

*As for everything else, so for a mathematical theory: beauty can be perceived but not explained -  
Arthur Cayley*

## 1 Review Topics

*Vector spaces, linear transformations, isomorphisms*

## 2 Exercises

### 2.1 Classify each operator as linear or not linear

- $T : \mathcal{C}[0, 1] \rightarrow \mathbb{R}, Tf(x) = \int_0^1 f(x) dx.$

$\int_0^1 \alpha f(x) + \beta g(x) dx = \alpha \int_0^1 f(x) dx + \beta \int_0^1 g(x) dx$ , thus  $T$  is linear.

- Recall that the dot-product between two vectors in  $\mathbb{R}^n$  is defined as  $\langle x, y \rangle := \sum_{i=1}^n x_i y_i$ . Define the operator  $T_a : \mathbb{R}^n \rightarrow \mathbb{R}, T_a x = \langle a, x \rangle$ .

$\sum_{i=1}^n a_i (\alpha x_i + \beta y_i) = \alpha \sum_{i=1}^n a_i x_i + \beta \sum_{i=1}^n a_i y_i$ , thus  $T$  is linear.

- $T : \mathbb{R} \rightarrow \mathbb{R}, Tx = mx + b.$

$T$  is linear if and only if  $b = 0$ . To see this, consider  $m(\alpha x + \beta y) + b = \alpha(mx + b) + \beta(my + b) + b(1 - \alpha - \beta)$ .

### 2.2 Characterize the set of solutions to the equations:

$$x_1 - x_2 + 2x_3 = 0$$

$$2x_1 + 2x_3 = 0$$

$$x_1 - 3x_2 + 4x_3 = 0$$

Solving the system gives:

$$x_1 = -x_3$$

$$x_2 = x_3$$

Thus, we can write any  $x_1, x_2, x_3$  in the set of solutions as:

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \alpha \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$$

for  $\alpha \in \mathbb{R}$ .

### 2.3 Show that the set of all polynomials of degree $n$ form a vector space.

Notice for  $p(x) = \sum_{k=0}^n a_k x^k$ ,  $q(x) = \sum_{k=0}^n b_k x^k$ , thus  $\alpha p(x) + \beta q(x) = \sum_{k=0}^n (\alpha a_k + \beta b_k) x^k$ , which is another polynomial of degree  $n$ . The null element is the constant 0, and the rest of the requirements are trivial to check.

**2.4 Show that if  $\{u, v, w\}$  is a set of linearly independent vectors, then  $\{u, u + v, u + v + w\}$  are linearly independent.**

Suppose  $\alpha_1 u + \alpha_2 (u + v) + \alpha_3 (u + v + w) = 0$ . That means that  $(\alpha_1 + \alpha_2 + \alpha_3)u + (\alpha_2 + \alpha_3)v + \alpha_3 w = 0$ . Thus,  $\alpha_1 + \alpha_2 + \alpha_3 = \alpha_2 + \alpha_3 = \alpha_3 = 0$ . Since  $\alpha_3 = 0$ ,  $\alpha_2 = 0$ , and thus  $\alpha_1 = 0$ .

**2.5 Let  $\mathcal{P}^n$  be the vector space of polynomials of degree  $n$ . Consider the differentiation operator  $T : \mathcal{P}^n \rightarrow \mathcal{P}^{n-1}$  defined by  $Tp(x) = \frac{d}{dx}p(x)$ . Compute  $\text{Im } T$ ,  $\ker T$ , and  $\text{rank } T$ .**

Observe that the derivative of any polynomial  $p(x)$  of degree at most  $k$  has degree at most  $k - 1$ . Thus,  $\text{Im } T = \mathcal{P}^{n-1}$ . What gets mapped to 0? Any constant polynomial, thus  $\ker T = \{a : a \in \mathbb{R}\}$ . The rank of  $T$  is  $n$ .

**2.6 Prove that a linear map  $T : X \rightarrow Y$  over two  $n$ -dimensional vector spaces is 1-to-1 if and only if it is onto.**

Let  $\{x_1, \dots, x_n\}$  be a basis for  $X$  and  $\{y_1, \dots, y_n\}$  be a basis for  $Y$ . First, suppose  $T$  is 1-to-1. To show  $T$  is onto, we can show that  $T$  maps a the basis in  $X$  to a basis in  $Y$ . Thus, consider the set  $\mathcal{B} := \{Tx_1, \dots, Tx_n\}$ . Since  $\dim \mathcal{B} = n = \dim Y$ , we need to show that  $\mathcal{B}$  is a linearly independent set and we are done. Suppose for  $a_1, \dots, a_n \in \mathbb{R}$ , we have that:

$$a_1 Tx_1 + \dots + a_n Tx_n = 0$$

Thus, by linearity, we have that:

$$T(a_1 x_1 + \dots + a_n x_n) = 0$$

Therefore, since  $T$  is 1-to-1, it must be that  $a_1 x_1 + \dots + a_n x_n = 0$ . However,  $\{x_1, \dots, x_n\}$  form a basis for  $X$ , so these equalities can hold if and only if  $a_1 = \dots = a_n = 0$ . Thus,  $\mathcal{B}$  is a linearly independent set and forms a basis for  $Y$ .

Now, consider that  $T$  is onto. This means that for any  $u \in Y$ , there exists  $w \in X$  such that  $Tw = u$ . Consider the set  $\mathcal{C} := \{v_1, \dots, v_n\}$  where  $Tv_i = y_i$ . We show  $\mathcal{C}$  forms a basis for  $X$ . This follows from almost identical reasoning as before: consider  $b_1 v_1 + \dots + b_n v_n = 0$ . Then:

$$T(b_1 v_1 + \dots + b_n v_n) = T0 = 0$$

therefore  $b_1 Tv_1 + \dots + b_n Tv_n = 0$  which can happen if and only if  $b_1 y_1 + \dots + b_n y_n = 0$ , so  $b_1 = \dots = b_n = 0$ . Thus,  $\mathcal{C}$  forms a basis for  $X$ . Now, suppose for  $w, z \in X$ ,  $Tw = Tz$ . Consider then that there exists  $c_1, \dots, c_n$  and  $d_1, \dots, d_n$  such that:

$$w = c_1 v_1 + \dots + c_n v_n$$

$$z = d_1 v_1 + \dots + d_n v_n$$

Thus, for  $Tw = Tz$ , it must be that  $c_i = d_i$  for all  $i$ , by linearity and the definition of  $\mathcal{B}$ , therefore  $w = z$ .