
Black Box Variational Inference

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Abstract

Variational inference has become a widely used method to approximate posteriors in complex latent variables models. However, deriving a variational inference algorithm generally requires significant model-specific analysis. These efforts can hinder and deter us from quickly developing and exploring a variety of models for a problem at hand. In this paper, we present a “black box” variational inference algorithm, one that can be quickly applied to many models with little additional derivation. Our method is based on a stochastic optimization of the variational objective where the noisy gradient is computed from Monte Carlo samples from the variational distribution. We develop a number of methods to reduce the variance of the gradient, always maintaining the criterion that we want to avoid difficult model-based derivations. We evaluate our method against the corresponding black box sampling based methods. We find that our method reaches better predictive likelihoods much faster than sampling methods. Finally, we demonstrate that Black Box Variational Inference lets us easily explore a wide space of models by quickly constructing and evaluating several models of longitudinal healthcare data.

1 Introduction

Probabilistic models with latent variables have become a mainstay in modern machine learning applications. With latent variables models, we posit a rich latent structure that governs our observations, infer that structure from large data sets, and use our inferences to sum-

marize observations, draw conclusions about current data, and make predictions about new data. Central to working with latent variable models is the problem of computing the posterior distribution of the latent structure. For many interesting models, computing the posterior exactly is intractable: practitioners must resort to approximate methods.

One of the most widely used methods for approximate posterior estimation is variational inference (Wainwright and Jordan, 2008; Jordan et al., 1999). Variational inference tries to find the member of a family of simple probability distributions that is closest (in KL divergence) to the true posterior distribution.

For a specific class of models, those where the conditional distributions have a convenient form (and where a convenient variational family exists), this optimization can be carried out with a closed-form coordinate ascent algorithm (Ghahramani and Beal, 2001). For generic models and arbitrary variational families, however, there is no closed-form solution: computing the required expectations becomes intractable. In these settings, practitioners have resorted to model-specific algorithms (Jaakkola and Jordan, 1996; Blei and Lafferty, 2007; Braun and McAuliffe, 2007) or generic algorithms that require model specific computations (Knowles and Minka, 2011; Wang and Blei, 2013; Paisley et al., 2012).

Deriving these algorithms on a model-by-model basis is tedious work. This hinders us from rapidly exploring modeling assumptions when solving applied problems, and it makes variational methods on complicated distributions impractical for many practitioners. Our goal in this paper is to develop a “black box” variational inference algorithm, a method that can be quickly applied to almost any model and with little effort. Our method allows practitioners to quickly design, apply, and revise models of their data, without painstaking derivations each time they want to adjust the model.

Variational inference methods frame a posterior estimation problem as an optimization problem, where the parameters to be optimized adjust a variational “proxy” distribution to be similar to the true posterior. Our method rewrites the gradient of that objective as the

expectation of an easy-to-implement function f of the latent and observed variables, where the expectation is taken with respect to the variational distribution; and we optimize that objective by sampling from the variational distribution, evaluating the function f , and forming the corresponding Monte Carlo estimate of the gradient. We then use these noisy gradients in a stochastic optimization algorithm to optimize the variational parameters.

From the practitioner’s perspective, this method requires only that he or she write functions to evaluate the model log-likelihood. The remaining calculations (properties of the variational distribution and evaluating the Monte Carlo estimate) are easily put into a library to share across models, which means our method can be quickly applied to new modeling settings.

We will show that reducing the variance of the gradient estimator is essential to the fast convergence of our algorithm. We develop several strategies for controlling the variance. The first is based on Rao-Blackwellization (Casella and Robert, 1996), which exploits the factorization of the variational distribution. The second is based on control variates (Ross, 2002; Paisley et al., 2012), using the gradient of the log probability of the variational distribution. We emphasize that these variance reduction methods preserve our goal of black box inference because they do not require computations specific to the model.

Finally, we show how to use recent innovations in variational inference and stochastic optimization to scale up and speed up our algorithm. First, we use adaptive learning rates (Duchi et al., 2011) to set the step size in the stochastic optimization. Second, we develop generic stochastic variational inference (Hoffman et al., 2013), where we additionally subsample from the data to more cheaply compute noisy gradients. This innovates on the algorithm of Hoffman et al. (2013), which requires closed form coordinate updates to compute noisy natural gradients.

