

ANN (APPROXIMATE NEAREST NEIGHBOR)

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INTRODUCTION



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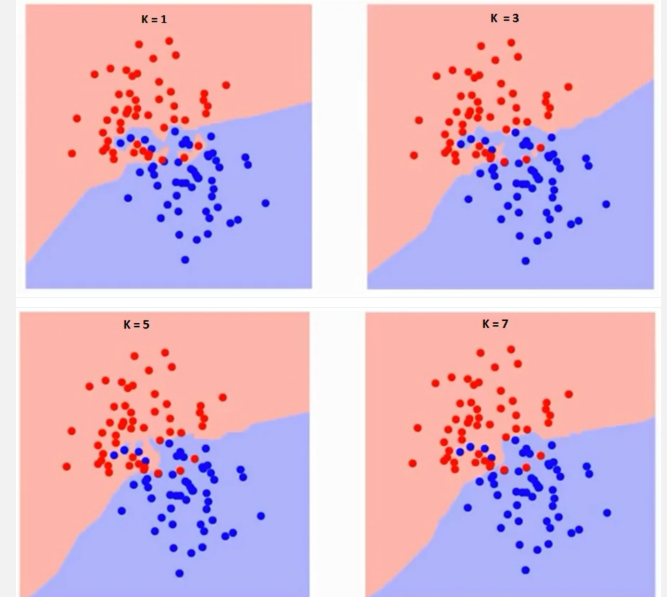
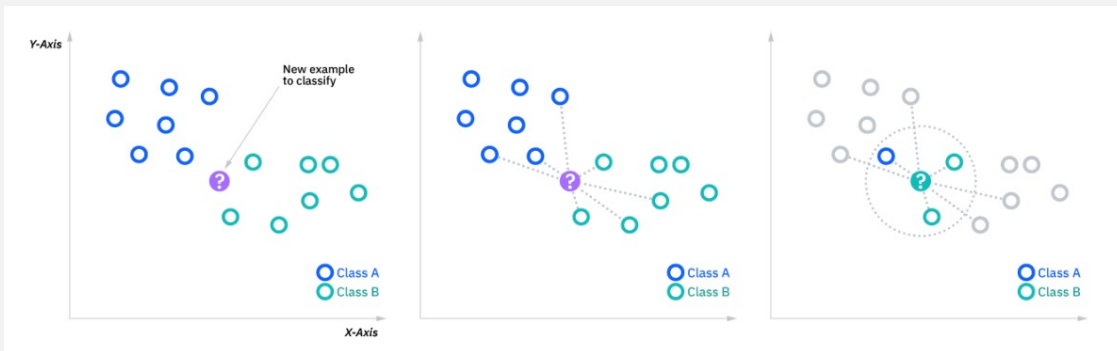
- Nearest Neighbors Motivation
 - What is KNN?
 - What is ANN?
 - KNN vs. ANN

KNN



ALGORITHM

- Non-parametric
- Supervised classifier
- How does it work? (lazy learning)
- Choosing the right K





PROS & CONS

PROS

- Easy to implement
 - Adapts easily
- Few hyperparameters

CONS

- Highly time consuming (single query = $O(N)$)
- Does not scale well (specific DS : 'ball-tree')
- Curse of dimensionality
 - Prone to overfit



ANN



ANN

- Basic intuition
 - Much faster – each query = $O(\log N)$
 - Trade off between accuracy & time
 - KNN is not really an option to consider
 - Different implementations such as:
 1. Facebook's PySparseNN (for sparse interaction matrices)
 2. Spotify's annoy (Approximate nearest neighbor, Oh YEAH)

HOW DOES IT WORK?



HOW DOES IT WORK?

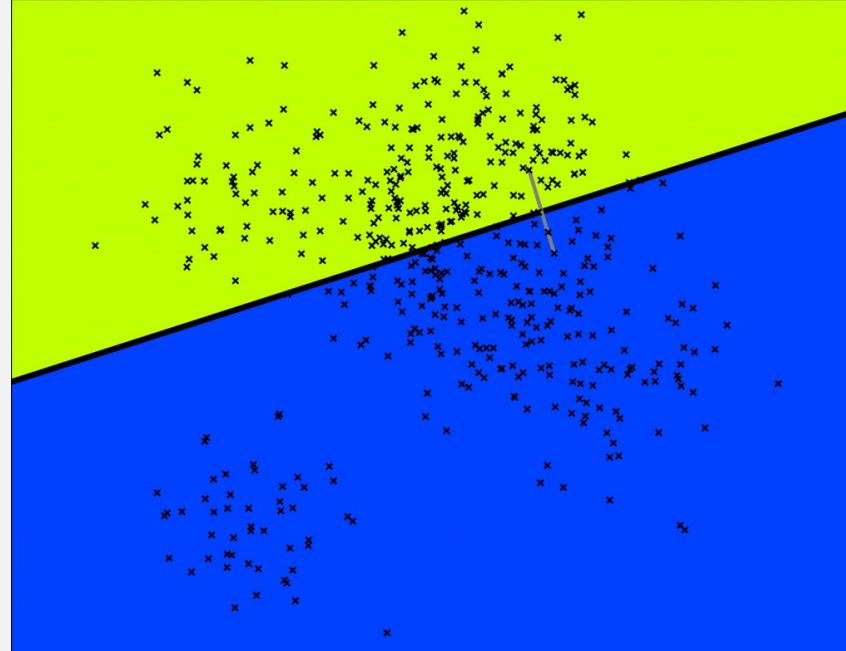
- Annoy
 - The explanation will be in 2D
 - It will apply to much higher dimension
- Goal : to build a **data structure** that let us find the nearest points to any query points in **sublinear** time
 - Its gonna be a **Tree!**
- A binary tree that each node is a random split





