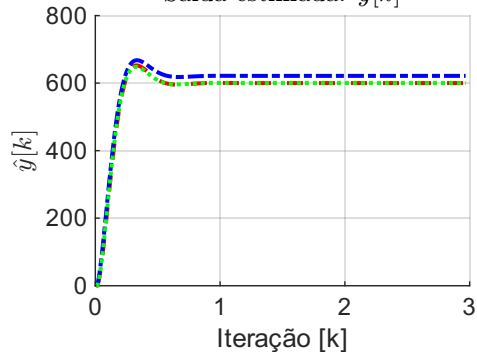
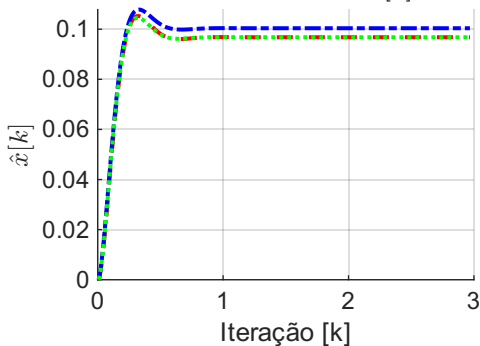


# Análise do observador

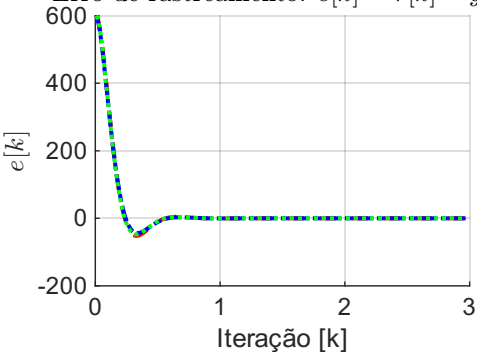
Saída estimada:  $\hat{y}[k]$



Estado estimado:  $\hat{x}[k]$



Erro de rastreamento:  $e[k] = r[k] - y[k]$



Erro de estimativa:  $\hat{e}[k] = x[k] - \hat{x}[k]$

