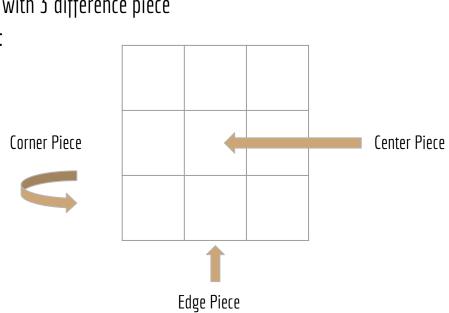
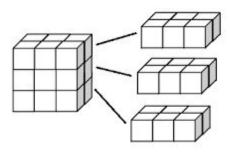
# Solving a Rubik's Cube with Reinforced Learning

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## Cube Background

Each Rubik's Cube has 6 faces with 3 difference piece types:

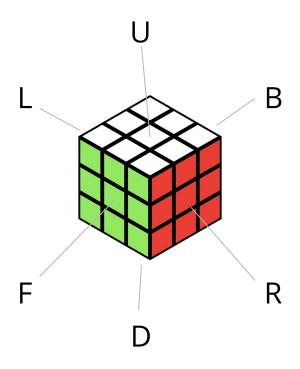




### Problem Statement

Can I train a DNN to solve a rubik's cube?

Facial Notation will be represented as such and each movement will be recorded with 'to represent a counterclockwise movement.

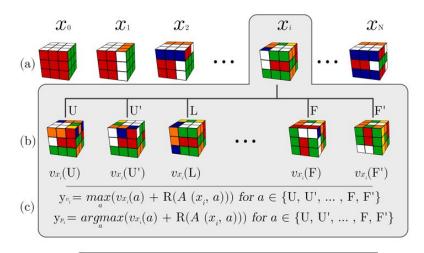


Example Notation: F U R L R' D' U B

### Approach

For data collection I decided to generate training samples starting from a solved state and taking random actions.

The method I chose to use is a method called Autodidactic Iteration (ADI), developed by UC Irvine Statistics and CS alumni, which is essentially an interactive surprised learning procedure that trains a neural network.



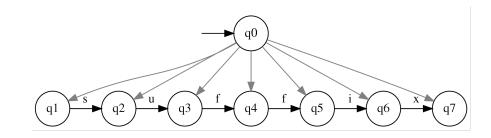
### Algorithm 1: Autodidactic Iteration

**Initialization:**  $\theta$  initialized using Glorot initialization **repeat** 

### Solving the cube:

Along with our trained neural network we build a search tree iteratively by beginning with a tree consisting only of our starting state.

This simulation is performed until we reach the solved state or exceeds maximum computation time.



### Results

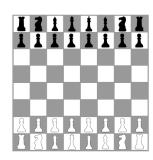
While optimizing for both computation time and moves made, it would average around 30 moves.
Compared to a human, between 50 - 60 moves, and the human world record sitting at 20 moves.
Computers say that the almost 100% of solves are within 16-19 moves.

### Extensions



### Some applications of DRL (Deep Reinforced Learning):

- Self Driving Cars
- NLP (Natural Language Processing)
- Other Games: Ex. Go, Chess, etc.





Recommendations

I would've liked to tried other types of methods while developing this neural net.
Methods that optimized for computation time or moves.

Creating a better interactive visualization

Reattempt this project using self collected image data

