# Nonzero-sum adversarial hypothesis testing games

Sarath A Y, Patrick Loiseau (Grenoble)

25 Sep 2019

- Classification in the presence of an adversary:
  - ▶ Traditionally, nature is unaware of the classification algorithm.
  - ▶ An adversary generates data to mislead the classifier.
  - Classifier wants to detect the presence of the adversary and the adversary wants the classifier to make an error.

- Classification in the presence of an adversary:
  - ▶ Traditionally, nature is unaware of the classification algorithm.
  - ▶ An adversary generates data to mislead the classifier.
  - Classifier wants to detect the presence of the adversary and the adversary wants the classifier to make an error.
- Applications:
  - Network security
  - Multimedia forensics
  - Biometrics

- Classification in the presence of an adversary:
  - ▶ Traditionally, nature is unaware of the classification algorithm.
  - ▶ An adversary generates data to mislead the classifier.
  - Classifier wants to detect the presence of the adversary and the adversary wants the classifier to make an error.
- Applications:
  - Network security
  - Multimedia forensics
  - Biometrics
- Two rational agents: the adversary and the classifier.

- Classification in the presence of an adversary:
  - ▶ Traditionally, nature is unaware of the classification algorithm.
  - ▶ An adversary generates data to mislead the classifier.
  - Classifier wants to detect the presence of the adversary and the adversary wants the classifier to make an error.
- Applications:
  - Network security
  - Multimedia forensics
  - Biometrics
- ▶ Two rational agents: the adversary and the classifier.
- Propose and analyse a game-theoretic model in this context of adversarial classification.

- Classification in the presence of an adversary:
  - ► Traditionally, nature is unaware of the classification algorithm.
  - ▶ An adversary generates data to mislead the classifier.
  - Classifier wants to detect the presence of the adversary and the adversary wants the classifier to make an error.
- Applications:
  - Network security
  - Multimedia forensics
  - Biometrics
- Two rational agents: the adversary and the classifier.
- Propose and analyse a game-theoretic model in this context of adversarial classification.
- ► Adversarial hypothesis testing—adversary picks a distribution and data is generated from this.

▶ Bayesian setting: the external agent is an attacker with probability  $\theta$  ( $H_1$ ), and a normal user with probability  $1 - \theta$  ( $H_0$ ).

- ▶ Bayesian setting: the external agent is an attacker with probability  $\theta$  ( $H_1$ ), and a normal user with probability  $1 \theta$  ( $H_0$ ).
- Normal user is not strategic. Generates n i.i.d. samples from a distribution p on  $\mathcal{X} = \{1, 2, \dots, d\}$ .

- ▶ Bayesian setting: the external agent is an attacker with probability  $\theta$  ( $H_1$ ), and a normal user with probability  $1 \theta$  ( $H_0$ ).
- Normal user is not strategic. Generates n i.i.d. samples from a distribution p on  $\mathcal{X} = \{1, 2, \dots, d\}$ .
- ▶ Attacker picks a  $q \in Q \subset M_1(\mathcal{X})$  (but there is a cost for this) and generates n i.i.d. samples from q.

- ▶ Bayesian setting: the external agent is an attacker with probability  $\theta$  ( $H_1$ ), and a normal user with probability  $1 \theta$  ( $H_0$ ).
- Normal user is not strategic. Generates n i.i.d. samples from a distribution p on  $\mathcal{X} = \{1, 2, \dots, d\}$ .
- ▶ Attacker picks a  $q \in Q \subset M_1(\mathcal{X})$  (but there is a cost for this) and generates n i.i.d. samples from q.
- ▶ Defender: upon observing  $\mathbf{x}^n$ , decide  $H_0$  or  $H_1$ .

