

NEURAL NETWORK LEARNING RULES CHAPTER 2



ARTIFICIAL NEURAL NETWORK LEARNING



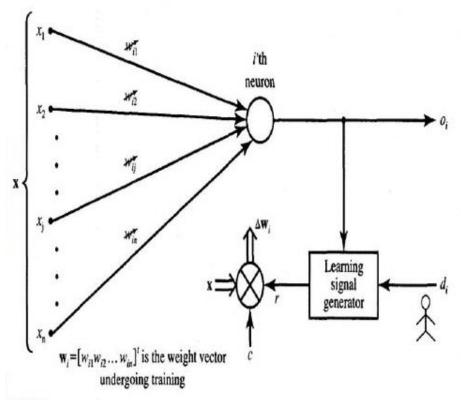


Neural Network Learning Rules

We know that, during ANN learning, to change the input/output behavior, we need to adjust the weights. Hence, a method is required with the help of which the weights can be modified. These methods are called Learning rules, which are simply algorithms or equations.



Neural Network Learning Rules



 The learning signal r in general a function of wi, x and sometimes of teacher's signal di.

$$r = r(\mathbf{w}_i, \mathbf{x}, d_i)$$

 Incremental weight vector wi at step t becomes:

$$\Delta \mathbf{w}_i(t) = cr \left[\mathbf{w}_i(t), \mathbf{x}(t), d_i(t) \right] \mathbf{x}(t)$$

Where c is a learning constant having +ve value.



Neural Network Learning Rules

- Perceptron Learning Rule -- Supervised Learning
- Hebbian Learning Rule Unsupervised Learning
- Delta Learning Rule -- Supervised Learning
- Widrow-Hoffs Learning Rule -- Supervised Learning
- > Correlation Learning Rule -- Supervised Learning
- Winner-Take-all Learning Rule -- Unsupervised Learning
- Outstar Learning Rule -- Supervised Learning

Hebbian Learning Rule For Ote Hebbian learning rule Ote learning signal is equal simply to the neuron's Output. T= + (wix) - 0

The encrement vector Dwi becomes

| Dwi= C. + (wit.x).x -

Single meight wij in adapted using,

Dwij= C+(wit-202; j=1,2,-...)

=> This learning rule requires weight initialization at small random values around w; = Oprior to learning.

Purely feed forward, unsupervised learning.

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One we net or ne



Hebbian learning with binary and contin Technology activation fenchions.

$$\alpha = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\chi = \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \\ \chi_4 \end{bmatrix} \qquad \omega = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0.5 \end{bmatrix}$$

Needs to be trained using the set of three enput nectors as belows-

$$\mathcal{X}_{1} = \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{5} \\ 0 \end{bmatrix} \qquad \mathcal{H}_{2} = \begin{bmatrix} -\frac{1}{5} \\ -\frac{2}{5} \\ -\frac{1}{5} \end{bmatrix} \qquad \mathcal{X}_{3} = \begin{bmatrix} 0 \\ -\frac{1}{5} \\ -\frac{1}{5} \end{bmatrix}$$

for an arbibary constants c=1.

Sol's Since, the enitial weights are nonzero value, the network has capparently been beared beginded. Assume first that bipolar binory neurous are used, and stus

Step 1: Input of applied to the network results in activation net as below: -

$$\text{Net}' = \omega^{1} \times_{1} = [1 - 1 \ 0 \ 0.5] \begin{bmatrix} 1 \\ -2 \\ 1.5 \\ 0 \end{bmatrix}$$

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The updated unights are,

$$w^2 = w^1 + (.sgn(net^1)x_1)$$

$$= \begin{bmatrix} -1 \\ 0.5 \end{bmatrix} + 1.12 \begin{bmatrix} -1 \\ 1.5 \end{bmatrix} = \begin{bmatrix} -3 \\ 1.5 \\ 0.5 \end{bmatrix}$$
Sgn(net^1)=1
became
net^1 > 0

