

Econ 712 Problem Set 1

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Question 1

(a)

The bellman equation is:

$$V(A_t, c_{t-1}) = \max_{c_t} u(c_t, c_{t-1}) + \beta V(R(A_t - c_t), c_t)$$

In order for the solution to be unique, the following conditions must hold: $F1, F2, F3, F4, \Gamma1, \Gamma2, \Gamma3$ from lecture.

The conditions for maximization can be found by taking the first order conditions and applying the envelope theorem.

$$\begin{aligned} 0 &= u_1(c', c) + \beta((-R)V_1(R(A - c'), c') + V_2(R(A - c'), c')) \\ V_1(A, c) &= R\beta V_1(R(A - c'), c') \\ V_2(A, c) &= u_2(c', c) \\ \Rightarrow 0 &= u_1(c', c) + \beta\left(\frac{-V_1(A, c)}{\beta} + u_2(c'', c')\right) \\ \Rightarrow V_1(A, c) &= u_1(c', c) + \beta u_2(c'', c') \\ \Rightarrow 0 &= u_1(c', c) + \beta((-R)(u_1(c'', c') - \beta u_2(c''', c'')) + u_2(c'', c')) \\ \Rightarrow 0 &= u_1(c', c) - \beta(-R)(u_1(c'', c') + \beta u_2(c''', c'')) + \beta u_2(c'', c') \end{aligned}$$

Thus our condition for maximization is $0 = u_1(c', c) - \beta(-R)(u_1(c'', c') + \beta u_2(c''', c'')) + \beta u_2(c'', c')$.

(b)

Let $u(c_t, c_{t-1}) = \log c_t + \gamma \log c_{t-1}$. Then our new bellman equation is:

$$V(A, c) = \max_{c'} \log c' + \gamma \log c + \beta V(R(A - c'), c')$$

*I have discussed this problem set with Emily Case, Michael Nattinger, Alex Von Hafften, and Danny Edgel.

The optimal choice of c' is:

$$\begin{aligned}
c' &= \arg \max_{c'} \log c' + \gamma \log c + \beta V(R(A - c'), c') \\
&= \arg \max_{c'} \log c' + \beta V(R(A - c'), c') \\
&= \arg \max_{c'} \log c' + \beta \max_{c''} \{\log c'' + \gamma \log c' + \beta V(R(A - c''), c'')\} \\
&= \arg \max_{c'} (1 + \gamma\beta) \log c' + \beta \max_{c''} \{\log c'' + \beta V(R(A - c''), c'')\}
\end{aligned}$$

Note, this argmax is independent of c . Using the new bellman equation, we can solve for the condition for maximization as follows:

$$\begin{aligned}
0 &= u_1(c', c) - \beta(-R)(u_1(c'', c') + \beta u_2(c''', c'')) + \beta u_2(c'', c') \\
\Rightarrow 0 &= \frac{1}{c'} - \frac{\beta R}{c''} - \frac{\beta^2 R \gamma}{c''} + \frac{\beta \gamma}{c'} \\
\Rightarrow \frac{\beta R(1 + \beta \gamma)}{c''} &= \frac{1 + \beta \gamma}{c'} \\
\Rightarrow c'' &= \beta R c'
\end{aligned}$$

Given A_t we will choose some consumption amount c_t that is some proportion a of A_t . Let $c_t = aA_t$ for some $a \in (0, 1)$. Then, we can combine this with our condition for maximization to form a guess for our value function: $\tilde{V}(A) = \sum_{i=0}^n \beta^i \log((\beta R)^i a A)$. Using this in our bellman equation, we have:

$$\sum_{i=0}^n \beta^i \log((\beta R)^i a A) = \max_{A'} \log(A'/R - A) + \beta \sum_{i=0}^{\infty} \beta^i \log((\beta R)^i a A')$$

Taking FOCs:

$$\begin{aligned}
\frac{1}{RA - A'} &= \beta \sum_{i=0}^{\infty} \beta^i \frac{(\beta R)^i a}{(\beta R)^i a A'} \\
\Rightarrow \frac{A'}{aRA} &= \frac{\beta}{1 - \beta} \\
\Rightarrow \frac{RA(1 - a)}{aRA} &= \frac{\beta}{1 - \beta} \\
\Rightarrow \frac{(1 - a)}{a} &= \frac{\beta}{1 - \beta} \\
\Rightarrow a &= 1 - \beta
\end{aligned}$$

(c)

In general this will not hold unless the utility function is separable.