PREPROCESS

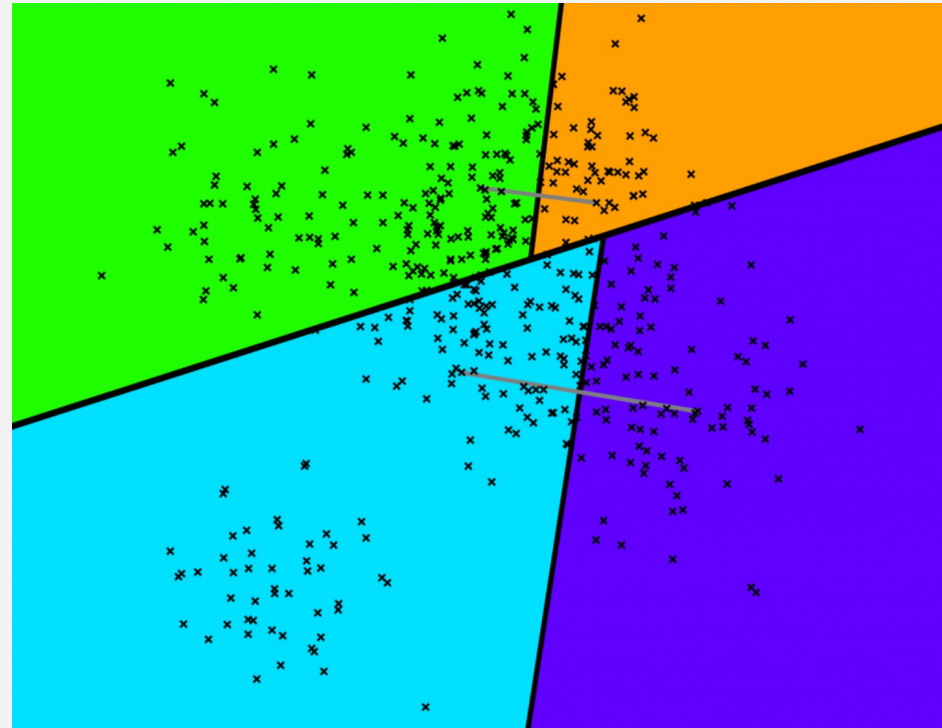
- pick two points randomly and then **split by the hyperplane equidistant** from those two points





PREPROCESS

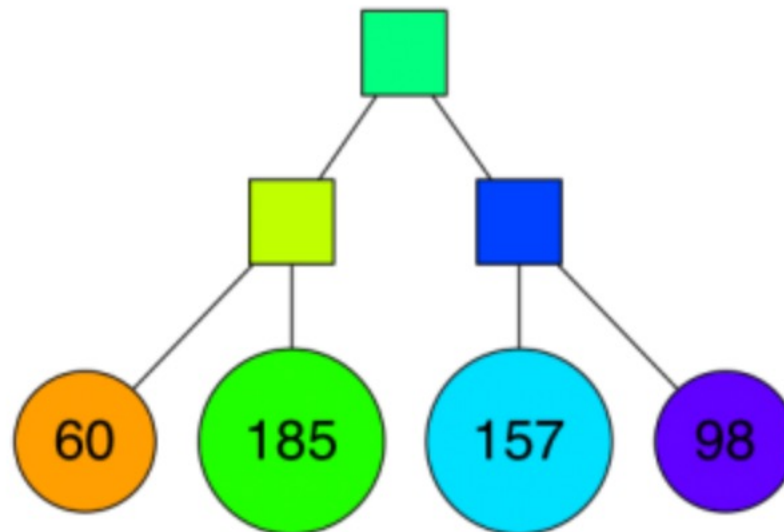
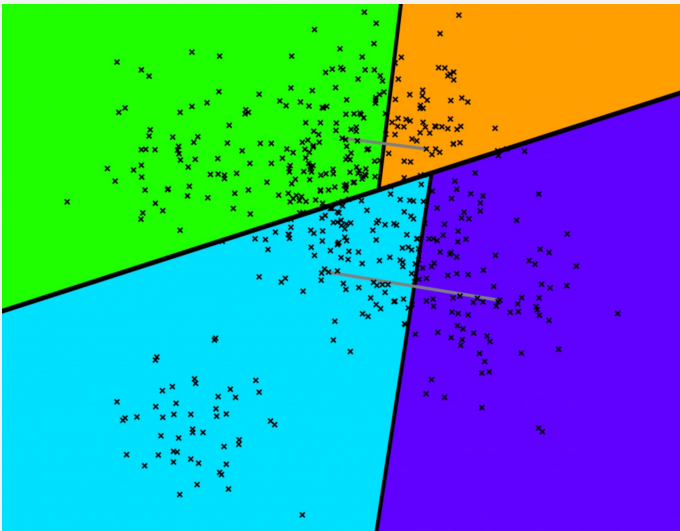
- keep splitting each subspace recursively





