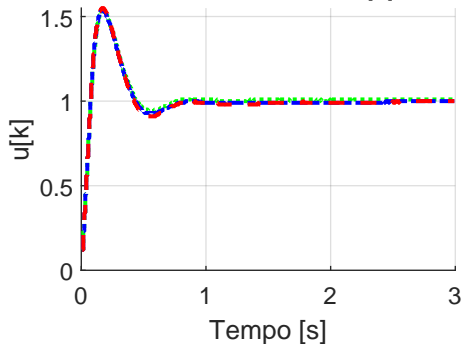
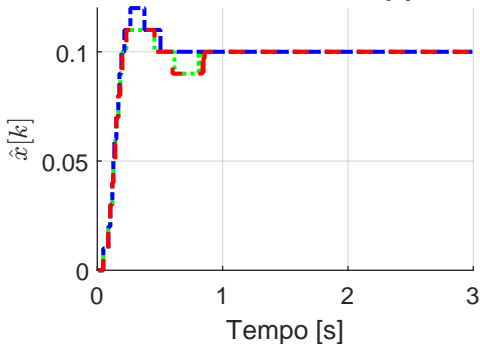


Resposta do sistema real- Controlador aplicado

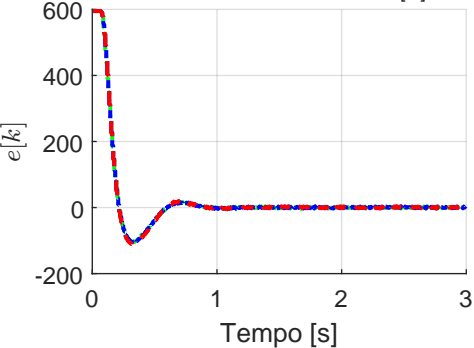
Sinal de Controle $u[k]$



Estado observado $\hat{x}[k]$



Erro de rastreamento $e[k]$



Saida $y[k]$