- ▶ Bayesian setting: the external agent is an attacker with probability  $\theta$  ( $H_1$ ), and a normal user with probability  $1 \theta$  ( $H_0$ ).
- Normal user is not strategic. Generates n i.i.d. samples from a distribution p on  $\mathcal{X} = \{1, 2, \dots, d\}$ .
- ▶ Attacker picks a  $q \in Q \subset M_1(\mathcal{X})$  (but there is a cost for this) and generates n i.i.d. samples from q.
- ▶ Defender: upon observing  $\mathbf{x}^n$ , decide  $H_0$  or  $H_1$ .
- ► The attacker and defender are strategic—we propose a game-theoretic model for this problem.

# The game $\mathcal{G}^{B}(d, n)$

► Two players: the attacker and defender.

# The game $\mathcal{G}^B(d,n)$

- Two players: the attacker and defender.
- Strategy spaces
  - lacktriangle Attacker: the set of probability distributions Q on  $\mathcal X$
  - ▶ Defender:  $\Phi_n = \{ \varphi : \mathcal{X}^n \to [0,1] \}; \ \varphi(\mathbf{x}^n) \ \text{denotes acceptance}$  probability of  $H_1$ .

# The game $\mathcal{G}^B(d,n)$

- Two players: the attacker and defender.
- Strategy spaces
  - lacksquare Attacker: the set of probability distributions Q on  $\mathcal X$
  - ▶ Defender:  $\Phi_n = \{ \varphi : \mathcal{X}^n \to [0,1] \}; \ \varphi(\mathbf{x}^n) \ \text{denotes acceptance}$  probability of  $H_1$ .
- Utility function of the attacker:

$$u_n^A(q,\varphi) = \sum_{\mathbf{x}^n} (1 - \varphi(\mathbf{x}^n)) q(\mathbf{x}^n) - c(q).$$

# The game $\mathcal{G}^B(d,n)$

- Two players: the attacker and defender.
- Strategy spaces
  - lacksquare Attacker: the set of probability distributions Q on  $\mathcal X$
  - ▶ Defender:  $\Phi_n = \{ \varphi : \mathcal{X}^n \to [0,1] \}; \ \varphi(\mathbf{x}^n) \ \text{denotes acceptance}$  probability of  $H_1$ .
- Utility function of the attacker:

$$u_n^A(q,\varphi) = \sum_{\mathbf{x}^n} (1 - \varphi(\mathbf{x}^n)) q(\mathbf{x}^n) - c(q).$$

Utility function of the defender

$$u_n^D(q,\varphi) = -\left(\sum_{\mathbf{x}^n} (1 - \varphi(\mathbf{x}^n))q(\mathbf{x}^n) + \gamma \sum_{\mathbf{x}^n} \varphi(\mathbf{x}^n)p(\mathbf{x}^n)\right).$$

# The game $\mathcal{G}^B(d, n)$

- Two players: the attacker and defender.
- Strategy spaces
  - lacktriangle Attacker: the set of probability distributions Q on  $\mathcal X$
  - ▶ Defender:  $\Phi_n = \{ \varphi : \mathcal{X}^n \to [0,1] \}$ ;  $\varphi(\mathbf{x}^n)$  denotes acceptance probability of  $H_1$ .
- Utility function of the attacker:

$$u_n^A(q,\varphi) = \sum_{\mathbf{x}^n} (1 - \varphi(\mathbf{x}^n)) q(\mathbf{x}^n) - c(q).$$

Utility function of the defender

$$u_n^D(q,\varphi) = -\left(\sum_{\mathbf{x}^n} (1 - \varphi(\mathbf{x}^n))q(\mathbf{x}^n) + \gamma \sum_{\mathbf{x}^n} \varphi(\mathbf{x}^n)p(\mathbf{x}^n)\right).$$

► Goal: analyse the above game. What is the most likely outcome of this game? How much revenue do each players get?

▶ Widely used solution concept for non-cooperative games.

- Widely used solution concept for non-cooperative games.
- ▶ Nash equilibrium (NE): unilateral deviations do not help.

