report_experiments

December 9, 2022

```
[36]: import matplotlib.pyplot as plt from PIL import Image from IPython.display import Video
```

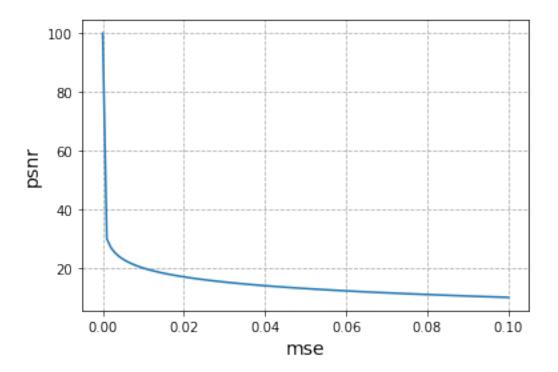
0.0.1 Peak Signal-to-Noise Ratio

```
PSNR = -10\log_{10}(MSE)
```

```
[35]: mse = np.linspace(0., 0.1, 100)
    psnr = -10. * np.log10(mse+1e-10)

fig = plt.figure()
    plt.plot(mse, psnr)
    plt.grid(linestyle='--')
    plt.xlabel("mse", fontsize=14)
    plt.ylabel("psnr", fontsize=14)
```

```
[35]: Text(0, 0.5, 'psnr')
```



1 Experiments

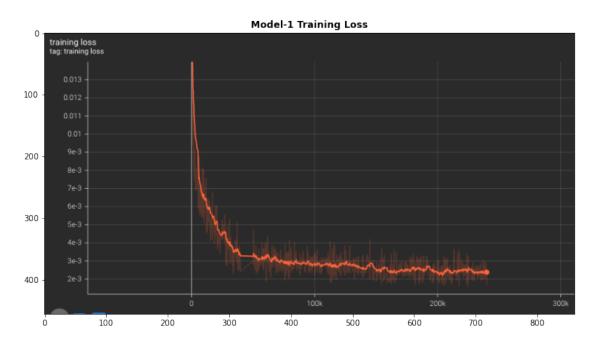
1.1 Experiment - Effect of Positional Encoding

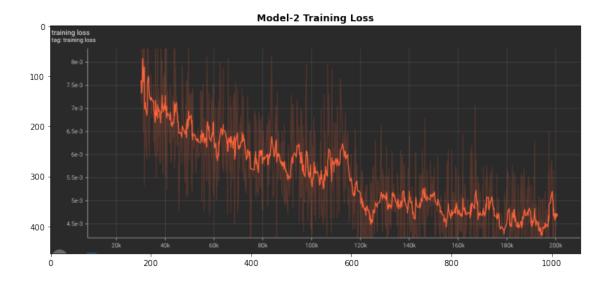
- Trained the network for 200k iterations on 150 training samples (100 train + 50 val) and performed validation on the remaining 50 validation samples.
- Denote: Model-1 with positional encoding and Model-2 without positional encoding.
- Clearly, Model-1 performs better than Model-2 based on the validation set PSNR.
- Model-1 Validation PSNR > 26, Model-2 Validation PSNR > 23

1.2 Model-1 (with positional encoding) & Model-2 (without positional encoding)

1.3 Model-1 vs Model-2 Loss Plot

[57]: Text(0.5, 1.0, 'Model-2 Training Loss')





1.4 Model-1 vs Model-2 Training PSNR Plot

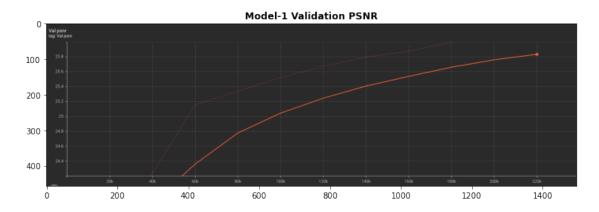
[58]: Text(0.5, 1.0, 'Model-2 Training PSNR')

