

Thompson Sampling for Bandit Convex Optimisation

Alireza Bakhtiari¹ Tor Lattimore² Csaba Szepesvári^{1,2}

University of Alberta¹ & Google DeepMind²

COLT 2025

- **Goal:** Understand how **Thompson Sampling (TS)** behaves in **bandit convex optimization (BCO)**.
- **Positive:**
 - $\text{BReg}_n(\text{TS}) = \tilde{O}(\sqrt{n})$ in 1 -D convex bandits.
 - $\text{BReg}_n(\text{TS}) = \tilde{O}(d^{2.5}\sqrt{n})$ for d -D *monotone convex ridge* losses.
- **Negative:**
 - TS can suffer $\Omega(\exp(d))$ regret for general d -D convex losses.
 - Classical info-ratio tricks \Rightarrow no better than $\tilde{\Omega}(d^{1.5}\sqrt{n})$ for general stochastic & adversarial BCO.

Problem Setup

- Convex action set $\mathcal{K} \subset \mathbb{R}^d$.
- \mathcal{F} be a set of convex functions from \mathcal{K} to $[0, 1]$.
- ξ is a known prior on \mathcal{F} .

¹The Bernoulli noise assumption is just for convenience.

Problem Setup

- Convex action set $\mathcal{K} \subset \mathbb{R}^d$.
- \mathcal{F} be a set of convex functions from \mathcal{K} to $[0, 1]$.
- ξ is a known prior on \mathcal{F} .
- At round t :
 - 1 Learner plays $X_t \in \mathcal{K}$.
 - 2 Observes scalar loss $Y_t \in \{0, 1\}$.¹

¹The Bernoulli noise assumption is just for convenience.

Problem Setup

- Convex action set $\mathcal{K} \subset \mathbb{R}^d$.
- \mathcal{F} be a set of convex functions from \mathcal{K} to $[0, 1]$.
- ξ is a known prior on \mathcal{F} .
- At round t :
 - ① Learner plays $X_t \in \mathcal{K}$.
 - ② Observes scalar loss $Y_t \in \{0, 1\}$.¹
- $\mathbb{E}[Y_t | X_1, Y_1, \dots, X_t, f] = f(X_t)$, where $f \in \mathcal{F}$ is convex.

¹The Bernoulli noise assumption is just for convenience.

Problem Setup

- Convex action set $\mathcal{K} \subset \mathbb{R}^d$.
- \mathcal{F} be a set of convex functions from \mathcal{K} to $[0, 1]$.
- ξ is a known prior on \mathcal{F} .
- At round t :
 - ① Learner plays $X_t \in \mathcal{K}$.
 - ② Observes scalar loss $Y_t \in \{0, 1\}$.¹
- $\mathbb{E}[Y_t | X_1, Y_1, \dots, X_t, f] = f(X_t)$, where $f \in \mathcal{F}$ is convex.
- \mathcal{A} (learner) is a mapping from histories & prior to \mathcal{K} .

¹The Bernoulli noise assumption is just for convenience.

Problem Setup

- Convex action set $\mathcal{K} \subset \mathbb{R}^d$.
- \mathcal{F} be a set of convex functions from \mathcal{K} to $[0, 1]$.
- ξ is a known prior on \mathcal{F} .
- At round t :
 - 1 Learner plays $X_t \in \mathcal{K}$.
 - 2 Observes scalar loss $Y_t \in \{0, 1\}$.¹
- $\mathbb{E}[Y_t | X_1, Y_1, \dots, X_t, f] = f(X_t)$, where $f \in \mathcal{F}$ is convex.
- \mathcal{A} (learner) is a mapping from histories & prior to \mathcal{K} .
- **Bayesian Regret**

$$\text{BReg}_n(\mathcal{A}, \xi) = \mathbb{E} \left[\sup_{x \in \mathcal{K}} \sum_{t=1}^n (f(X_t) - f(x)) \right],$$

where $f \sim \xi$.

¹The Bernoulli noise assumption is just for convenience.