- Widely used solution concept for non-cooperative games.
- Nash equilibrium (NE): unilateral deviations do not help.  $(\hat{q}, \hat{\varphi})$  is a NE of  $\mathcal{G}^B(d, n)$  if

$$u_n^A(\hat{q},\hat{\varphi}) \ge u_n^A(q,\hat{\varphi}) \ \forall q \in Q, \text{ and}$$
  
 $u_n^D(\hat{q},\hat{\varphi}) \ge u_n^D(\hat{q},\varphi) \ \forall \varphi \in \Phi_n.$ 

- Widely used solution concept for non-cooperative games.
- Nash equilibrium (NE): unilateral deviations do not help.  $(\hat{q}, \hat{\varphi})$  is a NE of  $\mathcal{G}^B(d, n)$  if

$$u_n^A(\hat{q},\hat{\varphi}) \ge u_n^A(q,\hat{\varphi}) \ \forall q \in Q, \text{ and}$$
  
 $u_n^D(\hat{q},\hat{\varphi}) \ge u_n^D(\hat{q},\varphi) \ \forall \varphi \in \Phi_n.$ 

But they may not always exist.

- Widely used solution concept for non-cooperative games.
- Nash equilibrium (NE): unilateral deviations do not help.  $(\hat{q}, \hat{\varphi})$  is a NE of  $\mathcal{G}^B(d, n)$  if

$$\begin{aligned} u_n^A(\hat{q},\hat{\varphi}) &\geq u_n^A(q,\hat{\varphi}) \; \forall q \in Q, \text{ and} \\ u_n^D(\hat{q},\hat{\varphi}) &\geq u_n^D(\hat{q},\varphi) \; \forall \varphi \in \Phi_n. \end{aligned}$$

- ▶ But they may not always exist.
- ▶ However mixed equilibria always exist for  $\mathcal{G}^B(d, n)$ .

- Q is equipped with the standard Euclidean topology.
- $ightharpoonup \Phi_n$  is equipped with the "sup-norm" distance

$$d_n(\varphi_1, \varphi_2) = \max_{\mathbf{x}^n \in \mathcal{X}^n} |\varphi_1(\mathbf{x}^n) - \varphi_2(\mathbf{x}^n)|,$$

- Q is equipped with the standard Euclidean topology.
- $ightharpoonup \Phi_n$  is equipped with the "sup-norm" distance

$$d_n(\varphi_1, \varphi_2) = \max_{\mathbf{x}^n \in \mathcal{X}^n} |\varphi_1(\mathbf{x}^n) - \varphi_2(\mathbf{x}^n)|,$$

- Assume:
  - ▶ (A1) Q is closed in  $M_1(\mathcal{X})$ .
  - (A2) c is continuous on Q.

- Q is equipped with the standard Euclidean topology.
- $ightharpoonup \Phi_n$  is equipped with the "sup-norm" distance

$$d_n(\varphi_1, \varphi_2) = \max_{\mathbf{x}^n \in \mathcal{X}^n} |\varphi_1(\mathbf{x}^n) - \varphi_2(\mathbf{x}^n)|,$$

- Assume:
  - ▶ (A1) Q is closed in  $M_1(\mathcal{X})$ .
  - ▶ (A2) c is continuous on Q.
- ▶ Both Q and  $\Phi_n$  are compact metric spaces.

- Q is equipped with the standard Euclidean topology.
- $ightharpoonup \Phi_n$  is equipped with the "sup-norm" distance

$$d_n(\varphi_1, \varphi_2) = \max_{\mathbf{x}^n \in \mathcal{X}^n} |\varphi_1(\mathbf{x}^n) - \varphi_2(\mathbf{x}^n)|,$$

- Assume:
  - ▶ (A1) Q is closed in  $M_1(\mathcal{X})$ .
  - $\blacktriangleright$  (A2) c is continuous on Q.
- ▶ Both Q and  $\Phi_n$  are compact metric spaces.
- ▶ Define randomisations over them:  $M_1(Q)$  and  $M_1(\Phi_n)$  denote the spaces of probability measure on Q and  $\Phi_n$ , respectively.

