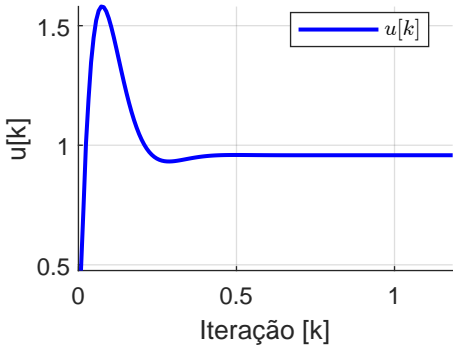
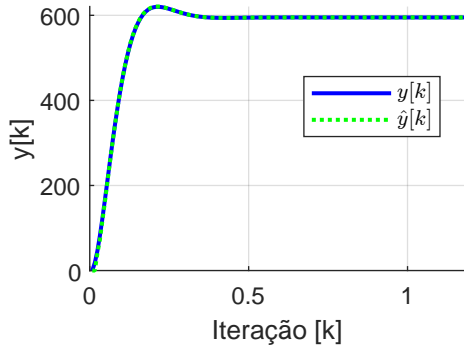


Análise do Observador (Kalman): ($L_k = 0.03$, $Q_k = 0.1$, $R_k = 100$)

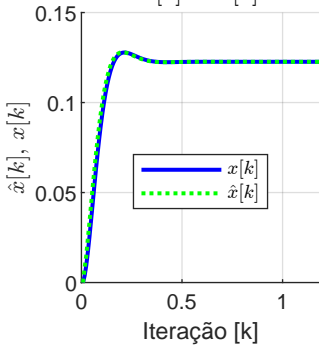
Sinal de Controle $u[k]$



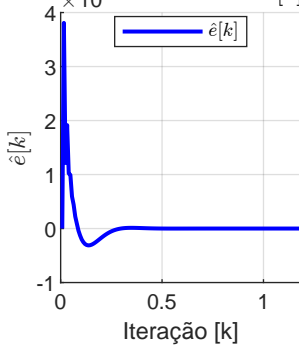
Saída $y[k]$



$\hat{x}[k]$ vs $x[k]$



Erro de estimativa: $\hat{e}[k]$



Erro $e[k]$