Thompson Sampling for BCO

Algorithm 1 Thompson Sampling

- 1: Prior ξ over convex losses.
 - 2: **for** $t = 1, \dots, n$ **do**
 - 3: Sample $f_t \sim \mathbb{P}(f = \cdot | X_1, Y_1, \dots, X_{t-1}, Y_{t-1})$
 - 4: Play $X_t \in \arg \min_{x \in \mathcal{K}} f_t(x)$ and observe Y_t
 - 5: **end for**
-

- Our analysis studies how

$$\text{BReg}^{\text{TS}}(\mathcal{F}) = \sup_{\xi \in \mathcal{P}(\mathcal{F})} \text{BReg}_n(\text{TS}, \xi),$$

behaves for various natural classes of convex functions \mathcal{F} .

Upper bounds - main results

- Positive results for two sets of functions $f : \mathcal{K} \rightarrow [0, 1]$:

\mathcal{F}_{bl} : $\mathcal{K} \subset \mathbb{R}$ and f is a 1-Lip and bounded convex function,

$\mathcal{F}_{\text{blrm}}$: $\mathcal{K} \subset \mathbb{R}^d$ and $f(x) = \ell(\langle x, \theta \rangle)$ for some $\theta \in \mathbb{R}^d$ and a convex 1-Lip bounded *monotone* $\ell : \mathbb{R} \rightarrow \mathbb{R}$.

Upper bounds – 1-D convex functions

TS achieves

$$\text{BReg}^{\text{TS}}(\mathcal{F}_{\text{bl}}) = \tilde{O}(\sqrt{n}) ,$$

And

$$\text{BReg}^{\text{TS}}(\mathcal{F}_{\text{blrm}}) = \tilde{O}(d^{2.5}\sqrt{n}) .$$

(Generalized) **Information Ratio (IR)**

- Let $x_g = \operatorname{argmin}_{x \in \mathcal{K}} g(x)$. (analysis is really about x_f and $f(x_f)$.)
- Let $(F_1, F_2) \sim \xi \otimes \xi$ and $\bar{f} = \mathbb{E}[F_1]$.
- Define

$$\Delta(\xi) = \mathbb{E}[\bar{f}(x_{F_1}) - F_1(x_{F_1})] \quad \text{and} \quad \mathcal{I}(\xi) = \mathbb{E}[(F_1(x_{F_2}) - \bar{f}(x_{F_2}))^2].$$

Generalized IR

Define generalized information ratio associated with π as

$$\operatorname{IR}(\mathcal{F}) = \left\{ (\alpha, \beta) \in \mathbb{R}_+^2 : \Delta(\xi) \leq \alpha + \sqrt{\beta \mathcal{I}(\xi)}, \forall \xi \in \mathcal{P}(\mathcal{F}) \right\}.$$

- $(0, \beta) \in \operatorname{IR}(\mathcal{F}) \Rightarrow \Delta(\xi)^2 / \mathcal{I}(\xi) \leq \beta$.

Upper bounds – regret & IR

Proposition 1 – regret bound through IR

Suppose that $\mathcal{F} \in \{\mathcal{F}_{\text{bl}}, \mathcal{F}_{\text{blrm}}\}$ and $(\alpha, \beta) \in \text{IR}(\mathcal{F})$. Then, the regret of TS is at most

$$\text{BReg}_n(\text{TS}, \xi_0) \leq n\alpha + O\left(\sqrt{\beta n d \log(n \text{diam}(\mathcal{K}))}\right).$$

Upper bounds – regret & IR

Proposition 1 – regret bound through IR

Suppose that $\mathcal{F} \in \{\mathcal{F}_{\text{bl}}, \mathcal{F}_{\text{blrm}}\}$ and $(\alpha, \beta) \in \text{IR}(\mathcal{F})$. Then, the regret of TS is at most

$$\text{BReg}_n(\text{TS}, \xi_0) \leq n\alpha + O\left(\sqrt{\beta n d \log(n \text{diam}(\mathcal{K}))}\right).$$

It remains to bound the IR of TS.

