SUPERVISED LEARNING WITH PROPHET & LSTM NETWORK

Time Series Analysis & Predictive Modeling Using Supervised Machine Learning

Stock price prediction using machine learning



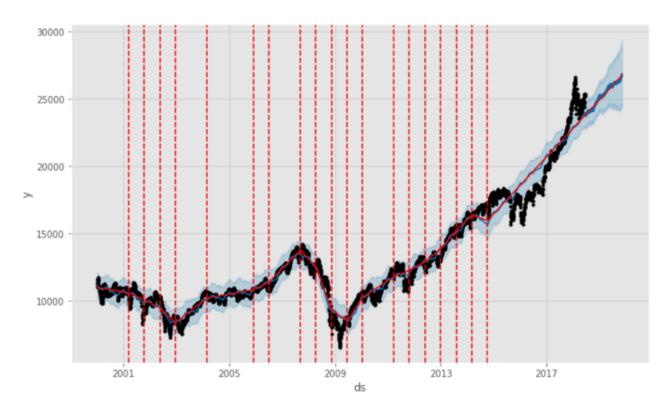


Image by author

I ime-Series involves temporal datasets that change over a period of time and timebased attributes are of paramount importance in these datasets. The trading
prices of stocks change constantly over time, and reflect various unmeasured factors
such as market confidence, external influences, and other driving forces that may be

hard to identify or measure. There are hypothesis like the Efficient Market Hypothesis, which says that it is almost impossible to beat the market consistently and there are others which disagree with it.

Problem Statement

Forecasting the future value of a given stock is a crucial task as investing in stock market involves higher risk.. Here, given the historical daily close price for Dow-Jones Index, we would like to prepare and compare forecasting models.

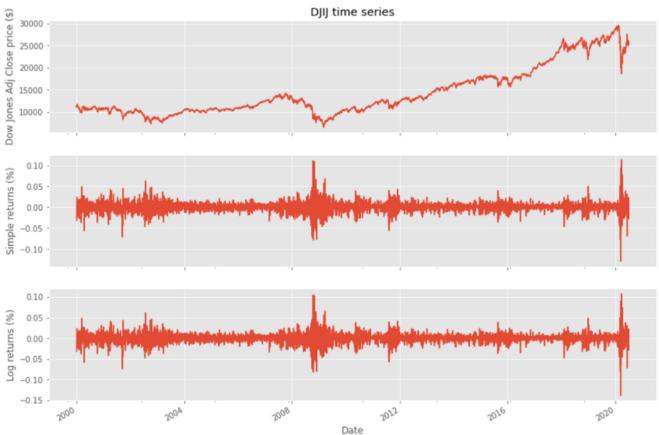
```
dji = web.DataReader('^DJI', data_source = 'yahoo', start = '2000-01-
01')
print(dji.head())
print('\n')
print(dji.shape)
```

```
Date
2000-01-03 11522.009766 11305.690430 11501.849609 11357.509766 169750000 11357.509766 2000-01-04 11350.059570 10986.450195 11349.750000 10997.929688 178420000 10997.929688 2000-01-05 11215.099609 10938.669922 10989.370117 11122.650391 203190000 11122.650391 2000-01-06 11313.450195 11098.450195 11113.370117 11253.259766 176550000 11253.259766 2000-01-07 11528.139648 11239.919922 11247.059570 11522.559570 184900000 11522.559570 (5158, 6)
```

```
dji_series = dji['Adj Close']

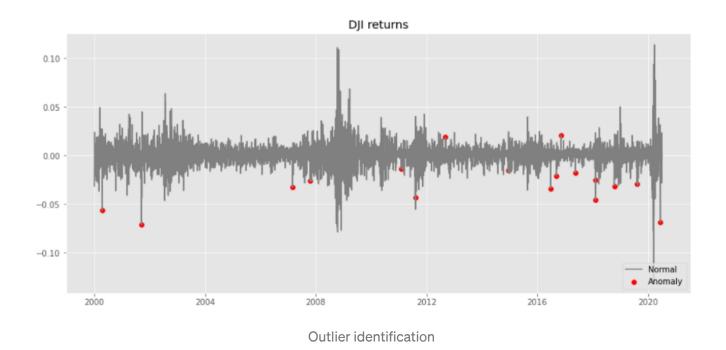
#Calculate the simple and log returns using the adj close prices:
dji['simple_rtn'] = dji_series.pct_change()
dji['log_rtn'] = np.log(dji_series/dji_series.shift(1))

fig, ax = plt.subplots(3, 1, figsize=(14, 10), sharex=True)
dji_series.plot(ax=ax[0])
ax[0].set(title = 'DJIJ time series', ylabel = 'Dow Jones Adj Close
price ($)')
dji.simple_rtn.plot(ax=ax[1])
ax[1].set(ylabel = 'Simple returns (%)')
dji.log_rtn.plot(ax=ax[2])
ax[2].set(xlabel = 'Date', ylabel = 'Log returns (%)')
plt.show()
```



```
#Calculate the rolling mean and standard deviation:
df rolling = dji[['simple rtn']].rolling(window=21) .agg(['mean',
'std'])
df rolling.columns = df rolling.columns.droplevel()
#Join the rolling metrics to the original data:
df outliers = dji.join(df rolling)
#Define a function for detecting outliers:
def indentify outliers(row, n sigmas=3):
x = row['simple rtn']
mu = row['mean']
sigma = row['std']
if (x > mu + 3 * sigma) | (x < mu - 3 * sigma):
return 1
else:
return 0
#Identify the outliers and extract their values for later use
df outliers['outlier'] = df outliers.apply(indentify outliers,axis=1)
outliers = df outliers.loc[df outliers['outlier'] == 1,
['simple rtn']]
#Plot the results:
fig, ax = plt.subplots()
ax.plot(df outliers.index, df outliers.simple rtn, color='gray',
```

```
label='Normal')
ax.scatter(outliers.index, outliers.simple_rtn, color='red',
label='Anomaly')
ax.set_title("DJI returns")
ax.legend(loc='lower right')
plt.show()
```



