This document list 34 skills associated with content of the course. A maximum of one skill is assigned per class meeting. Skills are drawn from techniques and concepts that are either central to the course or that were challenging for students on past assessments.

Contents

1	Fund	ctions, vectors, and derivatives	2
	1.1	expression for the distance between a point and a plane parallel to the xy -, xz -, or	
		yz-plane	2
	1.2	find a level surface of a function of three variables	2
	1.3	rewrite the equation of a plane in two ways	3
	1.4	compute a cross product	3
	1.5	compute a scalar triple product	4
	1.6	compute directional derivative	5
	1.7	find the equation of a tangent plane to a surface	5
	1.8	compute a derivative / Jacobian	6
	1.9	use the chain rule to evaluate a partial derivative	6
2	Inte	gration	7
	2.1	identify the sign of an integral using symmetry	7
	2.2	reverse the order of integration in a double integral	7
	2.3	sketch a cross-section of the region of integration for cylindrical coordinates	8
	2.4	sketch a cross-section of the region of integration for spherical coordinates	9
	2.5	set up a double integral to find a probability	10
	2.6	read integration information from Matlab code	10
3	Vect	tor calculus	10
	3.1	provide a parameterization of a circle that meets the given conditions	10
	3.2	find the velocity along a parameterized curve	11
	3.3	Identify the orientation and length of vectors in a vector field	11
	3.4	check whether parameterized curves are flow curves of a system of differential equations	12
	3.5	determine the sign of a line integral based on a diagram	12
	3.6	compute a line integral along a straight line path	12
	3.7	use the fundamental theorem of calculus for line integrals	13
	3.8	determine whether a vector field is irrotational	13
	3.9	use Green's theorem to convert from a line integral to an iterated integral	13
	3.10	given an oriented plane and vector field information, identify the sign of the flux	13
	3.11	set up an integral to compute the flux of a vector field through a surface	14
	3.12	find the flux out of a closed surface (use the divergence theorem)	14
	3.13	orient surfaces of a solid object to match the divergence theorem	15
4	Diffe	erential equations	15
	4.1	find equilibrium solutions to an autonomous first order differential equation	15
	4.2	classify the stability of equilibrium solutions	15
	4.3	use separation to find a solution to a simple diff eq	16

4.4	use separation to find a solution to an initial value problem	16
4.5	construct a phase portrait for an autonomous 1st order ODE	16
4 6	convert a 2nd order ODE into a 1st order system	17

1 Functions, vectors, and derivatives

1.1 expression for the distance between a point and a plane parallel to the xy-, xz-, or yz-plane

Question

Find an expression for the distance between the point (a, b, c) and the plane y = 7.

You'll be given a point and a plane of the form x = k or y = k or z = k where k is a constant).

Solution

Points in the plane are of the form (x,7,z) for any $x,z \in \mathbb{R}$.

The distance between (a, b, c) and an arbitrary point in the plane is given by

$$\sqrt{(a-x)^2+(b-7)^2+(c-z)^2}$$
.

The distance between the point and the plane is defined as the minimum of all possible distances between the point and a point in the plane.

x and z are arbitrary, and we choose them so as to find this minimum distance. $(a-x)^2$ is non-negative, so its minimum is zero (at x=a). Similarly for $(c-z)^2$. The distance is $\sqrt{(b-7)^2}$.

The distance can be written as |b-7| or as $\sqrt{(b-7)^2}$. The expression b-7 would not be correct because it may have a negative value.

1.2 find a level surface of a function of three variables

Question

Find an expression for a level surface of the function

$$f(x, y, z) = \ln(x^2 + 3z^2).$$

Is the level surface a

 \bigcirc plane \bigcirc sphere or ellipsoid \bigcirc circular or elliptical paraboloid \bigcirc cylinder

Solution

I set $\ln(x^2+3z^2)=c$. Using e to invert \ln , I have $x^2+3z^2=e^c$. Choose c=0 as a convenient value to construct a single level surface, with $e^0=1$. I have $x^2+3z^2=1$ as an expression for one level surface of f(x,y,z).

- There are quadratic monomials in the level surface equation, so this isn't the equation for a plane.
- ullet For a sphere or ellipsoid we would have x^2 , y^2 , z^2 all showing up, but we're missing y^2 .
- Paraboloids are linear in one variable and quadratic in the other two, so the surface isn't a paraboloid.
- y is missing from the expression, so this level surface will be a cylinder. It is specifically an elliptical cylinder.

1.3 rewrite the equation of a plane in two ways

Question

Rewrite the equation of the plane

$$3x - 5y + 2z = 10$$

- in intercept form.
- using a dot product between a normal vector and a vector parallel to the plane.

