

SJEČIŠTE BRAKE I SFERE

$$(p-c) \cdot (p-c) - R^2 = 0$$

$$(e+td-c) \cdot (e+td-c) - R^2 = 0$$

$$(d \cdot d)t^2 + 2d(e-c)t + (e-c) \cdot (e-c) - R^2 = 0$$

$$t_{1,2} = \frac{-d(e-c) \pm \sqrt{(d(e-c))^2 - (d \cdot d)((e-c) \cdot (e-c) - R^2)}}{d \cdot d}$$

SJEČIŠTE BRAKE I TROUGA

$$\alpha + \beta + \gamma = 1 : e+td = \alpha a + \beta b + \gamma c = a + \beta(b-a) + \gamma(c-a)$$

$$\begin{bmatrix} x_a - x_b & x_a - x_c & x_d \\ y_a - y_b & y_a - y_c & y_d \\ z_a - z_b & z_a - z_c & z_d \end{bmatrix} \begin{bmatrix} \beta \\ \gamma \\ t \end{bmatrix} = \begin{bmatrix} x_a - x_e \\ y_a - y_e \\ z_a - z_e \end{bmatrix}$$

$$A = \begin{bmatrix} x_a - x_b & x_a - x_c & x_d \\ y_a - y_b & y_a - y_c & y_d \\ z_a - z_b & z_a - z_c & z_d \end{bmatrix} = \begin{bmatrix} a & d & g \\ b & e & h \\ c & f & i \end{bmatrix}, \quad x = \begin{bmatrix} \beta \\ \gamma \\ t \end{bmatrix}, \quad b = \begin{bmatrix} x_a - x_e \\ y_a - y_e \\ z_a - z_e \end{bmatrix} = \begin{bmatrix} i \\ j \\ k \end{bmatrix}$$

$$\beta = \frac{\det[A_2, A_3]}{\det A}, \quad \gamma = \frac{\det[A_1, A_3]}{\det A}, \quad t = \frac{\det[A_1, A_2, b]}{\det A}$$

$$\beta = \frac{i(ei - hf) + k(gf - di) + e(dh - eg)}{a(ei - hf) + b(gf - di) + c(dh - eg)}$$

$$\gamma = \frac{i(af - gb) + h(jc - ad) + g(bl - kc)}{a(ei - hf) + b(gf - di) + c(dh - eg)}$$

$$t = - \frac{f(af - gb) + e(jc - ad) + d(bl - kc)}{a(ei - hf) + b(gf - di) + c(dh - eg)}$$