The black swan theory, which predicts that anomalous events, such as a stock market crash, are much more likely to occur than would be predicted by the normal distribution. A good example to illustrate the long-tailed nature of data is stock returns. Below shows the QQ-Plot for the daily DJI returns.

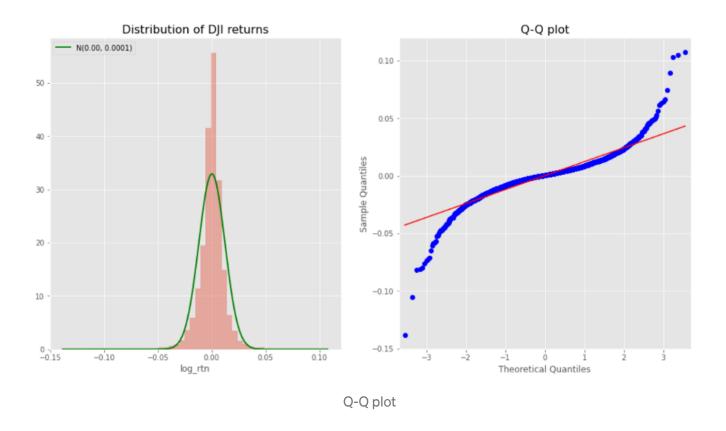
```
r_range = np.linspace(min(dji['log_rtn'].dropna()),
max(dji['log_rtn'].dropna()), num=1000)
mu = dji['log_rtn'].dropna().mean()
sigma = dji['log_rtn'].dropna().std()
norm_pdf = scs.norm.pdf(r_range, loc=mu, scale=sigma)

#Plot the histogram and the Q-Q plot
fig, ax = plt.subplots(1, 2, figsize=(16, 8))

# histogram
sns.distplot(dji['log_rtn'].dropna(), kde=False, norm_hist=True,
ax=ax[0])
ax[0].set_title('Distribution of DJI returns', fontsize=16)
ax[0].plot(r_range, norm_pdf, 'g', lw=2, label=f'N({mu:.2f},
```

```
{sigma**2:.4f})')
ax[0].legend(loc='upper left');

# Q-Q plot
qq = sm.qqplot(dji['log_rtn'].dropna().values, line='s', ax=ax[1])
ax[1].set_title('Q-Q plot', fontsize = 16)
plt.show()
```