- Q is equipped with the standard Euclidean topology.
- $ightharpoonup \Phi_n$  is equipped with the "sup-norm" distance

$$d_n(\varphi_1, \varphi_2) = \max_{\mathbf{x}^n \in \mathcal{X}^n} |\varphi_1(\mathbf{x}^n) - \varphi_2(\mathbf{x}^n)|,$$

- Assume:
  - ▶ (A1) Q is closed in  $M_1(\mathcal{X})$ .
  - ► (A2) c is continuous on Q.
- ▶ Both Q and  $\Phi_n$  are compact metric spaces.
- ▶ Define randomisations over them:  $M_1(Q)$  and  $M_1(\Phi_n)$  denote the spaces of probability measure on Q and  $\Phi_n$ , respectively.
- ► Mixed strategy:  $(\sigma^A, \sigma^D) \in M_1(Q) \times M_1(\Phi_n)$ .  $u_n^A(\sigma^A, \sigma^D) = \int u_n^A(q, \varphi) \sigma^A(dq) \sigma^D(d\varphi)$ ; similarly  $u_n^D$ .

- Q is equipped with the standard Euclidean topology.
- $ightharpoonup \Phi_n$  is equipped with the "sup-norm" distance

$$d_n(\varphi_1, \varphi_2) = \max_{\mathbf{x}^n \in \mathcal{X}^n} |\varphi_1(\mathbf{x}^n) - \varphi_2(\mathbf{x}^n)|,$$

- Assume:
  - (A1) Q is closed in  $M_1(\mathcal{X})$ .
  - ▶ (A2) *c* is continuous on *Q*.
- ▶ Both Q and  $\Phi_n$  are compact metric spaces.
- ▶ Define randomisations over them:  $M_1(Q)$  and  $M_1(\Phi_n)$  denote the spaces of probability measure on Q and  $\Phi_n$ , respectively.
- Mixed strategy:  $(\sigma^A, \sigma^D) \in M_1(Q) \times M_1(\Phi_n)$ .  $u_n^A(\sigma^A, \sigma^D) = \int u_n^A(q, \varphi) \sigma^A(dq) \sigma^D(d\varphi)$ ; similarly  $u_n^D$ .
- A strategy  $(\hat{\sigma}^A, \hat{\sigma}^D)$  is a mixed strategy Nash equilibrium if

$$u_n^A(\hat{\sigma}^A, \hat{\sigma}^D) \ge u_n^A(\sigma^A, \hat{\sigma}^D) \ \forall \sigma^A \in M_1(Q), \text{ and}$$
  
 $u_n^D(\hat{\sigma}^A, \hat{\sigma}^D) \ge u_n^D(\hat{\sigma}_A, \sigma^D) \ \forall \sigma^D \in M_1(\Phi_n).$ 



## Existence and partial characterisation of mixed NE

#### Proposition

Assume (A1) and (A2). Then, there exists a mixed strategy Nash equilibrium for  $\mathcal{G}^B(d,n)$ . If  $(\hat{\sigma}_n^A,\hat{\sigma}_n^D)$  is a NE, then so is  $(\hat{\sigma}_n^A,\hat{\varphi}_n)$  where  $\hat{\varphi}_n$  is the likelihood ratio test given by

$$\hat{\varphi}_{n}(\mathbf{x}^{n}) = \begin{cases} 1, & \text{if } q_{\hat{\sigma}_{n}^{A}}(\mathbf{x}^{n}) - \gamma p(\mathbf{x}^{n}) > 0, \\ \varphi_{\hat{\sigma}_{n}^{D}}, & \text{if } q_{\hat{\sigma}_{n}^{A}}(\mathbf{x}^{n}) - \gamma p(\mathbf{x}^{n}) = 0, \\ 0, & \text{if } q_{\hat{\sigma}_{n}^{A}}(\mathbf{x}^{n}) - \gamma p(\mathbf{x}^{n}) < 0, \end{cases}$$

where 
$$q_{\hat{\sigma}_n^A}(\mathbf{x}^n) = \int q(\mathbf{x}^n) \hat{\sigma}_n^A(dq)$$
, and  $\varphi_{\hat{\sigma}_n^D} = \int \varphi(\mathbf{x}^n) \hat{\sigma}_n^D(d\varphi)$ .