Solution

For intercept form, I want x/a+y/b+z/c=1 where a,b,c are the axis intercepts of the plane. Option 1: I'll divide by 10 to make the right hand side 1. I have 3x/10-y/2+z/5=1. Rearranging, this is $\frac{x}{10/3}+y/(-2)+z/5=1$.

Option 2: I'll find the intercepts. At (a,0,0) we have 3a=10, so a=10/3. At (0,b,0) we have -5b=10 so b=-2. At (0,0,c) we have 2c=10 so c=5. In intercept form the plane is

$$\frac{x}{10/3} + \frac{y}{-2} + \frac{z}{5} = 1.$$

For the dot product, I can "read" the normal vector off of the plan equation. It is $\langle 3, -5, 2 \rangle$. To form a vector parallel to the plane, I use $(x,y,z)-(x_0,y_0,z_0)$, where (x,y,z) is a variable point in the plane and (x_0,y_0,z_0) needs to be a specific point in the plane. The equation of the plane will be $\langle 3,-5,2 \rangle \cdot \langle x-x_0,y-y_0,z-z_0 \rangle = 0$, where (x_0,y_0,z_0) is a point on the plane. From the intercept form, we know that (0,0,5) is a point on the plane, so one way to write the equation of the plane is

$$\langle 3, -5, 2 \rangle \cdot \langle x, y, z - 5 \rangle = 0.$$

Of course, $\langle 3, -5, 2 \rangle \cdot \langle x, y+2, z \rangle = 0$ works as well. As do many other options. (So long as the point (x_0, y_0, z_0) satisfies $3x_0 - 5y_0 + 2z_0 - 10 = 0$, we will end up with a plane equation equivalent to 3x - 5y + 2z = 10.)

1.4 compute a cross product

Question

1. Let \underline{u} be the vector and \underline{v} be the vector

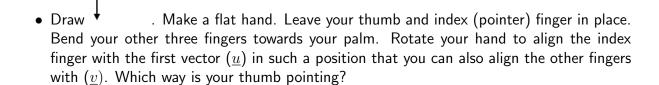
Is $\underline{u} \times \underline{v}$ into the page/screen (away from you) or out of the page/screen (towards you)?

- \bigcirc into the page \bigcirc out of the page
- 2. Compute $(2\underline{i} + \underline{j}) \times (2\underline{j})$ using distributive and scalar multiplication properties of the cross product along with the cross product relationships between i, j, k.

cross product:

Solution

1. Two options for finding the direction using the right hand rule:



• Draw \downarrow , with \underline{u} first and \underline{v} drawn from its tip. Place your palm along \underline{u} oriented so that you can bend your fingers to align with \underline{v} . Which way is your thumb pointing?

Your thumb should be into the page/screen in both cases.

2. Distribute:

$$(2\underline{i} + \underline{j}) \times (2\underline{j}) = (2\underline{i}) \times (2\underline{j}) + (\underline{j}) \times (2\underline{j})$$
$$= 4(\underline{i} \times \underline{j}) + 2(\underline{j} \times \underline{j})$$
$$= 4(\underline{i} \times \underline{j})$$
$$= 4k.$$

1.5 compute a scalar triple product

Question

Compute the scalar triple product of $\underline{u}=\begin{pmatrix}1\\3\\2\end{pmatrix}$, $\underline{v}=\begin{pmatrix}0\\-1\\1\end{pmatrix}$, $\underline{w}=\begin{pmatrix}2\\1\\0\end{pmatrix}$ using a determinant.

Solution

We can compute either $\det\left(\left[\underline{u}\ \underline{v}\ \underline{w}\right]\right)$ or $\det\left(\left[\begin{array}{c}\underline{u}^T\\\underline{v}^T\end{array}\right]\right)$ (they will be equal).

I'll expand using the top row, so +, -, +.

$$\det \begin{pmatrix} 1 & 3 & 2 \\ 0 & -1 & 1 \\ 2 & 1 & 0 \end{pmatrix} = (1) \begin{vmatrix} -1 & 1 \\ 1 & 0 \end{vmatrix} - (3) \begin{vmatrix} 0 & 1 \\ 2 & 0 \end{vmatrix} + (2) \begin{vmatrix} 0 & -1 \\ 2 & 1 \end{vmatrix}$$
$$= (1)(0-1) - 3(0-2) + 2(0+2)$$
$$= -1 + 6 + 4$$
$$= 9.$$