We demonstrate our method in two ways. First, we compare our method against Metropolis-Hastings-in-Gibbs (Bishop, 2006), a sampling based technique that requires similar effort on the part of the practitioner. We find our method reaches better predictive likelihoods much faster than sampling methods. Second, we use our method to quickly build and evaluate several models of longitudinal patient data. This demonstrates the ease with which we can now consider models generally outside the realm of variational methods.

Related work. There have been several lines of work that use sampling methods to approximate gradients in variational inference. Wingate and Weber (2013)

have independently considered a similar procedure to ours, where the gradient is construed as an expectation and the KL is optimized with stochastic optimization. They too include a term to reduce the variance, but do not describe how to set it. We further innovate on their approach with Rao-Blackwellization, specified control variates, adaptive learning rates, and data subsampling. Salimans and Knowles (2012) provide a framework based on stochastic linear regression. Unlike our approach, their method does not generalize to arbitrary approximating families and requires the inversion of a large matrix that becomes impractical in high dimensional settings. Kingma and Welling (2013) provide an alternative method for variational inference through a reparameterization of the variational distributions. In contrast to our approach, their algorithm is limited to only continuous latent variables. Carbonetto et al. (2009) present a stochastic optimization scheme for moment estimation based on the specific form of the variational objective when both the model and the approximating family are in the same exponential family. This differs from our more general modeling setting where latent variables may be outside of the exponential family. Finally, Paisley et al. (2012) use Monte Carlo gradients for difficult terms in the variational objective and also use control variates to reduce variance. However, theirs is not a black-box method. Both the objective function and control variates they propose require model-specific derivations.

2 Black Box Variational Inference

Variational inference transforms the problem of approximating a conditional distribution into an optimization problem (Jordan et al., 1999; Bishop, 2006; Wainwright and Jordan, 2008). The idea is to posit a simple family of distributions over the latent variables and find the member of the family that is closest in KL divergence to the conditional distribution.

In a probabilistic model, let x be observations, z be latent variables, and λ the free parameters of a variational distribution $q(z | \lambda)$. Our goal is to approximate $p(z | x)$ with the free parameter λ . In variational inference we optimize the Evidence Lower BOund (ELBO),

$$\mathcal{L}(\lambda) \triangleq \mathbb{E}_{q_{\lambda}(z)}[\log p(x, z) - \log q(z)]. \quad (1)$$

Maximizing the ELBO is equivalent to minimizing the KL divergence (Jordan et al., 1999; Bishop, 2006). Intuitively, the first term rewards variational distributions that place high mass on configurations of the latent variables that also explain the observations; the second term rewards variational distributions that are entropic, i.e., that maximize uncertainty by spreading their mass on many configurations.

Practitioners derive variational algorithms to maximize the ELBO over the variational parameters by expanding the expectation in Eq. 1 and then computing gradients to use in an optimization procedure. Closed form coordinate-ascent updates are available for conditionally conjugate exponential family models (Ghahramani and Beal, 2001), where the distribution of each latent variable given its Markov blanket falls in the same family as the prior, for a small set of variational families. However, these updates require analytic computation of various expectations for each new model, a problem which is exacerbated when the variational family falls outside this small set. This leads to tedious bookkeeping and overhead for developing new models.

The expectation in Eq. 1 is with respect to a known distribution whose parameter – λ – is known. We will therefore use stochastic optimization to maximize the ELBO. In stochastic optimization, we maximize a function using noisy estimates of its gradient (Robbins and Monro, 1951; Kushner and Yin, 1997; Bottou and LeCun, 2004). We will form the derivative of the objective as an expectation with respect to the variational approximation and then sample from the variational approximation to get noisy but unbiased gradients, which we use to update our parameters. For each sample, our noisy gradient requires evaluating the possibly unnormalized joint distribution of the observed and sampled variables, the variational distribution, and the gradient of the log of the variational distribution. This is a black box method in that the gradient of the log of the variational distribution and sampling method can be derived once for each type of variational distribution and reused for many models and applications.

