

SARAH AGUASVIVAS MANZANO

Address: 1475 Folsom St. Apt 2027, Boulder, CO, 80302

Web: sarahaguasvivas.github.io ◇ GitHub: github.com/sarahaguasvivas

Phone: (484)904-3875 ◇ Email: sarah.aguama@gmail.com ◇ LinkedIn: linkedin.com/in/sarahaguasvivas/

EDUCATION

PhD Student, Computer Science

University of Colorado, Boulder

Department of Computer Science, Correll Lab

August 2017 - Present

Expected Graduation: May 2022

GPA: 4.0/4.0

Master of Science, Computer Science

University of Colorado, Boulder

Granted August 2021

Master of Science, Aerospace Engineering

The Pennsylvania State University

Minors: Computational Science, Electrical Engineering

Thesis: *“Performance and Parsimony in Training Deep Neural Networks”*

Granted August 2017

GPA: 3.6/4.0

Bachelor of Science, Aerospace Engineering

The Pennsylvania State University

Thesis: *“Corrections to the BEMT Method for Highly Loaded Wind Turbine Blades”*

Granted May 2015

Class Rank: 4/103

GPA: 3.8/4.0

WORK EXPERIENCE

University of Colorado Boulder

Graduate Research Assistant

Jan 2018—Present

◇ Design, propose, build and deploy experiments on both software and hardware platforms on systems related with soft actuators and soft robots ◇ Mentor undergraduate and master students towards team-oriented research (*MS: Cooper Simpson, Ankit Srivastava, Aaron Selnick. Undergraduates: Aaron Parker, LeeLee Graham, Brian Noble, Zixi Yuan. High School: Jackson Moody*).

Google

Research Intern

Jun 2021—Sep 2021

◇ Designed, proposed and built software experiments in an open-ended computer science undisclosed research.

National Renewable Energy Lab

Graduate Research Intern

May 2019—August 2020

◇ Proposed, built and deployed *KFlow*: an OpenAI gym and set of stand-alone utilities that introduce the Dynamic Bicycle Model with varying tire models into the SUMO/TraCI API for continuous steering and acceleration control for the purpose of reinforcement learning. ◇ Collaborated, proposed, ran and analyzed benchmarking experiments for a novel reinforcement learning control technique using first-principled modeling and control methods.

National Institute of Standards and Technology

Guest Researcher

April 2018—September 2018

◇ *Theoretical Quantum Computing*: Parallelized a Python package for numerical quantum state tomography on a single qubit (speedup close to 20 at the internal HPC cluster). ◇ Improved the numerical computation with the help of statisticians, physicists and applied mathematicians. ◇ *PREP Student Payroll Database*: Developed user interface for financial information based on Access, SQL and VBA.

The Pennsylvania State University

PSU ICS Cluster Tech

Graduate Teaching Assistant

Undergraduate Research Assistant

May 2017—August 2017

August 2015—May 2017

May 2014—August 2015

JOURNAL PUBLICATIONS

Tripp, C., **Aguasvivas Manzano, S.**, *et. al.*. Autonomous Vehicle Trajectory Tracking via Model-Free Deep Reinforcement Learning. IEEE Transactions on Intelligent Transportation Systems. **Under Review.**

CONFERENCE PROCEEDINGS

Aguasvivas Manzano, S., *et. al.*. High-bandwidth nonlinear control for soft actuators with recursive network models. International Symposium of Experimental Robotics (ISER, Malta 2020). Link to arxiv.

Aguasvivas Manzano, S., *et. al.*. Embedded Neural Networks for Robot Autonomy. International Symposium on Robotics Research (ISRR Hanoi, 2019). Link to arxiv.

