashtable W
- 2. For t = 1, ..., T
  - For each example  $\mathbf{x}_i, y_i$ :
    - Compute the prediction for  $\mathbf{x}_i$ :

Time goes from O(nT) to O(mVT) where

- n = number of non-zero entries,
- m = number of examples
- V = number of features
- T = number of passes over data

$$p_i = \frac{1}{1 + \exp(-\sum_{j:x_i^j > 0} x_i^j w^j)}$$

- For each non-zero feature of  $\mathbf{x_i}$  with index j and value  $x^j$ :
  - \* If j is not in W, set W[j] = 0.
  - \* Set  $W[j] = W[j] + \lambda(y-p)x^j \lambda 2\mu w^j$
- 3. Output the hash table W.

#### This change is very important for large datasets

- We've lost the ability to do sparse updates
- This makes learning much much more expensive
  - $-2*10^6$  examples
  - 2\*10<sup>8</sup> non-zero entries
  - $-2*10^6 + features$
  - -10,000x slower (!)

#### Time goes from O(nT) to O(mVT) where

- n = number of non-zero entries,
- m = number of examples
- V = number of features
- T = number of passes over data

#### SPARSE UPDATES FOR REGULARIZED LOGISTIC REGRESSION

- Final algorithm:  $w^j = w^j + \lambda(y-p)x^j \lambda 2\mu w^j$
- Initialize hashtable W
- For each iteration t=1,...T
  - For each example  $(\mathbf{x}_i, y_i)$ 
    - $p_i = \dots$
    - For each feature W[j]

$$-W[j] = W[j] - \lambda 2\mu W[j]$$

 $-If x_i^j > 0$  then

$$W[j] = W[j] + \lambda (y_i - p^i) X_j$$

- Final algorithm:  $w^j = w^j + \lambda(y-p)x^j \lambda 2\mu w^j$
- Initialize hashtable W
- For each iteration t=1,...T
  - For each example  $(\mathbf{x}_i, y_i)$ 
    - $p_i = ...$
    - For each feature W[j]

$$-W[j] *= (1 - \lambda 2\mu)$$

 $-If x_i^j > 0$  then

$$W[j] = W[j] + \lambda (y_i - p^i) X_j$$

• Final algorithm:

$$w^{j} = w^{j} + \lambda(y - p)x^{j} - \lambda 2\mu w^{j}$$

- Initialize hashtable W
- For each iteration t=1,...T
  - For each example  $(\mathbf{x}_i, y_i)$ 
    - $p_i = \dots$
    - For each feature W[j]
      - $-\text{If } x_i^j > 0 \text{ then }$

$$W[j] *= (1 - \lambda 2\mu)^A$$

$$W[j] = W[j] + \lambda (y_i - p^i) X_j$$

A is number of examples seen since the last time we did an x>0 update on W[j]

Final algorithm: 
$$w^j = w^j + \lambda(y - p)x^j - \lambda 2\mu w^j$$

- Initialize hashtables W, A and set k=0
- For each iteration t=1,...T
  - For each example  $(\mathbf{x}_i, y_i)$ 
    - $p_i = ...; k++$
    - For each feature *W[j]* 
      - -If x > 0 then

k-A[j] is number of examples seen since the last time we did an x>0 update on W[j]

» 
$$W[j] *= (1 - \lambda 2\mu)^{k-A[j]}$$

$$W[j] = W[j] + \lambda (y_i - p^i) X_i$$

$$A[j] = k$$

Final algorithm:

$$w^j = w^j + \lambda(y - p)x^j - \lambda 2\mu w^j$$

- Initialize hashtables  $W_{i}A$  and set k=0
- For each iteration t=1,...T
  - For each example  $(\mathbf{x}_i, y_i)$

• 
$$p_i = ...; k++$$

- For each feature *W[j]* 
  - $-If x_i^j > 0 then$

» 
$$W[j] *= (1 - \lambda 2\mu)^{k-A[j]}$$

$$W[j] = W[j] + \lambda (y_i - p^i) x_j$$

$$A[j] = k$$

- k = "clock" reading
- A[j] = clock reading last time feature j was "active"
- we implement the "weight decay" update using a "lazy" strategy: weights are decayed in one shot when a feature is "active"

• Final algorithm:

$$w^j = w^j + \lambda(y - p)x^j - \lambda 2\mu w^j$$

- Initialize hashtables  $W_{i}A$  and set k=0
- For each iteration t=1,...T
  - For each example  $(\mathbf{x}_i, y_i)$ 
    - $p_i = ...; k++$
    - For each feature *W[j]* 
      - $-If x_i > 0$  then

Time goes from O(nT) to O(mVT) where

- n = number of non-zero entries,
- m = number of examples
- V = number of features
- T = number of passes over data

Memory use doubles.

$$|W[j]|^* = (1 - \lambda 2\mu)^{k-A[j]}$$

$$|W[j]| = W[j] + \lambda (y_i - p^i) x_j$$

$$|A[j]| = k$$

#### Comments

- What's happened here:
  - Our update involves a sparse part and a dense part
    - Sparse: empirical loss on this example
    - Dense: regularization loss not affected by the example
  - We remove the *dense part* of the update
    - Old example update:
      - for each feature { do something example-independent}
      - For each active feature { do something example-dependent}
    - New example update:
      - For each active feature:
        - » {simulate the prior example-independent updates}
        - » {do something example-dependent}