Stochastic optimization. Let us now review stochastic optimization. Let $f(x)$ be a function to be maximized and $h_t(x)$ be the realization of a random variable $H(x)$ whose expectation is the gradient of $f(x)$. Finally, let ρ_t be a nonnegative scalar. Stochastic optimization updates x at the t th iteration with

$$x_{t+1} \leftarrow x_t + \rho_t h_t(x_t).$$

This converges to a maximum of $f(x)$ when ρ_t , the learning rate, follows the Robbins-Monro conditions,

$$\begin{aligned} \sum_{t=1}^{\infty} \rho_t &= \infty \\ \sum_{t=1}^{\infty} \rho_t^2 &< \infty. \end{aligned}$$

Because of its simplicity, stochastic optimization is widely used in statistics and machine learning.

A noisy gradient of the ELBO. To optimize the ELBO with stochastic optimization, we need to develop an unbiased estimator of its gradient which can

Algorithm 1 Black Box Variational Inference

Input: data x , joint distribution p , mean field variational family q .

Initialize λ randomly, $t = 1$.

repeat

// Draw S samples from q

for $s = 1$ **to** S **do**

$z[s] \sim q$

end for

$\rho = t$ th value of a Robbins Monro sequence

$\lambda = \lambda + \rho \frac{1}{S} \sum_{s=1}^S \nabla_{\lambda} \log q(z[s] | \lambda) (\log p(x, z[s]) - \log q(z[s] | \lambda))$

$t = t + 1$

until change of λ is less than 0.01.

be computed from samples from the variational posterior. To do this, we write the gradient of the ELBO (Eq. 1) as an expectation with respect to the variational distribution,

$$\nabla_{\lambda} \mathcal{L} = \mathbb{E}_q[\nabla_{\lambda} \log q(z|\lambda) (\log p(x, z) - \log q(z|\lambda))]. \quad (2)$$

The derivation of Eq. 2 can be found in the appendix. Note that in statistics the gradient $\nabla_{\lambda} \log q(z|\lambda)$ of the log of a probability distribution is called the score function (Cox and Hinkley, 1979). The joint $p(x, z)$ can be replaced by its unnormalized version (see the appendix for details). For subsequent sections, any appearance of $p(x, z)$ may be replaced by an unnormalized version.

With this equation in hand, we compute noisy unbiased gradients of the ELBO with Monte Carlo samples from the variational distribution,

$$\nabla_{\lambda} \mathcal{L} \approx \frac{1}{S} \sum_{s=1}^S \nabla_{\lambda} \log q(z_s|\lambda) (\log p(x, z_s) - \log q(z_s|\lambda)), \quad \text{where } z_s \sim q(z|\lambda). \quad (3)$$

With Eq. 3, we can use stochastic optimization to optimize the ELBO.

The basic algorithm is summarized in Algorithm 1. We note that the score function and sampling algorithms depend only on the variational distribution, not the underlying model. Thus we can build up a collection of these functions for various variational approximations and reuse them in a package for a broad class of models. Further we did not make any assumptions about the form of the model, only that the practitioner can compute the log of the joint $p(x, z_s)$. This algorithm significantly reduces the effort needed to implement variational inference in a wide variety of models.

3 Controlling the Variance

We can use Algorithm 1 to maximize the ELBO, but the variance of the estimator of the gradient (under the Monte Carlo estimate in Eq. 3) can be too large to be useful. In practice, the high variance gradients would require very small steps which would lead to slow convergence. We now show how to reduce this variance in two ways, via Rao-Blackwellization and easy-to-implement control variates. We exploit the structure of our problem to use these methods in a way that requires no model-specific derivations, which preserves our goal of black-box variational inference.

3.1 Rao-Blackwellization

Rao-Blackwellization (Casella and Robert, 1996) reduces the variance of a random variable by replacing it with its conditional expectation with respect to a subset of the variables. Note that the conditional expectation of a random variable is a random variable with respect to the conditioning set. This generally requires analytically computing problem-specific integrals. Here we show how to Rao-Blackwellize the estimator for each component of the gradient without needing to compute model-specific integrals.

In the simplest setting, Rao-Blackwellization replaces a function of two variables with its conditional expectation. Consider two random variables, X and Y , and a function $J(X, Y)$. Our goal is to compute its expectation $E[J(X, Y)]$ with respect to the joint distribution of X and Y .

