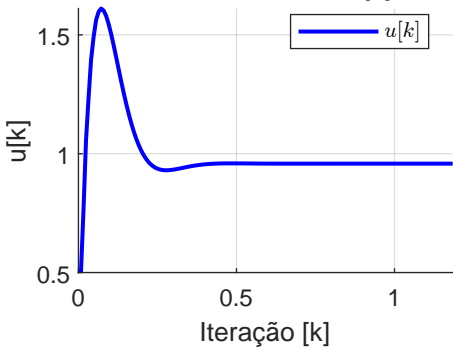
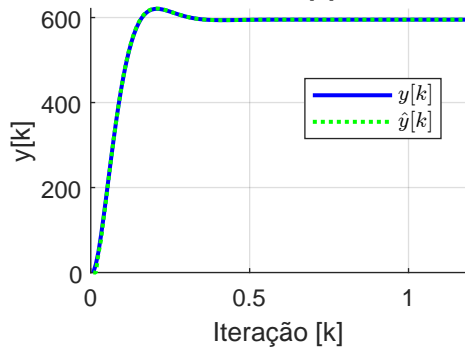


Análise do Observador (Kalman): ( $L_k = 0.032$ ,  $Q_k = 0.1$ ,  $R_k = 90$ )

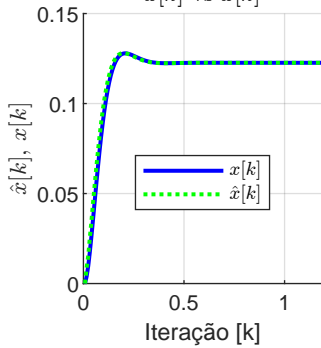
Sinal de Controle  $u[k]$



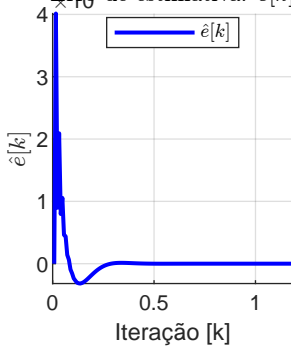
Saída  $y[k]$



$\hat{x}[k]$  vs  $x[k]$



Erro de estimativa:  $\hat{e}[k]$



Erro  $e[k]$

