

Backtracking 2

Agenda

- Print paths in staircase problem
- Print all paths from source to destination
- Shortest path in matrix with hurdles

Question 1

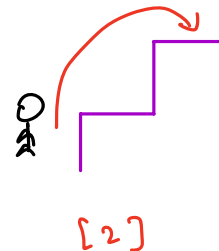
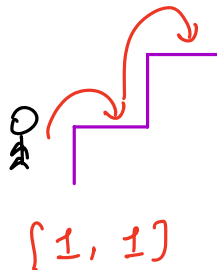
You are climbing a staircase and it takes N steps to reach the top.

Each time, you can take either 1 or 2 steps.

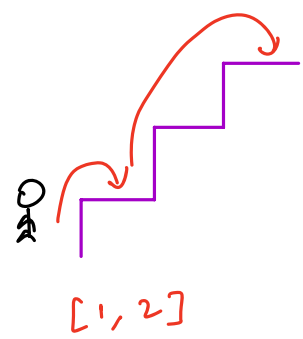
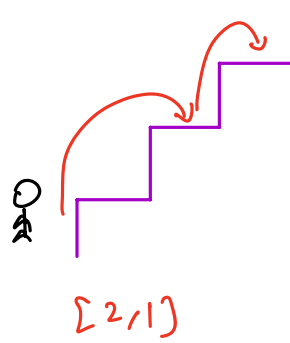
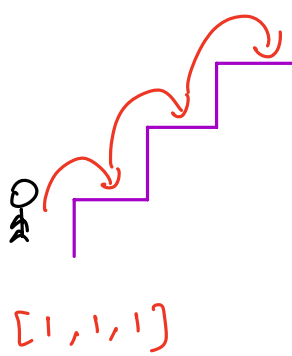
In how many distinct ways you can climb.

Return all distinct ways in lexicographical order.

$N=2$

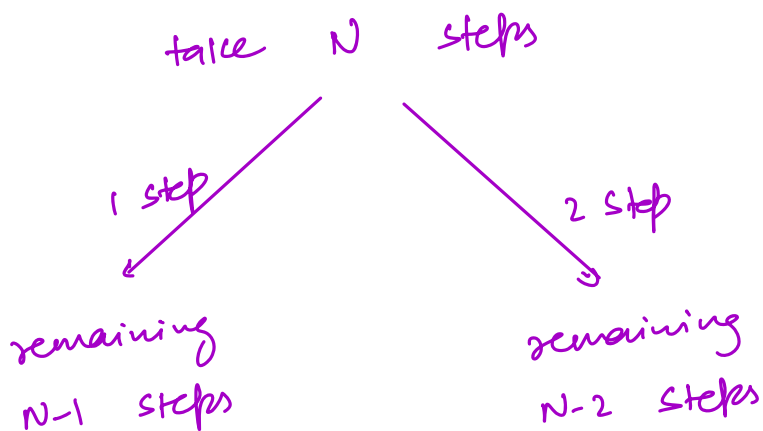


$N=3$



o/p: $[[1, 1, 1], [1, 2], [2, 1]]$

Solution

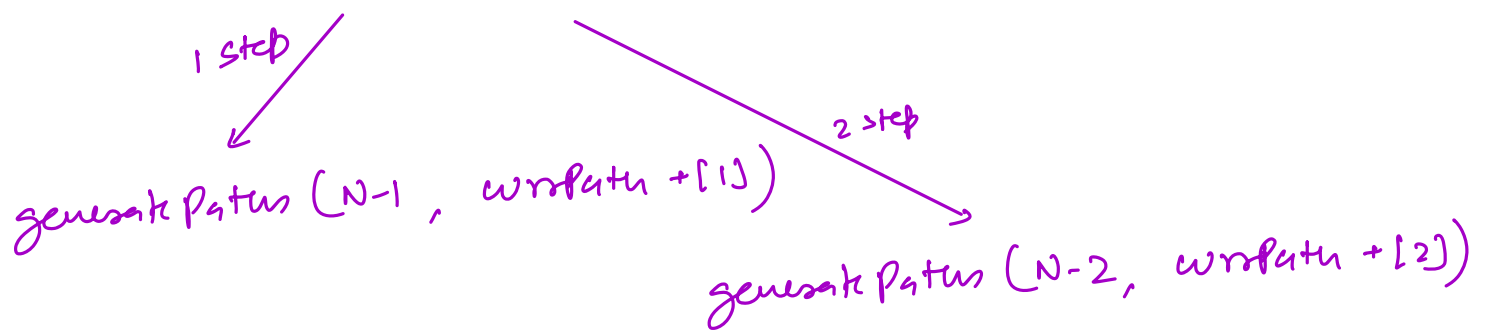


if N becomes 0, we have reached top and store the current in answer.

now to keep lexicographically sorted?

