Question 1. Show that the unit direction vector inclined equally to the coordinate axes is $\begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{2} \end{pmatrix}$

Solution: Let **m** be the given unit vector such that $\mathbf{m} = \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix}$. Let $\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$,

 $\mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ and $\mathbf{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ be the direction vectors of the coordinate axes. As \mathbf{m} is a unit vector, so $\|\mathbf{m}\| = 1$ and also we are given is that \mathbf{m} is inclined equally

 $\mathbf{e}_1^T \mathbf{m} = \mathbf{e}_2^T \mathbf{m} = \mathbf{e}_3^T \mathbf{m}$ (1)

Now, (1) implies

to the coordinate axis,

$$(\mathbf{e}_1 - \mathbf{e}_2)^T \mathbf{m} = 0$$
$$(\mathbf{e}_2 - \mathbf{e}_3)^T \mathbf{m} = 0$$
$$(\mathbf{e}_3 - \mathbf{e}_1)^T \mathbf{m} = 0$$

Thus, converting above system of equations into matrix form, we get

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ -1 & +0 & +1 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \xrightarrow{R_3 =} R_1 + R_3$$
 (2)

$$\begin{pmatrix}
+1 & -1 & +0 \\
+0 & +1 & -1 \\
-1 & +0 & +1
\end{pmatrix}
\begin{pmatrix}
m_x \\
m_y \\
m_z
\end{pmatrix} = \begin{pmatrix}
0 \\
0 \\
0
\end{pmatrix}
\xrightarrow{R_3 =} \xrightarrow{R_1 + R_3}$$
(2)
$$\begin{pmatrix}
+1 & -1 & +0 \\
+0 & +1 & -1 \\
+0 & -1 & +1
\end{pmatrix}
\begin{pmatrix}
m_x \\
m_y \\
m_z
\end{pmatrix} = \begin{pmatrix}
0 \\
0 \\
0
\end{pmatrix}
\xrightarrow{R_3 =} \xrightarrow{R_2 + R_3}$$
(3)
$$\begin{pmatrix}
+1 & -1 & +0 \\
+0 & +1 & -1 \\
+0 & +0 & +0
\end{pmatrix}
\begin{pmatrix}
m_x \\
m_y \\
m_z
\end{pmatrix} = \begin{pmatrix}
0 \\
0 \\
0
\end{pmatrix}
\xrightarrow{R_1 =} \xrightarrow{R_1 + R_2}$$
(4)
$$\begin{pmatrix}
+1 & +0 & +1 \\
-1 & +1 & -1 \\
+0 & +0 & +0
\end{pmatrix}
\begin{pmatrix}
m_x \\
m_y \\
m_z
\end{pmatrix} = \begin{pmatrix}
0 \\
0 \\
0
\end{pmatrix}$$
(5)

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ +0 & +0 & +0 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \xrightarrow[R_1+R_2]{R_1+R_2}$$
(4)

$$\begin{pmatrix} +1 & +0 & +1 \\ -1 & +1 & -1 \\ +0 & +0 & +0 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$
 (5)

From(5) we find out that

$$m_x = m_y = m_z$$

Taking, $m_x = m_y = m_z = 1$, we get

$$\mathbf{m} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

Also, we know that $\|\mathbf{m}\|=1$ as \mathbf{m} is a unit vector, thus

$$\mathbf{m} = \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$$

Thus, we see that $\mathbf{m}=\begin{pmatrix} \frac{1}{\sqrt{3}}\\ \frac{1}{\sqrt{3}}\\ \frac{1}{\sqrt{3}} \end{pmatrix}$ is the unit direction vector inclined equally to the coordinate axes.

The unit direction vector inclined equally to the coordinate axes

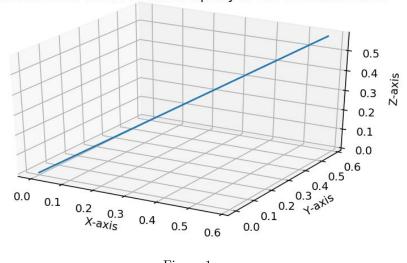


Figure 1