If I choose the middle row, I need to use -, +, - rather than +, -, +:

$$\det\begin{pmatrix} 1 & 3 & 2 \\ 0 & -1 & 1 \\ 2 & 1 & 0 \end{pmatrix} = -(0) + (-1) \begin{vmatrix} 1 & 2 \\ 2 & 0 \end{vmatrix} - (1) \begin{vmatrix} 1 & 3 \\ 2 & 1 \end{vmatrix}$$
$$= -(0 - 4) - (1 - 6)$$
$$= 4 + 5$$
$$= 9.$$

Check in Matlab:

1 det([1 3 2; 0 -1 1; 2 1 0])

1.6 compute directional derivative

Question

- 1. Compute the directional derivative of $f(x,y) = 3x^2y$ at (1,0) in the direction of $\underline{u} = \langle 1,3 \rangle$.
- 2. Find the maximum possible directional derivative at (1,0) (choosing from any direction).

Solution

 $Df=[6xy,3x^2].$ At (1,0) this is [0,3]. Creating a unit vector in the direction of interest, $\underline{\hat{u}}=\underline{u}/\|\underline{u}\|=\left(\begin{array}{c}1/\sqrt{10}\\3/\sqrt{10}\end{array}\right).$

The directional derivative is $f_{\underline{u}}=[0,3]\left(\begin{array}{c}1/\sqrt{10}\\3/\sqrt{10}\end{array}\right)=0(1/\sqrt{10})+3(3/\sqrt{10})=9/\sqrt{10}.$

The maximum possible directional derivative is $\|\nabla f\| = \|Df\| = 3$.

1.7 find the equation of a tangent plane to a surface

Question

Find the equation of a tangent plane to $x^2 + y^2 - z = 1$ at the point (1, 3, 9).

Solution

$$x^2 + y^2 - z = 1$$
 is of the form $F(x, y, z) = c$.

• Option 1: rewrite this as z=f(x,y), with the tangent plane calculated at (1,3). I have $z=x^2+y^2-1$.

The tangent plane is $z = f(1,3) + f_x|_{(1,3)} (x-1) + f_y|_{(1,3)} (y-3)$.

 $f_x = 2x$, $f_y = 2y$. The tangent plane is

$$z = 9 + 2(x - 1) + 6(y - 3)$$

• Option 2: $F = x^2 + y^2 - z$, so [DF] = (2x, 2y, -1). The function has a single output, so the gradient is defined and it is $\nabla F = (2x, 2y, -1)^T$.

The gradient vector evaluated at a point on the surface is normal to the tangent plane of F(x,y,z)=c at that point.

At (1,3,9), $\underline{\nabla}F|_{(1,3,9)}=(2,6,-1)^T$ is a vector normal to the tangent plane and (1,3,9) is a point on the plane.

$$2(x-1) + 6(y-3) + -1(z-9) = 0$$

is an equation for the tangent plane.

1.8 compute a derivative / Jacobian

Question

Construct $D\underline{f}$ for the function $\underline{f} = \begin{pmatrix} xze^y \\ x^2 + xyz \end{pmatrix}$.

Solution

 $D\underline{f}$ is the Jacobian matrix. The function has three inputs and two outputs, so the Jacobian will be a 2x3 matrix (two rows and three columns). Finding the six partials, we have $D\underline{f} = \begin{pmatrix} ze^y & xze^y & xe^y \\ 2x+yz & xz & xy \end{pmatrix}$

1.9 use the chain rule to evaluate a partial derivative

Question Let $z=f(x,y)=\ln(xy)$ with $x=u^2+v^2$ and $y=u^3v$. Let $\underline{x}=\begin{pmatrix}x\\y\end{pmatrix}$ and $\underline{u}=\begin{pmatrix}u\\v\end{pmatrix}$. Find $\frac{\partial z}{\partial\underline{u}}$ and $\frac{\partial \underline{x}}{\partial\underline{u}}$. Use the chain rule to find $\frac{\partial z}{\partial\underline{u}}$. Evaluate it at u=2,v=1.