PREPROCESS

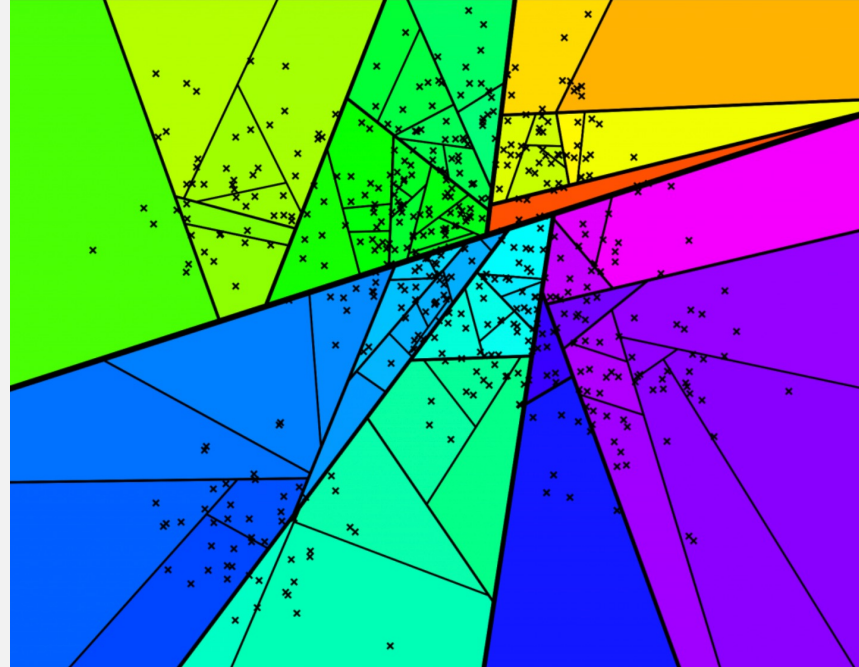
- keep splitting each subspace recursively
 - This is our tree so far!





PREPROCESS

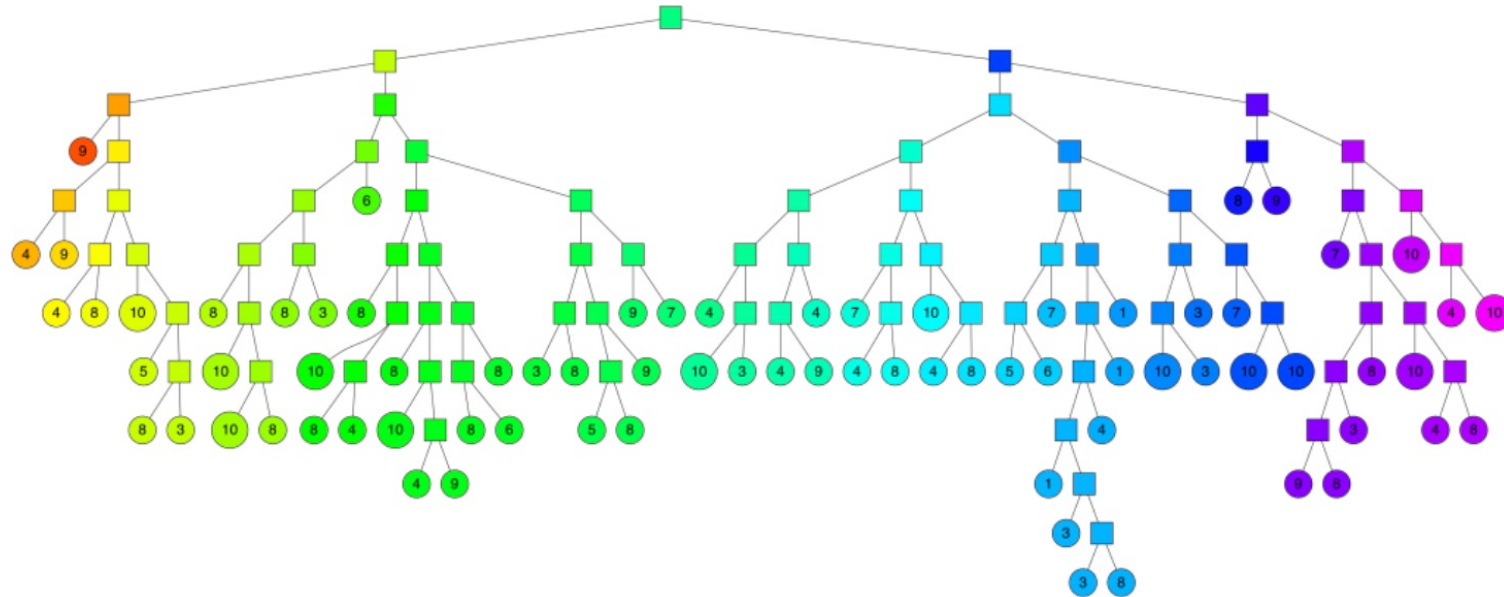
- We keep doing this until there's at most K items left in each node ($K=10$)





