

Statistical Foundations of Learning

Debarghya Ghoshdastidar

School of Computation, Information and Technology
Technical University of Munich

ERM over finite hypothesis classes

Outline

- Empirical risk minimisation: Overfitting if we optimise over all h
- Hypothesis class \mathcal{H} : Examples and ERM over \mathcal{H}
- Assume \mathcal{H} is a finite set
 - We will derive a generalisation error bound for ERM solution \hat{h}

$$L_{\mathcal{D}}^* \leq \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) \leq L_{\mathcal{D}}(\hat{h}) \leq \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \sqrt{\frac{2 \ln(|\mathcal{H}|) + c}{m}}$$

$\ln(\cdot)$ = natural logarithm, c = some additional term

Empirical risk minimisation

- Empirical risk (training error) of predictor h :

$$L_S(h) = \frac{1}{m} \sum_{i=1}^m \ell(h(x), y)$$

- $L_S(h)$ is estimate of the generalisation error $L_{\mathcal{D}}(h)$ $\mathbb{E}_S[L_S(h)] = L_{\mathcal{D}}(h)$
- Empirical risk minimisation (ERM): $\underset{h \in \mathcal{Y}^{\mathcal{X}}}{\text{minimise}} L_S(h)$
 - Proxy for minimising $L_{\mathcal{D}}(h)$
 - ERM solution \hat{h} has small $L_S(\hat{h})$, but may have high $L_{\mathcal{D}}(\hat{h})$

Understanding the failure of ERM

- Example of ERM solution (learning by memorisation):

$$h_{mem}(x) = \begin{cases} 1 & \text{if } (x, 1) \in S \\ 0 & \text{otherwise} \end{cases}$$

- Recall h_{mem} can be poor solution if $|\mathcal{X}| \gg m$

$$L_S(h_{mem}) = 0 \quad \text{but} \quad L_{\mathcal{D}}(h_{mem}) \text{ can be large}$$

- Question: Recall that we stated $\mathbb{E}_S[L_S(h)] = L_{\mathcal{D}}(h)$
 - Why is the same not true for h_{mem} ?

Understanding the failure of ERM

- Why is the *memorised* solution poor?
 - h_{mem} overfits the training sample S
 - Search space $\mathcal{Y}^{\mathcal{X}}$ has all functions (including complex ones that overfit)
- Solution: Reduce the search space to some $\mathcal{H} \subset \mathcal{Y}^{\mathcal{X}}$
 - \mathcal{H} is called hypothesis class / concept class
 - Example: Linear classifiers, decision stumps
 - Decision stumps over $\mathcal{X} = \mathbb{R}$

$$\mathcal{H} = \{b \cdot \text{sign}(t - x) : t \in \mathbb{R}, b \in \{\pm 1\}\} \subset \{-1, 1\}^{\mathbb{R}}$$



How good can ERM solution be?

- ERM over \mathcal{H} : minimise $L_S(h)$
 $h \in \mathcal{H}$
- Recall: Our goal is to find h with small $L_{\mathcal{D}}(h)$
- Smallest generalisation error we can have from ERM: $L_{\mathcal{D}}(\mathcal{H}) := \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h)$
- Smallest possible generalisation error (Bayes risk): $L_{\mathcal{D}}^* := \min_{h \in \mathcal{Y}^{\mathcal{X}}} L_{\mathcal{D}}(h)$
- Let \hat{h} be the solution of ERM over \mathcal{H}

$$L_{\mathcal{D}}(\hat{h}) \geq L_{\mathcal{D}}(\mathcal{H}) \geq L_{\mathcal{D}}^*$$

How good can ERM solution be?

