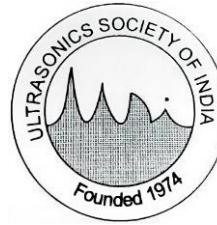




Development of Device for the Estimation of Ambient Temperature by measuring Ultrasonic Propagation Velocity in Air



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Introduction

What is an Ultrasound ?

- You can't hear it – ultrasound has a frequency above 20 kHz, beyond the human hearing range of 20 Hz–20 kHz.
- It needs a medium to travel – ultrasound moves through air, liquids, or solids as mechanical waves.
- It reflects back from objects – this echo behavior makes ultrasound useful for sensing, measurement, and imaging.

1. Longitudinal or Compression Waves
2. Transverse or Shear Waves

Generation:

- Piezoelectric Method
- EMAT Methods

Applications:

- Calibration
- Research and Engineering
- Medical

Ultrasonic testing methods:

- Single transducer method (Pulse-echo method)
- Two transducer method (Through transmission method)

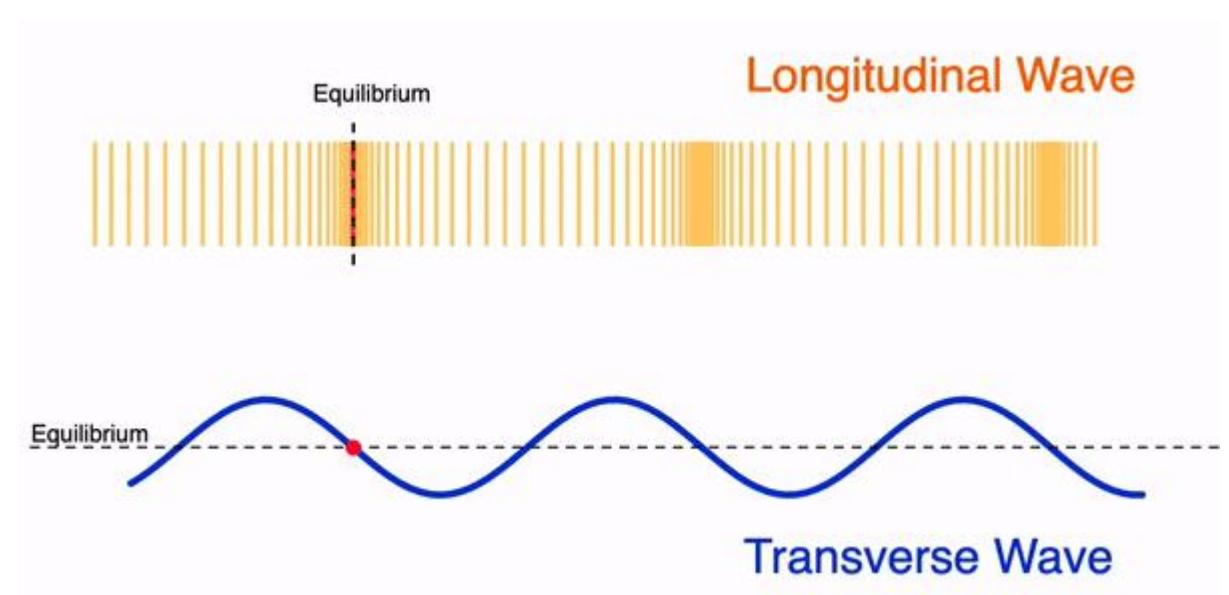


Fig.1 Propagation of waves

Ultrasonic Technique for Temperature Measurement:

- Time-of-Flight Method
- ✓ Measures the travel time of ultrasonic pulses between transducer and reflector
- ✓ Converts measured time into sound velocity to estimate temperature

Temperature Measurement using Ultrasonic Propagation Velocity

Working principle:

The principle used in the measurement of ambient temperature is based on the accurate determination of the ultrasonic velocity in air. The temperature T can be calculated by the following equation:

$$T = \frac{c - 331.4}{0.606} \quad (1)$$

where, c is the velocity of sound in air in m/s, **331.4** m/s is the velocity of sound at 0°C, **0.606** is the temperature coefficient, indicating how sound speed increases per degree rise in temperature, T is the ambient temperature in °C.

