

1. Task Overview

1. Bone Segmentation (Task 1.1)

- **Goal:** Extract femur & tibia from the CT scan.
- **Method:** Use thresholding + morphology (no AI).
- **Output:** `femur_mask.nii.gz`, `tibia_mask.nii.gz`.

2. Expand Mask by 2mm (Task 1.2)

- **Goal:** Grow tibia mask outward by 2mm.
- **Note:** 2mm must be adjustable.
- **Output:** `tibia_2mm.nii.gz`.

3. Randomized Mask (Task 1.3)

- **Goal:** Create masks between original and 2mm edges.
- **Rules:**
 - Never go beyond 2mm.
 - Never smaller than original.
- **Output:** `tibia_rand1.nii.gz`, `tibia_rand2.nii.gz`.

4. Landmark Detection (Task 1.4)

- **Goal:** Find lowest medial/lateral points on tibia
- **Output:**
 - `landmarks.txt` with coordinates.

2. Methodology

2.1 Task 1.1: Bone Segmentation

1. Thresholding:

- Applied threshold (HU=120) to extract bone structures
- Created initial bone mask: `img_bones = np.where(img >= threshold, img, 0)`

2. Edge Enhancement:

- Used unsharp masking to highlight edges
- Created edge-enhanced image: `img_edges = img_bones + (img_bones - blurred) * 2`

3. Mask Creation:

- Thresholded edge-enhanced image (value > 250)
- Removed small objects (<2000 voxels)
- Filled holes in both axial and sagittal planes

4. Femur/Tibia Separation:

- Used connected components labeling
- Separated bones by vertical position (centroid y-coordinate)
- Femur = upper components, Tibia = lower component

5. Post-processing:

- Applied morphological closing to each bone
- Filled remaining holes
- Multiplied with original image to get final segments

6. Output:

- Saved combined mask as `overall_segment.nii.gz`
- Note: Includes coordinate transformation to match original orientation

2.2 Task 1.2: Contour Expansion

1. Voxel-Aware Dilation:

- Calculated expansion in voxels using image spacing (mm/voxel)
- Created ellipsoidal structuring element matching physical dimensions
- Used binary dilation to expand mask outward

2. Outputs:

- Generated 2mm and 4mm expanded masks
- Saved as `overall_segment_expanded_2mm.nii.gz` and `overall_segment_expanded_4mm.nii.gz`

2.3 Task 1.3: Randomized Contour Adjustment

1. **Ring Selection:**

- Identified voxels between original and 2mm expanded boundaries
- Randomly selected 50% and 80% of these boundary voxels

2. **Mask Creation:**

- Combined original mask with randomly selected voxels
- Ensured output stayed within expansion limits

3. **Outputs:**

- Saved as `original_randomized_mask_1.nii.gz` (50%) and `original_randomized_mask_2.nii.gz` (80%)

2.4 Task 1.4: Landmark Detection

1. **Surface Extraction:**

- Identified all surface voxels (bone voxels with at least one empty neighbor)
- Split into medial/lateral regions using x-axis midpoint

2. **Lowest Point Detection:**

- Found most inferior (minimum z-coordinate) points in each region
- Returned as (z,y,x) coordinates in voxel space

3. **Implementation Notes:**

- Handled edge cases where no surface points were found
- Included coordinate transformation to match original DICOM orientation

3. Results

Landmark Detection Results (Tibia)

Coordinates in Voxel Space (Z,Y,X):

1. **Medial Lowest Point:** (72, 215, 244)
2. **Lateral Lowest Point:** (17, 0, 349)

4. Code Structure

```
NAMII/  
├─ data/  
│   └─ 3702_left_knee.nii           # Original CT scan input  
├─ results/  
│   ├── coordinates.txt             # Landmark coordinates output  
│   └─ (masks/)                     # segmentation outputs  
├─ segmentation_env/                # Virtual environment (optional)  
├─ src/  
│   └─ segmentation.ipynb           # Main segmentation code  
├─ .gitignore                       # Specifies untracked files  
├─ README.md                        # Project documentation  
└─ requirements.txt                 # Python dependencies
```