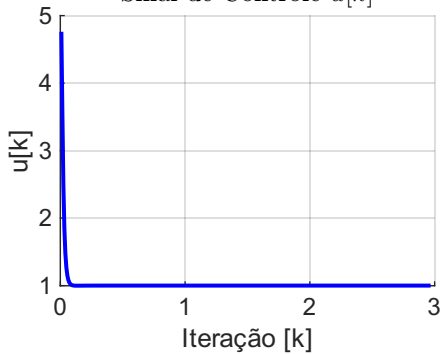
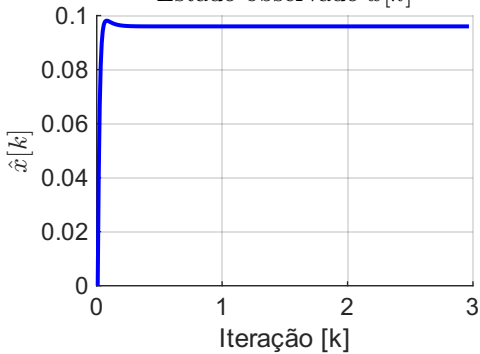


# Análise do controlador

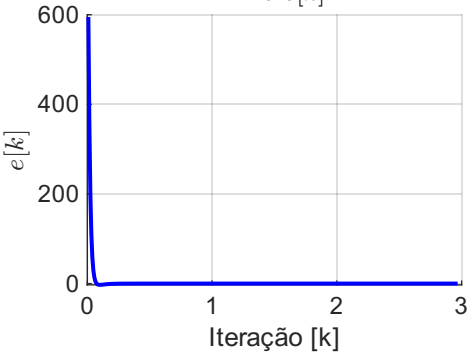
Sinal de Controle  $u[k]$



Estado observado  $\hat{x}[k]$



Erro  $e[k]$



Saida  $y[k]$