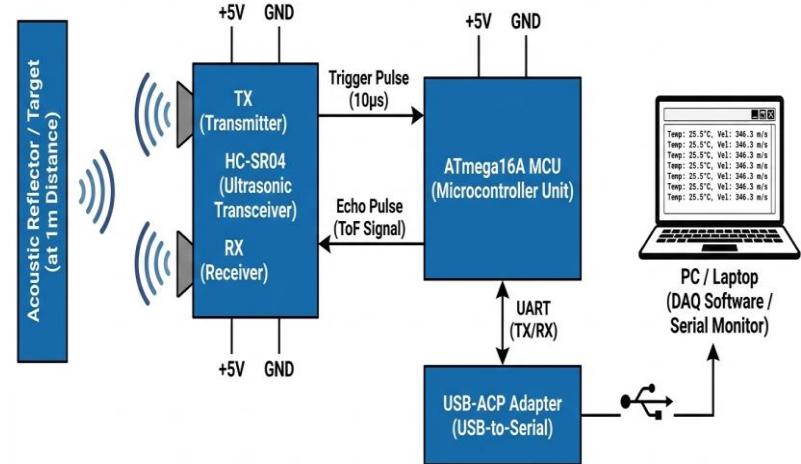


Fig.2 Systematic diagram

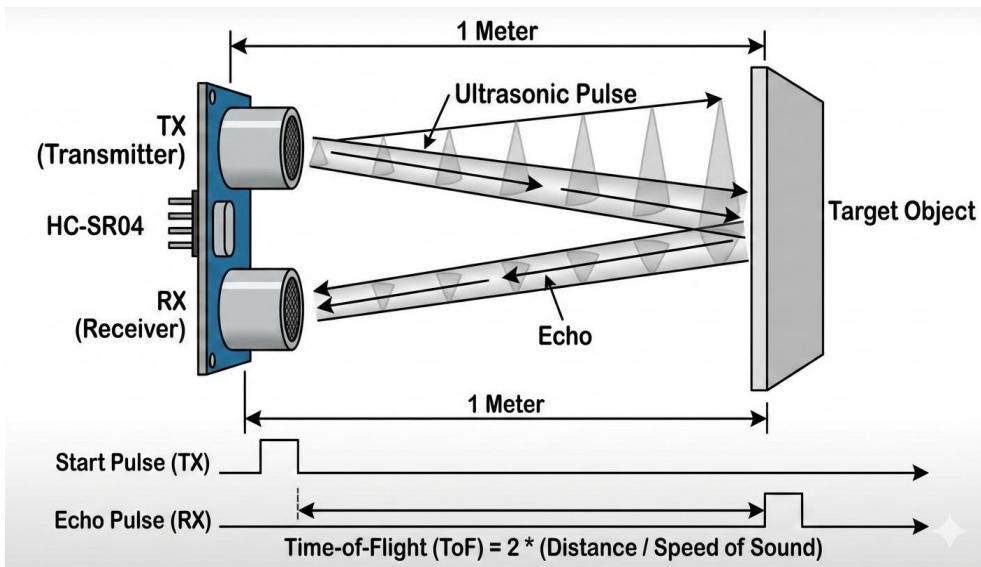


Fig.3 Representation of system

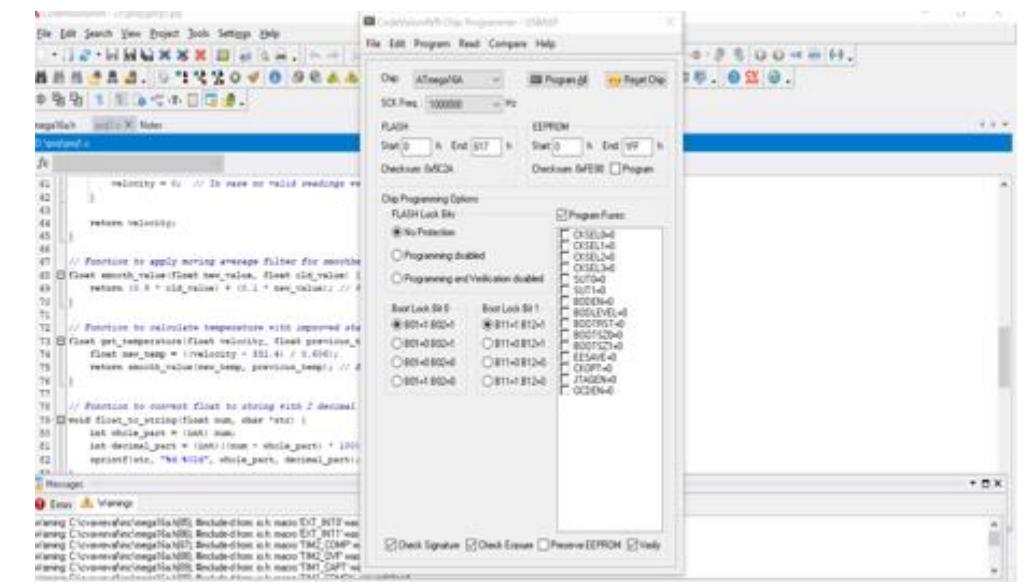


Fig.4 Software of ultrasonic system

Relationship between Velocity and Temperature

The ultrasonic pulse is emitted from the transducer and reflected back from a fixed reflector. The round-trip time of the pulse is measured digitally to determine the velocity of sound in air is given by [1,5,11]:

$$c = \frac{2d}{t} \quad (2)$$

In this equation, **c** represents the velocity of sound in air in m/s, **d** is the distance between the sensor and the reflector in m, and **t** is the measured round-trip time of flight in sec.

