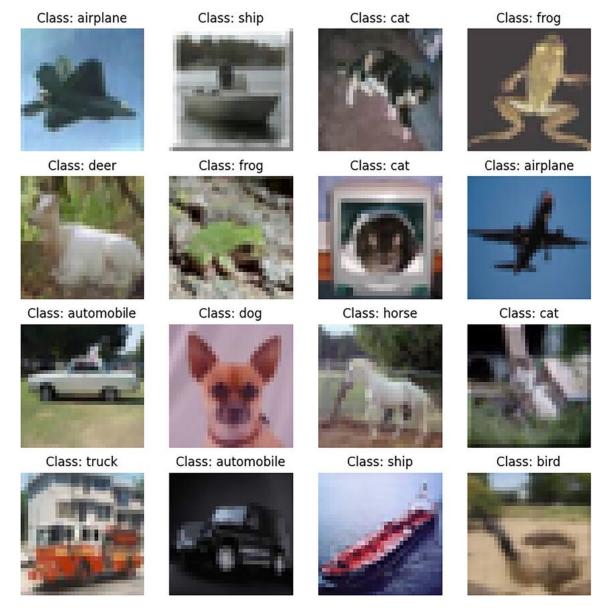
Object Recognition with CNNs & Transfer Learning (CIFAR-10)





https://www.researchgate.net/publication/391119246_Enhancing_CNNs_via_structural_intervention _with_XGBoost?_tp=eyJjb250ZXh0Ijp7ImZpcnN0UGFnZSI6Il9kaXJIY3QiLCJwYWdIIjoiX2RpcmVjdCJ9fQ

CIFAR-10: 60k images, 10 classes, 32×32×3

Dataset & Pre-processing

Train/Val/Test split: 45k/5k/10k

Normalisation, one-hot encoding, consistent preprocessing



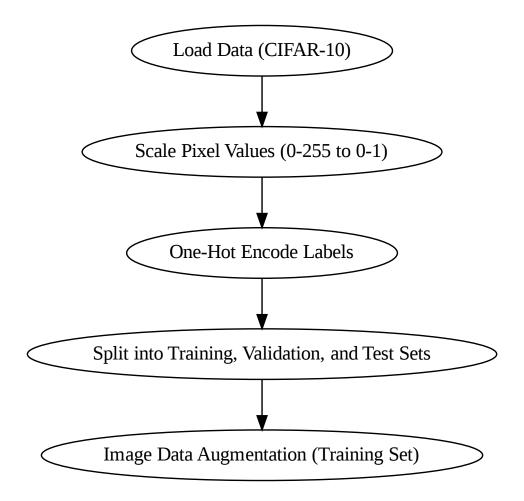
Random flip, rotation, zoom, translation

Data Augmentation

Enhances diversity and generalisation

Applied during training to both models







Conv-Conv-Pool $\times 2 \rightarrow$ Conv \rightarrow Dense(256) \rightarrow Dropout \rightarrow Softmax(10)

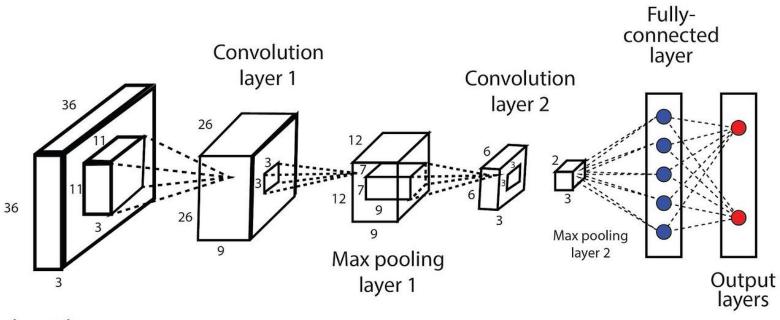
Model 1 – Baseline CNN (from scratch)

Optimizer: Adam (1e-3),

Loss: CCE, Dropout

regularisation





Input Layer



--- Custom CNN Model Summary (without data augmentation) ---Model: "sequential_2"

Layer (type)	Output Shape	Param #
conv2d_2 (Conv2D)	(None, 29, 29, 32)	1,568
max_pooling2d_2 (MaxPooling2D)	(None, 14, 14, 32)	0
conv2d_3 (Conv2D)	(None, 11, 11, 32)	16,416
max_pooling2d_3 (MaxPooling2D)	(None, 5, 5, 32)	0
flatten_2 (Flatten)	(None, 800)	0
dense_4 (Dense)	(None, 256)	205,056
dense_5 (Dense)	(None, 10)	2,570

