# Layered architecture

Application
ECUAL
MCAL
Microcontroller

ECUAL (Electronic unit application layer) for electronic components

MCAL (microcontroller application layer) for microcontroller

### **System modules**

Motor → ECUAL

Button→ECUAL

Led→ ECUAL

DIO →MCAL

Timer → MCAL

Application	
Application	
Button – led – motor	
DIO timer	
microcontroller	

# **APIs**

### **Motor APIs**

;void ADC\_Init(void)

Uint16t ADC\_Read(void)

## **Button APIs**

;void BTN0\_Init(void)

;Uint8t BTN0\_GetValue(void)

### **LED APIs**

```
;void LED_vInit(unsigned char portname,unsigned char pinnumber)
;void LED_vTurnOn(unsigned char portname,unsigned char pinnumber)
;void LED_vTurnOff(unsigned char portname,unsigned char pinnumber)
;void LED_vToggle(unsigned char portname,unsigned char pinnumber)
;unsigned char LED_u8ReadStatus(unsigned char portname,unsigned char pinnumber)
```

### **DIO APIs**

void DIO\_vsetPINDir(unsigned char portname,unsigned char pinnumber,unsigned char ;direction)

void DIO\_write(unsigned char portname,unsigned char pinnumber,unsigned char ;outputvalue)

;unsigned char DIO\_u8read(unsigned char portname,unsigned char pinnumber)

;void DIO\_toggle(unsigned char portname,unsigned char pinnumber)

;void DIO\_set\_port\_direction(unsigned char portname,unsigned char direction)

;void DIO\_write\_port(unsigned char portname,unsigned char portvalue)

;unsigned char DIO\_read\_port(unsigned char portname)

;void DIO\_vconnectpullup(char portname ,char pinnumber, char connect\_pullup)

;void write\_low\_nibble(unsigned char portname,unsigned char value)

void write\_high\_nibble(unsigned char portname,unsigned char value);

#### **Timer APIs**

```
;void timer_CTC_init_interrupt(void)
;void timer_wave_nonPWM(void)
;void timer_wave_fastPWM(void)
;void timer_wave_phasecorrectPWM(void)
```