```
# -*- coding: utf-8 -*-
"""cv_hw3_filters_saraGhavampour_9812762781.ipynb
Automatically generated by Colaboratory.
https://colab.research.google.com/drive/16EApS670kKQpXiBmjVgm4eGGgQJYHW0I
| wget --load-cookies /tmp/cookies.txt "https://docs.google.com/uc?export=download&confirm=$(wget --quiet --save-cookies /tmp/cookies.txt --keep-session-cookies --no-check-certificate
Bwget --load-cookies /tmp/cookies.txt "https://docs.google.com/uc?export=download&confirm=$(wget --quiet --save-cookies /tmp/cookies.txt --keep-session-cookies --no-check-certificate
# Commented out IPython magic to ensure Python compatibility.
import numpy as np
import matplotlib.pyplot as plt
import sklearn
import cv2
from math import *
from sklearn.metrics import mean_squared_error
# %matplotlib inline
elaine_img=cv2.imread('Elaine.bmp')
elaine_img = cv2.cvtColor(elaine_img,cv2.COLOR_BGR2GRAY)
plt.imshow(elaine_img,cmap='gray')
plt.axis('off')
plt.show()
#(512, 512) uint8
lena_img=cv2.imread('Lena.bmp')
lena_img = cv2.cvtColor(lena_img,cv2.COLOR_BGR2GRAY)
plt.imshow(lena_img,cmap='gray')
plt.axis('off')
plt.show()
def show_img(*args, figsize=10, is_gray=True, title=None, fontsize=12):
     if isinstance(figsize, int):
    figsize = (figsize, figsize)
images = args[0] if type(args[0]) is list else list(args)
     cmap=None
     cmap = worke
if not is_gray:
    images = list(map(lambda x: cv2.cvtColor(x, cv2.CoLOR_BGR2RGB), images))
.
           cmap =
     cmap = gray'
plt.figure(figsize=figsize)
for i in range(1, len(images)+1):
    plt.subplot(1, len(images), i)
          if title is not
                plt.title(title[i-1], fontsize=fontsize)
          plt.imshow(images[i-1], cmap=cmap)
          plt.axis('off')
"""3.1.3"""
def apply_box_filter_same_padding(img,window_size):
  out=img.copy()
pad = floor((window_size-1)/2)
  pad = !ioor((Window_size-1)//)
img=np.pad(img.copy(), ((pad.pad), (pad.pad)),mode='constant',constant_values=(0,0))
filter = np.ones((window_size,window_size))
for i in range(img.shape[0]-window_size+1):
    for j in range(img.shape[1]-window_size+1):
    window=img[i:i-window_size_j:j-window_size]
    out[i,j]=np.sum(window*filter)/(window_size**2)
  return out.astype('uint8')
# for i in range (0,20):
# elaine_box_filter_same_1 = apply_box_filter_same_padding(elaine_img,3)
# show_img(elaine_box_filter_same_1)
  elaine_box_filter_same_2 = apply_box_filter_same_padding(elaine_img,3)
show_img(elaine_box_filter_same_2)
# for i in range (0,150):
# elaine_box_filter_same_3 = apply_box_filter_same_padding(elaine_img,3)
# show img(elaine box filter same 3)
# for i in range (0,350):
# elaine box filter same 3 = apply box filter same padding(elaine img,3)
# show_img(elaine_box_filter_same_3)
"""3.1.4"""
from skimage.util import random_noise
def noise_distributer(img,noise_mode,noise_density,var):
  if noise mode == 's&p':
     out=random_noise(img, noise_mode, amount=noise_density)
  if noise mode ==
                          'gaussian': # mean?