Total params: 676,832 (2.58 MB)

Trainable params: 225,610 (881.29 KB)

Non-trainable params: 0 (0.00 B)
Optimizer params: 451,222 (1.72 MB)



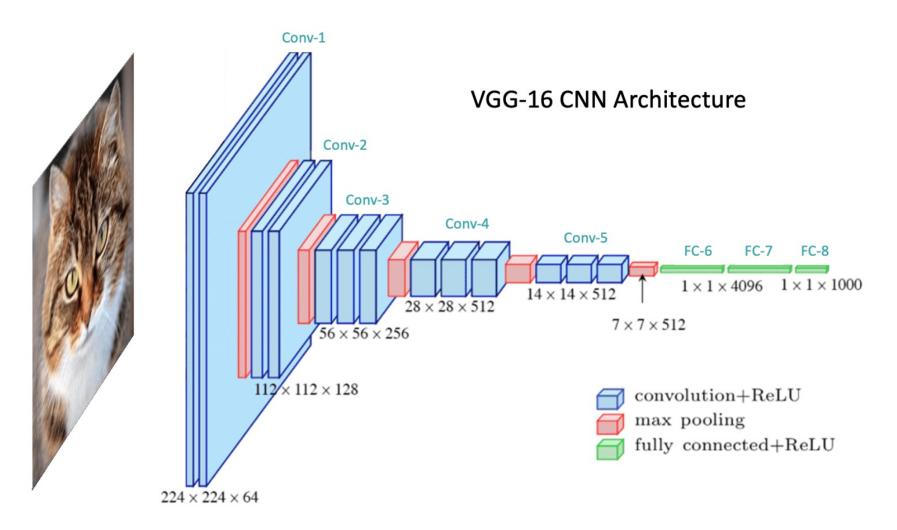
Base: VGG16 pretrained on ImageNet, include_top=False

Model 2 – Transfer Learning (VGG16 fine-tune)

Freeze early layers; fine-tune last block

Custom head: GAP →
Dense(256) → Dropout →
Softmax(10)





--- VGG16 Model Summary ---

Model: "sequential_3"

Layer (type)	Output Shape	Param #
vgg16 (Functional)	(None, 3, 3, 512)	14,714,688
flatten_3 (Flatten)	(None, 4608)	0
dense_6 (Dense)	(None, 256)	1,179,904
dense_7 (Dense)	(None, 10)	2,570

Total params: 18,262,112 (69.66 MB) Trainable params: 1,182,474 (4.51 MB)

Non-trainable params: 14,714,688 (56.13 MB)

Optimizer params: 2,364,950 (9.02 MB)



Compare CNN vs VGG16 training & validation accuracy

Training Curves (Accuracy/Loss)