Upper bounds – regret & IR

Proposition 1 – regret bound through IR

Suppose that $\mathcal{F} \in \{\mathcal{F}_{\text{bl}}, \mathcal{F}_{\text{blrm}}\}$ and $(\alpha, \beta) \in \text{IR}(\mathcal{F})$. Then, the regret of TS is at most

$$\text{BReg}_n(\text{TS}, \xi_0) \leq n\alpha + O\left(\sqrt{\beta n d \log(n \text{diam}(\mathcal{K}))}\right).$$

Proposition 2 – TS-IR Partitioning

If $\exists k, m \in \mathbb{N}$ such that for all $\tilde{f} \in \text{conv}(\mathcal{F})$ there is $\mathcal{F} = \cup_{i=1}^m \mathcal{F}_i$ for which

$$\sup_{f \in \mathcal{F}_i} (\tilde{f}(x_f) - f(x_f)) \leq \alpha + \sqrt{\underbrace{\beta \inf_{f_1, \dots, f_k \in \mathcal{F}_i} \sum_{j \neq l \in [k]} (f_j(x_{f_l}) - \tilde{f}(x_{f_l}))^2}_{\text{DIS}(\mathcal{F}_i, k)}},$$

for all i , then $(\alpha, k(k-1)m\beta) \in \text{IR}(\mathcal{F})$.

Upper bounds – regret & IR

Proposition 1 – regret bound through IR

Suppose that $\mathcal{F} \in \{\mathcal{F}_{\text{bl}}, \mathcal{F}_{\text{blrm}}\}$ and $(\alpha, \beta) \in \text{IR}(\mathcal{F})$. Then, the regret of TS is at most

$$\text{BReg}_n(\text{TS}, \xi_0) \leq n\alpha + O\left(\sqrt{\beta n d \log(n \text{diam}(\mathcal{K}))}\right).$$

Proposition 2 – TS-IR Partitioning

If $\exists k, m \in \mathbb{N}$ such that for all $\tilde{f} \in \text{conv}(\mathcal{F})$ there is $\mathcal{F} = \cup_{i=1}^m \mathcal{F}_i$ for which

$$\sup_{f \in \mathcal{F}_i} (\tilde{f}(x_f) - f(x_f)) \leq \alpha + \sqrt{\beta \inf_{f_1, \dots, f_k \in \mathcal{F}_i} \sum_{j \neq l \in [k]} (f_j(x_{f_l}) - \tilde{f}(x_{f_l}))^2},$$

$\underbrace{\hspace{10em}}_{\text{DIS}(\mathcal{F}_i, k)}$

worst case average regret within \mathcal{F}_i

for all i , then $(\alpha, k(k-1)m\beta) \in \text{IR}(\mathcal{F})$.

Upper bounds – regret & IR

Proposition 1 – regret bound through IR

Suppose that $\mathcal{F} \in \{\mathcal{F}_{\text{bl}}, \mathcal{F}_{\text{blrm}}\}$ and $(\alpha, \beta) \in \text{IR}(\mathcal{F})$. Then, the regret of TS is at most

$$\text{BReg}_n(\text{TS}, \xi_0) \leq n\alpha + O\left(\sqrt{\beta n d \log(n \text{diam}(\mathcal{K}))}\right).$$

Proposition 2 – TS-IR Partitioning

If $\exists k, m \in \mathbb{N}$ such that for all $\tilde{f} \in \text{conv}(\mathcal{F})$ there is $\mathcal{F} = \cup_{i=1}^m \mathcal{F}_i$ for which

$$\sup_{f \in \mathcal{F}_i} (\tilde{f}(x_f) - f(x_f)) \leq \alpha +$$

worst case average regret within \mathcal{F}_i

$$\beta \underbrace{\inf_{f_1, \dots, f_k \in \mathcal{F}_i} \sum_{j \neq l \in [k]} (f_j(x_{f_l}) - \tilde{f}(x_{f_l}))^2}_{\text{DIS}(\mathcal{F}_i, k)}$$

TS minimum inf. gain (discrepancy)

for all i , then $(\alpha, k(k-1)m\beta) \in \text{IR}(\mathcal{F})$.

Upper bounds – IR bound in 1-D

Theorem 3 – IR bound for 1-D

Suppose that $d = 1$ and $\alpha \in (0, 1)$. Then $(\alpha, 10^4 \lceil \log(1/\alpha) \rceil) \in \text{IR}(\mathcal{F}_{\text{bl}})$.