  out=random_noise(img,noise_mode,var=var)
return (out*255).astype('uint8')
elaine noise = noise distributer(elaine img, 'gaussian', 0, 0.05)
show_img(elaine_noise,figsize=8)
elaine_denoisel=apply_box_filter_same_padding(elaine_noise,3)
show_img(elaine_denoisel,figsize=6)
elaine_denoise2=apply_box_filter_same_padding(elaine_noise,5)
show_img(elaine_denoise2,figsize=6)
elaine_denoise4=apply_box_filter_same_padding(elaine_noise,11)
show_img(elaine_denoise4,figsize=6)
"""3.1.5"""
print(mean_squared_error(elaine_img,elaine_denoisel))
print(mean squared error(elaine img,elaine denoise2))
print(mean squared error(elaine img,elaine denoise3))
print(mean squared error(elaine img,elaine denoise4))
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"""3.1.6"""
elaine_120_blured=cv2.imread('120.jpeg')
elaine 120 blured = cv2.cvtColor(elaine 120 blured,cv2.COLOR_BGR2GRAY)
plt.imshow(elaine_120_blured,cmap='gray')
plt.axis('off')
plt.show()
copy = elaine_120_blured.copy()
for i in range(0,2):
    copy = cv2.filter2D(src=copy, ddepth=-1, kernel=laplacian_HV_filter)
 show_img(copy)
 copy = elaine 120 blured.copy()
copy = cv2.filter2D(src=copy, ddepth=-1, kernel=laplacian_HV_filter)
copy = cv2.f
show_img(copy)
copy = elaine_120_blured.copy()
for i in range(0,4):
   copy = cv2.filter2D(src=copy, ddepth=-1, kernel=laplacian_HV_filter)
 show_img(copy)
 copy = elaine_120_blured.copy()
for i in range(0,5):
    copy = cv2.filter2D(src=copy, ddepth=-1, kernel=laplacian_HV_filter)
show_img(copy)
 """3.2
 3.2.1
 noisy_sp_img_results=[]
noisy_sp_img_results.append(noise_distributer(elaine_img,'ssp',0.05,0))
noisy_sp_img_results.append(noise_distributer(elaine_img,'ssp',0.1,0))
noisy_sp_img_results.append(noise_distributer(elaine_img,'ssp',0.2,0))
noisy_sp_img_results.append(noise_distributer(elaine_img,'ssp',0.2,0))
noisy_sp_img_results.append(noise_distributer(elaine_img,'ssp',0.4,0))
titles=['salt&pepper noise with noise density 0.05', salt&pepper noise with noise density 0.2', salt&pepper noise with noise density 0.4']
show_img(noisy_sp_img_results, figsize=30,title=titles)
 def apply median filter(img, window size):
    img_copy=img.copy()
shift = floor(window_size/2)
    shift = floor(window_size/2)
x,y=img_copy.shape
out = np.zeros((x-2*shift,y-2*shift))
for i in range(shift,x-shift):
    for j in range(shift,y-shift):
    window = img_copy[i-shift:i+shift,j-shift:j+shift]
    window = window.ravel()
    median=pp.median(window)
    out[i-shift,j-shift]=median
    return out
 \begin{array}{lll} \tt elaine\_sp\_01\_median\_5=apply\_median\_filter(noisy\_sp\_img\_results[3],3) \\ \tt show\_img(elaine\_sp\_01\_median\_5) \\ \end{array} 
 elaine_sp_01_median_5
filter_wondow_sizes=[3,5,7,9,11]
median_filter_results=[]
median_filter_results_titles=[]
noise_densities=[0.05,0.1,0.2,0.4]
for i in range(0,np.array(median_filter_results).shape[0]):
    show_img(median_filter_results[i], figsize=30,title=median_filter_results_titles[i])
 """3.2.2"""
 noisy_gaussian_img_results=[]
noisy_gaussian_img_results.append(noise_distributer(elaine_img,'gaussian',0,0.01)) noisy_gaussian_img_results.append(noise_distributer(elaine_img,'gaussian',0,0.05)) noisy_gaussian_img_results.append(noise_distributer(elaine_img,'gaussian',0,0.1))
 titles=['qaussian noise with noise density 0.01','qaussian noise with noise density 0.05','qaussian noise with noise density 0.1']
 show_img(noisy_gaussian_img_results, figsize=20,title=titles)
filter_wondow_sizes=[3,5,7,9,11]
median_filter_results=[]
median_filter_results_titles=[]
for (index,noisy_img) in enumerate(noisy_gaussian_img_results):
    median_results_window=[] # each row for each imahe with density
    median_results_window_title=[]
    for size in filter_wondow sizes:
        median_img=apply_median_filter(noisy_img, size)
        median_results_window.append(median_img) # each col is size
        median_results_window_title.append(f'median_filter size: {size} on gaussian noise: {noise_densities[index]}')
        shift=floor(size/2)
        x,y=elaine_img_shape
        bounded_noisey_image = elaine_img[shift:x-shift,shift:y-shift]
        mse = mean_squared_error(bounded_noisey_image,median_img)
        print(f'mse_elaine_img_s_median_img)
        print(f'mse_elaine_img_s_median_img)
        print(f'mse_elaine_img_s_median_img)
        print(f'mse_elaine_img_s_median_img)
 noise densities=[0.01,0.05,0.1]
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median_filter_results.append(median_results_window)
median_filter_results_titles.append(median_results_window_title)
 for i in range(0,np.array(median_filter_results).shape[0]):
    show img(median_filter_results[i], figsize=30,title=median_filter_results_titles[i])
 def apply box filter(img, window size):
    img_copy=img.copy()
shift = floor(window_size)?