Solution
$$\frac{\partial z}{\partial \underline{x}} = Df = [f_x, f_y] = [1/x, 1/y].$$

$$\frac{\partial \underline{x}}{\partial u} = \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} = \begin{pmatrix} 2u & 2v \\ 3u^2v & u^3 \end{pmatrix}.$$

$$\frac{\partial z}{\partial \underline{u}} = \frac{\partial z}{\partial \underline{x}} \frac{\partial \underline{x}}{\partial \underline{u}} = \left[\frac{2u}{x} + \frac{3u^2v}{y}, \frac{2v}{x} + \frac{u^3}{y} \right] = \left[\frac{2u}{u^2 + v^2} + \frac{3u^2v}{u^3v}, \frac{2v}{u^2 + v^2} + \frac{u^3}{u^3v} \right] = \left[\frac{2u}{u^2 + v^2} + \frac{3}{u}, \frac{2v}{u^2 + v^2} + \frac{1}{v} \right]$$

At
$$(2,1)$$
 this is $\frac{\partial z}{\partial \underline{u}}\Big|_{(2,1)} = \left[\frac{4}{5} + \frac{3}{2}, \frac{2}{5} + 1\right] = \left[\frac{23}{10}, \frac{7}{5}\right]$

2 Integration

2.1 identify the sign of an integral using symmetry

Question Let D be the unit disk centered about the origin in xy-space. Identify the sign of $\int_D xy \ dA$. \bigcirc positive \bigcirc zero \bigcirc negative

See the beginning of the problems section in §16.1 for about sixteen more examples (odd numbered problems have answers at the end of the text).

Solution xy will be positive in the first and third quadrants. It will be negative in the second an fourth quadrants. For every small box ΔA in the first quadrant (containing the point (a,b)), there is a corresponding small box in the second quadrant (containing point (a,-b)). We have f(a,b)=-f(a,-b), and the contribution of those two small boxes to the integral is equal and opposite. We can make the same argument for the contributions of the third and fourth quadrants.

The integral will be zero due to this symmetry.

2.2 reverse the order of integration in a double integral

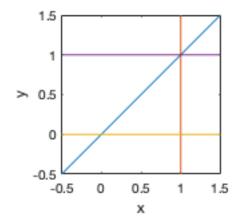
Question Reverse the order of integration for $\int_0^1 \int_y^1 e^{x^2} \ dx \ dy$ and evaluate the integral.

See the problems section in §16.2 for six or so examples of this (odd numbered problems have answers at the end of the text).

Solution

Start by drawing the region of integration based on the information in the bounds of the integral. x=y is the left bound for x and x=1 is the right bound for x. y=0 is the bottom bound for y and y=1 is the top bound for y.

```
syms x y
fimplicit(@(x,y) x-y) % plot x = y, or x - y = 0.
hold on
fimplicit(@(x,y) x-1) % plot x = 1, or x - 1 = 0.
fimplicit(@(x,y) y-0) % plot y = 0
fimplicit(@(x,y) y-1) % plot y = 1, or y - 1 = 0.
axis([-0.5 1.5 -0.5 1.5])
axis equal
xlabel('x'); ylabel('y');
```



Construct the integral in the new order:

- The inner integral is now with respect to y. y starts at 0 for all values of x and goes up to the line x y = 0, so the line y = x.
- The outer integral is with respect to x. The 'shadow' of the region on the x-axis is from 0 to 1.
- The function of integration (the integrand) does not change: $\int_0^1 \int_0^x e^{x^2} dy dx$

$$\int_{0}^{1} \int_{0}^{x} e^{x^{2}} dy dx = \int_{0}^{1} \left[y e^{x^{2}} \right]_{y=0}^{y=x} dx$$

$$= \int_{0}^{1} x e^{x^{2}} dx.$$
Let $u = x^{2}.du = 2xdx$

$$\int_{0}^{1} \int_{0}^{x} e^{x^{2}} dy dx = \int_{u=0^{2}}^{u=1^{2}} \frac{1}{2} e^{u} du$$

$$= \left[\frac{1}{2} e^{u} \right]_{0}^{1}$$

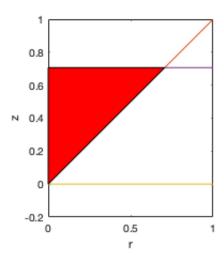
$$= \frac{1}{2} (e - 1).$$

2.3 sketch a cross-section of the region of integration for cylindrical coordinates

Question (cylindrical coordinates) Sketch the region in rz-space associated with the region of integration in the integral below and describe the shape of the region.

$$\int_{0}^{2\pi} \int_{0}^{1/\sqrt{2}} \int_{0}^{z} rz \ dr \ dz \ d\theta.$$

```
1 syms r z
2 fimplicit(@(r,z) r)
3 hold on
4 fimplicit(@(r,z) r-z)
5 fimplicit(@(r,z) z)
6 fimplicit(@(r,z) z-1/sqrt(2))
7 axis equal
8 fill([0, 0,1/sqrt(2)],[0,1/sqrt(2),1/sqrt(2)],'r')
9 xlabel('r'); ylabel('z');
10 axis([0 1 -0.2 1])
```



The region is a solid cone. (Imagine spinning this triangle around the z-axis through the angles 0 to 2π to form the solid region).

