Question 1. Show that the unit direction vector inclined equally to the coordinate axes is  $\begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$ .

**Solution:** Let **m** be the given unit vector such that  $\mathbf{m} = \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix}$ . Let  $\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ ,

 $\mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$  and  $\mathbf{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$  be the direction vectors of the coordinate axes. As  $\mathbf{m}$ 

is a unit vector, so  $\|\mathbf{m}\| = 1$  and also we are given is that  $\mathbf{m}$  is inclined equally to the coordinate axis,

$$\mathbf{e}_1^T \mathbf{m} = \mathbf{e}_2^T \mathbf{m} = \mathbf{e}_3^T \mathbf{m} \tag{1}$$

Now, (1) implies

$$(\mathbf{e}_1 - \mathbf{e}_2)^T \mathbf{m} = 0$$
$$(\mathbf{e}_2 - \mathbf{e}_3)^T \mathbf{m} = 0$$
$$(\mathbf{e}_3 - \mathbf{e}_1)^T \mathbf{m} = 0$$

Thus, converting above system of equations into matrix form, we get

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ -1 & +0 & +1 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \xleftarrow{R_3 \leftarrow R_1 + R_3}$$
 (2)

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ -1 & +0 & +1 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{array}{l} R_3 \leftarrow R_1 + R_3 \\ R_3 \leftarrow R_1 + R_3 \\ R_3 \leftarrow R_2 + R_3 \\ R_3 \leftarrow R_2 + R_3 \\ R_3 \leftarrow R_2 + R_3 \\ R_3 \leftarrow R_3 \leftarrow R_2 + R_3 \\ R_3 \leftarrow R_3 \leftarrow R_2 + R_3 \\ R_3 \leftarrow R_3$$

$$\begin{pmatrix} +1 & -1 & +0 \\ +0 & +1 & -1 \\ +0 & +0 & +0 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \stackrel{R_1 \leftarrow R_1 + R_2}{\longrightarrow}$$
(4)

$$\begin{pmatrix} +1 & -1 & +1 \end{pmatrix} \begin{pmatrix} m_z \\ +0 & +1 & -1 \\ +0 & +0 & +0 \end{pmatrix} \begin{pmatrix} m_x \\ m_y \\ m_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{matrix} R_1 \leftarrow R_1 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_1 \leftarrow R_1 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_1 \leftarrow R_1 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_1 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_1 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R_2 + R_2 \\ R_2 \Rightarrow \begin{matrix} R_2 \leftarrow R_2 + R$$

From (5) we find out that

$$m_x = m_y = m_z \tag{6}$$

$$\mathbf{m} = \begin{pmatrix} m_z \\ m_z \\ m_z \end{pmatrix} \quad and \quad \|\mathbf{m}\| = \sqrt{3}m_z \tag{7}$$

For **m** to be a unit vector, we need to divide each element of **m** by  $\|\mathbf{m}\|$ . Hence

$$\mathbf{m} = \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$$

Thus, we see that  $\mathbf{m} = \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$  is the unit direction vector inclined equally to the coordinate axes.

## The unit direction vector inclined equally to the coordinate axes

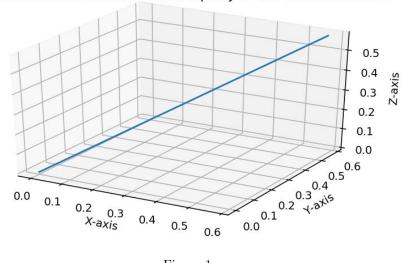


Figure 1