x,y=img_copy.shape
out = np.zeros((x-2*shift,y-2*shift))
for i in range(shift,x-shift):
    for j in range(shift,y-shift):
        window = img_copy[i-shift:i+shift+1,j-shift:j+shift+1]
             #print (window)
             box_avg = (np.sum(window)) / (window_size**2)
out[i-shift,j-shift]=box_avg
     return out.astype('uint8')
filter_wondow_sizes=[3,5,7,9,11]
boxfilter_filter_results=[]
boxfilter_filter_results_titles=[]
noise_densities=[0.01,0.05,0.1]
for (index,noisy_img) in enumerate(noisy_gaussian_img_results):
    boxfilter_results_window=[] # each row for each imahe with density
    boxfilter_results_window_title=[]
    for size in filter_wondow sizes:
    boxfilter_img=apply_box_filter(noisy_img, size)
    boxfilter_img=apply_box_filter(noisy_img, size)
    boxfilter_results_window.append(boxfilter_img) # each col is size
    boxfilter_results_window_title.append(f'boxfilter_filter_size: {size} on gaussian noise: {noise_densities[index]}')
    shift=floor(size/2)
    v_velate_img_shape
        boxfilter_filter_results_append (boxfilter_results_window)
boxfilter_filter_results_titles.append (boxfilter_results_window_title)
 for i in range(0,np.array(boxfilter_filter_results).shape[0]):
    show_img(boxfilter_filter_results[i], figsize=30,title=boxfilter_filter_results_titles[i])
 def apply_guessian_filter(img,window_size):
   img_copy=img.copy()
   shift = floor(window_size/2)
     x,y=img_copy.shape
out = np.zeros((x-2*shift,y-2*shift))
for i in range(shift,x-shift):
    for j in range(shift,y-shift):
            window = img copy[i-shift:j+shift+1,j-shift:j+shift+1] 
#print(window) box_avg = (np.sum(window)) / (window_size**2) 
out[i-shift,j-shift]=box_avg
            x, y = np.mgrid[-kernel size//2 + 1:kernel size//2 + 1, -kernel_size//2 + 1:kernel_size//2 + 1]
g = np.exp(-((x**2 + y**2)/(2.0*sigma**2)))
return g/g.sum()
     return out.astype('uint8')
 """3.4"""
 edge_detector_341a=1/2*np.array([1,0,-1])
edge_detector_341b=1/6*np.array([[1,0,-1],[1,0,-1],[1,0,-1]])
edge_detector_341c=1/8*np.array([[1,0,-1],[2,0,-2],[1,0,-1]])
 def convolve2D(img, filter):
    f=filter.shape[0]
pad = floor((f-1)/2)
     out=img.copy()
     img=np.pad(img.copy(),((pad,pad),(pad,pad)),mode='constant',constant values=(0,0))
     for i in range(img.shape[0]-f+1):
    for j in range(img.shape[1]-f+1):
        window=img[i:i+f,j:j+f]
            out[i,j]=np.sum(window*filter)
 elaine_341a = convolve2D(elaine_img,edge_detector_341a)
show_img(elaine_341a,figsize=10)
 elaine 341a = cv2.filter2D(src=elaine img, ddepth=-1, kernel=edge detector 341a)
 show_img(elaine_341a,figsize=10)
 elaine_341b = cv2.filter2D(src=elaine_img, ddepth=-1, kernel=edge_detector_341b)
 show img(elaine 341b,figsize=10)
 elaine_341c = cv2.filter2D(src=elaine_img, ddepth=-1, kernel=edge_detector_341c)
show_img(elaine_341c,figsize=10)
edge_detector_342a=np.array([[1,0],[0,-1]])
edge_detector_342b=np.array([[0,1],[-1,0]])
elaine_342a = cv2.filter2D(src=elaine_img, ddepth=-1, kernel=edge_detector_342a)
elaine_342b = cv2.filter2D(src=elaine_img, ddepth=-1, kernel=edge_detector_342b)
show_img(elaine_342a,elaine_342b,title=['3.4.2 filter a','3.4.2 filter b'],figsize=20)
                     unsharp masking"""
lena_gus3=cv2.GaussianBlur(lena_img,(3,3),2)
lena_gus5=cv2.GaussianBlur(lena_img,(5,5),2)
lena_gus7=cv2.GaussianBlur(lena_img,(7,7),2)
lena_gus9=cv2.GaussianBlur(lena_img,(9,9),2)
lena_gus11=cv2.GaussianBlur(lena_img,(11,11),2)
 show img(lena gusl1,lena img)
def unsharp_masking_formula(alpha,img,smooth_img):
   out = (1-alpha)*img + alpha*smooth_img
     return out
 lena_gus3_alpha0=unsharp_masking_formula(0,lena_img,lena_gus3)
lena_gus3_alpha1=unsharp_masking_formula(1,lena_img,lena_gus3)
show_img(lena_img,lena_gus3_alpha0,lena_gus3_alpha1,title=['lena_img','lena_gus3_alpha0','lena_gus3_alpha1'],figsize=16)
 lena_gus5_alpha0=unsharp_masking_formula(0,lena_img,lena_gus5)
lena_gus5_alpha1=unsharp_masking_formula(1,lena_img,lena_gus5)
show_img(lena_img,lena_gus5_alpha0,lena_gus5_alpha1,title=['lena_img','lena_gus5_alpha0','lena_gus5_alpha1'],figsize=16)
```

```
lena gus7 alpha0-unsharp masking formula().lena imp,lena gus7 lena gus7 alpha1-unsharp masking formula().lena imp,lena gus7 alpha1, titler('lena img','lena gus7 alpha0','lena gus7 alpha1), figsize=16)

lena gus9 alpha0-unsharp masking formula().lena imp,lena gus9 lena gus9 alpha0','lena gus1 alpha
```