2.4 sketch a cross-section of the region of integration for spherical coordinates

(spherical coordinates) Sketch the region in rz-space associated with the region of integration in the integral below and describe the shape of the region.

$$\int_0^{2\pi} \int_0^{\pi/4} \int_0^{\frac{1}{\sqrt{2}\cos\phi}} \rho^3 \sin\phi \cos\phi \ d\rho \ d\phi \ d\theta.$$

Solution

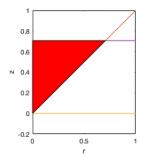
The shape in rz-space is set by the ρ and ϕ coordinates. θ then rotates the shape we find about the z-axis. Translating from spherical to cylindrical will allow us to find the rz shape.

We have $\rho=0$ and $\rho=\frac{1}{\sqrt{2}\cos\phi}$ for our ρ bounds, where $\rho=0$ is the origin, and $\rho\cos\phi=\frac{1}{\sqrt{2}}$ can be rewritten in cylindrical coordinates as $z=\frac{1}{\sqrt{2}}$.

The ρ limits tell us that we have lines radiating from the origin that extend until $z=\frac{1}{\sqrt{2}}$.

For ϕ , we have $\phi=0$ as the lower bound. This is the positive z-axis. And we have $\phi=\pi/4$ as the upper bound. This is a 45-degree line in the rz-plane.

The ϕ bounds tell us that the radial lines from 0 to z=1 are part of our region when they are between the positive z-axis and the 45-degree line.

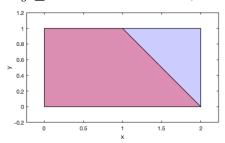


The region is a solid cone. (Imagine spinning this triangle around the z-axis through the angles 0 to 2π to form the solid region).

2.5 set up a double integral to find a probability

Question Let p be the joint probability density function such that p(x,y)=xy in the rectangle R where $0 \le x \le 2, 0 \le y \le 1$. p(x,y)=0 outside of the rectangle. Set up an integral to find the fraction of the population such that $x+y \le 2$.

Solution The probability that $x+y \leq 2$ is given by $\int_S p(x,y) \ dA$ where S is the region of R in which $x+y \leq 2$. R is shown in blue, with S plotted on top of it in red



Setting up the integral:

$$\int_{0}^{1} \int_{0}^{2-y} xy \ dx \ dy$$

If you were to integrate, you would find that the probability that $x + y \le 2$ is less than half.

2.6 read integration information from Matlab code

Question Based on the following code, identify (1) the rectangular box being used to enclose the region of integration, R, and (2) the region of integration.

```
1 fc = @(x,y) x.*y;
2 npoints = 100000;
3 xyvals = rand(npoints,2)*2;
4 indomain = (xyvals(:,1).^2+xyvals(:,2).^2)<4; %set to 1 if in domain; 0 if not
5 sum(fc(xyvals(:,1),xyvals(:,2)).*indomain)*4/npoints</pre>
```

Solution

- (1) The random numbers are generated in the interval [0,2] (see line 3), so the rectangular box is $0 \le x \le 2, 0 \le y \le 2$.
- (2) The region of integration comes from line 4: $x^2 + y^2 < 4$ (and we have $x, y \ge 0$). The region is the quarter disk in the first quadrant of the xy-plane.

3 Vector calculus

3.1 provide a parameterization of a circle that meets the given conditions Question

(parameterization of a circle). Provide a parameterization for a circle of radius 2, centered at (1,5), and traversed counterclockwise. Traverse the circle once. Choose a parameterization so that the traversal takes time 20.

Solution

One way to parameterize a circle is by using a variation on polar coordinates. The circle is of radius 2, so set $x(t) = 2\cos t$ and $y(t) = 2\sin t$. This circle is centered at (0,0) and it takes time 2π to traverse it. The traversal direction (as t increases) is counterclockwise.

Now make some adjustments: first shift the center of the circle. Let $x(t) = 1 + 2\cos t$ and $y(t) = 5 + 2\sin t$. The center of the circle has been shifted to (1,5).

Next adjust the traversal time. We want the input to \sin and \cos to be 2π when t=20. Write $x(t)=1+2\cos kt$ and $y(t)=5+2\cos kt$. At time t=20 we want $kt=2\pi$. So $20k=2\pi$ and $k=2\pi/20=\pi/10$.

Our parameterization of the circle is

$$x(t) = 1 + 2\cos(\pi t/10)$$
 and $y(t) = 5 + 2\sin(\pi t/10)$, $0 \le t \le 20$.