PREPROCESS

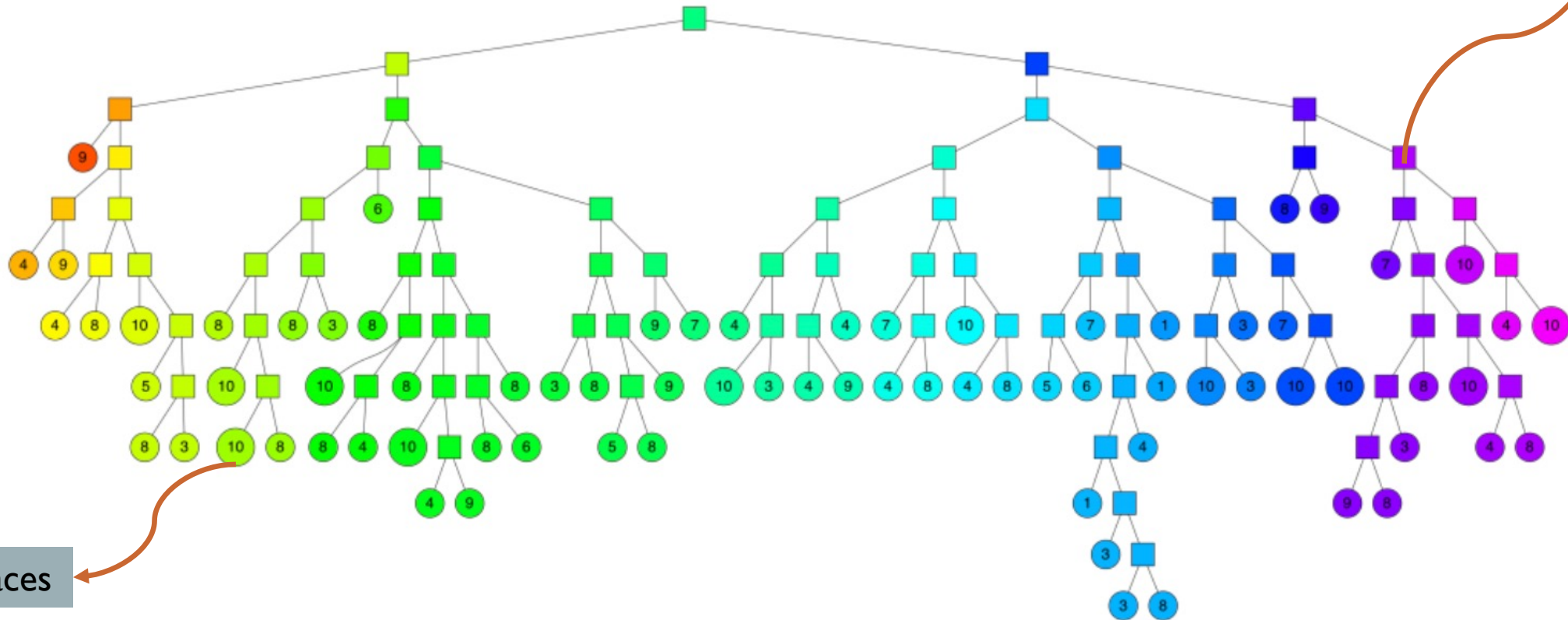
- Final tree





PREPROCESS

Hyperplane; to
figure out which
side of the
hyperplane to go



The final spaces

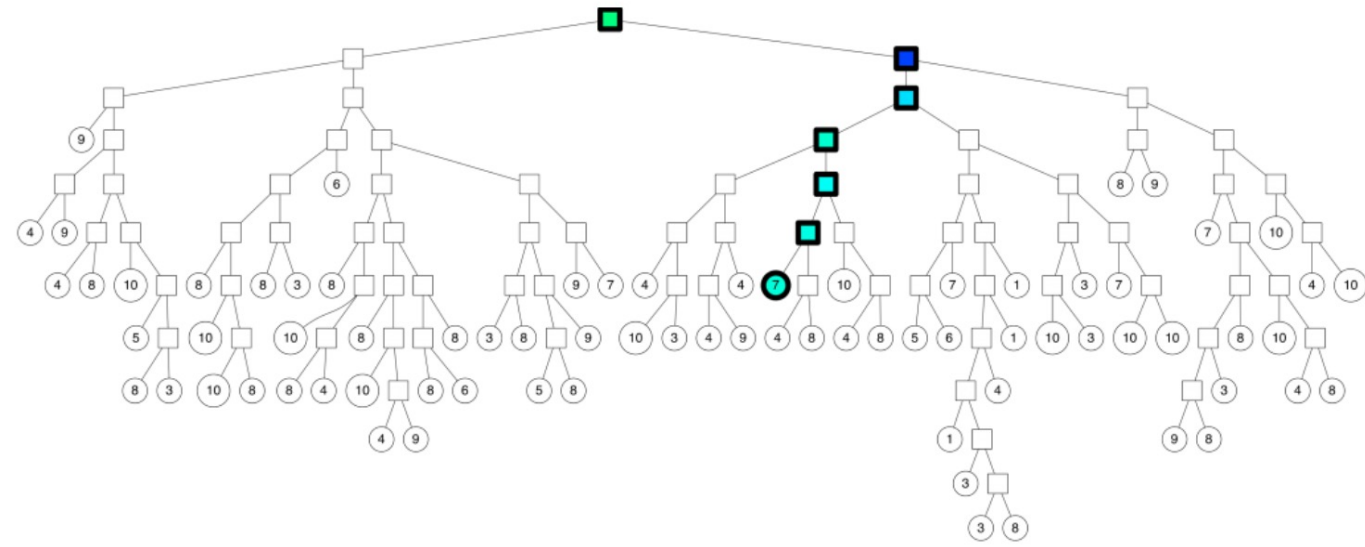
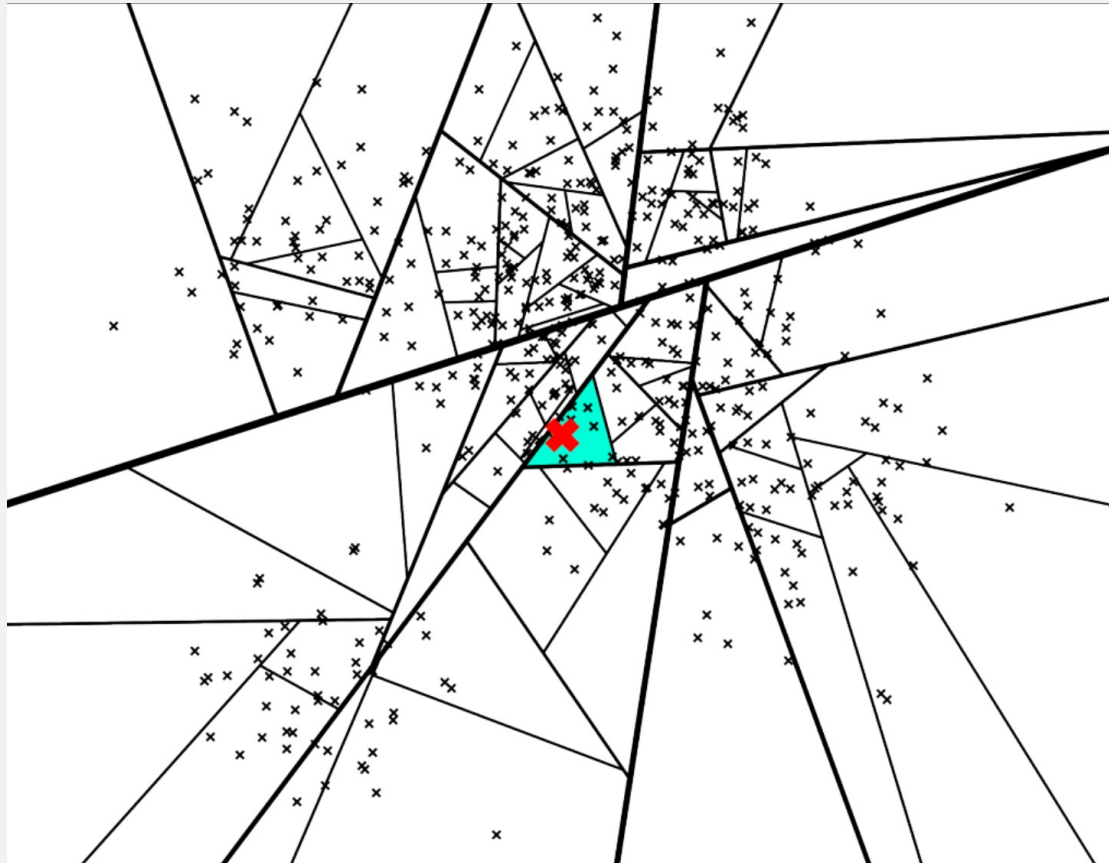


PREPROCESS

- The resulting binary tree partitions the space
- points that are close to each other in the space are more likely to be close to each other in the tree
