Question 1. Show that the unit direction vector inclined equally to the coordinate axes is  $\begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{5}} \end{pmatrix}$ .

**Solution:** Let **m** be the given unit vector such that 
$$\mathbf{m} = \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix}$$
. Let  $\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ ,

$$\mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$
 and  $\mathbf{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$  be the direction vectors of the coordinate axes. As  $\mathbf{m}$ 

is a unit vector, so  $\|\mathbf{m}\| = 1$  and also we are given is that  $\mathbf{m}$  is inclined equally to the coordinate axis,

$$\mathbf{e}_1^T \mathbf{m} = \mathbf{e}_2^T \mathbf{m} = \mathbf{e}_3^T \mathbf{m} \tag{1}$$

Now, (1) implies

$$(\mathbf{e}_1 - \mathbf{e}_2)^T \mathbf{m} = 0 \tag{2}$$

$$(\mathbf{e}_2 - \mathbf{e}_3)^T \mathbf{m} = 0 \tag{3}$$

$$(\mathbf{e}_3 - \mathbf{e}_1)^T \mathbf{m} = 0 \tag{4}$$

Thus, converting above system of equations into matrix form, we get

$$\mathbf{Am} = \mathbf{0} \tag{5}$$

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ -1 & +0 & +1 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{array}{c} r_3 \leftarrow r_1 + r_3 \\ \hline \\ 0 \end{pmatrix} \Leftrightarrow \begin{array}{c} (6) \\ \hline \\ (7) \\ \hline \\ (7) \\ \end{array}$$

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ +0 & -1 & +1 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{array}{c} r_3 \leftarrow r_2 + r_3 \\ \hline \\ 0 \end{pmatrix} \Leftrightarrow \begin{array}{c} (7) \\ \hline \end{array}$$

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ +0 & -1 & +1 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \xleftarrow{r_3 \leftarrow r_2 + r_3}$$
 (7)

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ +0 & +0 & +0 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \xrightarrow{r_1 \leftarrow r_1 + r_2}$$
 (8)

$$\begin{pmatrix} +1 & +0 & -1 \\ +0 & +1 & -1 \\ +0 & +0 & +0 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$
(9)

From (9) we find out that

$$m_x = m_y = m_z \tag{10}$$

$$\mathbf{m} = \begin{pmatrix} m_z \\ m_z \\ m_z \end{pmatrix} \quad and \quad \|\mathbf{m}\| = \sqrt{3}m_z \tag{11}$$

For **m** to be a unit vector, we need to divide each element of **m** by  $\|\mathbf{m}\|$ . Hence

$$\mathbf{m} = \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$$

Thus, we see that  $\mathbf{m} = \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$  is the unit direction vector inclined equally to the coordinate axes.

The unit direction vector inclined equally to the coordinate axes

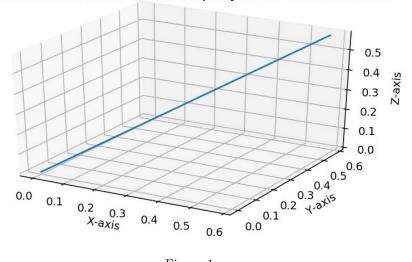


Figure 1