The points are close to the line for the data within one standard deviation of the mean. Tukey refers to this phenomenon as data being normal in the middle, but having much longer tails

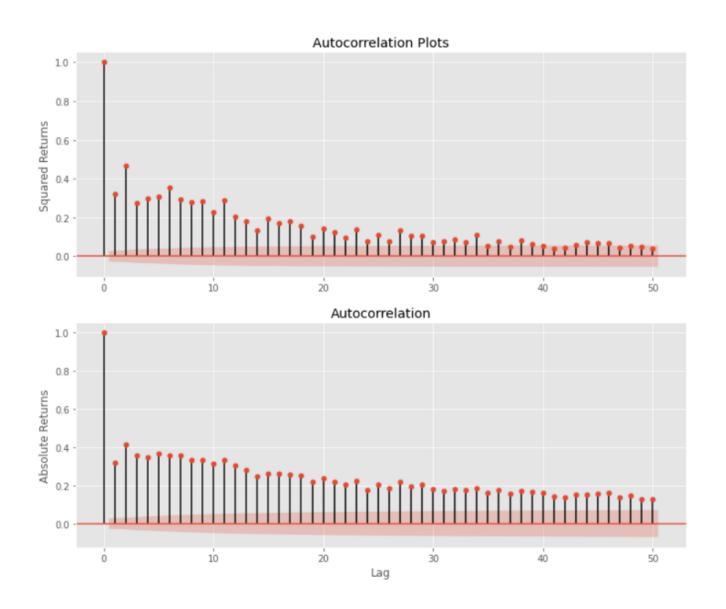
```
print("kurtosis:", scipy.stats.kurtosis(dji['log_rtn'].dropna(),bias=False))
print("skewness:", scipy.stats.skew(dji['log_rtn'].dropna(),bias=False))
print("JB:", scipy.stats.jarque_bera(dji['log_rtn'].dropna()))
```

kurtosis: 13.178200149240837 skewness: -0.374123198090276 JB: (37357.60391773232, 0.0)

Small and decreasing auto-correlation in squared/absolute returns

Motivation for modeling volatility by means of nonstationary processes is related to high persistence commonly observed in squared or absolute returns. This shows typical pattern if we draw ACF plots of the squared/absolute returns that are positive and slowly decreasing.

```
N_LAGS = 50
SIGNIFICANCE_LEVEL = 0.05
fig, ax = plt.subplots(2, 1, figsize=(12, 10))
smt.graphics.plot_acf(dji['log_rtn'].dropna() ** 2, lags=N_LAGS,
alpha=SIGNIFICANCE_LEVEL, ax = ax[0])
ax[0].set(title='Autocorrelation Plots', ylabel='Squared Returns')
smt.graphics.plot_acf(np.abs(dji['log_rtn'].dropna()), lags=N_LAGS,
alpha=SIGNIFICANCE_LEVEL, ax = ax[1])
ax[1].set(ylabel='Absolute Returns',xlabel='Lag')
plt.show()
```



Prediction with Prophet

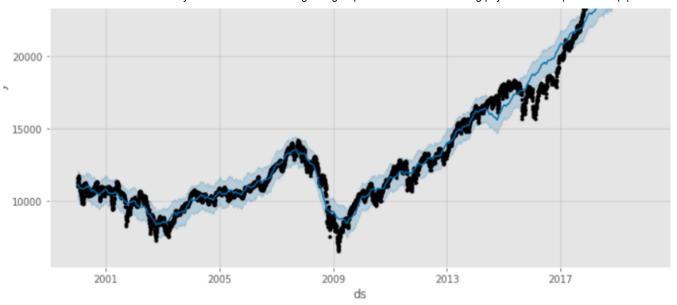
At its core, the Prophet procedure is an additive regression model with three main components:

- 1. A piece-wise linear or logistic growth curve trend. Prophet automatically detects changes in trends by selecting change-points from the data.
- 2. A yearly seasonal component modeled using <u>f</u>ourier series.
- 3. A weekly seasonal component using dummy variables.

```
prophet = dji series.reset index() # reset index to get date time as
a column
# prepare the required data-frame
prophet.rename(columns={'Date':'ds','Adj Close':'y'},inplace=True)
prophet = prophet[['ds','y']]
train percent = 0.90
# prepare train and test sets
train size = int(prophet.shape[0]*train percent)
train = prophet.iloc[:train size]
test = prophet.iloc[train size+1:]
model prophet = Prophet() # build a prophet model
model prophet.fit(train) # fit the model
# prepare a future dataframe
future dates =
model prophet.make future dataframe(periods=test.shape[0])
\# test.shape[0] = 515
forecast = model prophet.predict(future dates) # forecast values
model prophet.plot(forecast) # plot for prediction
plt.title('Prediction on Test data')
```

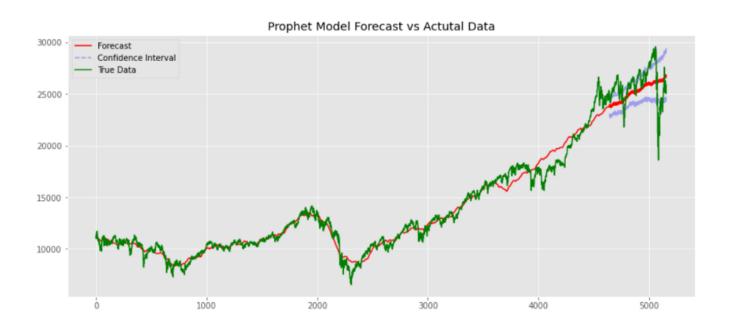
Prediction on Test data





```
lower_bound = (forecast.yhat_lower.iloc[train_size+1:])
upper_bound = (forecast.yhat_upper.iloc[train_size+1:])

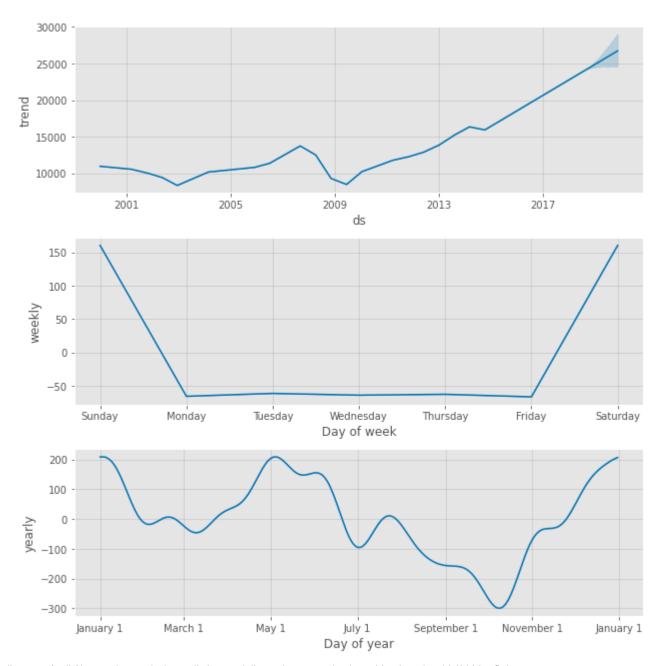
# plot against true data
plt.plot(forecast['yhat'],c='r',label='Forecast')
plt.plot(lower_bound, linestyle='--',c='b',alpha=0.3,
label='Confidence Interval')
plt.plot(upper_bound, linestyle='--',c='b',alpha=0.3)
plt.plot(prophet['y'],c='g',label='True Data')
plt.legend()
plt.title('Prophet Model Forecast vs Actutal Data')
```



Probably business wants to see the report in below format:

		ds	У	yhat	accuracy
	5153	2020-06-26	25015.550781	26609.526318	106.37%
	5154	2020-06-29	25595.800781	26844.013101	104.88%
	5155	2020-06-30	25812.880859	26851.057124	104.02%
	5156	2020-07-01	25734.970703	26631.613507	103.48%

model_prophet.plot_components(forecast)



We will explore the application of LSTMs to this use case and generate forecasts. There are a number of ways this problem can be modeled to forecast values.

