Swinburne University of Technology

School of Science, Computing and Engineering Technologies

FINAL EXAM COVER SHEET

Subject Code: COS30008
Subject Title: Data Structures & Patterns
Due date: June 8, 2023, 09:00 – 12:00 AEST
Lecturer: Dr. Markus Lumpe

Your name: Sartaj Khan **Your student id:** 103509694

Check Tutorial	Tues 08:30	Tues 10:30	Tues 12:30 BA603	Tues 12:30 ATC627	Tues 14:30	Wed 08:30	Wed 10:30	Wed 12:30	Wed 14:30	Thurs 08:30	Thurs 10:30
								✓			

Marker's comments:

Problem	Marks	Obtained
1	24	
2	88	
3	60	
4	60	
5	68	
Total	300	

This test requires approx. 2 hours and accounts for 50% of your overall mark.

```
 1
 2  // COS30008, Final Exam, 2023
 3
 4  #pragma once
 5
 6  #include "DoublyLinkedList.h"
 7  #include "DoublyLinkedListIterator.h"
 8
 9  template<typename T>
10  class List
11  {
12  private:
13      using Node = typename DoublyLinkedList<T>::Node;
14
15      Node fHead;
16      Node fTail;
17      size_t fSize;
18
19  public:
20
21      using Iterator = DoublyLinkedListIterator<T>;
22
23      List() noexcept :
24          fSize(0)
25      {}
26
27      // Final Exam, 2023
28      ~List()
29      {
30          // Problem 1
31          Node lCurrent = fTail;
32          fTail.reset();
33          while (lCurrent) {
34              Node lPrevious = lCurrent->fPrevious.lock();
35              if (lPrevious) {
36                  lPrevious->fNext.reset();
37                  lCurrent.reset();
38              }
39
40              lCurrent = lPrevious;
41          }
42      }
43
44      List( const List& aOther ) :
45          List()
46      {
47          for ( auto& item : aOther )
48          {
49              push_back( item );
```

```
50          }
51      }
52
53      List operator=( const List& aOther )
54      {
55          if ( this != &aOther )
56          {
57              this->~List();
58
59              new (this) List( aOther );
60          }
61
62          return *this;
63      }
64
65      List( List&& aOther ) noexcept :
66          List()
67      {
68          swap( aOther );
69      }
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77
78          return *this;
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80
81      void swap( List& aOther ) noexcept
82      {
83          std::swap( fHead, aOther.fHead );
84          std::swap( fTail, aOther.fTail );
85          std::swap( fSize, aOther.fSize );
86      }
87
88      size_t size() const noexcept
89      {
90          return fSize;
91      }
92
93      template<typename U>
94      void push_front( U&& aData )
95      {
96          Node lNode = DoublyLinkedList<T>::makeNode( std::forward<U>(aData) );
97
98          if ( !fHead )                                   // first element
```

```
 99          {
100              fTail = lNode;                          // set tail to first element
101          }
102          else
103          {
104              lNode->fNext = fHead;                   // new node becomes head
105              fHead->fPrevious = lNode;               // new node previous of head
106          }
107
108          fHead = lNode;                              // new head
109          fSize++;                                    // increment size
110      }
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124              fTail->fNext = lNode;                   // new node next of tail
125          }
126
127          fTail = lNode;                              // new tail
128          fSize++;                                    // increment size
129      }
130
131      void remove( const T& aElement ) noexcept
132      {
133          Node lNode = fHead;                         // start at first
134
135          while ( lNode )                             // Are there still nodes available?
136          {
137              if ( lNode->fData == aElement )         // Have we found the node?
138              {
139                  break;                              // stop the search
140              }
141
142              lNode = lNode->fNext;                   // move to next node
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```
144
145         if ( lNode )                                // We have found a first
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147             if ( fHead == lNode )                   // remove head
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150             }
151
152             if ( fTail == lNode )                   // remove tail
153             {
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                      tail, requires std::shared_ptr
155             }
156
157             lNode->isolate();                       // isolate node,
                  automatically freed
158             fSize--;                                // decrement count
159         }
160     }
161
162     const T& operator[]( size_t aIndex ) const
163     {
164         assert( aIndex < fSize );
165
166         Node lNode = fHead;
167
168         while ( aIndex-- )
169         {
170             lNode = lNode->fNext;
171         }
172
173         return lNode->fData;
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191     Iterator rend() const noexcept
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128          fSize++;                                    // increment size
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135          while ( lNode )                             // Are there still nodes available?
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159         }
160     }
161
162     const T& operator[]( size_t aIndex ) const
163     {
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166         Node lNode = fHead;
167
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193         return begin().rend();
194     }
195 };
196
```

```
1
2  // COS30008, Final Exam, 2023
3
4  #pragma once
5
6  #include <memory>
7  #include <cassert>
8  #include <algorithm>
9
10 template<typename T>
11 class TernaryTree
12 {
13 public:
14