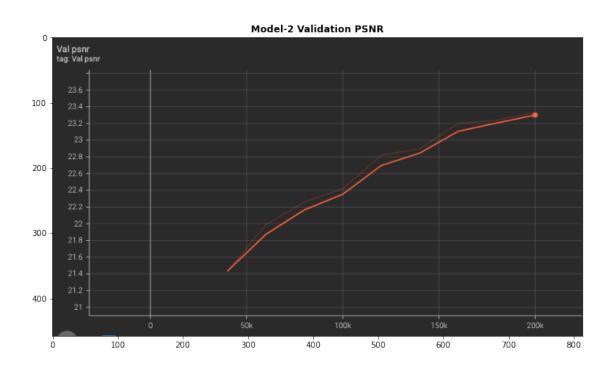




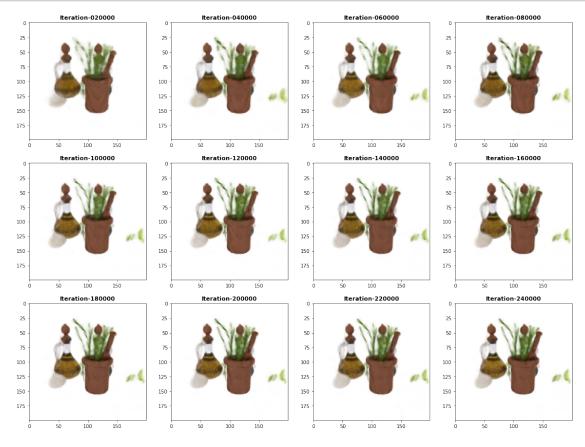
1.5 Model-1 vs Model-2 Validation PSNR Plot

[59]: Text(0.5, 1.0, 'Model-2 Validation PSNR')

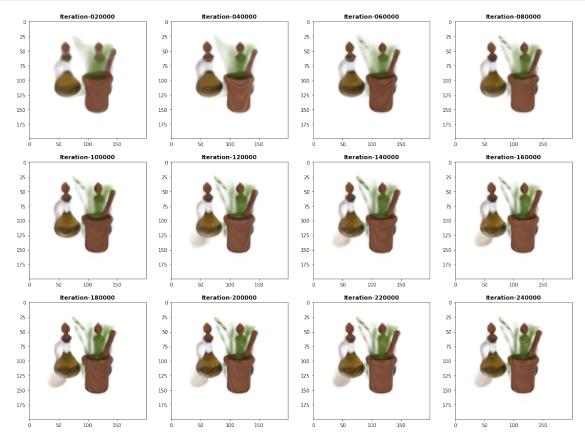




1.6 Model-1: Synthesized Validation Images during training : 1_val_0075.png



1.7 Model-2: Synthesized Validation Images during training: 1_val_0075.png



1.8 Model-1 Synthesized Images: 1 val 0050 - 1 val 0099

[40]: <IPython.core.display.Video object>

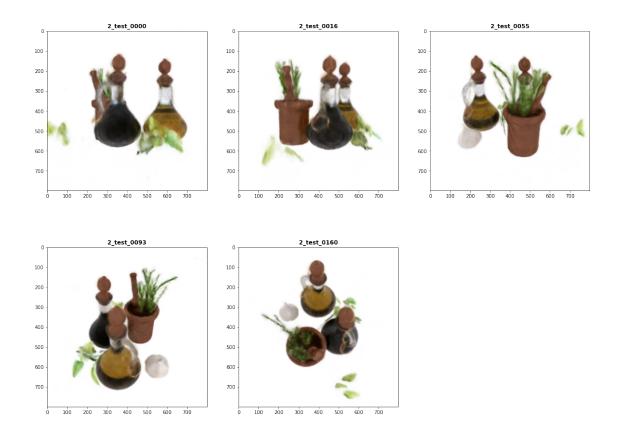
1.9 Model-2 Synthesized Images: 1_val_0050 - 1_val_0099

```
[45]: Video("../logdir/finalexp001_whitebkgd_noembed/

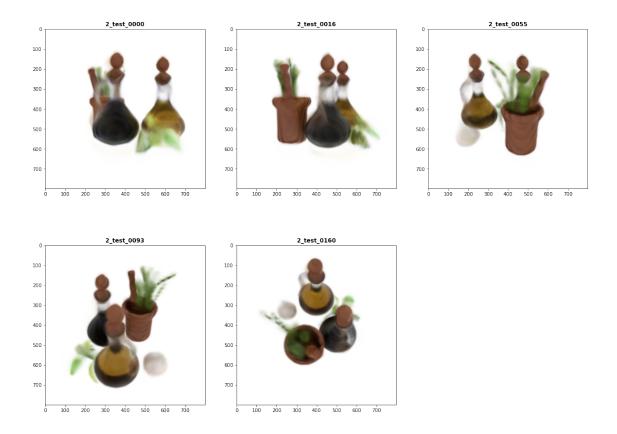
→finalexp001_whitebkgd_noembed_valset_240000_rgb.mp4")
```