LSTM windowed architecture

To model our current use case as a regression problem, we state that the stock price at timestamp t+1 (dependent variable) is a function of stock price at timestamps t, t -1, t -2, ..., t -n. Where n is the past window of stock prices.

Here a window size of 6 days is used. The value at time t+1 is forecasted using past six values. However, smaller or larger windows can be used to experiment the difference. We have data since 2000, so, multiple such sequences are created applying this windowed transformation in a rolling fashion.

```
# prepare training and testing data sets for LSTM based regression
modeling
def get reg train test(timeseries, sequence length= 51, train size =
0.9, roll mean window=5, normalize=True, scale=False):
# rolling mean is used to smoothen the time series
if roll mean window:
timeseries = timeseries.rolling(roll mean window).mean().dropna()
# create windows
result = []
for index in range(len(timeseries) - sequence length):
result.append(timeseries[index: index + sequence length])
# normalize data using every time step is the % change from the 1st
# value in that window
if normalize:
normalised data = []
for window in result:
normalised window = [((float(p) / float(window[0])) - 1) for p in
window]
normalised data.append(normalised window)
result = normalised data
# identify train-test splits
result = np.array(result)
row = round(train size * result.shape[0])
# split train and test sets
train = result[:int(row), :]
test = result[int(row):, :]
```

```
# scale data in 0-1 range
scaler = None
if scale:
scaler=MinMaxScaler(feature range=(0, 1))
train = scaler.fit transform(train)
test = scaler.transform(test)
# split independent and dependent variables
x train = train[:, :-1]
y train = train[:, -1]
x test = test[:, :-1]
y test = test[:, -1]
# Transforms for LSTM input
x train = np.reshape(x train, (x train.shape[0], x train.shape[1],
1))
x test = np.reshape(x test, (x test.shape[0], x test.shape[1], 1))
return x train, y train, x test, y test, scaler
```

```
# training and testing data sets for LSTM based sequence modeling
def get_seq_train_test(time_series, scaling=True,train_size=0.9):
    scaler = None
    if scaling:
        | scaler = MinMaxScaler(feature_range=(0, 1))
            time_series = np.array(time_series).reshape(-1,1)
            scaled_stock_series = scaler.fit_transform(time_series)
    else:
        | scaled_stock_series = time_series

    train_size = int(len(scaled_stock_series) * train_size)

    train = scaled_stock_series[0:train_size]
    test = scaled_stock_series[train_size:len(scaled_stock_series)]
    return train,test,scaler
```

```
# readout layer. TimeDistributedDense uses the same weights for all
# time steps.
model.add(TimeDistributed(Dense(1)))
start = time.time()

model.compile(loss="mse", optimizer="rmsprop")

if verbose:
    print("> Compilation Time : ", time.time() - start)
    print(model.summary())

return model
```

```
#plot each window in the prediction list
for i, data in enumerate(predicted_data):
    padding = [None for p in range(i * prediction_len)]
    plt.plot(padding + data, label='Prediction',c='black')

plt.title("Forecast Plot with Prediction Window={}".format(prediction_len))
plt.show()
```

Train-test split

```
x_train,y_train,x_test,y_test,scaler = get_reg_train_test(dji_series,
sequence_length=WINDOW+1, roll_mean_window =None, normalize=True,
scale=False)
print("Data Split Complete")
print("x_train shape={}".format(x_train.shape))
print("y_train shape={}".format(y_train.shape))
print("x_test shape={}".format(x_test.shape))
print("y_test shape={}".format(y_test.shape))
```

