



The Complexity of Flexible FOND HTN Planning

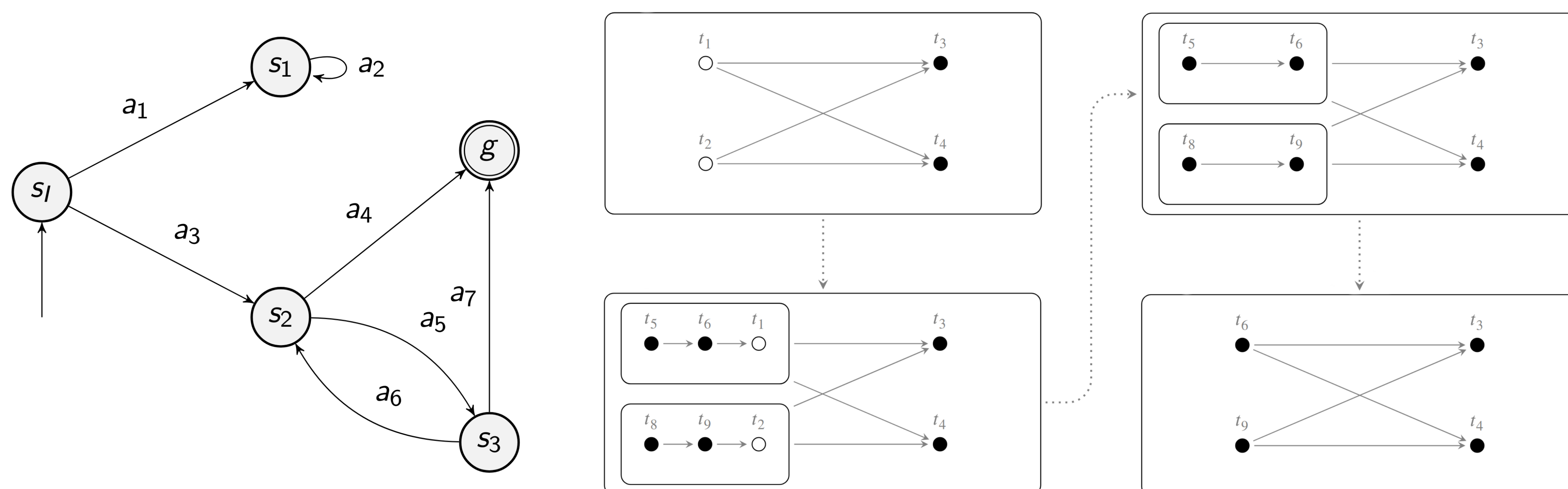
Dillon Chen, Pascal Bercher

The Australian National University

{dillon.chen, pascal.bercher} @anu.edu.au

HTN planning in a nutshell

- Aim of classical planning: reach a goal state with a sequence of actions.
- Aim of HTN planning: execute a given set of tasks with task decomposition.
 - tasks either compound or primitive
 - compound tasks can be decomposed into another set of tasks
 - primitive tasks = actions



Why HTN planning?

- Expressive - complexity ranges from tractable to undecidable
- Nice compilation from classical planning
- Easy to encode domain dependent knowledge
- Levels of abstraction helpful for communicating with users

Adding uncertainty

- Classical planning: actions may have several effects
- HTN planning: actions may have several effects
 - same!

Defining solutions

- Nondeterministic planning: policy of actions
- Nondeterministic HTN planning: policy of instructions
 - instructions = decomposition of compound tasks or execution of primitive tasks

executing a policy π :

- $s \leftarrow s_I$
- while $\pi(s)$ exists:
 - execute $\pi(s)$
 - $s \leftarrow \text{senseState}()$
 - if $s = s_G$: return success

executing an HTN policy π :

- $(s, tn) \leftarrow (s_I, tn_I)$
- while $\pi(s)$ exists:
 - perform $\pi(s)$
 - $s \leftarrow \text{senseState}()$
 - $tn \leftarrow \text{updateTaskNetwork}()$
 - if $tn = \emptyset$: return success

Complexity results

- problems are all made one class harder with nondeterminism
- nonhierarchical planning analogy: PSPACE-complete to EXPTIME-complete
- idea: progression algorithms are generalised using ATMs/AND-OR trees:
 - $\text{SPACE}(f(n)) = \bigcup_{c>0} \text{ATIME}(c^{f(n)})$
 - $\text{TIME}(f(n)) = \text{ASPACE}(f(n))$

Hierarchy	Order	Classical/Weak		Strong		Strong cyclic	
primitive	total	P*	[4.3]	P*	PSPACE	[4.2]	[4.2]
	partial	NP	[4.3]				
acyclic	total	PSPACE	[4.3]	EXPTIME	EXPTIME	[4.4]	[4.4]
	partial	NEXPTIME	[4.3]				
regular	total	PSPACE	[4.3]	EXPTIME	EXPTIME	[4.6]	[4.6]
	partial	PSPACE	[4.3]				
tail-recursive	total	PSPACE	[4.3]	EXPTIME	EXPTIME	[4.7]	[4.7]
	partial	EXPSPACE	[4.3]				
arbitrary	total	EXPTIME	[4.3]	semi-decidable*	semi-decidable*	[4.7]	[4.7]
	partial	semi-undecidable					