[45]: <IPython.core.display.Video object>

1.10 Model-1 Synthesized Test Images - 2_test_(0000, 0016, 0055, 0093, 0160)



1.11 Model-2 : Synthesized Test Images - 2_test_(0000, 0016, 0055, 0093, 0160)

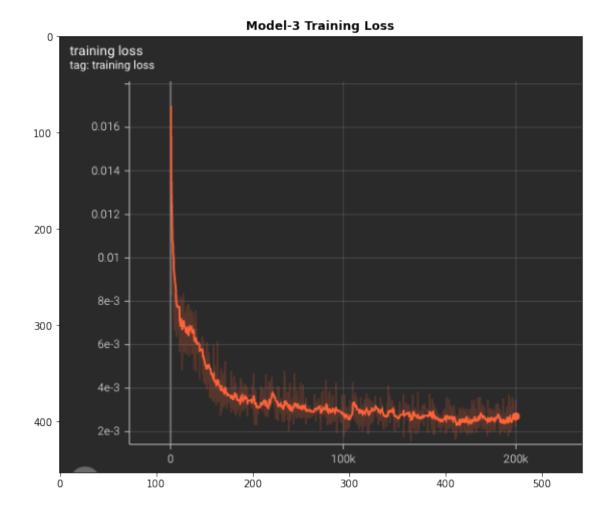


1.12 Experiment - Reducing the number of positional encoding parameters

- Used L=5 for encoding position coordinates instead of L=10 used for Model-1 and 2
- $\bullet~$ Used L = 2 for encoding direction coordinates instead of L=5 used for Model-1 and 2
- Denote this trained model by Model-3
- Trained this model for 200k iterations

```
[60]: fig = plt.figure(figsize=(12,8))
    plt.imshow(Image.open("../logdir/finalexp002_whitebkgd/train_loss_plot.png"))
    plt.title("Model-3 Training Loss", fontweight="bold")
```

[60]: Text(0.5, 1.0, 'Model-3 Training Loss')



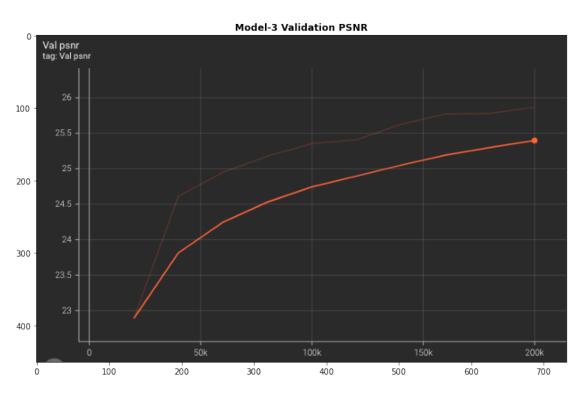
```
[61]: fig = plt.figure(figsize=(12,8))
    plt.imshow(Image.open("../logdir/finalexp002_whitebkgd/train_psnr_plot.png"))
    plt.title("Model-3 Training PSNR", fontweight="bold")
```

[61]: Text(0.5, 1.0, 'Model-3 Training PSNR')

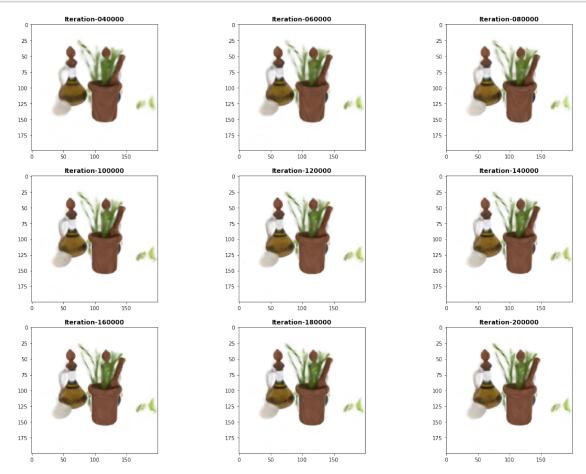


```
[62]: fig = plt.figure(figsize=(12,8))
    plt.imshow(Image.open("../logdir/finalexp002_whitebkgd/val_psnr_plot.png"))
    plt.title("Model-3 Validation PSNR", fontweight="bold")
```

[62]: Text(0.5, 1.0, 'Model-3 Validation PSNR')



1.13 Model-3 Synthesized Validation Images



$1.14 \quad Model-3 \ Synthesized \ Images: \ 1_val_0050 - 1_val_0099$

```
[52]: Video("../logdir/finalexp002_whitebkgd/finalexp002_whitebkgd_valset_200000_rgb. 

→mp4")
```

[52]: <IPython.core.display.Video object>