We are creating seven-day window that is comprised of six days of historical data (x_{train}) and one day forecast (y_{train})

```
window = 6
pred_length = int(window/2)
stock_index = '^DJI'

# prepare LSTM model
lstm_model=None
try:
lstm_model = get_reg_model(layer_units=[50,100],window_size=window)
except:
print("Model Build Failed. Trying Again")
lstm_model = get_reg_model(layer_units=[50,100],window_size=window)
```

```
> Compilation Time : 0.011904001235961914
Model: "sequential_2"
```

Layer (type)	Output Shape	Param #				
lstm_3 (LSTM)	(None, 6, 50)	10400				

dropout_3 (Dropout)	(None, 6, 50)	0
lstm_4 (LSTM)	(None, 100)	60400
dropout_4 (Dropout)	(None, 100)	0
dense_2 (Dense)	(None, 1)	101
activation_2 (Activation)	(None, 1)	0
Total params: 70,901		

Total params: 70,901 Trainable params: 70,901 Non-trainable params: 0

None

```
# eatrly stopping to avoid overfitting
callbacks = [keras.callbacks.EarlyStopping(monitor='val_loss',patience=2,verbose=0)]
lstm_model.fit(x_train, y_train, epochs=20, batch_size=16,verbose=1,validation_split=0.05,
callbacks=callbacks)
print("Model Fit Complete")

Train on 4404 samples, validate on 232 samples
Epoch 1/20
```

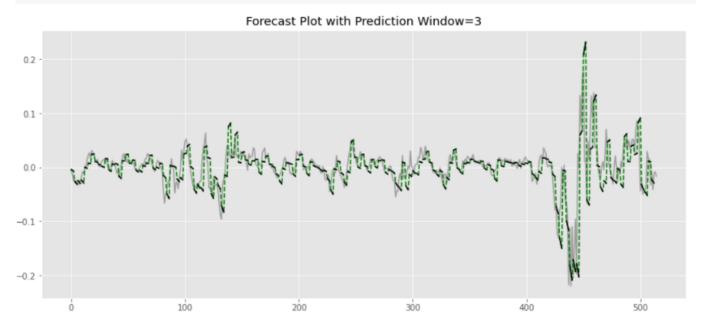
```
# Performance on train data
train_pred = predict_reg_multiple(lstm_model,x_train,
window_size=window,prediction_len=pred_length)
train_offset = y_train.shape[0] -
np.array(train_pred).flatten().shape[0]
train_rmse = math.sqrt(mean_squared_error(y_train[train_offset:],
np.array(train_pred).flatten()))
print('Train Score: %.2f RMSE' % (train_rmse))

# Performance on test data
test_pred = predict_reg_multiple(lstm_model,x_test,
window_size=window,prediction_len=pred_length)
test_offset = y_test.shape[0] -
np.array(test_pred).flatten().shape[0]
test_rmse = math.sqrt(mean_squared_error(y_test[test_offset:],
```

```
np.array(test_pred).flatten()))
print('Test Score: %.2f RMSE' % (test_rmse))
```

Train Score: 0.03 RMSE Test Score: 0.05 RMSE

```
# Plot Test Predictions
plot_reg_results(test_pred,y_test,prediction_len=pred_length)
plt.show()
```



The gray line is the original/true test data (normalized) and the black lines denote the predicted/forecast values in three-day periods. The dotted line is used to explain the overall flow of the predicted series. As is evident, the forecasts are having some similarity to the actual data.

Here also, we can bring the data to original shape to see the actual plot and generate report.

Window size along with other hyper-parameters of the network (like epochs, batch size, LSTM units, etc.) have an impact on the final output and therefore, these hyper-parameters can be chosen carefully for robust output.

For simplified version of developing RNN network architecture can be found here.