Proof sketch:

- 1 Use the partitioning lemma \Rightarrow partition based on x_f and $f(x_f)$.
- 2 Group functions with similar gaps (average regret) in \mathcal{F}_i :

Similar gaps: $\tilde{f}(x_f) - f(x_f) \in [\epsilon, 2\epsilon]$,

\tilde{f} monotone: $x_{\tilde{f}} \leq x_f \Rightarrow \tilde{f}$ (begin 1-D is crucial here).

- 3 Prove that $\text{DIS}(\mathcal{F}_i, k) \geq c^2 \epsilon_i^2$:

$$\text{DIS}(\mathcal{F}_i, k) = \inf_{f_1, \dots, f_k \in \mathcal{F}_i} \sum_{j \neq l \in [k]} (f_j(x_{f_l}) - \tilde{f}(x_{f_l}))^2 \geq c^2 \epsilon_i^2.$$

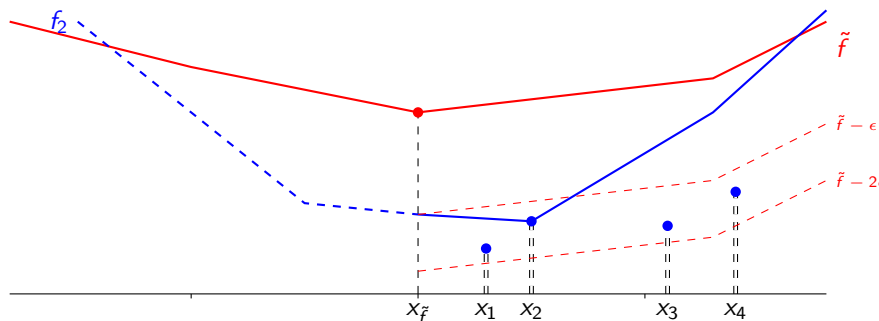
Upper bounds – IR bound in 1-D

Proof sketch:(proof by contradiction)

- Fix $k = 4$, $c \approx 1/16$, suppose that

$$\inf_{f_1, f_2, f_3, f_4 \in \mathcal{F}_i} \sum_{j \neq l \in [4]} (f_j(x_{f_l}) - \tilde{f}(x_{f_l}))^2 \leq c^2 \epsilon_i^2 \Rightarrow |f_j(x_{f_l}) - \tilde{f}(x_{f_l})| \leq c \epsilon_i, \forall j \neq l \in [4].$$

- WLOG, suppose that $x_{\tilde{f}} \leq x_1 \leq x_2 \leq x_3 \leq x_4$, for $x_i \triangleq x_{f_i}$.



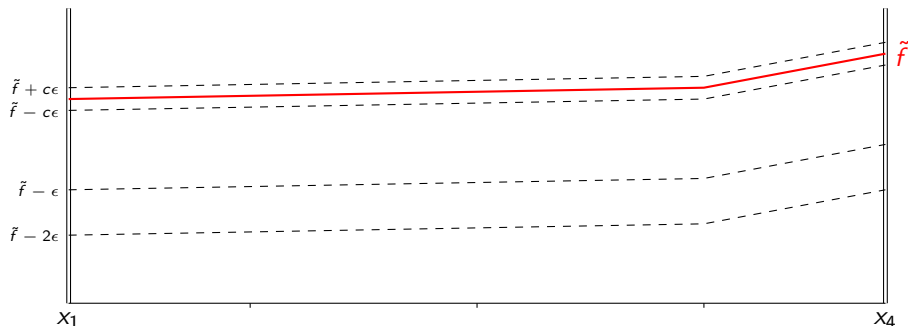
Upper bounds – IR bound in 1-D

Proof sketch:(proof by contradiction)

- Fix $k = 4, c \approx 1/16$, suppose that

$$\forall j \neq l \in [4], \quad |f_j(x_{f_l}) - \tilde{f}(x_{f_l})| \leq c\epsilon_j.$$

- f_j needs to be close to \tilde{f} , at minimizers x_{f_l} (double lines $||$) for $l \neq j$.