- How much worse is $L_{\mathcal{D}}(\hat{h})$ compared to $L_{\mathcal{D}}^*$?

$$L_{\mathcal{D}}(\hat{h}) - L_{\mathcal{D}}^* = \underbrace{L_{\mathcal{D}}(\mathcal{H}) - L_{\mathcal{D}}^*}_{\substack{\text{approximation error} \\ \text{or, inductive bias}}} + \underbrace{L_{\mathcal{D}}(\hat{h}) - L_{\mathcal{D}}(\mathcal{H})}_{\text{estimation error}}$$

- This decomposition is true for any learning paradigm

$$\hat{h} = \arg \min_{h \in \mathcal{H}} J(h)$$

$$J(h) = L_S(h) \text{ for ERM}$$

Approximation error / Inductive bias

$$L_{\mathcal{D}}(\hat{h}) - L_{\mathcal{D}}^* = \underbrace{L_{\mathcal{D}}(\mathcal{H}) - L_{\mathcal{D}}^*}_{\substack{\text{approximation error} \\ \text{or, inductive bias}}} + \underbrace{L_{\mathcal{D}}(\hat{h}) - L_{\mathcal{D}}(\mathcal{H})}_{\text{estimation error}}$$

- Minimum error that occurs because we restrict our search to \mathcal{H}
- Inductive bias = Bias induced by making model assumptions (\mathcal{H} is linear classifier)
- Cannot be controlled by learning algorithm
- Bias decreases if \mathcal{H} is increased

$$\mathcal{H} \subset \mathcal{H}' \quad \implies \quad L_{\mathcal{D}}(\mathcal{H}) - L_{\mathcal{D}}^* \geq L_{\mathcal{D}}(\mathcal{H}') - L_{\mathcal{D}}^*$$

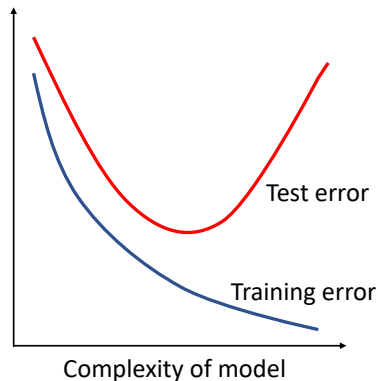
Estimation error

$$L_{\mathcal{D}}(\hat{h}) - L_{\mathcal{D}}^* = \underbrace{L_{\mathcal{D}}(\mathcal{H}) - L_{\mathcal{D}}^*}_{\substack{\text{approximation error} \\ \text{or, inductive bias}}} + \underbrace{L_{\mathcal{D}}(\hat{h}) - L_{\mathcal{D}}(\mathcal{H})}_{\text{estimation error}}$$

- Error of \hat{h} with respect to best possible $h \in \mathcal{H}$
- Could be controlled by learning algorithm
- Estimation error for ERM typically increases if \mathcal{H} is larger

Overfitting and underfitting / Bias-variance trade-off

- What happens if we increase \mathcal{H} ?
 - Allow \mathcal{H} to have more complex predictors
 - Linear classifier \rightarrow Quadratic decision boundary $\rightarrow \dots$
- Bias reduces \implies training error reduces (overfitting)
Estimation error increases
- Test error / generalisation error:
 - Large for small \mathcal{H} due to large bias (underfitting)
 - Large for large \mathcal{H} as estimation error high (overfitting)



Generalisation error bound

- \hat{h} or $\hat{h}_{ERM} = \arg \min_{h \in \mathcal{H}} L_S(h)$

- How good (or bad) is the generalisation error of \hat{h} ?

$$L_{\mathcal{D}}^* \leq L_{\mathcal{D}}(\mathcal{H}) \leq L_{\mathcal{D}}(\hat{h}) \leq ??$$

- To derive an upper bound, assume \mathcal{H} is finite

- Two settings:

- Simple: No randomness in label, $y = h_0(x)$ for some $h_0 \in \mathcal{H}$

- General: Random label, $(x, y) \sim \mathcal{D}$... also includes $y = h_0(x)$ where $h_0 \notin \mathcal{H}$

Bound on generalisation error: Simple case

$$y = h_0(x) \text{ with } h_0 \in \mathcal{H} \quad \implies \quad L_{\mathcal{D}}(\mathcal{H}) = \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) = 0 \text{ and } L_S(\hat{h}) = \min_{h \in \mathcal{H}} L_S(h) = 0$$

Theorem ERMH.1 (Generalisation error bound in simple case)

Assume \mathcal{H} is finite, $\ell = 0$ -1 loss and $\hat{h} = \text{ERM solution}$

$$\text{For } \epsilon \in (0, 1), \quad \mathbb{P}_{S \sim \mathcal{D}^m} \left(L_{\mathcal{D}}(\hat{h}) > \epsilon \right) \leq |\mathcal{H}| e^{-m\epsilon}$$