Step 2: This learning step is with x_2 as expect, $\operatorname{net}^2 = \omega^{2t} x_2 = [2 -3 \cdot 1.5 \cdot 0.5] \begin{bmatrix} -0.5 \\ -2.5 \end{bmatrix}$

$$= 2 + 1.5 - 3.0 - 0.75 = -1.0 + 0.75$$

= -0.25

The updated weights are,

$$\omega^{3} = \omega^{2} + \text{Sgn}(\text{net}^{2}) \times_{2}$$

$$= \omega^{2} + (-1) \times_{2}$$

$$= \begin{bmatrix} 2 \\ -3 \\ 0.5 \end{bmatrix} - \begin{bmatrix} -0.5 \\ -2 \\ -1.5 \end{bmatrix} = \begin{bmatrix} -2.5 \\ 2.5 \\ 2 \end{bmatrix}$$
net² < 0

Step 3: The learning step is with x_3 as enput, net $^3 = \omega^{3t} x_3 = \begin{bmatrix} 1 & -2.5 & 3.5 & 2 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \\ 1.5 \end{bmatrix}$ = 0 - 2.5 - 3.5 + 3.0 = -3.0

The updated weights care,

$$w^{4} = w_{3} + \text{Sgn}(\text{net}^{3}) \times_{3}$$

$$= \begin{bmatrix} -2.5 \\ 3.5 \\ 2 \end{bmatrix} + (-1) \begin{bmatrix} 0 \\ -1 \\ 1.5 \end{bmatrix} = \begin{bmatrix} 1 \\ -3.5 \\ 4.5 \\ 0.5 \end{bmatrix}$$

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Kevi ei hing, the same problem with Continuous bipolar actuation fenction + (net), using exput XI and enitial weight wi, we obtain neuron? Output values and updated neeights for 2=1. the finet) is computed as,



Step 2:

$$\text{net}^2 = \omega^{2t} \chi_2 = \begin{bmatrix} 1.905 & -2.81 & 1.36 & 0.9 \end{bmatrix} \begin{bmatrix} 1 & \text{of Engineering hology} \\ -1.5 & \text{of Engineering hology} \end{bmatrix}$$

$$f(net^{2}) = \frac{9}{1 + e^{-\lambda(-0.16)}}$$

$$= \frac{9}{1 + 1.17}$$

$$w^{3} = \omega_{2} + f(net^{2}) \chi_{2}$$

$$= \begin{bmatrix} 1.905 \\ -2.81 \\ 1.36 \\ 0.5 \end{bmatrix} + \begin{bmatrix} -0.077 \\ -0.5 \\ -1.5 \end{bmatrix}$$

$$= \begin{bmatrix} 1.905 \\ -2.81 \\ 1.36 \\ 0.5 \end{bmatrix} + \begin{bmatrix} -0.077 \\ 0.038 \\ 0.154 \\ 0.154 \\ 0.116 \end{bmatrix}$$

$$w_{3} = \begin{bmatrix} 1.928 \\ -0.944 \\ 1.974 \\ 1.974 \end{bmatrix} + \begin{bmatrix} 1.828 \\ -2.772 \\ 1.512 \\ 1.512 \end{bmatrix}$$



(

$$\frac{\text{CY}}{\text{SITY}} = \frac{3^{\circ}}{8} \cdot 4^{\circ} (\text{nef}^{3}) = \omega_{0}^{3t} \times 3^{\circ}$$

$$= [1.828 - 2.722 \cdot 1.512 \cdot 0.616) \begin{bmatrix} 0 \\ -1 \\ 1.5 \end{bmatrix}$$
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$$= 0 - 2.772 - 1.512 + 0.924$$

$$= -3.36$$

$$f(net^3) = 2 - 1$$

$$= 1 + e^{-71 \text{ net}_3}$$

$$= \frac{2}{1 + e^{-(1)(-3.36)}} - 1$$

$$= \frac{2}{1 + 28.78} - 1 = -0.932$$

$$\begin{array}{lll}
\omega_{3} + 2 \omega_{3} + 2 \omega_{5} & f(net^{3}) \times_{3} \\
&= \begin{bmatrix} 1.905 \\ -2.81 \\ 1.36 \\ 0.5 \end{bmatrix} + (-0.932) \begin{bmatrix} 0 \\ -1 \\ 1.5 \end{bmatrix}$$