→ always choose step 1 before step 2.

generatePaths (N, currPath)



Code

list < list < int > > ans;

def generatePaths (N, list < int > currPath) {

if (N == 0) {

ans.append(currPath);

return;

}

if (N >= 1) {

currPath.add(1);

generatePaths (N-1, currPath);

currPath.removeBack();

}

if (N >= 2) {

currPath.add(2);

generatePaths (N-2, currPath);

currPath.removeBack();

}

3

↻

```
def generatePaths(N, lit<int>currPath) {  
  if (N==0) {  
    ans.append(currPath);  
    return;  
  }  
  if (N>=1) {  
    currPath.add(1); [1]  
    generatePaths(N-1, currPath);  
    currPath.removeBack(); [1]  
  }  
  if (N>=2) {  
    currPath.add(2); [2]  
    generatePaths(N-2, currPath);  
    currPath.removeBack(); [2]  
  }  
}
```

↻

```
def generatePaths(N, lit<int>currPath) {  
  if (N==0) {  
    ans.append(currPath);  
    return;  
  }  
  if (N>=1) {  
    currPath.add(1); [2,1]  
    generatePaths(N-1, currPath);  
    currPath.removeBack(); [2]  
  }  
  if (N>=2) {  
    currPath.add(2); [2,2]  
    generatePaths(N-2, currPath);  
    currPath.removeBack(); [2]  
  }  
}
```

↻ N=0, [2,2]

↻

```
def generatePaths(N, lit<int>currPath) {  
  if (N==0) {  
    ans.append(currPath);  
    return;  
  }  
  if (N>=1) {  
    currPath.add(1); [1,1]  
    generatePaths(N-1, currPath);  
    currPath.removeBack(); [1]  
  }  
  if (N>=2) {  
    currPath.add(2); [1,2]  
    generatePaths(N-2, currPath);  
    currPath.removeBack(); [1]  
  }  
}
```

↻

```
def generatePaths(N, lit<int>currPath) {  
  if (N==0) {  
    ans.append(currPath);  
    return;  
  }  
  if (N>=1) {  
    currPath.add(1); [2,1,1]  
    generatePaths(N-1, currPath);  
    currPath.removeBack(); [2,1]  
  }  
  if (N>=2) {  
    currPath.add(2);  
    generatePaths(N-2, currPath);  
    currPath.removeBack();  
  }  
}
```

↻ N=0, [2,1,1]

↻

```
def generatePaths(N, lit<int>currPath) {  
  if (N==0) {  
    ans.append(currPath);  
    return;  
  }  
  if (N>=1) {  
    currPath.add(1); [1,1,1]  
    generatePaths(N-1, currPath);  
    currPath.removeBack(); [1,1]  
  }  
  if (N>=2) {  
    currPath.add(2); [1,1,2]  
    generatePaths(N-2, currPath);  
    currPath.removeBack(); [1,1]  
  }  
}
```

↻

```
def generatePaths(N, lit<int>currPath) {  
  if (N==0) {  
    ans.append(currPath);  
    return;  
  }  
  if (N>=1) {  
    currPath.add(1); [1,2,1]  
    generatePaths(N-1, currPath);  
    currPath.removeBack(); [1,2]  
  }  
  if (N>=2) {  
    currPath.add(2);  
    generatePaths(N-2, currPath);  
    currPath.removeBack();  
  }  
}
```

↻ N=0, [1,2,1]

$[1,1,1]$
 def generatePaths(N, list<int> currPath) {
 if (N == 0) {
 ans.append(currPath);
 return;
 }
 if (N >= 1) {
 currPath.add(1); $[1,1,1]$
 generatePaths(N-1, currPath);
 currPath.removeBack(); $[1,1]$
 }
 if (N >= 2) {
 currPath.add(2);
 generatePaths(N-2, currPath);
 currPath.removeBack();
 }
 }

$[1,1,2]$
 def generatePaths(N, list<int> currPath) {
 if (N == 0) {
 ans.append(currPath);
 return;
 }
 if (N >= 1) {
 currPath.add(1);
 generatePaths(N-1, currPath);
 currPath.removeBack();
 }
 if (N >= 2) {
 currPath.add(2);
 generatePaths(N-2, currPath);
 currPath.removeBack();
 }
 }

$[1,1,1,1]$
 def generatePaths(N, list<int> currPath) {
 if (N == 0) {
 ans.append(currPath);
 return;
 }
 if (N >= 1) {
 currPath.add(1);
 generatePaths(N-1, currPath);
 currPath.removeBack();
 }
 if (N >= 2) {
 currPath.add(2);
 generatePaths(N-2, currPath);
 currPath.removeBack();
 }
 }

$ans = [[1,1,1,1], [1,1,1,2], [1,2,1,1], [2,1,1,1], [2,2,2]]$

$$TC = O(2^N)$$

$$SC = O(N)$$

Question 2

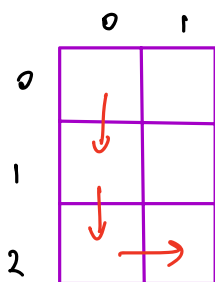
You are given a rectangular board of $N \times M$.