Define $\hat{J}(X) = E[J(X, Y)|X]$, and note that $E[\hat{J}(X)] = E[J(X, Y)]$. This means that $\hat{J}(X)$ can be used in place of $J(X, Y)$ in a Monte Carlo approximation of $E[J(X, Y)]$. The variance of $\hat{J}(X)$ is

$$\text{Var}(\hat{J}(X)) = \text{Var}(J(X, Y)) - E[(J(X, Y) - \hat{J}(X))^2].$$

Thus, $\hat{J}(X)$ has lower variance than $J(X, Y)$.

We return to the problem of estimating the gradient of \mathcal{L} . Suppose there are n latent variables $z_{1:n}$ and we are using the mean-field variational family, where each random variable z_i is independent and governed by its own variational distribution,

$$q(z | \lambda) = \prod_{i=1}^n q(z_i | \lambda_i), \quad (4)$$

where $\lambda_{1:n}$ are the n variational parameters characterizing the member of the variational family we seek. Consider the i th component of the gradient. Let $q_{(i)}$ be the distribution of variables in the model that depend on the i th variable, i.e., the Markov blanket of z_i and z_i ; and let $p_i(x, z_{(i)})$ be the terms in the joint that depend on those variables. We can write the gradient with

respect to λ_i as an iterated conditional expectation which simplifies to

$$\begin{aligned} \nabla_{\lambda_i} \mathcal{L} = \\ E_{q_{(i)}}[\nabla_{\lambda_i} \log q(z_i | \lambda_i)(\log p_i(x, z_{(i)}) - \log q(z_i | \lambda_i))]. \end{aligned} \quad (5)$$

The derivation of Eq. 5 can be found in the supplement. This equation says that we can Rao-Blackwellize each component of the gradient with respect to variables outside of the its Markov blanket without needing to compute model-specific conditional expectations.

We construct a Monte Carlo estimator for the gradient of λ_i using samples from the variational distribution,

$$\begin{aligned} \frac{1}{S} \sum_{s=1}^S \nabla_{\lambda_i} \log q_i(z_s | \lambda_i)(\log p_i(x, z_s) - \log q_i(z_s | \lambda_i)), \\ \text{where } z_s \sim q_{(i)}(z | \lambda). \end{aligned} \quad (6)$$

These noisy gradients can be used to maximize the ELBO. In our empirical study, Figure 2, we plot the variance of this estimator along with that of Eq. 3.

3.2 Control Variates

As we saw above, variance reduction methods work by replacing the function whose expectation is being approximated by Monte Carlo with another function that has the same expectation but smaller variance. That is, to estimate $E_q[f]$ via Monte Carlo we compute the empirical average of \hat{f} where \hat{f} is chosen so $E_q[f] = E_q[\hat{f}]$ and $\text{Var}_q[f] > \text{Var}_q[\hat{f}]$.

A control variate (Ross, 2002) is a family of functions with equivalent expectation. Recently, control variates have been of interest for variational inference (Paisley et al., 2012) and for general optimization problems that occur in machine learning (Wang et al., 2013).

Consider a function h , which has a finite first moment, and a scalar a . Define \hat{f} to be

$$\hat{f}(z) \triangleq f(z) - a(h(z) - E[h(z)]). \quad (7)$$

This is a family of functions, indexed by a , and note that $E_q[\hat{f}] = E_q[f]$ as required. Given a particular function h , we can choose a to minimize the variance of \hat{f} .

First we note that variance of \hat{f} can be written as

$$\text{Var}(\hat{f}) = \text{Var}(f) + a^2 \text{Var}(h) - 2a \text{Cov}(f, h).$$

This equation implies that good control variates have high covariance with the function whose expectation is being computed.

Taking the derivative of $\text{Var}(\hat{f})$ with respect to a and setting it equal to zero gives us the value of a that minimizes the variance,

$$a^* = \text{Cov}(f, h) / \text{Var}(h). \quad (8)$$

We now apply this method to Black Box Variational Inference. To maintain the generic nature of the algorithm, we want to choose a control variate that only depends on the variational distribution and for which we can easily compute its expectation. Meeting these criteria, we choose h to be the score function of the variational approximation, $\nabla_{\lambda} \log q(z)$, which always has expectation zero. (See the appendix.)