Question 2

(a)

The sequence problem is:

$$\max_{\{x_t\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \left(\frac{1}{1+r} \right)^t \left(ax_t + \frac{1}{2}bx_t^2 - \frac{1}{2}c(x_{t+1} - x_t)^2 \right)$$

This can be rewritten as a bellman equation:

$$V(x) = \max_y \left\{ ax - \frac{1}{2}bx^2 - \frac{1}{2}c(y-x)^2 + \delta V(y) \right\}$$

We can write this using an operator T for an arbitrary continuation value function, where the fixed point of T is the solution to the bellman equation.

$$T(v)(x) = \max_y \left\{ ax - \frac{1}{2}bx^2 - \frac{1}{2}c(y-x)^2 + \delta v(y) \right\}$$

(b)

F unbounded below

Let $L < 0$ and set $x < \frac{L}{a}$. Then

$$\begin{aligned} F(x, y) &= ax - \frac{1}{2}bx^2 - \frac{1}{2}c(y-x)^2 \\ &\leq ax \\ &< a\left(\frac{L}{a}\right) \\ &= L \\ &< 0 \end{aligned}$$

Thus F is unbounded below.

F bounded above

Taking FOC:

$$\begin{aligned}
0 &= a - bx + c(y - x) \\
0 &= -c(y - x) = 0 \\
\Rightarrow y &= x \\
\Rightarrow 0 &= a - bx + c(x - x) \\
\Rightarrow 0 &= a - bx \\
\Rightarrow x &= \frac{a}{b} \\
\Rightarrow F\left(\frac{a}{b}, \frac{a}{b}\right) &= a\left(\frac{a}{b}\right) - \frac{1}{2}b\left(\frac{a}{b}\right)^2 - \frac{1}{2}c\left(\left(\frac{a}{b}\right) - \left(\frac{a}{b}\right)\right)^2 \\
&= a\left(\frac{a}{b}\right) - \frac{1}{2}\left(\frac{a^2}{b}\right) \\
&= \frac{2a^2 - a^2}{2b} \\
&= \frac{a^2}{2b}
\end{aligned}$$

Thus F is bounded above by $\frac{a^2}{2b}$.

Value function bounded above

$$\begin{aligned}
\hat{v} &= \frac{a^2}{2b} + \delta \hat{v} \\
\Rightarrow \hat{v} &= \frac{a^2}{2b(1 - \delta)}
\end{aligned}$$

Thus our value function is bounded above by $\frac{a^2}{2b(1 - \delta)}$.

(c)

$$\begin{aligned}
T\hat{v}(x) &= \max_y \left\{ ax - \frac{1}{2}bx^2 - \frac{1}{2}c(y - x)^2 + \delta \hat{v} \right\} \\
0 &= -c(y - x) = 0 \\
\Rightarrow y &= x \\
\Rightarrow T\hat{v}(x) &= ax - \frac{1}{2}bx^2 + \delta \hat{v} \\
&\leq \frac{a^2}{2b} + \delta \left(\frac{a^2}{2b(1 - \delta)} \right) \\
&= \hat{v}
\end{aligned}$$

(d)

Base case: as shown in (c), $T^1\hat{v}(x) = \alpha_1x - \frac{1}{2}\beta_1x^2 + \gamma_1$ where $\alpha_1 = a, \beta_1 = b, \gamma_1 = \delta\hat{v}$.