Print all possible paths from top-left to bottom-right corner of board.

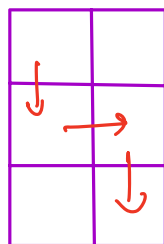
You can only move down (D) or right (R)

Print all paths in lexicographical order.

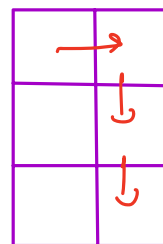
$N=3, M=2$



DDR



DRD



RDD

`printPaths (r, c , currPath)`

go down
↙

`printPaths (r+1, c, currPath + 'D')`

go right
↘

`printPaths (r, c+1, currPath + 'R')`

Code

```
list<String> ans
def printPath (r, c, N, M, currPath) {
    if (r == N-1 && c == M-1) {
        ans.add(currPath);
        return;
    }
    if (r < N-1) {
        printPath (r+1, c, N, M, currPath + "D");
    }
    if (c < M-1) {
        printPath (r, c+1, N, M, currPath + "R");
    }
}
```

no need to
remove back since
we are not updating
currPath

TC = $2^{\text{path length}}$

$$TC = O(2^{N+M})$$

$$SC = O(N+M)$$

path length =

rows + # cols

$$N+M$$

Question 3

Given $N \times M$ matrix with 0 or 1 values.

find the shortest path from a given source to a given destination.

A cell with value 0 is a hurdle. The path can only be created with cells of value 1.

	0	1	2	3
0	1	1	0	0
1	0	1	1	0
2	0	0	1	1
3	0	0	0	1

4

start = (0,0)

end = (3,3)

path length = 6

	0	1	2	3
0	1	1	0	0
1	0	1	0	0
2	0	0	1	1
3	0	0	0	1

4

start = (0,0)

end = (3,3)

path length = -1

	0	1	2	3
0	1	1	1	1
1	0	0	1	1
2	1	1	1	0
3	0	0	0	1

4

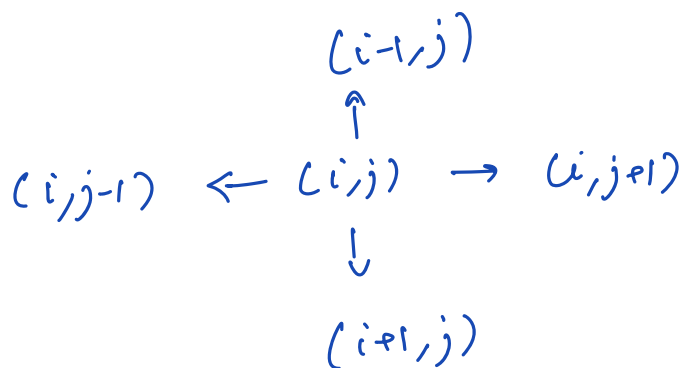
start = (0,0)

end = (2,0)

path length = 6

Solution :

1. Start from given source cell and explore all four possible paths.
2. Check if destination is reached or not.
3. Backtrack if not reached
4. Keep track of cells visited.



if you are at cell (i,j) , then you can go to
cell $(i+1,j)$ iff

$$\text{cell}[i+1][j] == 1 \quad \&\& \quad i+1 < N \\ i < N-1$$

code

row = {⁰-1, ¹1, ²0, ³0}
col = {0, 0, 1, -1}

int ans = INT_MAX

def explorePath(A, visited, ^{source}i, ^{destination}j, p, q, pathlength) {

if (i == p && j == q) {

ans = min(ans, pathlength)

return;

}

for (k = 0 to 3) {

ni = i + row[k]

nj = j + col[k]

if (ni >= 0 && ni < N && nj >= 0 && nj < M
&& A[ni][nj] == 1 && NOT visited[ni][nj]) {

visited[ni][nj] = true

explorePath(A, visited, ni, nj, p, q, pathlength + 1)

visited[ni][nj] = false

}

}

}

if (ans == INT_MAX)

ans = -1

TC = $O(4^{n \times m})$

SC = $O(N \times M)$