- In other words if two points are close to each other in the space, it's unlikely that any hyperplane will cut them apart
- Searching for a point can be done in logarithmic time since that is the height of the tree



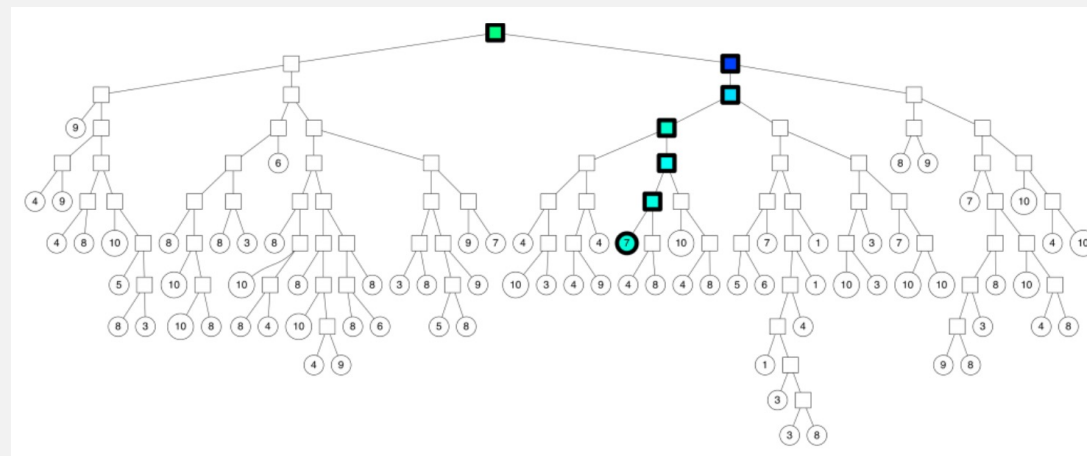
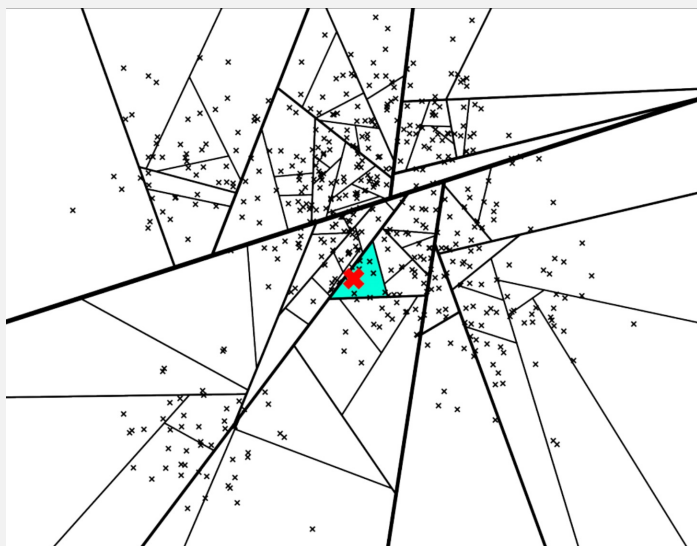
QUERY