Basu, K., Melton, R., **Aguasvivas Manzano, S.** Time-Optimal Reorientation using Neural Networks and Particle Swarm Formulation. AAS/AIAA Astrodynamics Specialist Conference Columbia River Gorge, Stevenson, WA (2017). Link to publication in AIAA

Aguasvivas Manzano, S., Hughes, D., Correll, N. Wireless Online Impact Source Localization on a Composite. 4th International Conference on System-Integrated Intelligence (2018). Link to movie

SKILLS

Open-ended research ◊ Python ◊ C/C++ ◊ Rust ◊ Teaching ◊ Core Aerospace Concepts ◊ HPC ◊ MATLAB ◊ Linux ◊ Engr. Mechanics ◊ Math/Numerical Methods ◊ Neural Networks ◊ OpenAI ◊ SUMO ◊ SWIG

TEACHING EXPERIENCE

| | | |
|-------------------|------------|--|
| CSCI 1320 | CU Boulder | Introduction to Programming for Engineering Students |
| CMPSC 200 and 201 | Penn State | Intro to MATLAB and Intro to C++ |
| AERSP 430 | Penn State | Spacecraft Propulsion |
| AERSP 497I/597I | Penn State | Spacecraft-Environment Interactions |
| AERSP 313 | Penn State | Aerospace Analysis (Numerical Analysis in MATLAB) |
| AERSP 305W | Penn State | Aerospace Technology Laboratory: Aerodynamics Lab |

RELEVANT PROJECTS

Deployable Learning and Control on Soft Robots

Ongoing

PhD Dissertation

Distributed algorithm based on an scalable natural language processing algorithm for semi-supervised learning applied to soft actuator systems. Most challenging part is ensuring deployability and tractability on low-cost microcontrollers.

nn4mc: Neural Networks for Microcontrollers (Open Source)

Ongoing

Open source compiler and set of command line tools that translate neural network trained model file binaries into embedded C code to be used in a microcontroller. Created, trained and manage a team of undergraduates and graduate students for front- and back- end software development. Link to repository.

Nonlinear Output Tracking Technique for Soft Actuators

Completed

In collaboration with the Organic Robotics Lab at Cornell University and the Advanced Medical Technologies Laboratory at CU Boulder—Proposed, developed, deployed and published novel output tracking technique for soft actuators that achieved millimeter-accurate control with less than 2.22kB of flash memory required.

NREL Connected Autonomous Vehicles

Completed

Research project on the feasibility of reinforcement learning applied to continuous acceleration and steering control on autonomous vehicles. Implemented multiple state-of-the-art first-principled controllers for benchmarking on an in-house simulator and also created a SUMO-based simulator for these methods to be carried out.

Terrain Sensitive Tire in Autonomous Driving Car

Completed

Worked on a team that developed a ROS based controller for autonomous driving in a hallway. Developed a method to determine the static friction coefficient between the cars tire and multiple terrains using a convolutional neural network in Keras with inputs from embedded piezoelectric strip sensors at the tire. [Link to code](#)

ACTIVITIES, HONORS AND AWARDS

- ◇ Mentor and Aerospace Judge at 2020 NASA SpaceApp Challenge Santo Domingo
- ◇ Women's team jiu jitsu coach at 10th Planet Boulder
- ◇ Science Judge and Score Keeper 2020 Virtual Colorado Regional High School Science Bowl ([Link to media.](#))
- ◇ 2020 Berkeley Rising Stars Workshop Participant
- ◇ 2nd Place: Unearthed Denver Hackathon (2017). Team Roosters ([Link to rankings](#))
- ◇ NIST PREP Fellow
- ◇ CU Boulder Deans Assistantship Award
- ◇ PSU Dean's List all semesters coursed
- ◇ Member of Sigma Gamma Tau (invitation only)
- ◇ Most Innovative Concept Award. NASA BigIdea Challenge ([Link to media](#))
- ◇ Volunteered for STEMrev (<http://stemrev.org/>) and Make4Covid
- ◇ CU Research Expo Award Winning Poster and Publication Recognition Award
- ◇ Member of Black in AI
- ◇ Invited speaker at CU Boulder Robotics Summer Seminar Series
- ◇ High School Valedictorian

PEER REVIEW

Conferences: IEEE International Conference on Robotics and Automation (ICRA), IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS),

Journals: Robotics and Autonomous Systems, Sensors