Notice that I have included the time range in my answer (so that we traverse the circle exactly once).

3.2 find the velocity along a parameterized curve

Question

(velocity) Find $\underline{v}(t)$ for $\underline{r}(t)=t\underline{i}+t^2j+t^3\underline{k}.$

Solution

$$\underline{v}(t) = \frac{d\underline{r}}{dt} = \langle 1, 2t, 3t^2 \rangle.$$

3.3 Identify the orientation and length of vectors in a vector field

Question

1. Assume $x, y > 0$. For $\underline{F} = x\underline{j}$, decide if	
(a) the vectors in the vector field are	
\bigcirc parallel to the x -axis \bigcirc parallel to the y -axi	s neither
(b) As x increases the length of the vectors	
○ increases ○ decreases ○ neither	
(c) As y increases the length of the vectors	
○ increases ○ decreases ○ neither	

- 1. (a) The vector field is $\langle 0, x \rangle$ so vectors are parallel to the y-axis.
 - (b) As x increases $||\underline{F}|| = |x|$ also increases.
 - (c) As y increases $||\underline{F}|| = |x|$ does not change, so neither increases nor decreases.

3.4 check whether parameterized curves are flow curves of a system of differential equations

Question

- 1. For $\underline{v} = x\underline{i} + y\underline{j}$,
 - (a) find the system of differential equations associated with the vector field.
 - (b) Does the flow $x(t)=ae^t,y(t)=be^{-t}$ satisfy the system? Show your calculation steps \bigcirc yes \bigcirc no

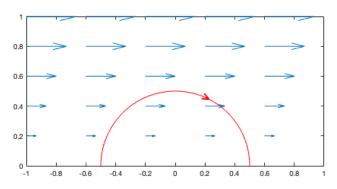
Solution

- 1. (a) $\frac{dx}{dt} = x, \frac{dy}{dt} = y$.
 - (b) $x(t)=ae^t$ so $\frac{dx}{dt}=ae^t$. Does this satisfy $\frac{dx}{dt}=x$? Yes: $ae^t=ae^t$. $y(t)=be^{-t}$ so $\frac{dy}{dt}=-be^{-t}$. Does this satisfy $\frac{dy}{dt}$? No: $be^{-t}\neq -be^{-t}$.

3.5 determine the sign of a line integral based on a diagram

Question

Is the sign of the line integral for the pictured vector field and given curve to be positive, negative, or zero?



opositive neg

negative zero

Solution

The angle between the velocity vector direction and the vector field is less than $\pi/2$ at every point, so the dot product that contributes to the line integral will always be positive. That means we are integrating a positive function, so the integral will be positive.

3.6 compute a line integral along a straight line path

Question

Find $\int_C \underline{F} \cdot d\underline{r}$ for $\underline{F} = x^3\underline{i} + y^2\underline{j} + z\underline{k}$ and C the line from the origin to the point (2,3,4). Solution

Parameterizing a line segment. I'll use $0 \le t \le 1$. So x(t) = 2t, y(t) = 3t, z(t) = 4t.

$$\int_C \underline{F} \cdot \underline{r} = \int_0^1 \langle (2t)^3, (3t)^2, (4t) \rangle \cdot \langle 2, 3, 4 \rangle dt$$

$$= \int_0^1 16t^3 + 27t^2 + 16t \ dt$$

$$= 4t^4 + 9t^3 + 8t^2 \Big|_0^1$$

$$= 4 + 9 + 8$$

$$= 21.$$

3.7 use the fundamental theorem of calculus for line integrals

Question

Let $f=x^2y$ and $\underline{F}=\nabla f$. Let C be a path connecting (0,0) to (1,4). Use the ftcli to find $\int_C \underline{F} \cdot d\underline{r}$.

Solution

The ftcli says $\int_C \nabla f \cdot d\underline{r} = f(Q) - f(P)$ where path C starts at point P and ends at point Q. We have P = (0,0) and Q = (1,4). So $\int_C \nabla f \cdot d\underline{r} = 1^2(4) - 0^2(0) = 4$.

3.8 determine whether a vector field is irrotational

Question

Find the scalar curl for $\underline{F} = \langle y, xy \rangle$. Then identify whether \underline{F} is an irrotational vector field, or not.

Solution

Q=xy, P=y. $Q_x=y$. $P_y=1$. $Q_x-P_y=y-1$. The scalar curl is y-1, which is sometimes nonzero, so \underline{F} is not irrotational.

