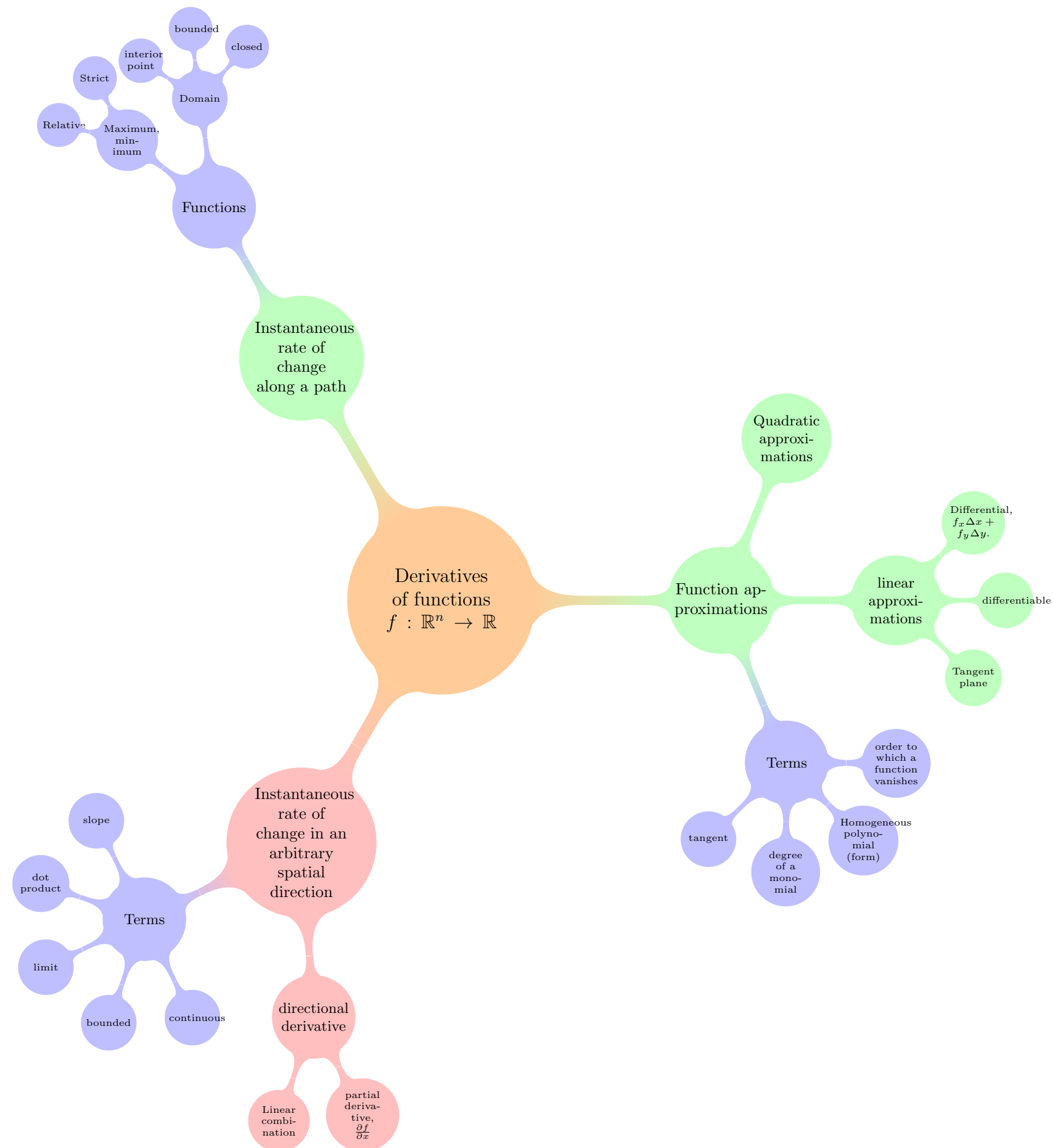


# 1 Partial differentiation mindmap



## Glossary

**continuous** Roughly speaking: the function  $u = f(x, y)$  is continuous at the point  $(x_0, y_0)$  when the value of  $f(x, y)$  is close to the value of  $f(x_0, y_0)$  for  $(x, y)$  close to  $(x_0, y_0)$ . To make this precise: If  $f$  has domain  $R$  and  $P_0 = (x_0, y_0)$  is a point in  $R$  then  $r$  is continuous at  $P_0$  if for every  $\epsilon > 0$  there exists a  $\delta > 0$  such that  $|f(P) - f(P_0)| = |f(x, y) - f(x_0, y_0)| < \epsilon$  for all  $P = (x, y)$  in  $R$  within a  $\delta$ -neighborhood of  $P_0$  (meaning that  $d(P, P_0) = \sqrt{(x - x_0)^2 + (y - y_0)^2} < \delta$ ). Note that the sum, the product, and the difference of two continuous functions are also continuous. The quotient requires more care to avoid zeros of the denominator. (Courant and John).