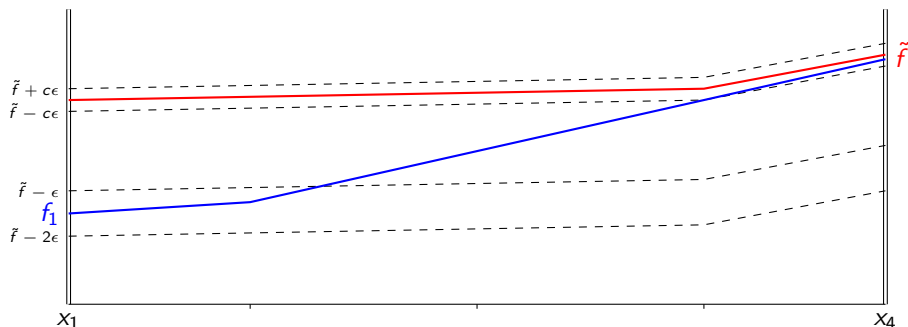
Upper bounds – IR bound in 1-D

Proof sketch:(proof by contradiction)

- Fix $k = 4, c \approx 1/16$, suppose that

$$\forall j \neq l \in [4], \quad |f_j(x_{f_l}) - \tilde{f}(x_{f_l})| \leq c\epsilon_i.$$

- f_j needs to be close to \tilde{f} , at minimizers x_{f_l} (double lines $||$) for $l \neq j$.



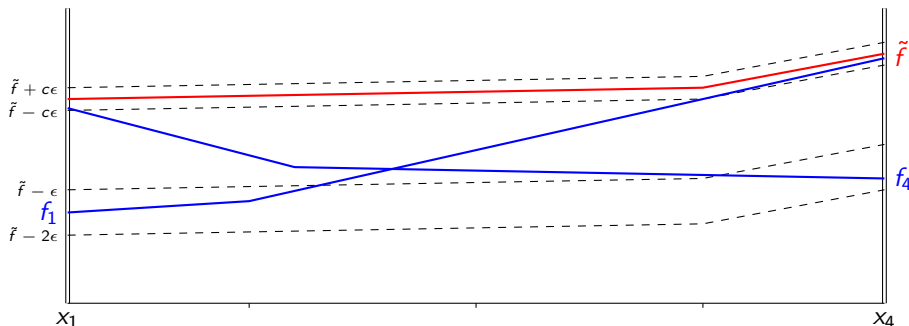
Upper bounds – IR bound in 1-D

Proof sketch:(proof by contradiction)

- Fix $k = 4, c \approx 1/16$, suppose that

$$\forall j \neq l \in [4], |f_j(x_{f_l}) - \tilde{f}(x_{f_l})| \leq c\epsilon_j.$$

- f_j needs to be close to \tilde{f} , at minimizers x_{f_l} (double lines $||$) for $l \neq j$.



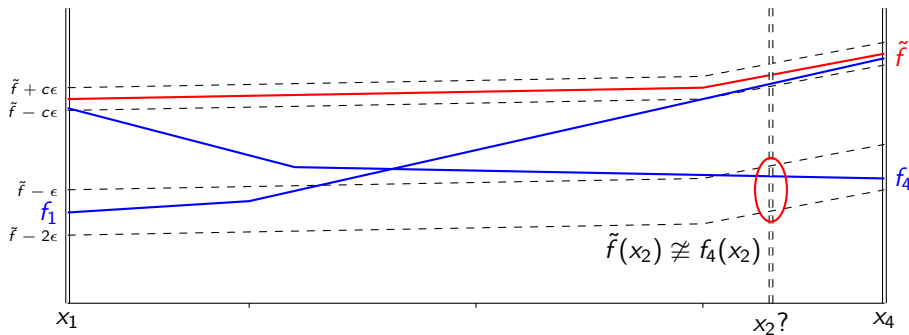
Upper bounds – IR bound in 1-D

Proof sketch:(proof by contradiction)

- Fix $k = 4, c \approx 1/16$, suppose that

$$\forall j \neq l \in [4], |f_j(x_{f_l}) - \tilde{f}(x_{f_l})| \leq c\epsilon_i.$$

- f_j needs to be close to \tilde{f} , at minimizers x_{f_l} (double lines ||) for $l \neq j$.