- Follows from the Glicksberg fixed point theorem.
- ▶ Randomisation over  $\Phi_n$  is needed so show existence of NE.
- $q_{\hat{\sigma}_A^A}$  need not be a product of elements from Q.

- $(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  is a NE. What can we say about  $u_n^A(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  and  $u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ ?
- ► Consider the classification error:  $e_n(\hat{\sigma}_n^A, \hat{\sigma}_n^D) = -u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ .

- $(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  is a NE. What can we say about  $u_n^A(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  and  $u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ ?
- ► Consider the classification error:  $e_n(\hat{\sigma}_n^A, \hat{\sigma}_n^D) = -u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ .
- ▶ Decision rule  $\varphi^{\delta}$ : accept  $H_0$  when the empirical distribution of  $\mathbf{x}^n(\mathcal{P}_{\mathbf{x}^n})$  falls in a  $\delta$ -neighbourhood of p. (Picture on board)

- $(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  is a NE. What can we say about  $u_n^A(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  and  $u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ ?
- ► Consider the classification error:  $e_n(\hat{\sigma}_n^A, \hat{\sigma}_n^D) = -u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ .
- ▶ Decision rule  $\varphi^{\delta}$ : accept  $H_0$  when the empirical distribution of  $\mathbf{x}^n(\mathcal{P}_{\mathbf{x}^n})$  falls in a  $\delta$ -neighbourhood of p. (Picture on board)
- ▶ By the law of large numbers, one expects that  $e_n(\hat{\sigma}_n^A, \varphi^\delta) \to 0$  as  $n \to \infty$ .

- $(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  is a NE. What can we say about  $u_n^A(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  and  $u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ ?
- ► Consider the classification error:  $e_n(\hat{\sigma}_n^A, \hat{\sigma}_n^D) = -u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ .
- ▶ Decision rule  $\varphi^{\delta}$ : accept  $H_0$  when the empirical distribution of  $\mathbf{x}^n(\mathcal{P}_{\mathbf{x}^n})$  falls in a  $\delta$ -neighbourhood of p. (Picture on board)
- ▶ By the law of large numbers, one expects that  $e_n(\hat{\sigma}_n^A, \varphi^\delta) \to 0$  as  $n \to \infty$ .
- ▶ We have  $e_n(\hat{\sigma}_n^A, \hat{\sigma}_n^D) \leq e_n(\hat{\sigma}_n^A, \varphi^\delta) \to 0$  as  $n \to \infty$ .

- $(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  is a NE. What can we say about  $u_n^A(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$  and  $u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ ?
- ► Consider the classification error:  $e_n(\hat{\sigma}_n^A, \hat{\sigma}_n^D) = -u_n^D(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ .
- ▶ Decision rule  $\varphi^{\delta}$ : accept  $H_0$  when the empirical distribution of  $\mathbf{x}^n(\mathcal{P}_{\mathbf{x}^n})$  falls in a  $\delta$ -neighbourhood of p. (Picture on board)
- ▶ By the law of large numbers, one expects that  $e_n(\hat{\sigma}_n^A, \varphi^\delta) \to 0$  as  $n \to \infty$ .
- ▶ We have  $e_n(\hat{\sigma}_n^A, \hat{\sigma}_n^D) \leq e_n(\hat{\sigma}_n^A, \varphi^\delta) \to 0$  as  $n \to \infty$ .
- ▶ Thus, we anticipate that  $\hat{\sigma}^A$  to concentrate on the set  $\{q^* \in Q : c(q^*) \le c(q) \, \forall q \in Q\}.$

