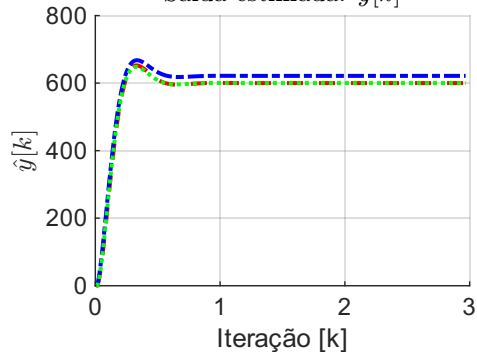
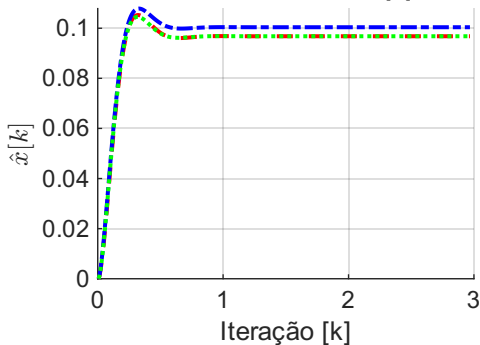


Análise do observador

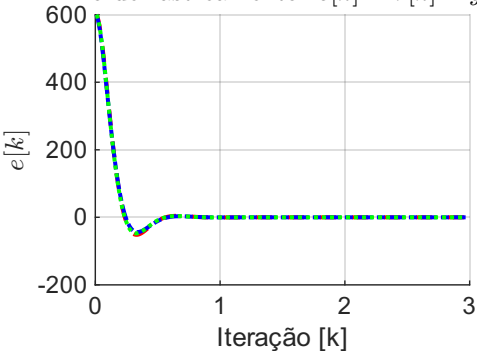
Saída estimada: $\hat{y}[k]$



Estado estimado: $\hat{x}[k]$



Erro de rastreamento: $e[k] = r[k] - y[k]$



Erro de estimativa: $\hat{e}[k] = x[k] - \hat{x}[k]$

