



IDEAS:

- movement_mappings.json
- RobotSocial(timer)
 - init() - initialize log, init timer and set callback
 - start() - create gui, and display
 - make_sound() - add to log
 - do_movement() - add to log
 - onTimeEnd() - save to logs folder csv, and move to next screen.
- RobotNonSocial(timer, "csv")
 - init() init timer
 - onTimeEnd() - move to next screen

-Test()