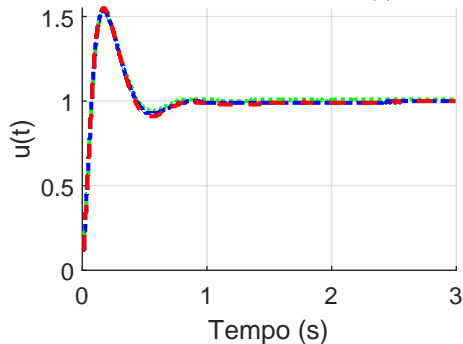
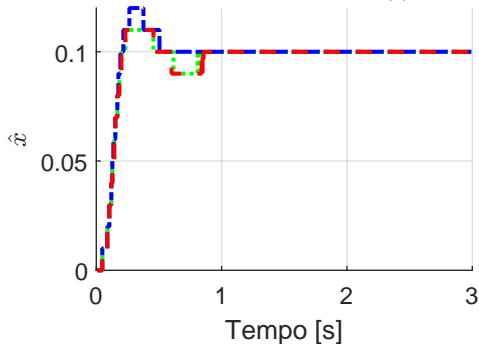


Resposta do sistema real- Controlador aplicado

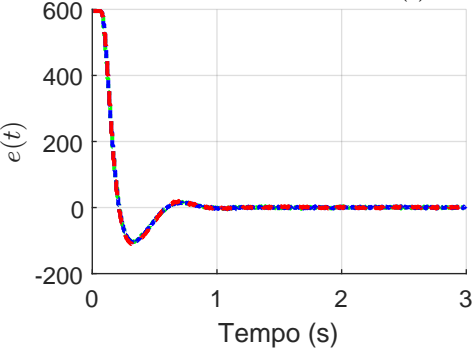
Sinal de Controle $u(t)$



Estado observado $\hat{x}(t)$



Erro de rastreamento $e(t)$



Saida $y(t)$