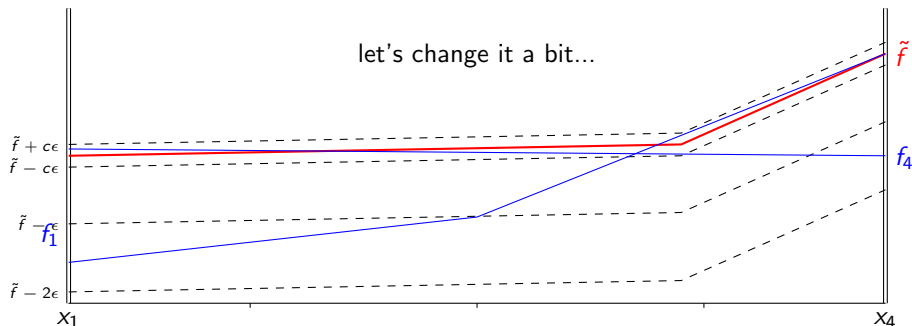
Upper bounds – IR bound in 1-D

Proof sketch:(proof by contradiction)

- Fix $k = 4, c \approx 1/16$, suppose that

$$\forall j \neq l \in [4], \quad |f_j(x_{f_l}) - \tilde{f}(x_{f_l})| \leq c\epsilon_i.$$

- f_j needs to be close to \tilde{f} , at minimizers x_{f_l} (double lines $||$) for $l \neq j$.



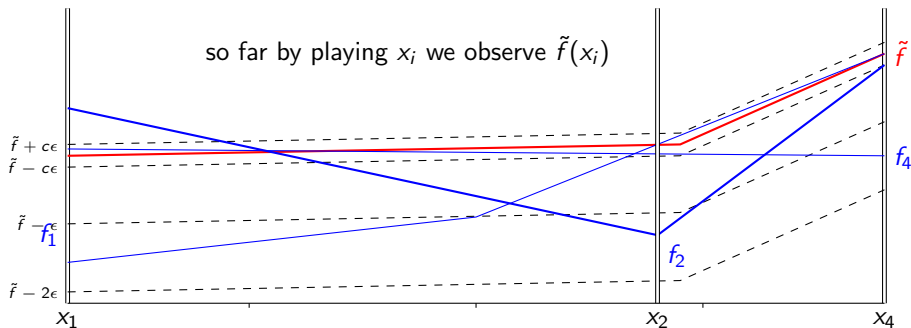
Upper bounds – IR bound in 1-D

Proof sketch:(proof by contradiction)

- Fix $k = 4, c \approx 1/16$, suppose that

$$\forall j \neq l \in [4], \quad |f_j(x_{f_l}) - \tilde{f}(x_{f_l})| \leq c\epsilon_i.$$

- f_j needs to be close to \tilde{f} , at minimizers x_{f_l} (double lines $||$) for $l \neq j$.



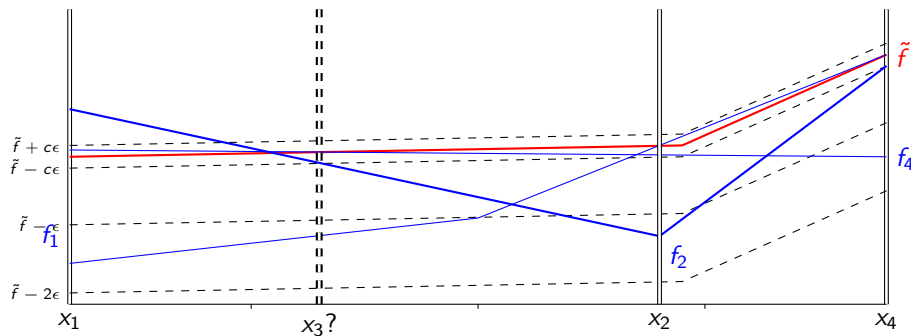
Upper bounds – IR bound in 1-D

Proof sketch:(proof by contradiction)

- Fix $k = 4, c \approx 1/16$, suppose that

$$\forall j \neq l \in [4], \quad |f_j(x_{f_l}) - \tilde{f}(x_{f_l})| \leq c\epsilon_i.$$

- f_j needs to be close to \tilde{f} , at minimizers x_{f_l} (double lines $||$) for $l \neq j$.