#### Concentration of NE

- ▶ To proceed further, we need another assumption:
  - ▶ (A3) There exists a unique  $q^* \in Q$  such that

$$q^* = \arg\min_{q \in Q} c(q).$$

#### Concentration of NE

- ▶ To proceed further, we need another assumption:
  - ▶ (A3) There exists a unique  $q^* \in Q$  such that

$$q^* = \arg\min_{q \in Q} c(q).$$

#### Lemma

Assume (A1)-(A3). Then,  $\hat{\sigma}_n^A \to \delta_{q^*}$  weakly as  $n \to \infty$ :

$$\int_Q f(q) \hat{\sigma}_n^A(dq) o f(q^*)$$

for all bounded continuous functions  $f: Q \to \mathbb{R}$ .

#### Concentration of NE

- ▶ To proceed further, we need another assumption:
  - ▶ (A3) There exists a unique  $q^* \in Q$  such that

$$q^* = \arg\min_{q \in Q} c(q).$$

#### Lemma

Assume (A1)-(A3). Then,  $\hat{\sigma}_n^A \to \delta_{q^*}$  weakly as  $n \to \infty$ :

$$\int_Q f(q) \hat{\sigma}_n^A(dq) o f(q^*)$$

for all bounded continuous functions  $f: Q \to \mathbb{R}$ .

▶ Proof idea: Subsequential limits of  $\{\hat{\sigma}_n^A\}_{n\geq 1}$  exist (Prohorov). Use  $e_n(\hat{\sigma}_n^A,\hat{\sigma}_n^D) \to 0$  and the fact that  $(\hat{\sigma}_n^A,\hat{\sigma}_n^D)$  is a NE to show that every limit point coincides with  $\delta_{q^*}$ .

# Support of $\hat{\sigma}_n^A$

- ▶ Lemma 1 does not imply that  $\operatorname{dist}(supp(\hat{\sigma}_n^A), q^*) \to 0$ . (Picture on board)
- One more assumption: (A4) The point p is distant from the set Q relative to the point q\*, i.e.,

$$\{\mu \in M_1(\mathcal{X}) : D(\mu||p) \leq D(\mu||q^*)\} \cap Q = \emptyset.$$

#### Lemma

Assume (A1)-(A4). Let  $(q_n)_{n\geq 1}$  be a sequence such that  $q_n \in supp(\hat{\sigma}_n^A)$  for each  $n \geq 1$ . Then,  $q_n \to q^*$  as  $n \to \infty$ .

▶ Proof idea: Show that  $\sup_{q \in Q} e_n(q, \hat{\sigma}_n^D) \to 0$ . Then use uniqueness of  $q^*$ .

# Main result: error exponents

Define

$$\Lambda_0(\lambda) = \log \sum_{i \in \mathcal{X}} \exp \left(\lambda \frac{q^*(i)}{p(i)}\right) p(i), \ \lambda \in \mathbb{R},$$

the log-moment generating function of  $\frac{q^*(X)}{p(X)}$  under  $H_0$ , i.e., when  $X \sim p$ , and its convex dual

$$\Lambda_0^*(x) = \sup_{\lambda \in \mathbb{R}} \{\lambda x - \Lambda_0(\lambda)\}, \ x \in \mathbb{R}.$$

# Main result: error exponents

Define

$$\Lambda_0(\lambda) = \log \sum_{i \in \mathcal{X}} \exp \left(\lambda \frac{q^*(i)}{p(i)}\right) p(i), \ \lambda \in \mathbb{R},$$

the log-moment generating function of  $\frac{q^*(X)}{p(X)}$  under  $H_0$ , i.e., when  $X \sim p$ , and its convex dual

$$\Lambda_0^*(x) = \sup_{\lambda \in \mathbb{R}} \{\lambda x - \Lambda_0(\lambda)\}, \ x \in \mathbb{R}.$$

#### Theorem

Assume (A1)-(A4). Then,

$$\lim_{n\to\infty}\frac{1}{n}\log e_n(\hat{\sigma}_n^A,\hat{\sigma}_n^D)=-\Lambda_0^*(0).$$

▶ Lower bound: let the attacker play the strategy  $q^*$ .