15     using Node = std::unique_ptr<TernaryTree>;
16
17 public:
18
19     TernaryTree(const T& aKey = T{}) noexcept : fKey(aKey)
20
21     {
22         for (size_t i = 0; i < 3; i++) {
23             fNodes[i] = nullptr;
24         }
25     }
26     TernaryTree(T&& aKey) noexcept : fKey(std::move(aKey))
27     {
28         for (size_t i = 0; i < 3; i++) {
29             fNodes[i] = nullptr;
30         }
31     }
32
33     template<typename... Args>
34     static Node makeNode(Args&&... args) {
35         return std::make_unique<TernaryTree>(std::forward<Args>(args)...);
36     }
37
38     const T& operator*() const noexcept {
39         return fKey;
40     }
41
42     TernaryTree& operator[](size_t aIndex) const {
43         assert(aIndex < 3);
44         return *fNodes[aIndex];
45     }
46
47     void add(size_t aIndex, Node& aNode) {
48         assert(aIndex < 3);
49         if (this) {
```

```
50              if (!fNodes[aIndex]) {
51                  fNodes[aIndex] = std::move(aNode);
52              }
53          }
54      }
55      Node remove(size_t aIndex) {
56          assert(aIndex < 3);
57          if (this) {
58              if (fNodes[aIndex]) {
59                  Node lRemoved = std::move(fNodes[aIndex]);
60                  return lRemoved;
61              }
62          }
63      }
64
65      bool leaf() const noexcept {
66          if (this) {
67              for (size_t i = 0; i < 3; i++) {
68                  if (fNodes[i] == nullptr)  {
69                      continue;
70                  }
71                  else {
72                      return false;
73                  }
74              }
75          }
76          return true;
77      }
78      size_t height() const noexcept {
79          if (leaf()) {
80              return 0;
81          }
82          else {
83              size_t lHeight = fNodes[0]->height();
84              size_t mHeight = fNodes[1]->height();
85              size_t rHeight = fNodes[2]->height();
86
87              if (lHeight >= mHeight && lHeight >= rHeight) return lHeight+1;
88              if (mHeight >= lHeight && mHeight >= rHeight) return mHeight+1;
89              if (rHeight >= mHeight && rHeight >= lHeight) return rHeight+1;
90          }
91      }
92
93  private:
94
95      T fKey;
96      Node fNodes[3];
97  };
98
```

```cpp

// COS30008, Final Exam, 2023

#include "DSPString.h"

#include <cassert>
#include <algorithm>

DSPString::DSPString( const char* aContents )
{
    size_t lSize = 0;

    while ( aContents[lSize] )
    {
        lSize++;
    }

    fContents = new char[++lSize];

    for ( size_t i = 0; i < lSize; i++ )
    {
        fContents[i] = aContents[i];
    }
    fSize = lSize;
}

DSPString::~DSPString()
{
    delete[] fContents;

}

DSPString::DSPString( const DSPString& aOther ) :
    DSPString( aOther.fContents )
{}

DSPString& DSPString::operator=( const DSPString& aOther )
{
    if (!(*this == aOther)) {
        this->~DSPString();

        new (this) DSPString(aOther.fContents);
    }

    return *this;

}

DSPString::DSPString( DSPString&& aOther ) noexcept :
```

```
50      DSPString( "\0" )
51  {
52      std::swap(fContents, aOther.fContents);
53      std::swap(fSize, aOther.fSize);
54  }
55
56  DSPString& DSPString::operator=( DSPString&& aOther ) noexcept
57  {
58      if (!(this == &aOther)) {
59          std::swap(fContents, aOther.fContents);
60          std::swap(fSize, aOther.fSize);
61      }
62      return *this;
63  }
64
65  size_t DSPString::size() const noexcept
66  {
67      return fSize;
68
69  }
70
71  char DSPString::operator[]( size_t aIndex ) const noexcept
72  {
73      assert(aIndex < fSize);
74      return fContents[aIndex];
75  }
76
77  bool DSPString::operator==( const DSPString& aOther ) const noexcept
78  {
79      if ( size() == aOther.size() )
80      {
81          for ( size_t i = 0; i < size(); i++ )
82          {
83              if ( fContents[i] != aOther.fContents[i] )
84              {
85                  return false;
86              }
87          }
88
89          return true;
90      }
91
92      return false;
93  }
94
95  std::ostream& operator<<( std::ostream& aOStream, const DSPString& aObject )
96  {
97      return aOStream << aObject.fContents;
98  }
```

```cpp

// COS30008, Final Exam, 2023

#include "DSPStringIterator.h"

DSPStringIterator::DSPStringIterator( const DSPString& aCollection ) :
    fCollection( std::make_shared<DSPString>( aCollection ) ),
    fIndex( 0 )
{}

char DSPStringIterator::operator*() const noexcept
{
    return (*fCollection.get())[fIndex];
}

DSPStringIterator& DSPStringIterator::operator++() noexcept
{
    fIndex++;
    return *this;
}

DSPStringIterator DSPStringIterator::operator++( int ) noexcept
{
    DSPStringIterator old = *this;

    ++(*this);

    return old;
}

DSPStringIterator& DSPStringIterator::operator--() noexcept
{
    fIndex--;
    return *this;
}

DSPStringIterator DSPStringIterator::operator--( int ) noexcept
{
    DSPStringIterator old = *this;

    --(*this);

    return old;
}

bool DSPStringIterator::operator==( const DSPStringIterator& aOther ) const noexcept
{
    return fIndex == aOther.fIndex && fCollection == aOther.fCollection;
```

```
49  }
50
51  bool DSPStringIterator::operator!=( const DSPStringIterator& aOther ) const
      noexcept
52  {
53      return !(*this == aOther);
54  }
55
56  DSPStringIterator  DSPStringIterator::begin() const noexcept
57  {
58      DSPStringIterator begin = *this;
59      begin.fIndex = 0;
60      return begin;
61  }
62
63  DSPStringIterator DSPStringIterator::end() const noexcept
64  {
65      DSPStringIterator end = *this;
66      end.fIndex = fCollection.get()->size()-1;
67      return end;
68  }
69
70  DSPStringIterator DSPStringIterator::rbegin() const noexcept
71  {
72      DSPStringIterator rBegin = *this;
73      return rBegin.end();
74  }
75
76  DSPStringIterator DSPStringIterator::rend() const noexcept
77  {
78      DSPStringIterator rEnd = *this;
79      rEnd.fIndex = -1;
80      return rEnd;
81  }
82
```