We apply our control variates to estimate each entry of the Rao-Blackwellized gradient. More formally, in our above notation, the control variates for the d th entry of the gradient are

$$\begin{aligned} f_d(z) &= \nabla_{\lambda_d} \log q(z | \lambda_i) (\log p_i(x, z) - \log q_i(x, z)), \\ h_d(z) &= \nabla_{\lambda_d} \log q(z | \lambda_i), \end{aligned}$$

when the d th entry belongs to the i th factor.

The optimal scalings for the control variates are given by Eq. 8. We estimate the necessary variance and covariances on a small number of samples. Given the estimated scalings \hat{a}_d the control variate Monte Carlo estimate of the gradient using S samples is

$$\begin{aligned} \hat{\nabla}_{\lambda_d} \mathcal{L} &\triangleq \frac{1}{S} \sum_{s=1}^S \nabla_{\lambda_d} \log q_i(z_s | \lambda_i) \\ &\quad (\log p_i(x, z_s) - \log q_i(z_s) - \hat{a}_d). \end{aligned} \quad (9)$$

This estimator uses both Rao-Blackwellization and control variates. We show in the empirical study that this generic control variate further reduces the variance of the estimator.

3.3 Black Box Variational Inference (II)

Putting together the noisy gradient, Rao-Blackwellization, and control variates, we present Black Box Variational Inference (II). It takes samples from the variational approximation to compute noisy gradients with Eq. 9. These noisy gradients are then used in a stochastic optimization procedure to maximize the ELBO.

We summarize the procedure in Algorithm 2. Algorithm 2 is easily used on many models. It only requires samples from the variational distribution, computations about the variational distribution, and easy computations about the model.

Algorithm 2 Black Box Variational Inference (II)

Input: data x , joint distribution p , mean field variational family q .

Initialize $\lambda_{1:n}$ randomly, $t = 1$.

repeat

 // Draw S samples from the variational approximation

for $s = 1$ **to** S **do**

$z[s] \sim q$

end for

for $d = 1$ **to** D **do**

for $s = 1$ **to** S **do**

$f_d[s] = \nabla_{\lambda_d} \log q_i(z[s] | \lambda_i) (\log p_i(x, z[s]) - \log q_i(z[s] | \lambda_i))$

$h_d[s] = \nabla_{\lambda_d} \log q_i(z[s] | \lambda_i)$

end for

$\hat{a}_d^* = \frac{\text{Cov}(f_d, h_d)}{\text{Var}(h_d)}$, Estimate from a few samples

$\hat{\nabla}_{\lambda_d} \mathcal{L} \triangleq \frac{1}{S} \sum_{s=1}^S f_d[s] - \hat{a}_d h_d[s]$

end for

$\rho = t$ th value of a Robbins Monro sequence

$\lambda = \lambda + \rho \hat{\nabla}_{\lambda} \mathcal{L}$

$t = t + 1$

until change of λ is less than 0.01.

4 Extensions

We extend the main algorithm in two ways. First, we address the difficulty of setting the step size schedule. Second, we address scalability by subsampling observations.

4.1 AdaGrad

One challenge with stochastic optimization techniques is setting the learning rate. Intuitively, we would like the learning rate to be small when the variance of the gradient is large and vice-versa. Additionally, in problems like ours that have different scales¹, the learning rate needs to be set small enough to handle the smallest scale. To address this issue, we use the AdaGrad algorithm (Duchi et al., 2011). Let G_t be a matrix containing the sum across the first t iterations of the outer products of the gradient. AdaGrad defines the learning rate as

$$\rho_t = \eta \text{diag}(G_t)^{-1/2}. \quad (10)$$

This is a per-component learning rate since $\text{diag}(G_t)$ has the same dimension as the gradient. Note that since AdaGrad only uses the diagonal of G_t , those are the only elements we need to compute. AdaGrad captures noise and varying length scales through the square of the noisy gradient and reduces the number

¹Probability distributions have many parameterizations.

of parameters to our algorithm from the standard two parameter Robbins-Monro learning rate.

