S&DS 355 / 365 / 565 Data Mining and Machine Learning

Bias, Variance and Cross Validation

Tuesday, September 17th

Outline

- Finish off SGD
- Bias/variance redux
- Cross validation

SGD for general loss

SGD update:

$$\beta \longleftarrow \beta - \eta \nabla L(y, \beta^T x)$$
$$\beta_j \longleftarrow \beta_j - \eta \frac{\partial L(y, \beta^T x)}{\partial \beta_j}$$

- η is the *learning rate* or "step size"
- Needs to be chosen carefully, getting smaller over time

SGD: choice of learning rate

A conservative choice of learning rate is

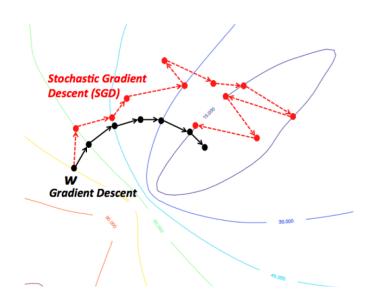
$$\eta_t = \frac{1}{t}$$

A more agressive choice is

$$\eta_t = \frac{1}{\sqrt{t}}$$

Which is more appropriate for GD? Which is more appropriate for SGD?

Diagramatic Differences



SGD: choice of learning rate

Learning rate should scale as

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Problem: Some of the updates may be on different scales.

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Solution: Let
$$g_{tj} = \frac{\partial L(y_t, \beta^T x_t)}{\partial \beta_j}$$

Scale gradients to get update rule

$$\beta_j \longleftarrow \beta_j - \eta \frac{g_{tj}}{\sqrt{\sum_{s=1}^t g_{sj}^2}}$$

SGD: scaling issues

For a linear model, the SGD update is

$$\beta_j \longleftarrow \beta_j - C_t x_j$$

If x_j increases by a factor of two, the weight β_j should decrease by a factor of two.

This update doesn't respect that scaling

SGD: scaling issues

Usual solution is to "standardize" each variable — subtract out the mean and divide by the standard deviation

$$x_j \leftarrow \frac{x_j - \mathsf{mean}(x_j)}{\sqrt{\mathsf{var}(x_j)}}$$

But this involves "looking ahead" to compute the mean and variance, and destroys the online property of the algorithm

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Solution: The mean and variance can be updated in an online manner, in constant time, by storing auxiliary variables for each component j.

SGD: Regularization

A "ridge" penalty $\lambda \sum_{j=1}^{d} \beta_{j}^{2}$ is easily handled.

Gradient changes by an additive term $2\lambda\beta_i$. Update becomes

$$\beta_{j} \leftarrow \beta_{j} + \eta \{ (y - \pi)x_{j} - \lambda \beta_{j} \}$$

$$= (1 - \eta \lambda)\beta_{j} + \eta (y - \pi)x_{j}$$

$$\beta_{j}x_{j} \leftarrow (1 - \eta \lambda)\beta_{j}x_{j} + \eta (y - \pi)x_{j}^{2}$$

Observe that this "does the right thing" whether β_j wants to be large positive or negative.

• The penalty shrinks β_i toward zero

Batch GD vs. SGD

- In a "batch" algorithm, we compute the exact gradient by summing over the entire training set
- In a "stochastic" algorithm, we tolerate noise in the estimate of the gradient, in exchange for speed
- Could also compute the gradient over "mini batches"
- Note: SGD is (apparently) difficult to parallelize

SGD: Linear regression

Batch gradient descent update step (using all $\{(x_i, y_i)\}_{i=1}^n$ observations):

$$\beta_j \leftarrow \beta_j + \rho \sum_{i=1}^n (y_i - x_i^t \beta) x_{ij}.$$

Stochastic gradient descent update (using a single observation (x, y)):

$$\beta_j \leftarrow \beta_j + \rho(y - x^t \beta) x_j.$$

SGD: Linear regression

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Stochastic gradient descent update (using a single observation (x, y)):

$$\beta_j \leftarrow \beta_j + \rho(y - x^t \beta) x_j.$$

Equivalently,

$$\beta_j \leftarrow \beta_j + \rho(y - \widehat{y})x_j.$$

SGD: Linear regression

$$\beta_j \leftarrow \beta_j + \rho(y - \widehat{y})x_j$$
.

In words:

- Initialize all coefficients β_j to 0.
- For observation x:
 - ▶ Predict $\hat{y} = x^t \beta$.
 - Observe true response y.
 - Update β so that \hat{y} is closer to y.