NOT GREAT

1. What if we want more than 7 neighbors?
2. Some of the nearest neighbors are actually outside of this leaf polygon



IMPROVEMENTS

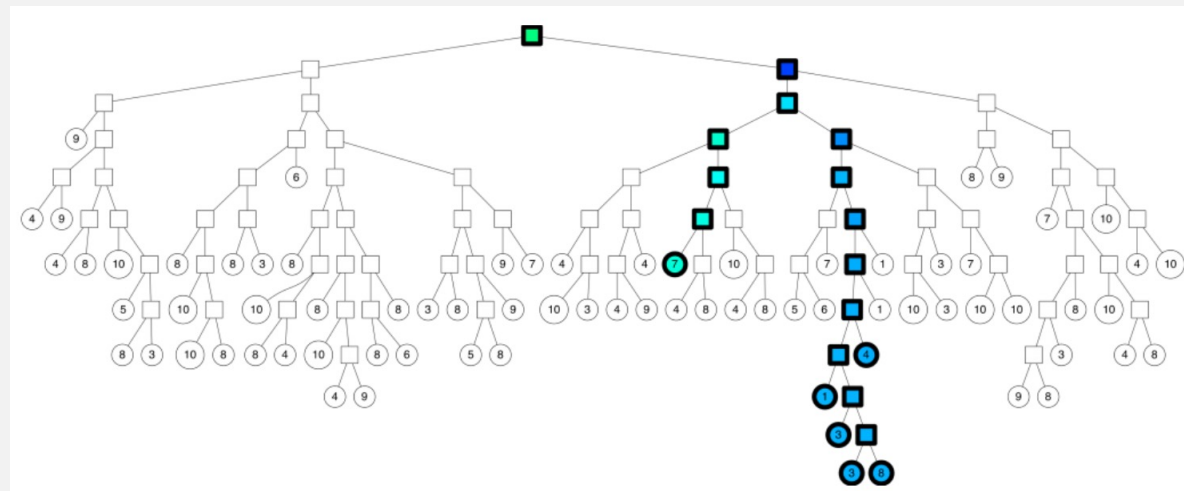
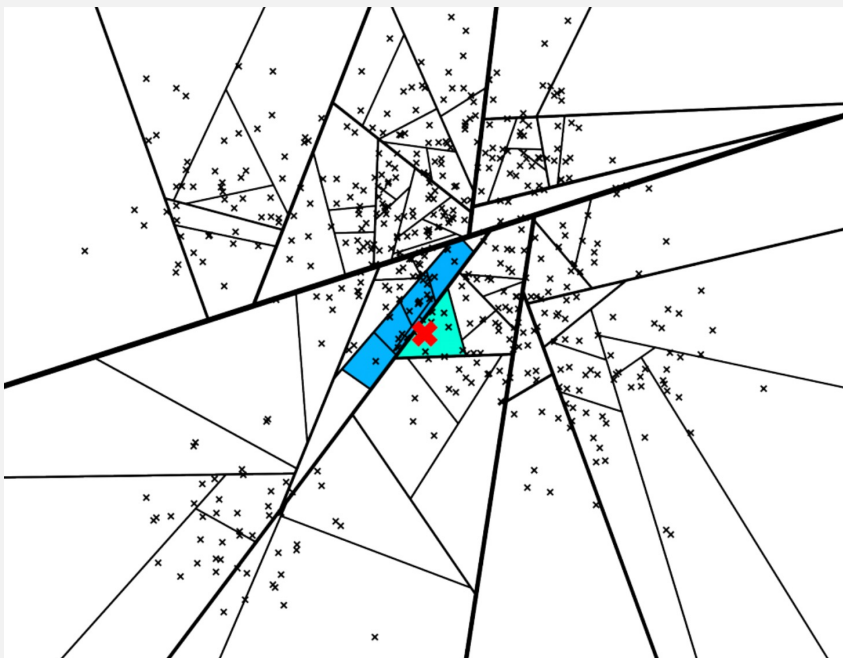


TRICK I

- We go down on both sides of a split if we are “close enough”
- We acknowledge a **threshold** of how far we are willing to go into the “wrong” side of the split. **If the threshold is 0, then we will always go on the “correct” side of the split.**
- So instead of just going down one path of the binary tree, we will go down a few more