The velocity of sound in air depends on the ambient temperature, which is described by the equation is given by [4]:

$$c = 331.4 + 0.606 T \quad (3)$$

Here, **T** is the ambient air temperature in °C.

Rearranging this equation gives the final expression for temperature:

$$T = \frac{c - 331.4}{0.606} = \frac{\frac{2d}{t} - 331.4}{0.606} \quad (\text{Substituting 2 in 3})$$

This final equation directly relates the measured time of flight to the ambient temperature, forming the core principle of the device.

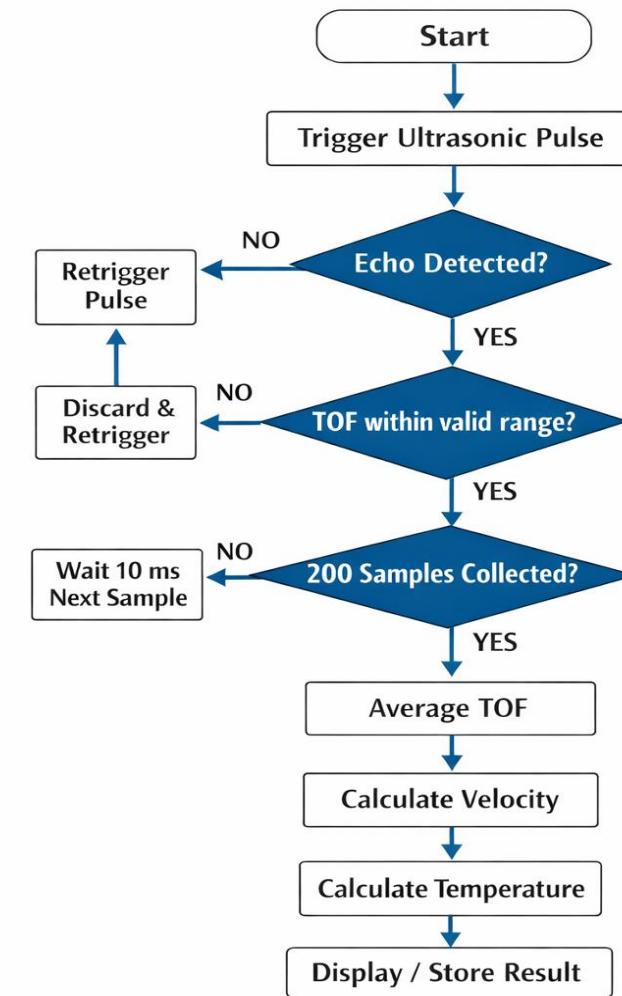


Fig.5 Flowchart

Features, Advantages and Factors Affecting Ultrasonic Velocity

- **Features:** There are many features of ultrasonic temperature

measurement. Some of them are:

- Real-Time Calculation.
- Automated Ultrasonic Triggering

- Multi-Sample Averaging

- **Advantages:**

- High Accuracy

- Easy Integration

- Low Cost

- **Factors which affect the ultrasonic velocity:**

- Pressure & Humidity

- Scattering & Diffraction

- Frequency

- Attenuation



Fig.6 Factors Affecting Ultrasonic Velocity

Results

➤ Change in Temperature w.r.t. Velocity

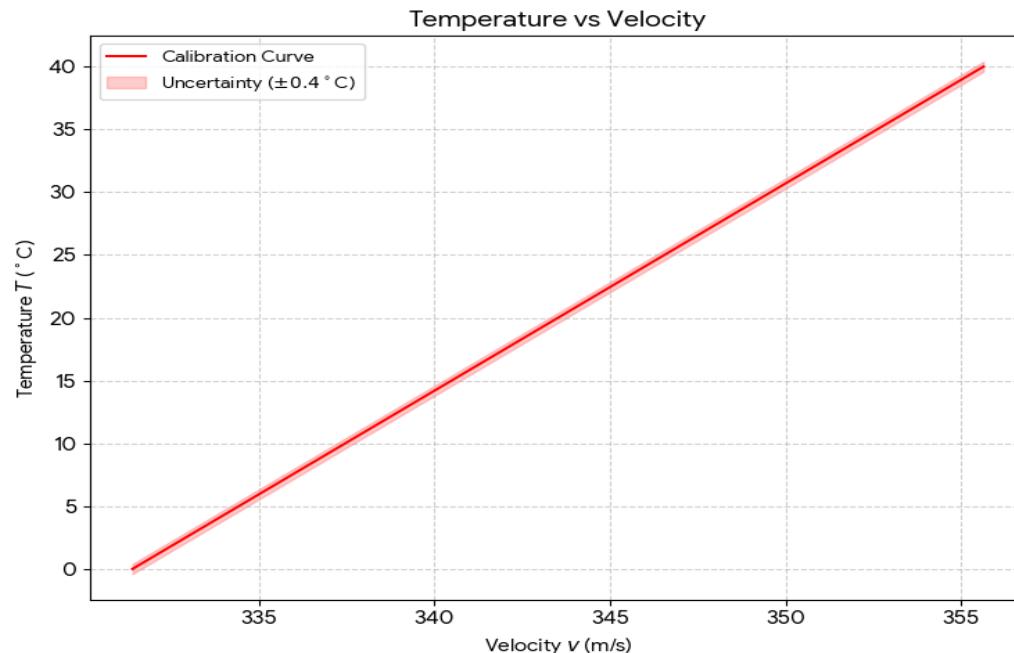


Fig.7 Graph of measured velocity vs calculated temperature

➤ Total Counts w.r.t. Temperature

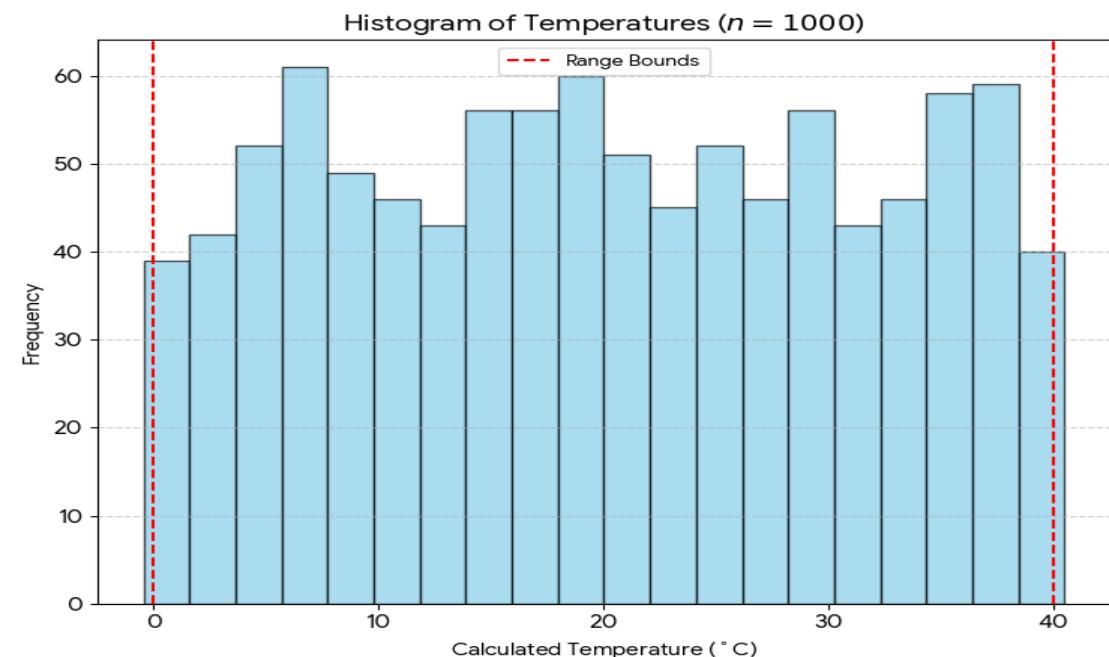


Fig.8 Statistical Frequency vs calculated temperature

Temperature (T) [$^{\circ}$ C]	Velocity (v) [m/s]	Statistical Frequency (Counts)	Uncertainty in T [$^{\circ}$ C]
15	340.49	56	± 0.4
20	343.52	60	± 0.4
25	346.55	52	± 0.4
30	349.58	56	± 0.4
35	352.61	58	± 0.4

Conclusion

- **High-Precision Temperature Estimation:** The system successfully measured ambient temperature by calculating ultrasonic propagation velocity with a ± 0.4 °C uncertainty.
- **Effective Signal Processing:** Implementing 200-sample averaging and timing synchronization minimized errors due to environmental noise and sensor fluctuations.
- **Robust Embedded Implementation:** The ATmega16A-based prototype with HC-SR04 and acoustic reflector provided a stable, repeatable setup for real-time measurements.
- **Practical Applicability:** The method demonstrates a non-contact, low-cost, and reliable technique for ambient temperature estimation, suitable for laboratory and industrial settings.
- **Foundation for Future Innovations:** The project establishes a framework for advanced ultrasonic sensing applications, including assistive technology, environmental monitoring, and precision instrumentation.
- **Real-World Impact:** This approach can enhance temperature monitoring in sensitive environments (labs, industrial setups, or clinical settings), reducing manual errors and improving safety and efficiency.

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*Thank
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