Equivalent statement:

$$\text{For } \delta \in (0, 1), \quad \mathbb{P}_{S \sim \mathcal{D}^m} \left(L_{\mathcal{D}}(\hat{h}) > \frac{\ln(|\mathcal{H}|) + \ln(\frac{1}{\delta})}{m} \right) \leq \delta$$

Equivalent statement:

$$\text{For } \delta \in (0, 1), \quad L_{\mathcal{D}}(\hat{h}) \leq \frac{\ln(|\mathcal{H}|) + \ln(\frac{1}{\delta})}{m} \quad \text{with probability } \geq 1 - \delta$$

The above result in simple words

- Set $\delta = 0.01 \implies \ln(\frac{1}{\delta}) = 4.6 < 5$
- Consider T independent runs of following thought experiment (T is large)
 - Sample $S \sim \mathcal{D}^m$, and solve ERM to get \hat{h}
 - Compute $L_{\mathcal{D}}(\hat{h})$ (equivalently, compute test error on infinitely many samples)
- Out of T runs: $L_{\mathcal{D}}(\hat{h}) \leq \frac{\ln(|\mathcal{H}|) + 5}{m}$ holds in $0.99T$ runs
- If we have only one run (typical happens in practice):
 - The bound will typically be true

Equivalence of the three statements

- Verify 3^{rd} statement is rephrasing of 2^{nd}
- Try getting 2^{nd} statement from 1^{st}
- Solution: Set $\delta = |\mathcal{H}|e^{-m\epsilon}$, and write ϵ in terms of δ
- Due to equivalence, we prove only the first statement

Proof of generalisation error bound

$$\mathbb{P}_{S \sim \mathcal{D}^m} \left(L_{\mathcal{D}}(\hat{h}) > \epsilon \right) \leq |\mathcal{H}| e^{-m\epsilon}$$

Let $\mathcal{H}_{bad} = \{h \in \mathcal{H} : L_{\mathcal{D}}(h) > \epsilon\}$

$$L_{\mathcal{D}}(\hat{h}) > \epsilon \implies \hat{h} \in \mathcal{H}_{bad} \implies \text{there is } h \in \mathcal{H}_{bad} \text{ such that } L_S(h) = 0$$

Try to write above in terms of events and their probabilities

$$\begin{aligned} \mathbb{P}_{S \sim \mathcal{D}^m} \left(L_{\mathcal{D}}(\hat{h}) > \epsilon \right) &\leq \mathbb{P}_{S \sim \mathcal{D}^m} \left(\text{there is } h \in \mathcal{H}_{bad} \text{ such that } L_S(h) = 0 \right) \\ &\leq \mathbb{P}_{S \sim \mathcal{D}^m} \left(\bigcup_{h \in \mathcal{H}_{bad}} \{L_S(h) = 0\} \right) \end{aligned}$$

Proof: Union bound

Recall for events A, B : $\mathbb{P}(A \cup B) \leq \mathbb{P}(A) + \mathbb{P}(B)$

Using above,
$$\mathbb{P}_{S \sim \mathcal{D}^m} \left(\bigcup_{h \in \mathcal{H}_{bad}} \{L_S(h) = 0\} \right) \leq \sum_{h \in \mathcal{H}_{bad}} \mathbb{P}_{S \sim \mathcal{D}^m} (L_S(h) = 0)$$

Proof: Independence of training samples

Recall for independent events A, B : $\mathbb{P}(A \cap B) \leq \mathbb{P}(A) \cdot \mathbb{P}(B)$

Bounding $\mathbb{P}_{S \sim \mathcal{D}^m}(L_S(h) = 0)$ for $h \in \mathcal{H}_{bad}$

$$L_S(h) = 0 \quad \implies \quad \ell(h(x_i), y_i) = 0 \text{ for every } (x_i, y_i) \in S$$