TRICK I



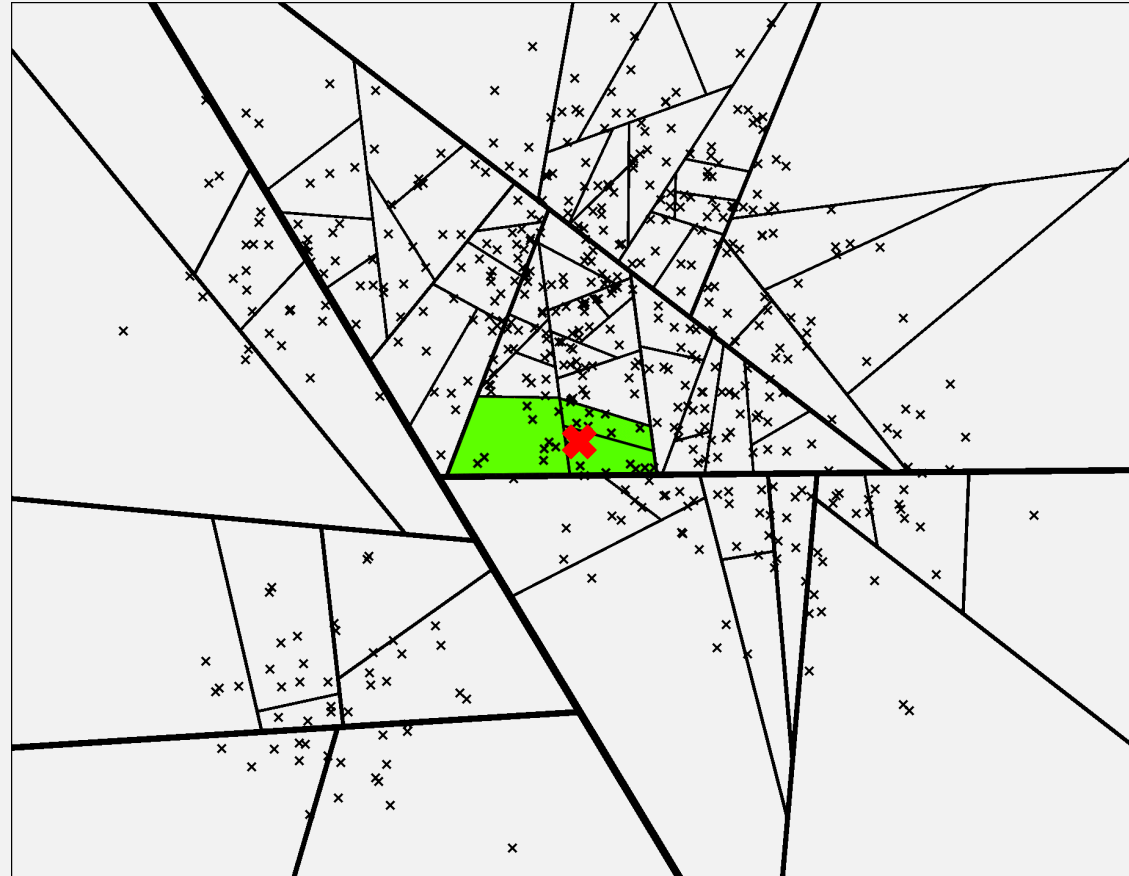


TRICK II

- Build a forest of trees
 - Search down all these trees at the same time
- If we look at the union of the leaf nodes we get a pretty good neighborhood

