1) Setting: Linear Contextual Bandits - contexts $x \in X \subseteq \mathbb{R}^d$ drawn from distribution $O \in \Delta(X) \times_{t} \sim D$ -action "arms" a e A = {1,--, k} - rewards rt = r(xt, at) F[Y(x,a)] = $Ya(x) = \Theta_a^T x$ linear function $\Theta_a \in \mathbb{R}^d$ (unknown) - hovizon Goal: find a policy of=TT(Xt), acheive low regret $R(T) = \sum_{t=1}^{L} \mathbb{E} \left[\max_{X_t} \Theta_a^T X_t - \Theta_{a_t}^T X_t \right]$ yx(Xt) Tix(xx) Example: music recommendation arm = artists

antext = user's affinity

towards traits

slow

produce

pro Last lecture: explore-then-commit based on supervised learning at=argmax ya(Xt) $M_a = \underset{\text{MeM}}{\operatorname{argmin}} \frac{N}{\sum} (M(X_i^a) - v_i^a)^2$ data calected during exploration

Liwar Repression

Sink
$$y_a(x) = \Theta^T X$$
, $M = \{y(x) = \Theta^T X \mid \Theta \in \mathbb{R}^d\}$

$$\widehat{\Theta}_a = \underset{i=1}{\text{argmin}} \sum_{i=1}^{N} (\Theta^T X_i^a - Y_i^a)^2$$

Lemma: as long as $(x_i)_{i=1}^{N} \text{ span } \mathbb{R}^d$

$$\widehat{\Theta} = (\sum_{i=1}^{N} x_i x_i^T)^{-1} \sum_{i=1}^{N} x_i Y_i = A^T b$$

Proof: $\nabla_{\Theta} \left[\sum_{i=1}^{N} (\Theta^T X_i - Y_i)^2 \right] = 2 \sum_{i=1}^{N} (2^T X_i - Y_i) X_i = 0$

$$\left[\sum_{i=1}^{N} x_i x_i^T \right] = \sum_{i=1}^{N} x_i Y_i$$

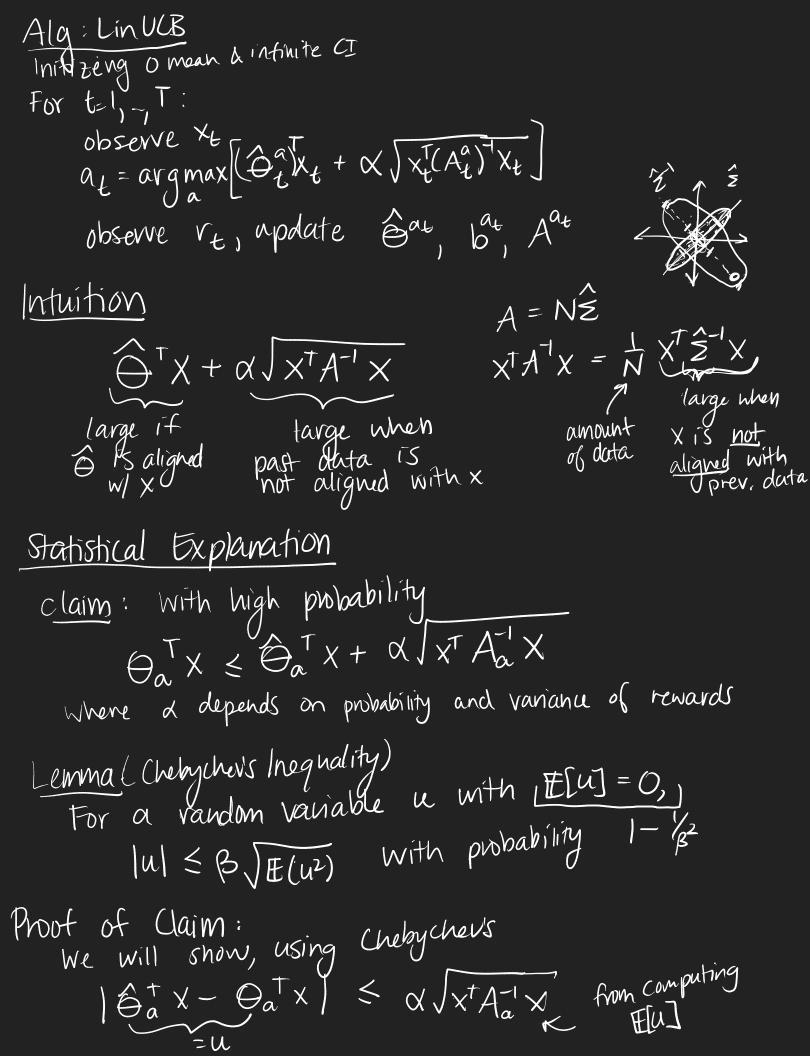
A is related to europinical covariance of X

$$Z = \mathbb{H} \left[x x^T \right] = \sum_{i=1}^{N} x_i x_i^T \qquad A = N \hat{\Xi}$$

3) Linux Algorithm

We keep track of:
$$A^a = \sum_{i=1}^{N} x_i x_i^T = \sum_{i=1}^{N} x_i x_i Y_i = 0$$

 $A_{t}^{a} = \sum_{k=1}^{t} X_{k} X_{k}^{T} 1 \{ a_{k} = a \}$ $b_{t}^{q} = \sum_{k=1}^{t} X_{k} Y_{k} 1 \{ a_{k} = a \}$ $\Theta_{t}^{\alpha} = (A_{t}^{\alpha})^{-1}b_{t}^{\alpha}$



I)
$$\begin{aligned}
& \left[\left[\left(\frac{\partial}{\partial x} \times - \Theta^{T} X \right) \right] \stackrel{?}{=} O \\
& \left[\left(\frac{\partial}{\partial x} \times (x_{i})^{T} \right) \right] \stackrel{?}{=} V_{i} \\
& \left[\left(\frac{\partial}{\partial x} \times (x_{i})^{T} \right) \right] \stackrel{?}{=} V_{i} \stackrel{?}{$$