Bit formatting + alpha beta search:

https://markusthill.github.io/programming/connect-4-introduction-and-tree-search-algorithms/

Board games and AI

https://openreview.net/pdf?id=SkIPFVXUsN

ML AGENTS:

Required software (20/07/2020)

- Unity 2018.4 or Later
- Unity MLAgents package
- Python 3.6/3.7 (64 bit)

Creating a Python virtual environment

- Create a folder for your virtual environments
 C:\python-envs
- Create a new virtual environment
 python -m venv C:\python-envs\mlagents-env

Using a the virtual environment

- Activate using
 - C:\python-envs\mlagents-env\Scripts\activate
- Deactivate using

deactivate

Prepare using mlagents

Install mlagents

pip3 install mlagents

https://github.com/Unity-Technologies/ml-agents/blob/release_4_docs/docs/Getting-Started.md

https://docs.unity3d.com/Packages/com.unity.ml-agents@1.0/api/ Unity.MLAgents.Agent.html#Unity_MLAgents_Agent_CollectObservations_Unity_MLAgents_ Sensors_VectorSensor_

https://github.com/gzrjzcx/ML-agents/blob/master/docs/Training-PPO.md

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https://blogs.unity3d.com/2019/11/11/training-your-agents-7-times-faster-with-ml-agents/

Self play

https://blogs.unity3d.com/2020/02/28/training-intelligent-adversaries-using-self-play-with-ml-agents/

Improvements

https://www.codeproject.com/Articles/5160398/A-Tic-Tac-Toe-Al-with-Neural-Networks-and-Machine

Symetrical games

Reducing action space by using translations, rotations and mirroring on the original board state so

idea's:

minmax with ml agents evalution

training data

TEST RUNS:

TEST1 AlO vs Al1: 500.000 matches = dumb Al (no preventing or finishing 4 in a row, no prioritizing middle row)

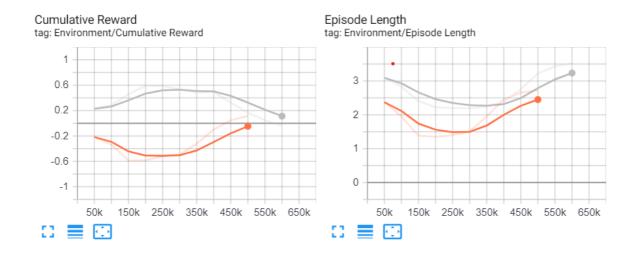
TEST 2 AI vs RND: 500.000 matches = dumb AI (no preventing or finishing 4 in a row, no prioritizing middle row)

TEST 3 AlO vs Al1: 4x4 connect3 -> starting player makes vertical 3 in a rows, second player stops them, no further tactics visible (still dumb Al)

TEST 3 AlO vs Al1: 4x4 connect3 -> starting player makes vertical 3 in a rows, second player stops them, no further tactics visible (still dumb Al)

=>> used basic yaml file which only was one layer deep so obviously the results were bad					

Tic Tac Toe:



Behaviour A trained against Behaviour B with Behaviour A always being the starting player.

1000 < Games	Beginner wins	Draw	Beginner loses
Perfect vs Perfect	100.0%	0.0%	0.0%
Random vs Random	58.2%	11.7%	30.2%
Behaviour A vs Behaviour A	97.5%	1.7%	0.8%
Behaviour B vs Behaviour B	80.4%	10.4%	9.2%
Behaviour A vs Random	96.0%	2.2%	1.8%
Behaviour B vs Random	81.0%	10.6%	8.4%
Random vs Behaviour A	21.4%	5.0%	73.6%
Random vs Behaviour B	49.9%	16.5%	33.6%
Behaviour A vs Behaviour B	21.0%	49.4%	29.6%
Behaviour B vs Behaviour A	67.9%	17.1%	14.9%

These are some really weird results, at least it is visible the training actually worked. Some remarks:

- You would expect Behaviour vs Behaviour matches to have only one outcome, but they seem to be creative. As for now we are clueless why this is happening.
- Although Behaviour B was trained by always responding to the moves of Behaviour A it also performs okay in the starting position.
- Behaviour B became an expert in drawing/winning to Behaviour A (79% of the matches) but has more trouble drawing/winning against random moves (50% of the matches) which is clearly a case of overfitting.
- Although these results look good these behaviours still miss finishing/blocking every three in a row. The behaviours do not understand the game of TicTacToe, they just have an incomplete statistical idea of which moves are good. Many previous tests are not reported because the results looked worthless while probably they would have given a winrate just above Random vs Random.

$cd \ C:\Github\BoardGameAI\Four\Assets\ML-Agents$ $mlagents-learn \ C:\Github\BoardGameAI\Four\Assets\ML-Agents\Basic.yaml --run-id=XXX$

tensorboard --logdir=results

TENNIS SAC:

```
behaviors:
```

Tennis:

trainer_type: sac

hyperparameters:

batch_size: 128

buffer_size: 50000

buffer_init_steps: 0

init_entcoef: 1.0

learning_rate: 0.0003

learning_rate_schedule: constant

save_replay_buffer: false

steps_per_update: 10.0

tau: 0.005

reward_signal_steps_per_update: 10.0

network_settings:

normalize: true

hidden_units: 256

num_layers: 2

vis_encode_type: simple

reward_signals:

```
extrinsic:
```

gamma: 0.99

strength: 1.0

keep_checkpoints: 5

max_steps: 20000000

time_horizon: 64

summary_freq: 10000

threaded: true

self_play:

save_steps: 50000

team_change: 250000

swap_steps: 50000

window: 10

play_against_latest_model_ratio: 0.5

initial_elo: 1200.0

TENNIS PPO

behaviors:

Tennis:

trainer_type: ppo

hyperparameters:

batch_size: 2048

buffer_size: 20480

learning_rate: 0.0003

beta: 0.005

epsilon: 0.2

lambd: 0.95

num_epoch: 3

learning_rate_schedule: constant

network_settings:

normalize: true

hidden_units: 256

num_layers: 2

vis_encode_type: simple

reward_signals:

extrinsic:

gamma: 0.99

strength: 1.0

keep_checkpoints: 5

max_steps: 50000000

time_horizon: 1000

summary_freq: 10000

threaded: true

self_play:

save_steps: 50000

team_change: 100000

swap_steps: 2000

window: 10

play_against_latest_model_ratio: 0.5

initial_elo: 1200.0