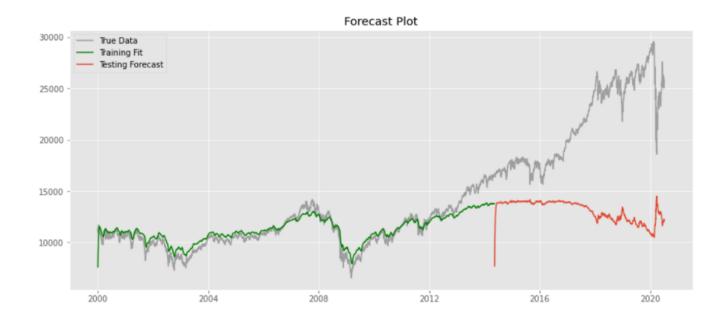
LSTM Sequence Modeling

Let us model it now as sequence where value at each time step is a function of previous values. Here we do not divide the time series into windows of fixed sizes, rather we would utilize the LSTMs to learn from the data and determine which past values to utilize for forecasting.

```
train percent = 0.7
verbose=True
# split train and test datasets
train, test, scaler = \
get seq train test(dji series, scaling=True, train size=train percent)
train = np.reshape(train, (1, train.shape[0], 1))
test = np.reshape(test, (1, test.shape[0], 1))
train x = train[:,:-1,:]
train y = train[:,1:,:]
test x = test[:,:-1,:]
test y = test[:,1:,:]
print("Data Split Complete")
print("train x shape={}".format(train x.shape))
print("train y shape={}".format(train y.shape))
print("test x shape={}".format(test x.shape))
print("test y shape={}".format(test y.shape))
# build RNN model
seq 1stm model=None
seq lstm model = get seq model(input shape=(train x.shape[1],1),
verbose=verbose)
except:
print("Model Build Failed. Trying Again")
seq lstm model = get seq model(input shape=
(train x.shape[1],1), verbose=verbose)
# train the model
seq lstm model.fit(train x, train y, epochs=10, batch size=1,
verbose=2)
print("Model Fit Complete")
# train fit performance
train predict = seq lstm model.predict(train x)
# inverse train transformation
train predict = scaler.inverse transform(train predict.reshape(-1,1))
# pad sequences is used to ensure that all sequences in a list have
the same length.
test predict = pad sequences(test x,maxlen=train x.shape[1],
padding='post', value=0,dtype='float')
# inverse test transformation
test predict = scaler.inverse transform(test predict.reshape(-1,1))
```

```
# plot the true and forecasted values
train_size = len(train_predict)+1
plt.plot(dji_series.index, dji_series.values,c='black',
alpha=0.3,label='True Data')
plt.plot(dji_series.index[1:train_size], train_predict, label=
'Training Fit',c='g')
plt.plot(dji_series.index[train_size+1:],test_predict[:test_x.shape[1
]],label='Testing Forecast')
plt.title('Forecast Plot')
plt.legend()
```

Though I have used padding utility of keras.preprocessing.sequence module; however, this can also be done taking the last few values from train window as per window size.



Here, we could observe poor performance model on test data; rather generalization issue where model under-fit the data during in validation stage. We can go back to training stage and try adjusting the hyper-parameters to validate again on test set.

- 1. increase the number of training set,
- 2. tune the number of epochs,
- 3. tune batch size,
- 4. tuning the number of neuron and validate again on test set.

Also, I would recommend to use time series split using the below code snippet to get better result when dealing with time series observation with temporal order.

This split provides train/test indices to split time series data samples that are observed at fixed time intervals, in train/test sets. In each split, test indices must be higher than before, and thus shuffling in cross validator is inappropriate. This CV object is a variation of Kfold. In the kth split, it returns first k folds as train set and the (k+1)th fold as test set.

```
# taken from sklearn user guide
tscv = TimeSeriesSplit()
print(tscv)
TimeSeriesSplit(max_train_size=None, n_splits=5)
for train_index, test_index in tscv.split(X):
    print("TRAIN:", train_index, "TEST:", test_index)
    X_train, X_test = X[train_index], X[test_index]
    y_train, y_test = y[train_index], y[test_index]
```

However, this was an experimentation and illustration of how supervised algorithms can effectively use to predict stock prices.

Conclusion

We have experimented with the prediction modeling of DOW Jones Industrial Average and found that Prophet is quite powerful and effective in time series forecasting. The forecast error using the historical data. can also be measured by comparing the predicted values with the actual values and using cross validation. The performance of neural networks too can be improved significantly optimizing parameters as suggested and selecting the window size.

I can be reached here.

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