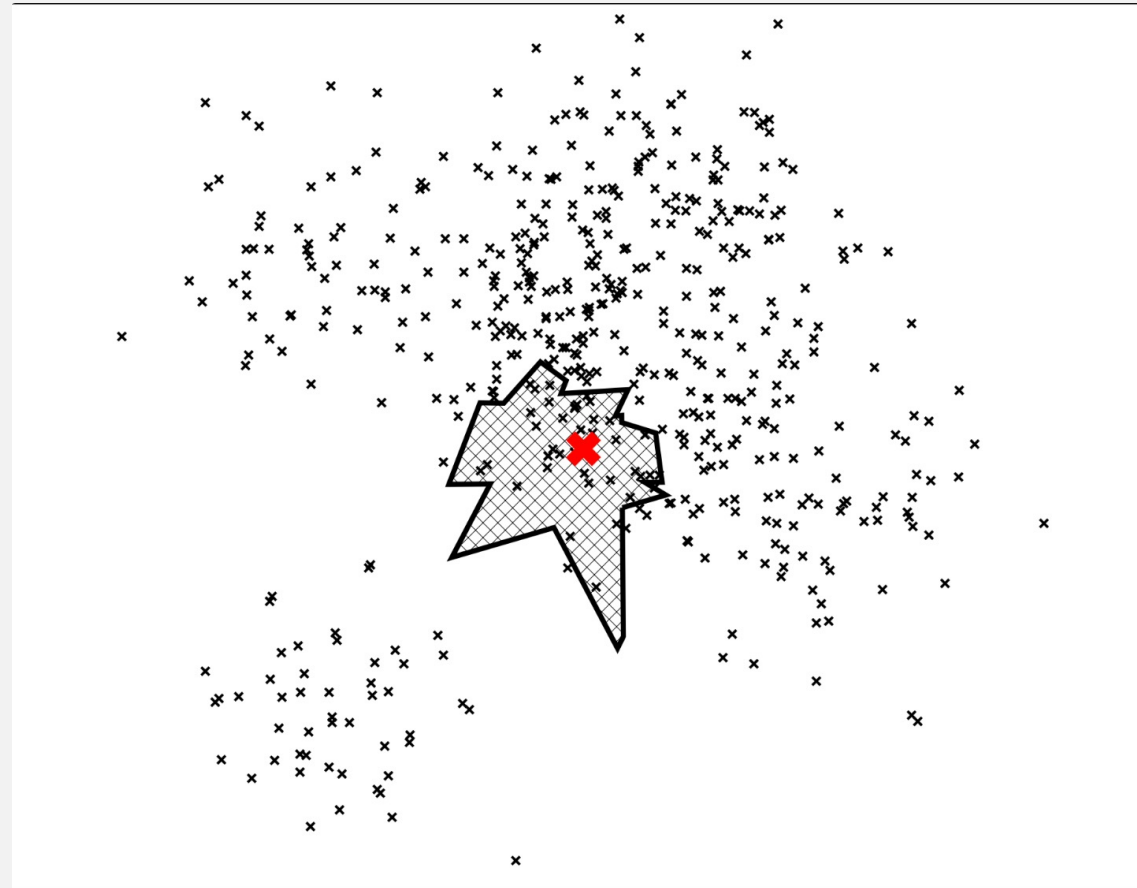


TRICK II – THE FOREST





TRICK II – UNION OF THE LEAVES

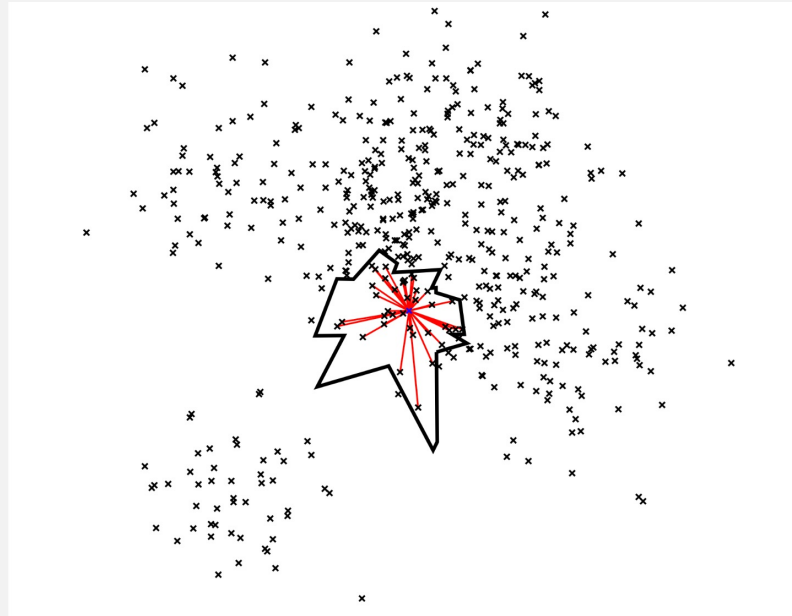


FINAL STEP



FINAL STEP

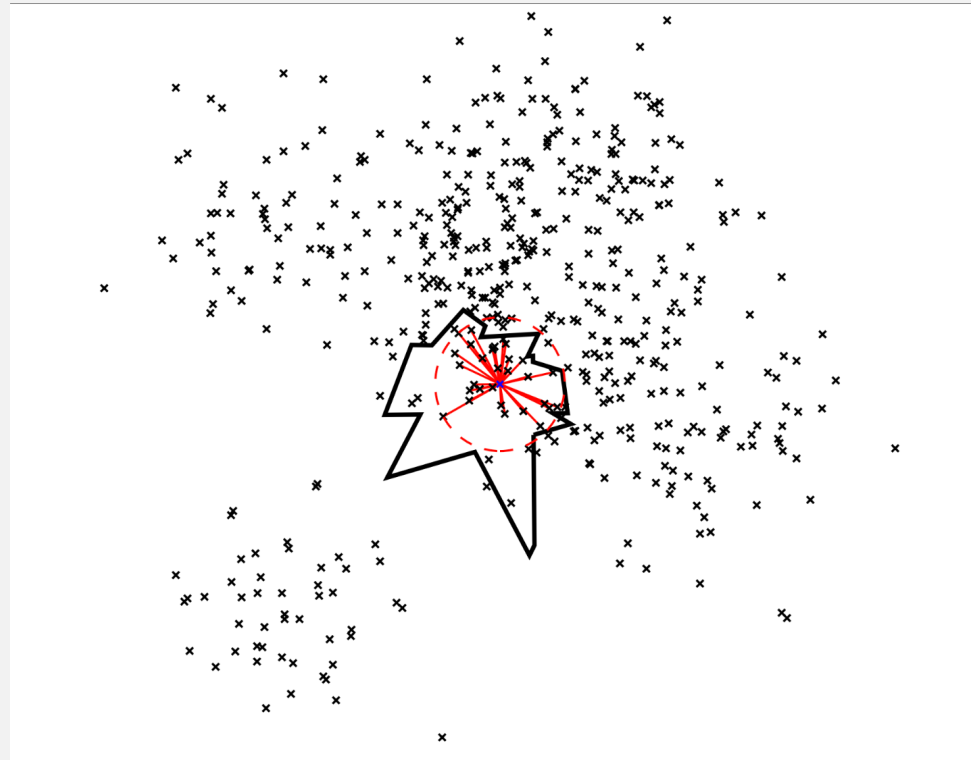
- Now we have a small set of points that are almost the closest ones
- We **only** compute the distance of these points (**instead of the whole data set**)
 - And just like KNN we rank the distances and so on!





FINAL STEP

- The trade off between time and accuracy



FINAL WORDS



REFERENCES

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THANKS FOR YOUR ATTENTION.
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