Stochastic Gradient Descent

Key points:

- Randomize data beforehand
- ρ (the learning rate) needs to be selected in a way that decreases with time
 - ightharpoonup e.g. $ho_t = rac{1}{t}$, $ho_t = rac{1}{\sqrt{t}}$
- Scaling data can ensure that variance of variables don't interfere

$$x_j \leftarrow \frac{x_j - \mathsf{mean}(x_j)}{\sqrt{\mathsf{var}(x_j)}}$$

 Takes a windier path, and may not actually converge to the global minimum.

For purposes of prediction, minimizing test error is priority.

Recall our two error metrics for evaluating predictions $\hat{f}(x_i)$:

Regression:

$$MSE = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{f}(x_i))^2$$

Classification:

$$Err = \frac{1}{n} \sum_{i=1}^{n} \mathbb{1} \left\{ \widehat{f}(x_i) \neq y_i \right\}$$

Bias-Variance Tradeoff

(Regression case)

Given $Y = f(X) + \epsilon$, where $E(\epsilon) = 0$ and $Var(\epsilon) = \sigma^2$, consider a predictor \hat{f} .

Expected MSE for predicting a new Y at X = x can be decomposed into:

$$E[(Y - \widehat{f}(x))^{2}] = Var(\widehat{f}(x)) + [Bias(\widehat{f}(x))]^{2} + \sigma^{2}$$

Bias-Variance Tradeoff

$$E[(Y - \hat{f}(x))^2] = Var(\hat{f}(x)) + [Bias(\hat{f}(x))]^2 + \sigma^2$$

- $Var(\hat{t})$ is the amount of variability in our predictor with different training set.
- $Bias(\hat{f})$ is the systematic error introduced by model approximation.
- σ^2 is *irreducible error*, inherent in the error term ϵ .

Bias-Variance Tradeoff

$$E[(Y - \hat{f}(x))^2] = Var(\hat{f}(x)) + [Bias(\hat{f}(x))]^2 + \sigma^2$$

- $Var(\hat{t})$ is the amount of variability in our predictor with different training set. Increases with increasing model flexibility.
- Bias(f) is the systematic error introduced by model approximation. Decreases with increasing model flexibility.
- σ^2 is *irreducible error*, inherent in the error term ϵ . Cannot get rid of this!

Need to balance bias and variance.

Bias-Variance

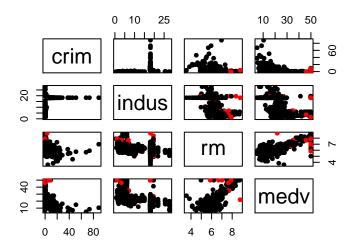
How does this apply to the *k*-NN algorithm?

Cross-Validation

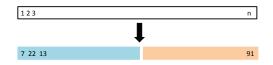
Cross-validation is an intuitive, widely-applicable approach for:

- model assessment
- model selection

Example: Boston Housing



We've been doing this:



- 1 Divide dataset randomly into a training set and a validation set.
- 2 Fit the model on the training set.
- Use the validation set to obtain estimated test error.
- 4 Repeat!

```
set.seed(365)
train <- sample(1:nrow(Boston), nrow(Boston)/2, replace=FALSE)
test <- Boston[-train,]
train <- Boston[train,]
m1 <- lm(medv ~ lstat, data=train)
p1 <- predict(m1, test)</pre>
```

Example:

$$\widehat{medv} = \widehat{\beta}_0 + \widehat{\beta}_1 Istat$$

Estimated test error:

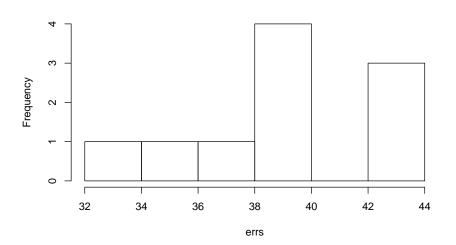
```
mean((p1 - test$medv)^2)
## [1] 43.57431
```

Repeat x 10:

```
set.seed(665)
errs <- rep(NA, 10)
for (i in 1:10) {
  train <- sample(1:nrow(Boston), nrow(Boston)/2, replace=FALSE)
  test <- Boston[-train,]
  train <- Boston[train,]
  m1 <- lm(medv ~ lstat, data=train)
  summary(m1)
  p1 <- predict(m1, test)
  errs[i] <- mean((p1 - test$medv)^2)
}</pre>
```

Histogram of errors

hist(errs, main="")



- highly variable validation error
- only uses a fraction of the training set

How do we use more data to train with?