4.2 Stochastic Inference in Hierarchical Bayesian Models

Stochastic optimization has also been used to scale variational inference in hierarchical Bayesian models to massive data (Hoffman et al., 2013). The basic idea is to subsample observations to compute noisy gradients. We can use a similar idea to scale our method.

In a hierarchical Bayesian model, we have a hyperparameter η , global latent variables β , local latent variables $z_{1...n}$, and observations $x_{1...n}$ having the log joint distribution

$$\log p(x_{1...n}, z_{1...n}, \beta) = \log p(\beta|\eta) + \sum_{i=1}^n \log p(z_i|\beta) + \log p(x_i|z_i, \beta). \quad (11)$$

This is the same definition as in Hoffman et al. (2013), but they place further restrictions on the forms of the distributions and the complete conditionals. Under the mean field approximating family, applying Eq. 9 to construct noisy gradients of the ELBO would require iterating over every datapoint. Instead we can compute noisy gradients using a sampled observation and samples from the variational distribution. The derivation along with variance reductions can be found in the supplement.

5 Empirical Study

We use Black Box Variational Inference to quickly construct and evaluate several models on longitudinal medical data. We demonstrate the effectiveness of our variance reduction methods and compare the speed and predictive likelihood of our algorithm to sampling based methods. We evaluate the various models using predictive likelihood to demonstrate the ease at which several models can be explored.

5.1 Longitudinal Medical Data

Our data consist of longitudinal data from 976 patients (803 train + 173 test) from a clinic at CUMC who have been diagnosed with chronic kidney disease. The data are obtained from CUMC under IRB protocol. These patients visited the clinic a total of 33K times. During each visit, a subset, determined by the doctor, of 17 measurements (labs) were collected.

The data are observational and consist of measurements (lab values) taken at the doctor’s discretion when the patient is at a checkup. This means both that the

labs at each time step are sparse and that the time between patient visits are highly irregular. The labs values are all positive, as the labs measure the amount of a particular quantity such as sodium concentration in the blood.

Our modeling goal is to come up with a low dimensional summarization of patients’ labs at each of their visits. From this, we aim to find latent factors that summarize each visit as positive random variables. As in medical data applications, we want our factors to be latent indicators of patient health.

We evaluate our model using predictive likelihood. To compute predictive likelihoods, we need an approximate posterior on both the global parameters and the per visit parameters. We use the approximate posterior on the global parameters and calculate the approximate posterior on the local parameters on 75% of the data in the test set. We then calculate the predictive likelihood on the other 25% of the data in the validation set using Monte Carlo samples from the approximate posterior.

We initialize randomly and choose the variational families to be fully-factorized with gamma distributions for positive variables and normals for real valued variables. We use both the AdaGrad and doubly stochastic extensions on top of our base algorithm. We use 1,000 samples to estimate the gradient and 100 samples to estimate the control variate scaling. We set the batch size at 25 for all our experiments.

5.2 Model

To meet our goals, we construct a Gamma-Normal time series (Gamma-Normal-TS) model. We model our data using weights drawn from a Normal distribution and observations drawn from a Normal, allowing each factor to both positively and negative affect each lab while letting factors represent lab measurements. The generative process for this model with hyperparameters denoted with σ is

Draw $W \sim \text{Normal}(0, \sigma_w)$, an $L \times K$ matrix

For each patient p : 1 to P

Draw $o_p \sim \text{Normal}(0, \sigma_o)$, a vector of L

Draw $x_{p1} = \text{GammaE}(\sigma_x, \sigma_x)$

Draw $l_{p1} \sim \text{Normal}(Wx_{p1} + o_p, \sigma_l)$, a vector of L .

For each visit v : 2 to v_p

Draw $x_{pv} \sim \text{GammaE}(x_{pv-1}, \sigma_x)$

Draw $l_{pv} \sim \text{Normal}(Wx_{pv} + o_p, \sigma_l)$, a vector of L .

We set σ_w , σ_o , σ_x to be 1 and σ_l to be .01. In our model, GammaE is the expectation/variance parameterization of the (L-dimensional) gamma distribution. (The mapping between this parameterization and the more standard one can be found in the supplement.)