Induction step: Assume that for $n = k$, $T^k\hat{v}(x)$ takes the form $T^k\hat{v}(x) = \alpha_kx - \frac{1}{2}\beta_kx^2 + \gamma_k$. Then for $n = k + 1$:

$$\begin{aligned}
T^{k+1}\hat{v}(x) &= \max_y ax - \frac{b}{2}x^2 - \frac{c}{2}(y-x)^2 + \delta(\alpha_ky - \frac{1}{2}\beta_ky^2 + \gamma_k) \\
&\Rightarrow 0 = cx - cy + \delta\alpha_k - \delta\beta_ky \\
&\Rightarrow y = \left(\frac{cx + \delta\alpha_k}{c + \delta\beta_k} \right) \\
T^{k+1}\hat{v}(x) &= ax - \frac{b}{2}x^2 - \frac{c}{2} \left(\left(\frac{cx + \delta\alpha_k}{c + \delta\beta_k} \right) - x \right)^2 + \delta \left(\alpha_k \left(\frac{cx + \delta\alpha_k}{c + \delta\beta_k} \right) - \frac{1}{2}\beta_k \left(\frac{cx + \delta\alpha_k}{c + \delta\beta_k} \right)^2 + \gamma_k \right) \\
&= ax - \frac{b}{2}x^2 - \frac{c\delta^2\alpha_k^2}{2(c + \delta\beta_k)^2} + \frac{c\delta^2\alpha_k\beta_k}{(c + \delta\beta_k)^2}x - \frac{c\delta^2\beta_k^2}{2(c + \delta\beta_k)^2}x^2 + \frac{\delta^2\alpha_k^2}{c + \delta\beta_k} + \frac{\delta\alpha_kc}{c + \delta\beta_k}x \\
&\quad - \frac{1}{2} \frac{\delta\beta_kc^2x^2}{(c + \delta\beta_k)^2} - \frac{1}{2} \frac{\delta\alpha_kcx}{(c + \delta\beta_k)^2} - \frac{1}{2} \frac{\delta^2\alpha_k^2}{(c + \delta\beta_k)^2} + \delta\gamma_k \\
&= \left(a + \frac{2c\delta^2\alpha_k\beta_k}{(c + \delta\beta_k)^2} + \frac{\delta\alpha_kc}{c + \delta\beta_k} - \frac{1}{2} \frac{\delta\alpha_kc}{(c + \delta\beta_k)^2} \right) x \\
&\quad - \frac{1}{2} \left(b + \frac{c\delta^2\beta_k^2}{(c + \delta\beta_k)^2} + \frac{\delta\beta_kc^2}{(c + \delta\beta_k)^2} \right) x^2 \\
&\quad + \left(-\frac{c\delta^2\alpha_k^2}{2(c + \delta\beta_k)^2} + \frac{\delta^2\alpha_k^2}{c + \delta\beta_k} - \frac{1}{2} \frac{\delta^2\alpha_k^2}{(c + \delta\beta_k)^2} + \delta\gamma_k \right) \\
&= \alpha_{k+1}x - \frac{1}{2}\beta_{k+1}x^2 + \gamma_{k+1}.
\end{aligned}$$

where $\alpha_{k+1} = \left(a + \frac{2c\delta^2\alpha_k\beta_k}{(c + \delta\beta_k)^2} + \frac{\delta\alpha_kc}{c + \delta\beta_k} - \frac{1}{2} \frac{\delta\alpha_kc}{(c + \delta\beta_k)^2} \right)$

$$\beta_{k+1} = \left(b + \frac{c\delta^2\beta_k^2}{(c + \delta\beta_k)^2} + \frac{\delta\beta_kc^2}{(c + \delta\beta_k)^2} \right)$$

$$\gamma_{k+1} = \left(-\frac{c\delta^2\alpha_k^2}{2(c + \delta\beta_k)^2} + \frac{\delta^2\alpha_k^2}{c + \delta\beta_k} - \frac{1}{2} \frac{\delta^2\alpha_k^2}{(c + \delta\beta_k)^2} + \delta\gamma_k \right).$$