VGG16 converges faster; CNN may overfit earlier









Validation/Test Accuracy for both models

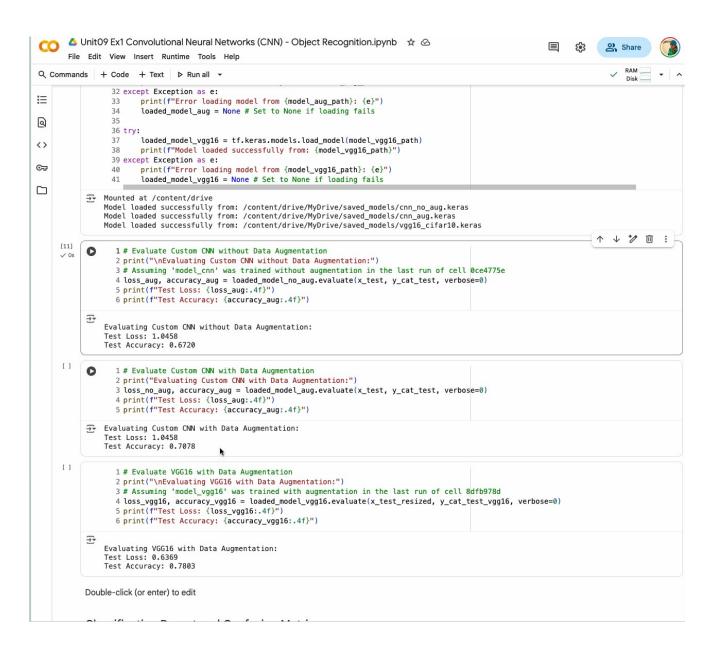
Results & Confusion Matrices

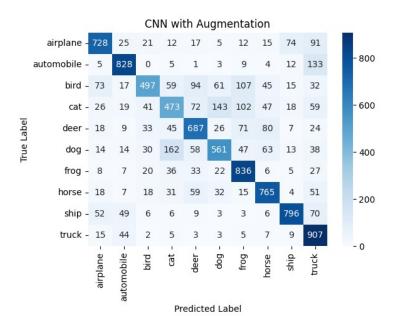
Confusion matrices highlight misclassifications

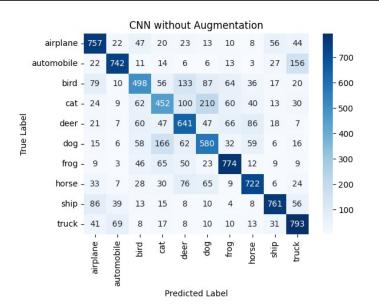
VGG16 reduces class confusion vs CNN

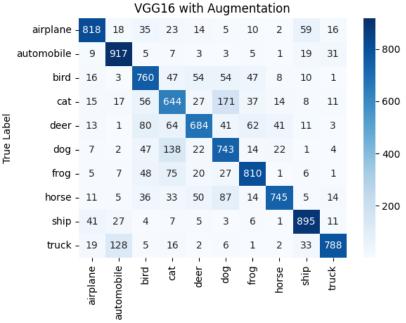


Model	Data Augmentation	Test Loss	Test Accuracy
Custom CNN	No	1.0458	67.20%
Custom CNN	Yes	1.0458	70.78%
VGG16	Yes	0.6369	78.03%











Predicted Label

Class	Precision	Recall	F1-Score	Support
airplane	0.7	0.76	0.73	1000
automobile	0.81	0.74	0.78	1000
bird	0.6	0.5	0.54	1000
cat	0.51	0.45	0.48	1000
deer	0.58	0.64	0.61	1000
dog	0.55	0.58	0.57	1000
frog	0.74	0.77	0.76	1000
horse	0.73	0.72	0.73	1000
ship	0.81	0.76	0.78	1000
truck	0.69	0.79	0.74	1000
Accuracy	nan	nan	0.67	10000
Macro avg	0.67	0.67	0.67	10000
Weighted avg	0.67	0.67	0.67	10000

CNN no augmentation

Class	Precision	Recall	F1-Score	Support
airplane	0.76	0.73	0.74	1000
automobile	0.81	0.83	0.82	1000
bird	0.74	0.5	0.6	1000
cat	0.57	0.47	0.52	1000
deer	0.67	0.69	0.68	1000
dog	0.65	0.56	0.6	1000
frog	0.69	0.84	0.76	1000
horse	0.74	0.77	0.75	1000
ship	0.84	0.8	0.82	1000
truck	0.63	0.91	0.75	1000
Accuracy	nan	nan	0.71	10000
Macro avg	0.71	0.71	0.7	10000
Weighted avg	0.71	0.71	0.7	10000

CNN with augmentation

Class	Precision	Recall	F1-Score	Support
airplane	0.86	0.82	0.84	1000
automobile	0.82	0.92	0.86	1000
bird	0.71	0.76	0.73	1000
cat	0.61	0.64	0.63	1000
deer	0.78	0.68	0.73	1000
dog	0.65	0.74	0.69	1000
frog	0.81	0.81	0.81	1000
horse	0.89	0.74	0.81	1000
ship	0.85	0.9	0.87	1000
truck	0.9	0.79	0.84	1000
Accuracy	nan	nan	0.78	10000
Macro avg	0.79	0.78	0.78	10000
Weighted avg	0.79	0.78	0.78	10000

VGG16



Discussion – Strengths & Trade-offs



CNN: lightweight, flexible, lower compute



Transfer Learning: higher accuracy, faster convergence, heavier mode



Lessons Learned & Insights



Hyperparameter tuning



Importance of Validation Set



Power of dataaugmentation





Autonomous Vehicles, Biometric Authentication, Medical Imaging

Applications, Ethics & Future Work



Ethical and practical dimensions of Al



ResNet50/MobileNetV2





https://stanfordmag.org/contents/in-two-years-there-could-be-10-million-self-driving-cars-on-the-roads

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