- ▶ Lower bound: let the attacker play the strategy  $q^*$ .
- ▶ Upper bound: let the defender play a fixed decision rule and make use of the concentration properties of NE.

- ▶ Lower bound: let the attacker play the strategy  $q^*$ .
- ▶ Upper bound: let the defender play a fixed decision rule and make use of the concentration properties of NE.
- ▶ The result holds for all NE  $(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ .

- ▶ Lower bound: let the attacker play the strategy  $q^*$ .
- Upper bound: let the defender play a fixed decision rule and make use of the concentration properties of NE.
- ▶ The result holds for all NE  $(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ .
- We obtain this result without explicitly computing the structure of NE.

- ▶ Lower bound: let the attacker play the strategy  $q^*$ .
- Upper bound: let the defender play a fixed decision rule and make use of the concentration properties of NE.
- ▶ The result holds for all NE  $(\hat{\sigma}_n^A, \hat{\sigma}_n^D)$ .
- We obtain this result without explicitly computing the structure of NE.
- ▶ The error exponent is the same as that of classical binary hypothesis testing between p and  $q^*$ .

## Proof sketch

- Lower bound:
- Define

$$u_n^{eq}(q,\varphi) = \sum_{\mathbf{x}^n} (1 - \varphi(\mathbf{x}^n)) q(\mathbf{x}^n) + \gamma \sum_{\mathbf{x}^n} \varphi(\mathbf{x}^n) p(\mathbf{x}^n) - c(q).$$

- $\mathcal{G}^B(d,n)$  is equivalent to the zerosum game with utility  $e_n^{eq}$ .
- $u_n^{eq}(\hat{\sigma}_n^A, \hat{\sigma}_n^D) \ge u_n^{eq}(q^*, \hat{\sigma}_n^D).$
- Can show (using the uniqueness of q\*)

$$e_n(\hat{\sigma}_n^A,\hat{\sigma}_n^D) \geq \sum_{\mathbf{x}^n} \left( (1 - \varphi_n^*(\mathbf{x}^n)) q^*(\mathbf{x}^n) + \gamma \varphi_n^*(\mathbf{x}^n) p(\mathbf{x}^n) \right).$$

▶ Use the error exponent for classical testing of p versus  $q^*$ :

$$\liminf_{n\to\infty}\frac{1}{n}\log e_n(\hat{\sigma}_n^A,\hat{\sigma}_n^D)\geq -\Lambda_0^*(0).$$



## Proof sketch

Upper bound:

$$\varphi_n'(\mathbf{x}^n) = \left\{ egin{array}{ll} 1, & ext{if } rac{q^*(\mathbf{x}^n)}{p(\mathbf{x}^n)} \geq 1, \\ 0, & ext{otherwise.} \end{array} 
ight.$$

▶ Decision region of  $\varphi'_n$  (in terms of empirical distribution):

$$\Gamma' = \{ \nu \in M_1(\mathcal{X}) : D(\nu||q^*) - D(\nu||p) > 0 \}.$$

- $e_n(\hat{\sigma}_n^A, \hat{\sigma}_n^D) \leq e_n(\hat{\sigma}_n^A, \varphi_n').$
- Easy to check:

$$e_n(\hat{\sigma}_n^A, \varphi_n') = \int q(\mathcal{P}_{\mathbf{x}^n} \in \Gamma') \hat{\sigma}_n^A(dq) + p(\mathcal{P}_{\mathbf{x}^n} \in (\Gamma')^c).$$

We can show that

$$q(\mathcal{P}_{\mathbf{x}^n} \in \Gamma') \leq (n+1)^d e^{-n\inf_{\nu \in \Gamma'} D(\nu||q)}.$$



## Proof sketch

▶ Using the concentration of  $\hat{\sigma}_n^A$ , we have, for any  $\varepsilon > 0$ ,

$$D(\nu || q) \ge D(\nu || q^*) - \varepsilon$$
 for all  $q \in \text{supp}(\hat{\sigma}_n^A)$ .

for sufficiently large n.

