

Matrix theory - Challenge problem 2

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Abstract—This document illustrates how to find closest points in skew lines in 3D

Download all python codes from

https://github.com/shreeprasadbhat/matrix-theory/tree/master/challenging_problems/challenge_2/codes

and latex-tikz codes from

https://github.com/shreeprasadbhat/matrix-theory/blob/master/challenging_problems/challenge_2/

1 PROBLEM

We know that in 3D, it is possible that 2 lines are not parallel, but do not meet. They are known as skew lines. Find a way to points on these lines that are closest to each other?

2 SOLUTION

Let's illustrate this problem with an example. Find the closest point between two skew lines

$$L_1 : r_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \lambda_1 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \quad (2.0.1)$$

$$L_2 : r_2 = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} + \lambda_2 \begin{pmatrix} 3 \\ -5 \\ 2 \end{pmatrix} \quad (2.0.2)$$

Let P and Q be two closest points on line L_1 and L_2 respectively. Then direction vector along line PQ is $P - Q$

$$P - Q = \begin{pmatrix} 2 - 1 \\ 1 - 1 \\ -1 - 0 \end{pmatrix} + \lambda_2 \begin{pmatrix} 3 \\ -5 \\ 2 \end{pmatrix} - \lambda_1 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \quad (2.0.3)$$

can also be written as

$$P - Q = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} - \begin{pmatrix} 2 & -3 \\ -1 & 5 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} \quad (2.0.4)$$

We know that dot product of a vector and an another vector perpendicular to it is 0. The direction vector of L_1 is $\begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$ and $P - Q$ is \perp to it, hence

$$\begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}^T (P - Q) = 0 \quad (2.0.5)$$

Also, direction vector of L_2 is $\begin{pmatrix} 3 \\ -5 \\ 2 \end{pmatrix}$ and it is \perp to $P - Q$, hence

$$\begin{pmatrix} 3 \\ -5 \\ 2 \end{pmatrix}^T (P - Q) = 0 \quad (2.0.6)$$

Substituting equation (2.0.4) in (2.0.5)

$$\begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}^T \left(\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} - \begin{pmatrix} 2 & -3 \\ -1 & 5 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} \right) = 0 \quad (2.0.7)$$

Rearranging above equation

$$\begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}^T \begin{pmatrix} 2 & -3 \\ -1 & 5 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}^T \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \quad (2.0.8)$$

$$(6 \quad -13) \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} = (1) \quad (2.0.9)$$

$$\Rightarrow 6\lambda_1 - 13\lambda_2 = 1 \quad (2.0.10)$$

Substituting equation (2.0.4) in (2.0.6)

$$\begin{pmatrix} 3 \\ -5 \\ 2 \end{pmatrix}^T \left(\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} - \begin{pmatrix} 2 & -3 \\ -1 & 5 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} \right) = 0 \quad (2.0.11)$$

Rearranging above equation

$$\begin{pmatrix} 3 \\ -5 \\ 2 \end{pmatrix}^T \begin{pmatrix} 2 & -3 \\ -1 & 5 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} = \begin{pmatrix} 3 \\ -5 \\ 2 \end{pmatrix}^T \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \quad (2.0.12)$$

$$\begin{pmatrix} 13 & -38 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} = \begin{pmatrix} 1 \end{pmatrix} \quad (2.0.13)$$

$$\Rightarrow 13\lambda_1 - 38\lambda_2 = 1 \quad (2.0.14)$$

Solve (2.0.10) and (2.0.14) to get λ_1 and λ_2

$$\begin{pmatrix} 6 & -13 \\ 13 & -38 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad (2.0.15)$$

Augmented matrix will be

$$\begin{pmatrix} 6 & -13 & 1 \\ 13 & -38 & 1 \end{pmatrix} \xrightarrow{R_2 = R_2 - \frac{13}{6}R_1} \begin{pmatrix} 6 & -13 & 1 \\ 0 & \frac{-59}{13} & \frac{-7}{13} \end{pmatrix} \quad (2.0.16)$$

$$\lambda_2 = \frac{-7}{13} \times \frac{13}{-9} = \frac{7}{59} \quad (2.0.17)$$

Substituting λ_2 in (2.0.10)

$$6\lambda_1 - \left(13 \times \frac{7}{59}\right) = 1 \quad (2.0.18)$$

$$6\lambda_1 = 1 + \left(13 \times \frac{7}{59}\right) \quad (2.0.19)$$

$$\lambda_1 = \frac{150}{59 \times 6} \quad (2.0.20)$$

$$\lambda_1 = \frac{25}{59} \quad (2.0.21)$$

Substituting in λ_1 equation (2.0.1)

$$P = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \frac{25}{59} \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \quad (2.0.22)$$

$$P = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} \frac{50}{59} \\ \frac{-25}{59} \\ \frac{25}{59} \end{pmatrix} \quad (2.0.23)$$

$$P = \begin{pmatrix} \frac{109}{59} \\ \frac{59}{34} \\ \frac{59}{25} \\ \frac{59}{59} \end{pmatrix} = \begin{pmatrix} 1.85 \\ 0.58 \\ 0.42 \end{pmatrix} \quad (2.0.24)$$

Substituting λ_2 in equation (2.0.2)

$$Q = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} + \frac{7}{59} \begin{pmatrix} 3 \\ -5 \\ 2 \end{pmatrix} \quad (2.0.25)$$

$$Q = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} + \begin{pmatrix} \frac{21}{59} \\ \frac{-35}{59} \\ \frac{14}{59} \end{pmatrix} \quad (2.0.26)$$

$$Q = \begin{pmatrix} \frac{139}{59} \\ \frac{24}{59} \\ \frac{-45}{59} \end{pmatrix} = \begin{pmatrix} 2.36 \\ 0.41 \\ -0.76 \end{pmatrix} \quad (2.0.27)$$

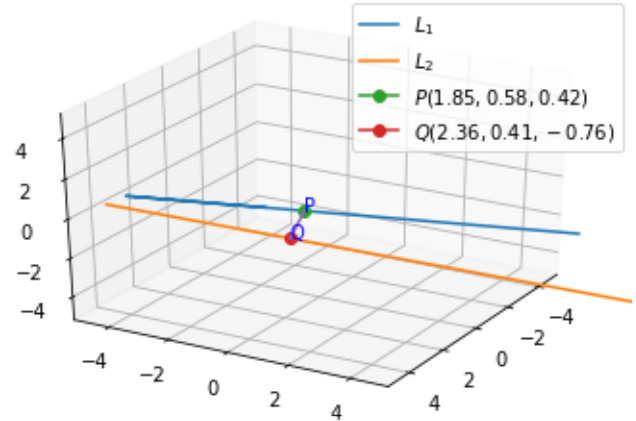


Fig. 0: Closest points between skew lines L_1 and L_2