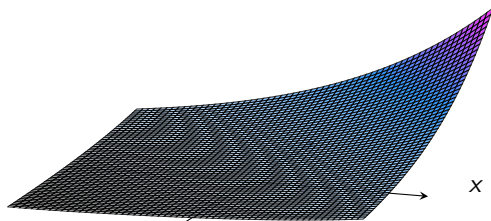


Upper bounds – IR bound in d-D

Theorem 7 – IR bound in d-D

$(\alpha, \beta \lceil \log(1/\alpha) \rceil) \in \text{IR}(\mathcal{F}_{\text{blrm}})$ whenever $\alpha \in (0, 1)$ and

$$\text{BReg}^{\text{TS}}(\mathcal{F}_{\text{blrm}}) = \tilde{O}(d^{2.5} \sqrt{n}).$$



$f(x, y) = e^{x+y}$ — a convex ridge function with $\theta = (1, 1)$ and $\ell(t) = e^t$.

Lower bounds – main results

The following lower bounds share the same construction.

Lower Bound 4

When $\mathcal{K} = \mathbb{B}_1 \subset \mathbb{R}^d$, there exists a prior ξ on $\mathcal{F}_{\mathbb{B}_1}$ such that

$$\text{BReg}_n(\text{TS}) \geq \frac{1}{2} \min\left\{n, \frac{1}{4} e^{\Omega(d/32)}\right\}.$$

Lower Bound 2

Suppose that $\mathcal{K} = \mathbb{B}_1 \subset \mathbb{R}^d$ and $d > 256$. Then there exists a prior ξ on $\mathcal{F}_{\mathbb{B}_1}$ such that

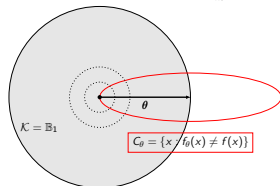
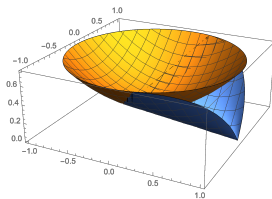
$$\Delta(\pi, \xi) \geq 2^{-19} \frac{d}{\log(d)} \sqrt{\mathcal{I}(\pi, \xi)},$$

for all policies π on \mathcal{K} .

Lower bound 2 shows that for general convex losses in \mathbb{R}^d the **classical info-ratio machinery** cannot give regret better than the known $\tilde{O}(d^{1.5} \sqrt{n})$.

Lower bounds – construction

- Idea:
 - 1 All $f_\theta \sim \xi$ are mostly equal to a fixed f on \mathbb{B}_1 .
 - 2 Uniform prior and no noise!
- TS lower bound:
 - 1 TS plays on the “perimeter” \mathbb{S}_1 where the minimizers are.
 - 2 Suffers constant regret for $\exp(d)$ rounds.
- IR lower bound:
 - 1 Radial symmetry.
 - 2 Optimize for r in $\frac{\Delta(r)^2}{\mathcal{I}(r)}$:
 - 1 Closer to 0, **very low inf.** with **good prob.**
 - 2 Closer to \mathbb{S}_1 , **high inf.** with **very low prob.**



- **Goal:** Understand how **Thompson Sampling (TS)** behaves in **bandit convex optimization (BCO)**.
- **Positive:**
 - $\text{BReg}_n(\text{TS}) = \tilde{O}(\sqrt{n})$ in 1 -D convex bandits.
 - $\text{BReg}_n(\text{TS}) = \tilde{O}(d^{2.5}\sqrt{n})$ for d -D *monotone convex ridge* losses.
- **Negative:**
 - TS can suffer $\Omega(\exp(d))$ regret for general d -D convex losses.
 - Classical info-ratio tricks \Rightarrow no better than $\tilde{O}(d^{1.5}\sqrt{n})$ for general stochastic & adversarial BCO.

Thanks!