Hence

$$\begin{aligned} \mathbb{P}_{S \sim \mathcal{D}^m}(L_S(h) = 0) &= \mathbb{P}_{S \sim \mathcal{D}^m} \left(\bigcap_{i=1}^m \{\ell(h(x_i), y_i) = 0\} \right) \\ &= \prod_{i=1}^m \mathbb{P}_{(x_i, y_i) \sim \mathcal{D}}(\ell(h(x_i), y_i) = 0) \end{aligned}$$

Proof: ℓ is 0-1 loss

$\ell(h(x_i), y_i)$ is Bernoulli with

$$\begin{aligned}\mathbb{P}_{(x_i, y_i) \sim \mathcal{D}}(\ell(h(x_i), y_i) = 1) &= \mathbb{P}_{(x, y) \sim \mathcal{D}}(h(x) \neq y) \\ &= L_{\mathcal{D}}(h) \\ &> \epsilon\end{aligned}$$

... for $h \in \mathcal{H}_{bad}$

Thus, $\mathbb{P}_{(x_i, y_i) \sim \mathcal{D}}(\ell(h(x_i), y_i) = 0) \leq 1 - \epsilon$

Proof: Final steps

$$\begin{aligned}\mathbb{P}_{S \sim \mathcal{D}^m} \left(L_{\mathcal{D}}(\hat{h}) > \epsilon \right) &\leq \sum_{h \in \mathcal{H}_{bad}} \mathbb{P}_{S \sim \mathcal{D}^m} (L_S(h) = 0) && \dots \text{ union bound} \\ &\leq \sum_{h \in \mathcal{H}_{bad}} \prod_{i=1}^m \mathbb{P}_{(x_i, y_i) \sim \mathcal{D}} (\ell(h(x_i), y_i) = 0) && \dots \text{ independent samples} \\ &\leq \sum_{h \in \mathcal{H}_{bad}} (1 - \epsilon)^m \\ &= |\mathcal{H}_{bad}| (1 - \epsilon)^m \\ &\leq |\mathcal{H}| (1 - \epsilon)^m && \dots \text{ since } \mathcal{H}_{bad} \subset \mathcal{H} \\ &\leq |\mathcal{H}| e^{-m\epsilon} && \dots 1 - \epsilon \leq e^{-\epsilon} \text{ for all } \epsilon\end{aligned}$$

General case: True labels can be random

We use the following result to derive a generalisation error bound

Theorem ERMH.2 (Uniform convergence of $L_S(\cdot)$ for finite \mathcal{H})

Let $\epsilon \in (0, 1)$, $\mathcal{H} \subset \{-1, +1\}^{\mathcal{X}}$ and we measure risk with respect to 0-1 loss.

$$\mathbb{P}_{S \sim \mathcal{D}^m} \left(\max_{h \in \mathcal{H}} |L_S(h) - L_{\mathcal{D}}(h)| > \epsilon \right) \leq 2|\mathcal{H}|e^{-2m\epsilon^2}$$

Equivalent statement: Let $\delta \in (0, 1)$. With probability $\geq 1 - \delta$,

$$\max_{h \in \mathcal{H}} |L_S(h) - L_{\mathcal{D}}(h)| \leq \sqrt{\frac{\ln(|\mathcal{H}|) + \ln(\frac{2}{\delta})}{2m}}$$

Generalisation error from uniform convergence

\hat{h} = solution of ERM

With probability at least $1 - \delta$, the following hold simultaneously:

$$\begin{aligned} L_{\mathcal{D}}(\hat{h}) - L_S(\hat{h}) &\leq \sqrt{\frac{\ln(|\mathcal{H}|) + \ln(\frac{2}{\delta})}{2m}} \\ L_S(h) - L_{\mathcal{D}}(h) &\leq \sqrt{\frac{\ln(|\mathcal{H}|) + \ln(\frac{2}{\delta})}{2m}} \quad \text{for every } h \in \mathcal{H} \end{aligned}$$

Using above, we can show following generalisation error bound

$$L_{\mathcal{D}}(\hat{h}) \leq L_{\mathcal{D}}(\mathcal{H}) + \sqrt{\frac{2 \ln(|\mathcal{H}|) + 2 \ln(\frac{2}{\delta})}{m}} \quad \text{with probability } 1 - \delta$$