(e)

Note that the expressions for $\alpha_{k+1}, \beta_{k+1}, \gamma_{k+1}$ are first order difference equations. By solving for the steady state values, we can see how these parameters look in the limit.

$$\begin{aligned}\bar{\alpha} &= \lim_{n \rightarrow \infty} \alpha_n = \frac{a(c + \beta\delta)}{c + \beta\delta - c\delta} \\ \bar{\beta} &= \lim_{n \rightarrow \infty} \beta_n = \frac{-c + \delta(b + c) + \sqrt{4bc\delta + (c - \delta(b + c))^2}}{2\delta} \\ \bar{\gamma} &= \lim_{n \rightarrow \infty} \gamma_n = \frac{1}{2(1 - \delta)} \left(\frac{\bar{\alpha}^2 \delta^2}{c + \beta\delta} \right) \\ \Rightarrow \lim_{n \rightarrow \infty} T^n \hat{v}(x) &= \bar{\alpha}x - \frac{1}{2}\bar{\beta}x^2 + \bar{\gamma}\end{aligned}$$

Question 3

(a)

The bellman equation is:

$$V(k) = \max_{k'} \{ \pi(k) - \gamma(k' - (1 - \delta)k) + \frac{1}{R}V(k') \}$$

The condition for maximization can be found by taking first order conditions and applying the envelope theorem:

$$\begin{aligned}\gamma'(k' - (1 - \delta)k) &= \frac{1}{R}V'(k') \\ V'(k) &= \pi'(k) + (1 - \delta)\gamma'(k' - (1 - \delta)k) \\ \Rightarrow \pi'(k') + (1 - \delta)\gamma'(k'' - (1 - \delta)k') &= R\gamma'(k' - (1 - \delta)k)\end{aligned}$$

(b)

Let $k = k' = k'' = \bar{k}$. Note, $\bar{k} = (1 - \delta)\bar{k} + \bar{I} \rightarrow \bar{I} = \delta\bar{k}$. Then our conditions for optimization become:

$$\begin{aligned}\gamma'(\delta\bar{k}) &= \frac{1}{R}(\pi'(\bar{k}) + \gamma'(\delta\bar{k})(1 - \delta)) \\ \Rightarrow R\gamma'(\delta\bar{k}) &= \pi'(\bar{k}) + \gamma'(\delta\bar{k})(1 - \delta) \\ \Rightarrow (R - 1 + \delta)\gamma'(\delta\bar{k}) &= \pi'(\bar{k}) \\ \Rightarrow \frac{\pi'(\bar{k})}{\gamma'(\delta\bar{k})} &= R - 1 + \delta\end{aligned}$$

By the strict concavity of π , the strict convexity of γ , and the Inada conditions, the solution exists and is unique. If R were to increase, the steady state level of $\pi'(\bar{k})$ would increase, \bar{k} would decrease, and \bar{I} would decrease.

(c)

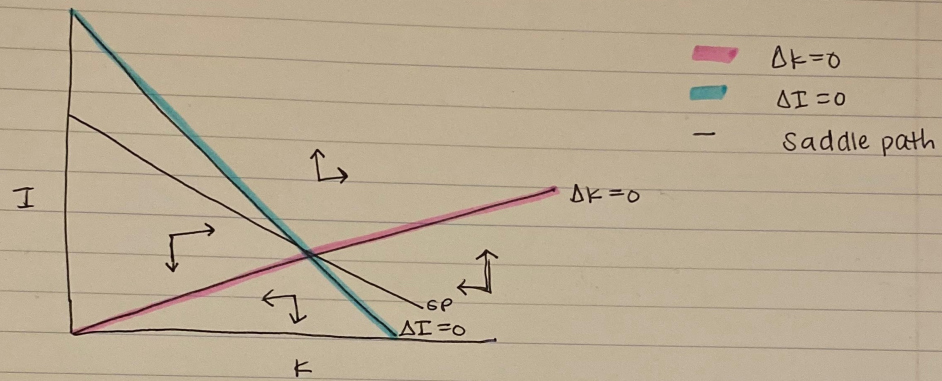
Our conditions for maximization become:

$$\begin{aligned} -(k' - k^*) &= R(k' - (1 - \delta)k) - (1 - \delta)(I') \\ \Rightarrow -(k' - k^*) &= RI - (1 - \delta)I' \end{aligned}$$

This, in addition to our law of motion for capital, $k' = I + (1 - \delta)k$, forms the difference equations for capital and investment.