**degree** The *degree of a monomial*  $a_{mn}x^m y^n$  is the sum  $m + n$  of the exponents of the variables appearing in it (given that  $a_{mn} \neq 0$ ). The *degree of a polynomial* written as a linear combination of monomials is the highest degree of the monomial terms (Courant and John, Wikipedia).

**differentiable** The function  $u = f(x, y)$  is called *differentiable* at the point  $(x, y)$  if it can be approximated in the neighborhood of this point by a linear function. That is, if  $f(x + h, y + k) = Ah + Bk + C + \epsilon\sqrt{h^2 + k^2}$  where  $A, B, C$  are independent of the variables  $h$  and  $k$ , and  $\epsilon$  tends to 0 as  $h$  and  $k$  do (Courant and John).

**directional derivative** The *derivative in the direction*  $\vec{v}$  is the rate of change of  $f$  at the point  $(x, y)$  with respect to distance as we leave  $(x, y)$  along the ray in the direction of  $\vec{v}$ . The *directional derivative* is a linear combination of the derivatives  $f_x$  and  $f_y$  in the  $x$ - and  $y$ - directions with the coefficients  $\cos \alpha$  and  $\sin \alpha$  where  $\alpha$  is the angle the vector  $\vec{v}$  makes with the  $x$ -axis (Courant and John).

**form** A *homogeneous polynomial*, or a *form*, is a polynomial consisting of monomials which all have the same degree  $N$ . For example,  $x^2 + 4xy$  is a quadratic form (Courant and John).

**limit** Suppose  $f(x, y)$  is a function with domain  $R$  and  $P_0 = (x_0, y_0)$  is a point in the closure of  $R$ . We say  $f$  has the *limit*  $L$  for  $(x, y)$  tending to  $(x_0, y_0)$ , written  $\lim_{(x, y) \rightarrow (x_0, y_0)} f(x, y) = L$  or  $\lim_{P \rightarrow P_0} f(P) = L$  if for every  $\epsilon > 0$  we can find a  $\delta$ -neighborhood of  $P_0$  (meaning points  $P$  where

$d(P, P_0) = \sqrt{(x - x_0)^2 + (y - y_0)^2} < \delta$ ) such that  $|f(P) - L| = |f(x, y) - L| < \epsilon$  for all  $P = (x, y)$  in that neighborhood and belonging to  $R$ . (Courant and John).

**linear** A linear function is a polynomial of degree one ( $u = ax + by + c$  where  $a, b, c$  are constants). (Courant and John).

**monomial** Term of the form  $a_{mn}x^m y^n$  where  $m, n$  are non-negative integers and  $a_{mn}$  is arbitrary (Courant and John).

**order** Consider a function  $\phi(h, k)$  which tends to 0 as  $h$  and  $k$  do. Let  $\rho = \sqrt{h^2 + k^2}$ . A function  $\phi(h, k)$  vanishes as  $\rho \rightarrow 0$  to at least the same order as  $\rho$  provided there exists a constant  $C$  independent of  $h$  and  $k$  such that  $\left| \frac{\phi(h, k)}{\rho} \right| \leq C$  holds for all sufficiently small values of  $\rho$ . We write  $\phi(h, k) = O(\rho)$ . More generally, if a comparison function  $\omega(h, k)$  is defined for all nonzero values of  $(h, k)$  in a sufficiently small circle about the origin and is not equal to 0 then  $\phi(h, k)$  *vanishes to at least the same order as*  $\omega(h, k)$  as  $\rho \rightarrow 0$  if for some suitably chosen constant  $C$  the relation  $\left| \frac{\phi(h, k)}{\omega(h, k)} \right| \leq C$  holds in a neighborhood of the point  $(0, 0)$ . We write  $\phi(h, k) = O(\omega(h, k))$  (Courant and John).

**partial derivative** The *partial derivative of*  $f(x, y)$  *with respect to*  $x$  at the point  $(x_0, y_0)$  is  $\lim_{h \rightarrow 0} \frac{f(x_0 + h, y_0) - f(x_0, y_0)}{h}$ , denoted  $\frac{\partial f}{\partial x}$  with the round letter  $\partial$  (Courant and John).

**tangent** A tangent line to a function  $f(x)$  at a point  $a$  has equation  $y = f(a) + (x - a)f'(a)$ . A tangent plane to a function  $f(x, y)$  at a point  $(a, b)$  has equation  $z = f(a, b) + (x - a)f_x(a, b) + (y - b)f_y(a, b)$ . The tangent is a linear function with matching position and slope to the original function at the point of tangency (Wolfram MathWorld).