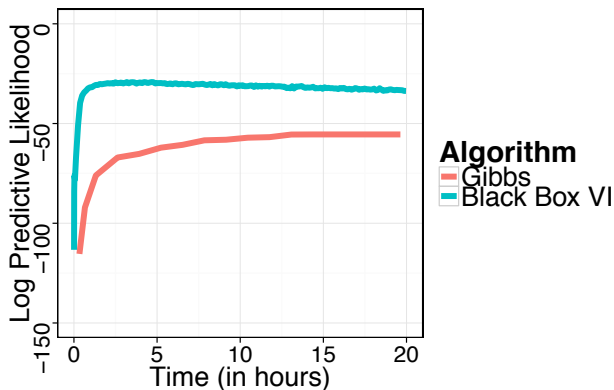


Figure 1: Comparison between Metropolis-Hastings within Gibbs and Black Box Variational Inference on the Gamma-Normal-TS model. The x axis is time and the y axis is the log predictive likelihood of the held out set. Black Box Variational Inference reaches better predictive likelihoods faster than Gibbs sampling. Variational inference overfits slightly in the 20 hour period. The Gibbs sampler’s progress slows considerably after 5 hours.

Black Box Variational Inference allows us to make use of non-standard parameterizations for distributions that are easier to reason about. This is an important observation, as the standard set of families used in variational inference tend to be fairly limited. In this case, the expectation parameterization of the gamma distribution allows the previous visit factors to define the expectation of the current visit factors. Finally, we emphasize that coordinate ascent variational inference and Gibbs sampling are not available for this algorithm because the required conditional distributions do not have closed form.

5.3 Sampling Methods

We compare Black Box Variational Inference to a standard sampling based technique, Metropolis-Hastings (Bishop, 2006), that also only requires the joint distribution.²

Metropolis-Hastings works by sampling from a proposal distribution and accepting or rejecting the samples based on the likelihood. Standard Metropolis-Hastings can work poorly in high dimensional models. We find that it fails for the Gamma-Normal-TS model. Instead, we compare to a Gibbs sampling method that uses Metropolis-Hastings to sample from the complete con-

²Methods that involve a bit more work such as Hamiltonian Monte Carlo could work in this setting, but as our technique only requires the joint distribution and could benefit from added analysis used in more complex methods, we compare against a similar methods.

ditionals. For our proposal distribution we use the same distributions as found in the previous section, with the mean equal to the value of the previous parameter.

We compute predictive likelihoods using the posterior samples generated by the MCMC methods on held out data in the test set.

We compared our method to Metropolis-Hastings inside Gibbs on the Gamma-Normal-TS model. We used a fixed computational budget of 20 hours. Figure 1 plots predictive likelihood versus time on the held out set for both methods. We found similar results with different random initializations of both methods. Black Box Variational Inference gives better predictive likelihoods and gets them faster.³

5.4 Variance Reductions

We next studied how much variance is reduced by our variance reduction methods. In Figure 2, we plot the variance of various estimators of the gradient of the variational approximation for a factor in the patient time-series versus iteration number. We compare the variance of the Monte Carlo gradient (Eq. 3) to that of the Rao-Blackwellized gradient (Eq. 6) and that of the gradient using both Rao-Blackwellization and control variates (Eq. 9). We allow the estimators without control variates to leverage the samples used by the control variate estimator to estimate the scalings. We found that Rao-Blackwellization reduces the variance by several orders of magnitude. Applying control variates reduces the variance further. This reduction in variance drastically improves the speed at which Black Box Variational Inference converges. In fact, in the time allotted, Algorithm 1—the algorithm without variance reductions—failed to make much progress.

5.5 Exploring Models

We developed Black Box Variational Inference to make it easier to quickly explore and fit many new models to a data set. We demonstrate this by considering a sequence of three other models for our data: Gamma, Gamma-TS, and Gamma-Normal.

Gamma. We model the latent factors that summarize each visit in our models as positive random variables; as noted above, we expect these to be indicative of patient health. The Gamma model is a positive-value factor model where all of the factors, weights, and observations have positive values. The generative process for this model is

³Black Box Variational Inference also has better predictive mean-squared error on the labs than Gibbs style Metropolis-Hastings.

