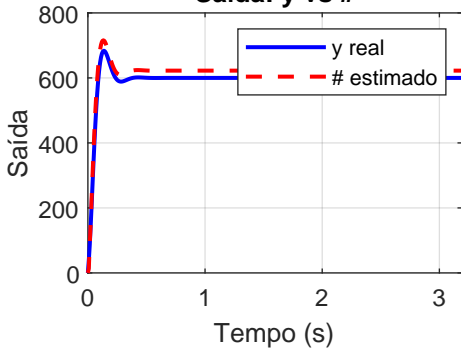
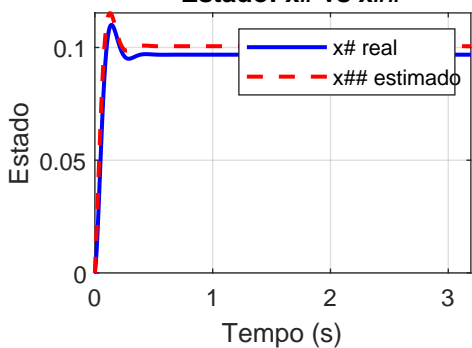


Comparação entre sistema e observador (Tustin)

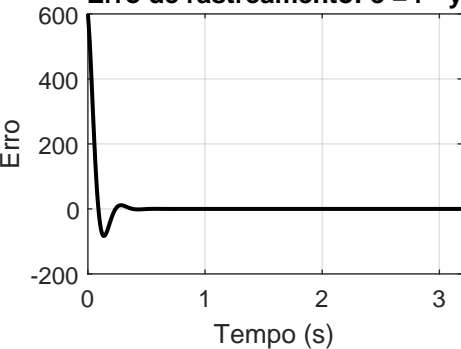
Saída: y vs $\#$



Estado: $x\#$ vs $x\#\#$



Erro de rastreamento: $e = r - y$



Erro de estimação: $\hat{e}\# = x\# - x\#\#$

