

Class 04: Bifurcations in 1D systems

Activity

All Teams: Write your names in the corner of the whiteboard.

Teams 5 and 6: Post screenshots of your work to the course Google Drive today (make or use a 'C04' folder). Include words, labels, and other short notes on your whiteboard that might make those solutions useful to you or your classmates. Find the link in Canvas.

1. Think of

$$\dot{x} = x(1 + x)$$

as one member of the family

$$\dot{x} = x(r + x),$$

obtained when $r = 1$. We want to understand how the phase portrait changes as the parameter r changes. A **bifurcation diagram** summarizes this.

For this problem: r is a parameter, t is the independent variable, and x is the dependent variable.

- (a) Find the fixed points $x^*(r)$ as functions of r .
- (b) Pick **one** fixed point and use linear stability analysis to determine its stability as a function of r . Then determine the stability of the other fixed point without doing a stability calculation (use phase portrait/vector field reasoning).
- (c) Draw the bifurcation diagram: plot the fixed points $x^*(r)$ vs r . Use solid for stable and dashed for unstable.
- (d) For any fixed value of r , look at the fixed points from bottom to top. The stability must alternate.

Why? Between two fixed points \dot{x} does not change sign, so the flow on the phase portrait points in a single direction throughout that interval. As a result, one fixed point must have the arrow pointing towards it, and the other must have the arrow pointing away from it.

Use this rule to check your bifurcation diagram.

- (e) A bifurcation occurs at parameter value $r = r_c$ where the phase portrait changes qualitatively. Identify r_c .
- (f) Name the bifurcation at $r = r_c$.

2. Consider the differential equation

$$\dot{x} = rx - \tanh x.$$

Recall that $\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$.

- (a) Fixed points satisfy $rx = \tanh x$. Think of this as an intersection problem between the line $y = rx$ and the curve $y = \tanh x$.

As r varies, identify the qualitatively different phase portraits that can occur (i.e. how many fixed points exist, and which are stable/unstable).

- (b) A tangency between $y = rx$ and $y = \tanh x$ means the graphs touch but do not cross. What value of r is associated with a tangency at $x = 0$? Explain by comparing the slopes of $y = rx$ and $y = \tanh x$ at $x = 0$.

- (c) Use your answer in (b) to argue that a bifurcation occurs at that value of r . Identify the bifurcation type. If relevant, state whether it is supercritical or subcritical.
- (d) One fixed point is easy to identify. Use linear stability analysis at that point to compute the critical value r_c where the fixed point becomes non-hyperbolic. This value of r is the bifurcation point.

Your answer should match part (b).

- (e) Sketch a rough bifurcation diagram.

3. (based on 3.4.14) Consider the system $\dot{x} = rx + x^3 - x^5$.

- (a) Find the fixed points as a function of r .

Factor out x . For the nonzero fixed points, let $\xi = x^2$ and reduce the equation to a quadratic in ξ .

- (b) As r varies, new nonzero fixed points appear via a saddle-node bifurcation.

Find r_s , the value of r where the saddle-node bifurcation occurs.

- (c) Sketch the bifurcation diagram.

4. (Potential functions)

So far we have analyzed 1D autonomous systems $\dot{x} = f(x)$ by finding fixed points and their stability.

Sometimes it is also useful to describe the dynamics using a **potential function** $V(x)$, defined by

$$\dot{x} = -\frac{dV}{dx}.$$

We borrow the term “potential” from physics.

- (a) For $\dot{x} = -x$, one potential function is $V(x) = \frac{1}{2}x^2$.

- Sketch $V(x)$ versus x .
- Mark the location of the stable fixed point on the x -axis.
- What feature of $V(x)$ corresponds to a stable fixed point?

- (b) An important fact about potential functions is that $\frac{dV}{dt} \leq 0$ along any solution $x(t)$.

To show this, use the chain rule to express $\frac{dV}{dt}$ in terms of $\frac{dV}{dx}$ and \dot{x} . Then use the definition $\dot{x} = -\frac{dV}{dx}$ to argue that $V(x(t))$ can only decrease or stay constant in time.

- (c) Consider $\dot{x} = r - x^2$.

- Find a potential function $V(x)$ (you may ignore an additive constant).
- Sketch $V(x)$ for a few values of r , including all qualitatively different cases.
- On each sketch, mark the fixed points on the x -axis and indicate which are stable/unstable based on the shape of V .