3.9 use Green's theorem to convert from a line integral to an iterated integral

Question

Let C be the unit circle, traversed counterclockwise. Use Green's theorem to set up an iterated integral to find $\oint_C x^2 dx + xy dy$.

Solution

 $mbF=\langle x^2,xy \rangle$, so $P=x^2,Q=xy$. $Q_x=y,P_y=0$. The scalar curl is $Q_x-P_y=y$. In polar, this is $r\sin\theta$. The curve C is oriented counterclockwise, so Green's theorem directly applies. Integrate over the unit disk: $\int_0^{2\pi}\int_0^1 r\sin\theta\ rdrd\theta=\int_0^{2\pi}\int_0^1 r^2\sin\theta\ drd\theta.$

3.10 given an oriented plane and vector field information, identify the sign of the flux

Question

Identify the sign of the flux of $\underline{F}=x\underline{j}$ through the surface S, where S is the piece of the plane y=2 with $-3\leq x\leq 0, 0\leq z\leq 2$ and S is oriented with its normal vector pointing towards the xz-plane. Provide brief justification.

Solution

On the region S, xj points in the negative j direction because $x \leq 0$.

S is a piece of the plane y=2 so its normal vector is j or -j.

We've been told to orient S so that the normal vector points towards the y=0 plane, so -j.

The vector field and the normal vector are pointing in the same direction. The flux will be positive.

3.11 set up an integral to compute the flux of a vector field through a surface

Question

Set up an integral to compute the flux of $\underline{F} = \cos y\underline{i} + z\underline{j} + \underline{k}$ through S where S is oriented upward and is the part of the surface $z = x^2 + 2y$ above the region $0 \le x \le 2, 0 \le y \le 1$.

Solution

 $f(x,y)=x^2+2y$ so $f_x=2x$, $f_y=2$. The vector $\underline{u}=\langle -f_x,-f_y,1\rangle$ is normal to f and points upwards. It is $\underline{u}=\langle -2x,-2,1\rangle$.

The component of \underline{F} pushing upwards through z=f(x,y) is $\underline{F}\cdot\frac{\underline{u}}{\|\underline{u}\|}$. On the surface, $\underline{F}=\cos y\underline{i}+(x^2+2y)\underline{j}+\underline{k}$, so $\underline{F}\cdot\underline{u}=-2x\cos y-2(x^2+2y)+1$

We have

$$\begin{split} \int_S \underline{F} \cdot d\underline{A} &= \int_S \underline{F} \cdot \frac{\underline{u}}{\|\underline{u}\|} dS \\ &= \int_R \underline{F} \cdot \frac{\underline{u}}{\|\underline{u}\|} \|\underline{u}\| dA \\ &= \int_R \underline{F} \cdot \underline{u} \ dA \ \text{(you can jump straight to this expression)} \\ &= \int_0^1 \int_0^2 (-2x \cos y - 2(x^2 + 2y) + 1) dx dy \end{split}$$

Recall that S is the original surface (in 3-space) and R is its projection/shadow in the xy-plane. In this problem, R was specified in the problem statement. dS is a tiny piece of S while dA is a tiny piece of R. (But $d\underline{A}$ and $d\underline{S}$ are each used to refer to the area vector associated with a tiny piece of S).

3.12 find the flux out of a closed surface (use the divergence theorem)

Question

Find the flux of $\underline{F}=(x+3e^{yz})\underline{i}+(\ln(x^2z^2+1)+y)\underline{j}+z\underline{k}$ out of the closed solid cylindrical region of radius 2 centered on the z-axis, $0\leq r\leq 2$, $3\leq z\leq 7$.

Solution

Using the divergence theorem, $\nabla \cdot \underline{F} = 1 + 1 + 1 = 3$ so the flux is $\int_W 3dV = 3 \int_W dV$. $3 \int_W dV = 3 \int_0^{2\pi} \int_0^2 \int_3^7 r dz dr d\theta = 12 \int_0^{2\pi} \int_0^2 r dr = 24 \int_0^{2\pi} d\theta = 48\pi$

3.13 orient surfaces of a solid object to match the divergence theorem

Question

Consider a solid ball W. Let S_1 be the surface of the upper half of the ball, oriented upwards. Let S_2 be the surface of the lower half of the ball, also oriented upwards. Provide an equation that relates $\int_{S_1} \underline{F} \cdot d\underline{S}, \int_{S_2} \underline{F} \cdot d\underline{S}, \int_W \nabla \cdot \underline{F} \ dV$.

Solution

The surface of W, ∂W , is oriented outwards, so $\partial W = S_1 - S_2$. By the divergence theorem, $\int_W \operatorname{div} \underline{F} dV = \int_{S_1 - S_2} \underline{F} \cdot d\underline{S}$.