- ▶ Thus,  $q(\mathcal{P}_{\mathbf{x}^n} \in \Gamma') \le (n+1)^d e^{-n(\inf_{\nu \in \Gamma'} D(\nu || q^*) \varepsilon)}$
- Similarly,

$$p(\mathcal{P}_{\mathbf{x}^n} \in (\Gamma')^c) \le (n+1)^d e^{-n(\inf_{\nu \notin \Gamma'} D(\nu \| \rho) - \varepsilon)}$$

- Exercise:  $\inf_{\nu \notin \Gamma'} D(\nu \| p) = \inf_{\nu \in \Gamma'} D(\nu \| q^*) = \Lambda_0^*(0)$ .
- Thus,

$$\limsup_{n\to\infty}\frac{1}{n}\log e_n(\hat{\sigma}_n^A,\hat{\sigma}_n^D)\leq -\Lambda_0^*(0).$$



# Numerical examples: No pure NE

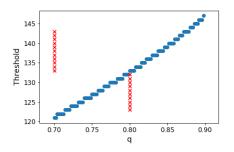


Figure: 
$$Q = [0.7, 0.9], c(q) = |q - 0.8|, n = 200$$

## Numerical examples: Pure NE

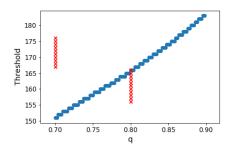


Figure: Q = [0.7, 0.9], c(q) = |q - 0.8|, n = 250

► This suggest that pure NE exists for large *n*.

## Numerical examples: Error exponent

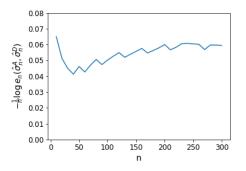


Figure:  $Q = [0.7, 0.9], c(q) = |q - 0.8|, \Lambda_0^*(0) \approx 0.054$ 

## Numerical examples: Error exponent

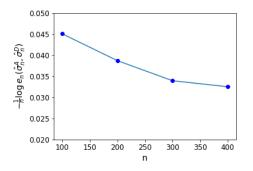


Figure:  $Q = [0.6, 0.9], c(q) = 3|q - 0.9|, \Lambda_0^*(0) \approx 0.111$ 

▶ A game-theoretic model to study adversarial classification.

- ▶ A game-theoretic model to study adversarial classification.
- Results:
  - Existence and partial characterisation of mixed NE in these games.
  - Concentration properties of NE.
  - Error exponents associated with classification error.

- A game-theoretic model to study adversarial classification.
- Results:
  - Existence and partial characterisation of mixed NE in these games.
  - Concentration properties of NE.
  - Error exponents associated with classification error.
- Future work:
  - ► Characterisation of all NE and algorithms to compute them.
  - ▶ Relax assumptions. What if c has multiple minima? A weaker assumption than (A4)?
  - Sequential hypothesis testing game.
  - Conditions of existence of pure NE.

- A game-theoretic model to study adversarial classification.
- Results:
  - Existence and partial characterisation of mixed NE in these games.
  - Concentration properties of NE.
  - Error exponents associated with classification error.
- Future work:
  - ► Characterisation of all NE and algorithms to compute them.
  - ▶ Relax assumptions. What if c has multiple minima? A weaker assumption than (A4)?
  - Sequential hypothesis testing game.
  - Conditions of existence of pure NE.
- Acknowledgment: Cisco-IISc Research Fellowship Grant.

# Thank you