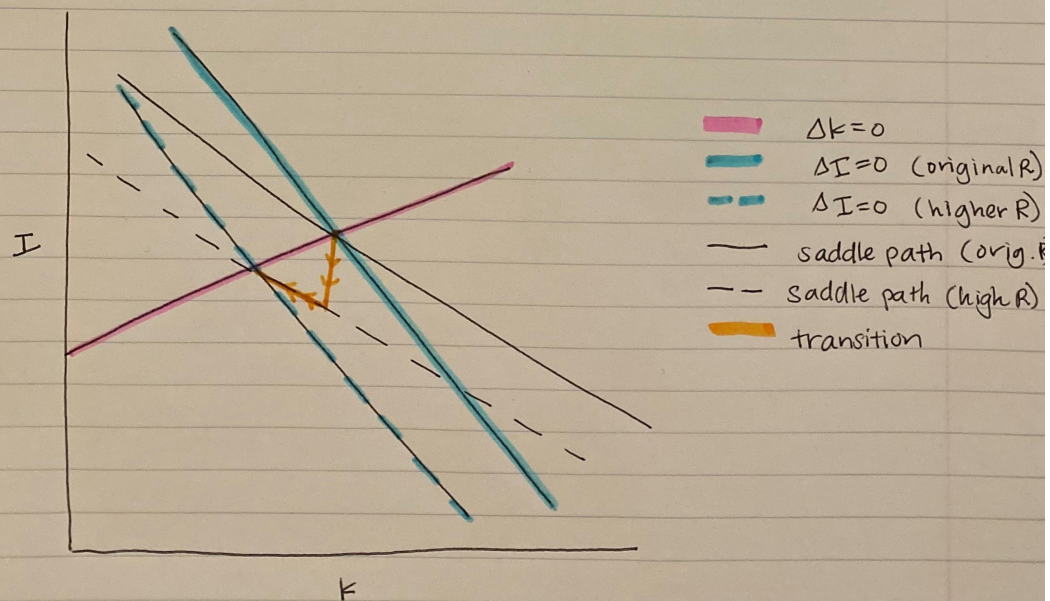
For the phase diagram, we know that $\Delta k = 0$ implies that $I = \delta k$. $\Delta I = 0$ implies that $-(I + (1 - \delta)k - k^*) = RI - (1 - \delta)I \Rightarrow I = \frac{k^*}{R + \delta} - \frac{(1 - \delta)}{R + \delta}k$. If we are above $\Delta k = 0$ then we are investing more than the rate of depreciation so capital goes to the right. If we are to the right of $\Delta I = 0$ then we are underinvesting so I will increase. We can draw the phase diagram below.

Phase Diagram



Transition Dynamics

Transition Dynamics



Question 4

(a)

The bellman equation is:

$$V(k) = \max_{k'} \left\{ \frac{(((1-\delta)k + f(k) - k')G^\eta)^{1-\gamma}}{1-\gamma} + \beta V(k') \right\}$$

The condition for maximization can be found by taking first order conditions and applying the envelope theorem:

$$\begin{aligned} \beta V'(k') &= ((1-\delta)k + f(k) - k')^{-\gamma} G^{\eta(1-\gamma)} \\ V'(k') &= ((1-\delta)k' + f(k') - k'')^{-\gamma} (G')^{\eta(1-\gamma)} ((1-\delta) + f'(k')) \\ \Rightarrow ((1-\delta)k + f(k) - k')^{-\gamma} G^{\eta(1-\gamma)} &= \beta ((1-\delta)k' + f(k') - k'')^{-\gamma} (G')^{\eta(1-\gamma)} ((1-\delta) + f'(k')) \\ \Rightarrow \left(\frac{c'}{c}\right)^\gamma &= \left(\frac{G'}{G}\right)^{\eta(1-\gamma)} \beta (1-\delta + f'(k')) \end{aligned}$$