Generalisation error from uniform convergence

With probability $1 - \delta$,

$$\begin{aligned}L_{\mathcal{D}}(\hat{h}) &\leq L_S(\hat{h}) + \sqrt{\frac{\ln(|\mathcal{H}|) + \ln(\frac{2}{\delta})}{2m}} \\&= \min_{h \in \mathcal{H}} L_S(h) + \sqrt{\frac{\ln(|\mathcal{H}|) + \ln(\frac{2}{\delta})}{2m}} && \dots \hat{h} \text{ minimises } L_S(h) \\&\leq \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + 2\sqrt{\frac{\ln(|\mathcal{H}|) + \ln(\frac{2}{\delta})}{2m}} && \dots 2^{nd} \text{ statement of previous slide} \\&= L_{\mathcal{D}}(\mathcal{H}) + \sqrt{\frac{2 \ln(|\mathcal{H}|) + 2 \ln(\frac{2}{\delta})}{m}}\end{aligned}$$

Uniform convergence of empirical risk

Theorem ERMH.3 (Uniform convergence of $L_S(\cdot)$ for finite \mathcal{H})

Let $\epsilon \in (0, 1)$, $\mathcal{H} \subset \{-1, +1\}^{\mathcal{X}}$ and we measure risk with respect to 0-1 loss.

$$\mathbb{P}_{S \sim \mathcal{D}^m} \left(\max_{h \in \mathcal{H}} |L_S(h) - L_{\mathcal{D}}(h)| > \epsilon \right) \leq 2|\mathcal{H}|e^{-2m\epsilon^2}$$

- We prove above statement
- Earlier slide mentioned an equivalent statement
 - Verify that they are equivalent

Two useful probability inequalities

Theorem ERMH.4 (Tail bound for maximum (consequence of union bound))

Let Z_1, \dots, Z_n be n random variables.

$$\mathbb{P}\left(\max_{1 \leq i \leq n} Z_i > \epsilon\right) \leq \sum_{i=1}^n \mathbb{P}(Z_i > \epsilon)$$

Theorem ERMH.5 (Hoeffding's inequality)

Let Z_1, \dots, Z_n be n independent random variables such that $\mathbb{P}(Z_i \in [a_i, b_i]) = 1$ for all i .

$$\mathbb{P}\left(\left|\sum_{i=1}^n (Z_i - \mathbb{E}[Z_i])\right| > \epsilon\right) \leq 2 \exp\left(-\frac{2\epsilon^2}{\sum_{i=1}^n (b_i - a_i)^2}\right)$$

Try to prove uniform convergence using above

Proof of uniform convergence

$$\begin{aligned} & \mathbb{P}_{S \sim \mathcal{D}^m} \left(\max_{h \in \mathcal{H}} |L_S(h) - L_{\mathcal{D}}(h)| > \epsilon \right) \\ & \leq \sum_{h \in \mathcal{H}} \mathbb{P}_{S \sim \mathcal{D}^m} (|L_S(h) - L_{\mathcal{D}}(h)| > \epsilon) && \dots \text{ union bound} \\ & \leq \sum_{h \in \mathcal{H}} \mathbb{P}_{S \sim \mathcal{D}^m} \left(\frac{1}{m} \left| \sum_{i=1}^m \left(\ell(h(x_i), y_i) - L_{\mathcal{D}}(h) \right) \right| > \epsilon \right) && \dots \text{ definition of } L_S(h) \\ & \leq \sum_{h \in \mathcal{H}} \mathbb{P}_{S \sim \mathcal{D}^m} \left(\frac{1}{m} \left| \sum_{i=1}^m \left(\ell(h(x_i), y_i) - \mathbb{E}[\ell(h(x_i), y_i)] \right) \right| > \epsilon \right) && \dots \text{ definition of } L_{\mathcal{D}}(h) \\ & = \sum_{h \in \mathcal{H}} \mathbb{P}_{S \sim \mathcal{D}^m} \left(\left| \sum_{i=1}^m \left(Z_i - \mathbb{E}[Z_i] \right) \right| > m\epsilon \right) && \dots \text{ define } Z_i = \ell(h(x_i), y_i) \end{aligned}$$

Use Hoeffding's inequality noting that Z_1, \dots, Z_m independent with $Z_i \in [0, 1]$