Problem 5 (68 marks)

Answer the following questions in one or two sentences:

a. What is a weak pointer and when do we use it? (8)

5a)

Weak Pointers are smart pointers that do not reference count for an object. Weak pointers are used to break the circular dependency created by shared pointers.

b. How do we guarantee preconditions for operations in C++? (2)

5b)

We use assert statements to ensure the condition we are looking for is true. Otherwise, the function can cause undefined behavior or crash, so we abort the execution of the function using the assert statement.

c. What are the canonical methods in C++? (12)

5c)

d. Is Quick Sort strictly better than Merge Sort? Justify. (8)

5d)

Quick sort has complexity O(n^2) and merge sort O(nlogn). Quick sort is very fast for smaller arrays while merge sort is faster over increasing array sizes.

e. What is the purpose of an empty tree? Justify. (8)

5e)

Practically, it is impossible to have an n-ary tree with all nodes having the same degree since this will lead to an infinite data structure. The notion of empty trees allow a brute-force way to define the definite degree to a tree and allow us to create an n-ary tree without an infinite structure. Whenever, a node does not have a child node, we replace it with an empty tree.

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f. Which modern C++ abstraction do we use when we need to return a value that does not exist? (2)

5f)

We use std::optional<>

g. What does amortized analysis show? (4)

5g)

Amortized analysis accounts for the worst case scenario for an algorithm or data structure. It averages the intensive operations and tells us the behavior for the worst case. The importance of this is, the intensive operations might be seldom used in the data structure so regarding the total behavior will lead to a wrong analysis of the behavior of the data structure. Averaging balances this act and gives us a proper notion - a weighted average which signifies the intensity and complexity of each statement of the data structure.

h. What is a load factor and what are the recommended factors, thresholds, and aims for expansion and contraction of dynamic memory? (12)

5h)

Load factors are used to alter the size of objects during runtime. It utilises a ratio of empty space to total space and uses this to decide whether the size needs to be increased or decreased. For example, a load factor of 1 means we should double the space for more objects to be stored whereas, a load factor of one-quarter means, we can halve the space.

i. What is required to test the equivalence of iterators? (4)

5i)

Test whether each of the iterator attributes are the same and return the value by and-ing all of them.

j. When do we need to implement a state machine? (8)

5j)

When we have an interface, to tack the execution of actions, inputs and outputs we use state machines. This gives us a visual description of the functionality of the program and the flow of the program execution.

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5g)

Amortized analysis accounts for the worst case scenario for an algorithm or data structure. It averages the intensive operations and tells us the behavior for the worst case. The importance of this is, the intensive operations might be seldom used in the data structure so regarding the total behavior will lead to a wrong analysis of the behavior of the data structure. Averaging balances this act and gives us a proper notion - a weighted average which signifies the intensity and complexity of each statement of the data structure.

h. What is a load factor and what are the recommended factors, thresholds, and aims for expansion and contraction of dynamic memory? (12)

5h)

Load factors are used to alter the size of objects during runtime. It utilises a ratio of empty space to total space and uses this to decide whether the size needs to be increased or decreased. For example, a load factor of 1 means we should double the space for more objects to be stored whereas, a load factor of one-quarter means, we can halve the space.

i. What is required to test the equivalence of iterators? (4)

5i)

Test whether each of the iterator attributes are the same and return the value by and-ing all of them.

j. When do we need to implement a state machine? (8)

5j)

When we have an interface, to tack the execution of actions, inputs and outputs we use state machines. This gives us a visual description of the functionality of the program and the flow of the program execution.

f. Which modern C++ abstraction do we use when we need to return a value that does not exist? (2)

5f)

We use std::optional<>

g. What does amortized analysis show? (4)

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