- Use a tiny validation set (e.g. (x_1, y_1))
- Train with the rest (e.g. $\{(x_2, y_2), \dots, (x_n, y_n)\}\)$

How do we feel about error rate evaluated on a single observation?

How do we use more data to train with?

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How do we feel about error rate evaluated on a single observation?

Not good, but we can iterate through the dataset, each time using a different (x_i, y_i) as the validation set and obtaining an error MSE_i .

	Iteration						
Obs	1	2	3	4		n	
1	valid	train	train	train		train	
2	train	valid	train	train		train	
3	train	train	valid	train		train	
4	train	train	train	valid		train	
	• • •	• • •	• • •	• • •	• • •		
n	train	train				valid	
MSE	MSE ₁	MSE ₂	MSE ₃	MSE ₄		MSE _n	

LOOCV estimate of test error is given by:

$$CV_{(n)} = \frac{1}{n} \sum_{i} MSE_{i}$$

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For our example, a single number:

```
## 1
## 38.8901
```

A potentially faster approach:

- Randomly divide the dataset into k folds.
- For b = 1, ..., k:
 - Use b-th fold ("batch") as validation set.
 - Use everything else as training set.
 - Compute validation error on b-th fold.
- Estimate test error using:

$$CV_{(k)} = \sum_{b} \frac{n_b}{n} MSE_b,$$

where n_b is the total # observations in the b-th fold, and n is the total # observations in the entire dataset.

Iteration						
Obs	1	2	3	4		k
1	valid	train	train	train		train)
2	valid	train	train	train		train $fold 1$
3	valid	train	train	train		train J
4	train	valid	train	train		train
n – 2	train	train				valid)
<i>n</i> − 1	train	train				$\frac{\text{valid}}{\text{valid}}$ fold v
n	train	train				valid)
MSE	MSE₁	MSE ₂	MSE ₃	MSE ₄		MSE_k

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4	train	valid	train	train		train	
<i>n</i> − 2	train	train				valid)	
<i>n</i> − 1	train	train				$\frac{\text{valid}}{\text{old}}$ fold v	
n	train	train				valid)	
MSE	MSE ₁	MSE ₂	MSE ₃	MSE ₄		MSE_k	

n-fold CV is just LOOCV.

Running k = 5 and k = 10:

```
set.seed(665)
kvals <-c(5, 10)
errs <- rep(0, length(kvals))
z <- Boston[sample(1:nrow(Boston)),]</pre>
for (j in 1:length(kvals)) {
  k <- kvals[i]
  folds <- as.numeric(cut(1:nrow(z), k))</pre>
  for (i in 1:k) {
    train <- z[folds != i,]
    valid \leftarrow z[folds == i,]
    m1 <- lm (medv ~ lstat, data=train)
    p1 <- predict (m1, test)
    errs[i] <- errs[i] +
         sum(folds==i)/nrow(z) *mean((p1-test$medv)^2)
errs[1]/nrow(z)
## [1] 0.4546264
```

Estimated error for k = 5 and k = 10:

```
errs[1]/nrow(z)
## [1] 0.4546264
errs[2]/nrow(z)
## [1] 0.4546724
```

A slick shortcut

Suppose that the fitted values can be written $\widehat{Y} = LY$ where L is an $n \times n$ matrix.

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Then the leave-one-out-cross-validation error is

$$R_{LOO} = \frac{1}{n} \sum_{i=1}^{n} (Y_i - \widehat{Y}_{(-i)})^2$$
$$\frac{1}{n} \sum_{i=1}^{n} \left(\frac{Y_i - \widehat{Y}_i}{1 - L_{ii}} \right)^2$$

where L_{ii} is the *i*th diagonal entry.

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So, no need to fit n regressions!

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Suppose we are interested in comparing the following 3 models:

Model 1:

$$\widehat{\textit{medv}} = \widehat{\beta}_0 + \widehat{\beta}_1 \textit{lstat}$$

Model 2:

$$\widehat{\log(medv)} = \widehat{\beta}_0 + \widehat{\beta}_1 \operatorname{Istat}$$

Model 3:

$$\widehat{\textit{medv}} = \widehat{\beta}_0 + \widehat{\beta}_1 \textit{lstat} + \widehat{\beta}_2 \textit{lstat}^2$$

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Model 3:

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We can use cross-validation to estimate the test error for each of these models, and select the model with the lowest test error.

What did we learn today?

- Cross validation is a practical way of estimating the variability of test error. Used for model selection.
- Leave-one-out CV is the most important version of CV. Has a shortcut formula.