We have
$$\int_W \operatorname{div} \underline{F} \ dV = \int_{S_1} \underline{F} \cdot d\underline{S} - \int_{S_2} \underline{F} \cdot d\underline{S}$$

4 Differential equations

4.1 find equilibrium solutions to an autonomous first order differential equation

Question

Find all solutions to $\frac{dx}{dt} = x(1-x)$ where x(t) = c with c a constant (these are all of the equilibrium solutions).

Solution

 $\frac{dx}{dt}=x(1-x)=0$ when x=0 or 1-x=0 so x(t)=0 is an equilibrium solution and x(t)=1 is an equilibrium solution.

4.2 classify the stability of equilibrium solutions

Question

Classify the stability of the equilibrium solutions of $\frac{dx}{dt} = x(1-x)(3-x)$.

- 1. Find the equilibrium solutions: Equilibrium solutions when $\frac{dx}{dt}=0$ for some x, so $x^*=0,1,3$.
- 2. To identify stability, check $f'(x^*)$.
- 3. Using the product rule, $\frac{df}{dx} = (1)(1-x)(3-x) + x(-1)(3-x) + x(1-x)(-1)$.
- 4. Substitute the different equilibrium solutions:

Substituting
$$x^* = 0$$
, $f' = (1)(3) = 3$. Unstable

Substituting
$$x^* = 1$$
, $f' = 1(-1)(2) = -2$. Stable

Substituting
$$x^* = 3$$
, $f' = 3(-2)(-1) = 6$. Unstable

4.3 use separation to find a solution to a simple diff eq

Question

Show the mathematical steps to find a solution to $\frac{dx}{dt} = -4x, x(0) = 2$.

Solution

For the skill check, you'll need to show your mathematical steps but do not need to provide written descriptions of the steps.

- 1. 'Separate' variables: $\frac{1}{r}\frac{dx}{dt} = -4$.
- 2. Integrate both sides with respect to time. $\int \frac{1}{r(t)} \frac{dx}{dt} dt = \int -4 dt.$
- 3. Change variables on the left hand side: u=x(t), $du=\frac{dx}{dt}dt$. $\int \frac{1}{u}du=-4t+C$
- 4. Integrate the left hand side. $\ln |u| = -4t + C$.
- 5. Rearrange: $u = e^C e^{-4t}$
- 6. Return to the original variables: $x(t) = e^{C}e^{-4t}$.
- 7. Set C so that x(0) = 2. $x(0) = e^{C}e^{0} = e^{C} = 2$. $x(t) = 2e^{-4t}$.

4.4 use separation to find a solution to an initial value problem

Question

Find a family of solutions to the initial value problem $\frac{dx}{dt} = x^2t, x(1) = 1.$

Separating: $\frac{1}{x^2}\frac{dx}{dt} = t$. Integrating with respect to t (and changing the variable of integration on the left hand side) $\int \frac{1}{x^2} dx = \int t \ dt$. $-\frac{1}{x} = \frac{1}{2}t^2 + c$, so $x(t) = \frac{1}{t^2/2 + c}$. x(1) = 1 so $\frac{1}{1/2+c}=1.$ c=1/2. We have $x(t)=\frac{1}{t^2/2+1/2}$

4.5 construct a phase portrait for an autonomous 1st order ODE

Question

Sketch the phase portrait in phase space for $\dot{x} = x(1+x)(2+x)$. (Construct the phase line) Solution

 $\dot{x}=0$ for x=0,-1,-2, so those are the locations with circles.

For x > 0, $\dot{x} = + + + > 0$ (the three terms of the product are each positive).

For $-1 < x < 0, \dot{x} = -++<0$.

For $-2 < x < -1, \dot{x} = --+>0$.

For $-2 < x, \dot{x} = --- < 0$.

Drawing these arrows onto the line, and filling in the circle at x = -1, I have:



4.6 convert a 2nd order ODE into a 1st order system

Question

Rewrite the differential equation $2\ddot{x} + 7\sin t\dot{x} - 3x^2 = 0$ as a system of first order differential equations.

Let
$$y = \dot{x}$$
. We have $\ddot{x} = \dot{y} = \frac{3}{2}x^2 - \frac{7\sin t}{2}\dot{x} = \frac{3}{2}x^2 - \frac{7\sin t}{2}y$.

The system should be written in terms of just
$$x,y,t$$
, and it is $\begin{cases} \dot{x}=y \\ \dot{y}=\frac{3}{2}x^2-\frac{7\sin t}{2}y \end{cases}$