The difference equations are $\left(\frac{c'}{c}\right)^\gamma = \left(\frac{G'}{G}\right)^{\eta(1-\gamma)} \beta (1-\delta + f'(k'))$ and $k' = (1-\delta)k + f(k) - c$.

(b)

Let $G' = gG, c = c' = \bar{c}, k = k' = \bar{k}$. Then using our difference equations:

$$\begin{aligned} \left(\frac{\bar{c}}{c}\right)^\gamma &= \left(\frac{gG}{G}\right)^{\eta(1-\gamma)} \beta (1-\delta + f'(\bar{k})) \\ \Rightarrow 1 &= g^{\eta(1-\gamma)} \beta (1-\delta + f'(\bar{k})) \\ \Rightarrow \frac{1}{\beta g^{\eta(1-\gamma)}} &= 1-\delta + f'(\bar{k}) \\ \Rightarrow \frac{1}{\beta g^{\eta(1-\gamma)}} - 1 + \delta &= f'(\bar{k}) \\ \Rightarrow \bar{k} &= f'^{(-1)}\left(\frac{1}{\beta g^{\eta(1-\gamma)}} - 1 + \delta\right) \\ \Rightarrow \bar{c} &= f(\bar{k}) - \delta \bar{k} \end{aligned}$$

By the strict concavity of f and the Inada conditions, the steady state exists and is unique.

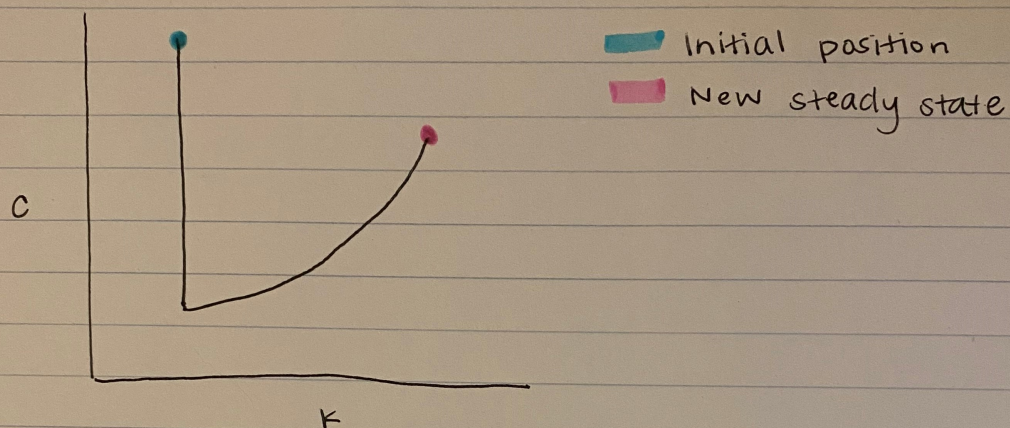
(c)

When there is an unexpected increase in g , the next periods capital has already been predetermined, so k' does not change. However, the increase in g will cause an increase in c' . In the following period, the increase in c' will lead to a decrease in k'' , which will lead to an increase in $f'(k)$, and consequently an increase in c'' .

Eventually, the system will approach a new steady state, which has a lower value of \bar{k} since $f'(k)$

increased. However, the impact on \bar{c} cannot be determined since $f(\bar{k})$ and $\delta\bar{k}$ will both decrease. The more the agent prefers government spending, the higher the value of η will be. Higher values of η will cause \bar{c} to drop, while lower values of η will cause \bar{c} to rise.

Transition Dynamics : high η



Transition Dynamics : low η