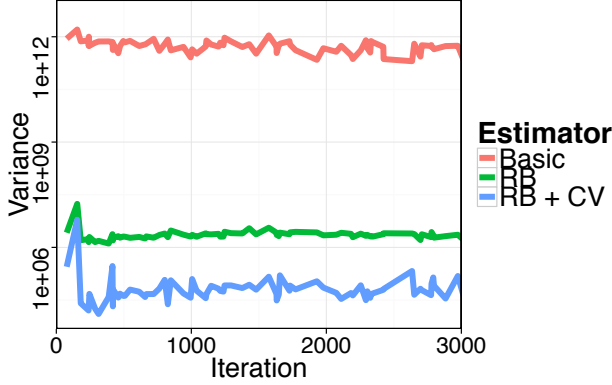


Figure 2: Variance comparison for the first component of a random patient on the following estimators: Eq. 3, the Rao-Blackwellized estimator Eq. 6, and the Rao-Blackwellized control variate estimator Eq. 9. We find that Rao-Blackwellizing the naive estimator reduces the variance by several orders of magnitude. Adding control variates reduces the variance even further.

Draw $W \sim \text{Gamma}(\alpha_w, \beta_w)$, an $L \times K$ matrix
 For each patient p : 1 to P
 Draw $o_p \sim \text{Gamma}(\alpha_o, \beta_o)$, a vector of L
 For each visit v : 1 to v_p
 Draw $x_{pv} \sim \text{Gamma}(\alpha_x, \beta_x)$
 Draw $l_{pv} \sim \text{GammaE}(Wx_{pv} + o_p, \sigma_o)$, a vector of L .

We set all hyperparameters save σ_o to be 1. As in the previous model, σ_o is set to 0.01.

Gamma-TS. We can link the factors through time using the expectation parameterization of the gamma distribution. (Note this is harder with the usual natural parameterization of the gamma.) This changes x_{pv} to be distributed as $\text{GammaE}(x_{pv-1}, \sigma_v)$. We draw x_{p1} as above. In this model, the expected values of the factors at the next visit is the same as the value at the current visit. This allows us to propagate patient states through time.

Gamma-Normal. Similar to the above, we can change the time-series Gamma-Normal-TS (studied in the previous section) to a simpler factor model. This is similar to the Gamma model, but a normal prior.

These combinations lead to a set of four models that are all nonconjugate and for which standard variational techniques are difficult to apply. Our variational inference method allows us to compute approximate posteriors for these models to determine which provides the best low dimensional latent representations.

We determined convergence using change in log predictive likelihood on a validation set. We set the AdaGrad step to 0.5 for the Gamma models and 1 for the others.

Model	Predictive Likelihood
Gamma-Normal	-31.2
Gamma-Normal-TS	-30.0
Gamma-Gamma	-146
Gamma-Gamma-TS	-132

Table 1: A comparison between several models for our patient health dataset. We find that taking into account the longitudinal nature of the data in the model leads to a better fit. The Gamma models perform relatively poorly. This is likely due to the fact that some labs are negatively correlated as the Gamma models cannot capture such relationships.

Model Comparisons. Table 1 details our models along with their predictive likelihoods. From this we see that time helps in modeling our longitudinal health-care data. We also see that the Gamma-Gamma models perform poorly. This is likely because they cannot capture the negative correlations that exist between different medical labs. More importantly, by using Black Box Variational Inference we were able to quickly fit and explore a set of complicated non-conjugate models. Without a generic algorithm, approximating the posterior of any of these models is a project in itself.

6 Conclusion

We developed and studied Black Box Variational Inference, a new algorithm for variational inference that drastically reduces the analytic burden. Our main approach is a stochastic optimization of the ELBO by sampling from the variational posterior to compute a noisy gradient. Essential to its success are model-free variance reductions to reduce the variance of the noisy gradient. Our method works wells on new models, while requiring minimal analytic work by the practitioner.

There are several natural directions for future improvements to this work. First, software libraries can be created with score functions for a wide variety of variational families (each score function is simply the log gradient of the variational distribution with respect to the variational parameters). Second, we believe that number of samples could be set dynamically. Finally, carefully-selected samples from the variational distribution (e.g., with quasi-Monte Carlo methods) are likely to significantly decrease sampling variance.

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