MSDSM Final Year Project Presentation

Presentation Attack Detection in Biometric
Security Using Deep Learning Techniques - A
Comparative Analysis

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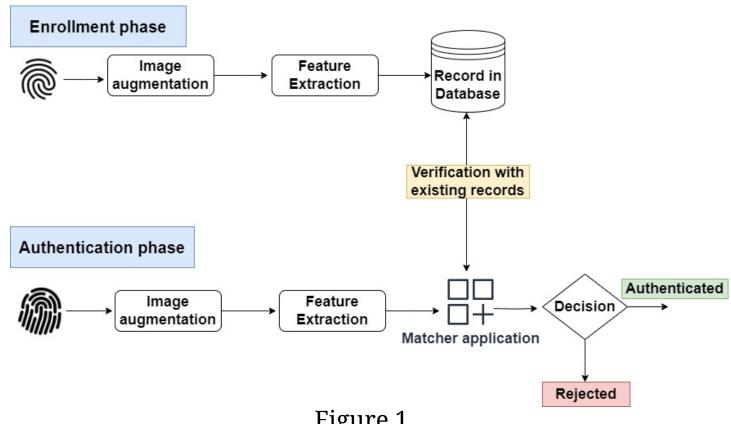
19 June 2024

Agenda

- A quick overview of the problem
- Previous works on the problem
- Current work by presenter
- Observations and conclusion

What is FRS?

Fingerprint Recognition System [3]



What are PA and FPAD?

 Presentation Attack (PA) – methods to deceive the FRS

Fingerprint Presentation Attack Detection
 (FPAD) – methods to detect the deception

What are fake fingerprints?

 Fake finger prints can be made from various materials like Ecoflex, Wood Glue, Play-doh, Gelatin etc using direct or latent fingerprint impressions of subjects.











Ecofle x

Gelati n

Latex

Wood glue

Figure 2 : Real and fake fingerprint samples

Related Works

 Adversarial Representation Learning Coupled with Style Transfer for Cross-Sensor Generalization [4]

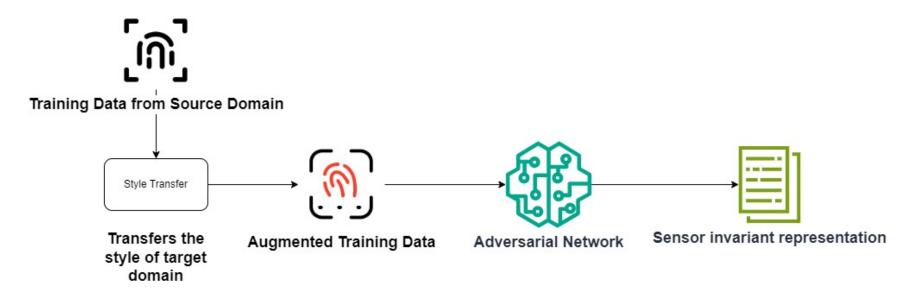


Figure 3 : Flow diagram for this approach

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Related Works

 Convolution Auto-encoders on Short Wave Infrared (SWIR) Images of Fingerprints [5]

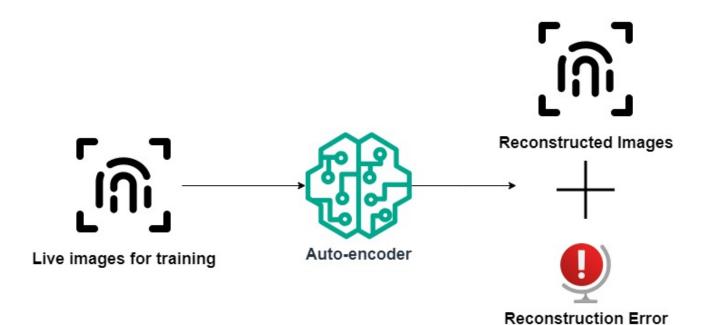


Figure 4 : Flow diagram for this approach

Related Works

 Feature Denoising through Suppression of Noise Channels [6]

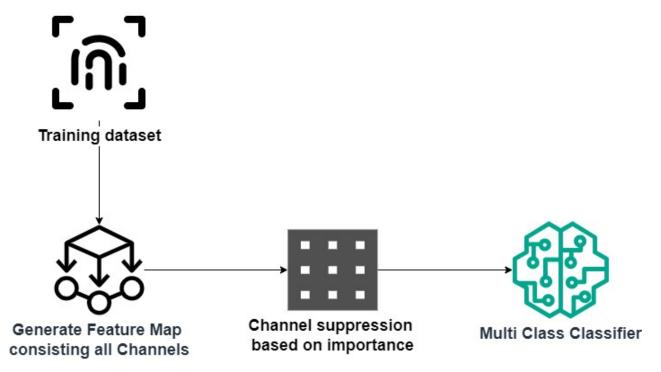


Figure 5 : Flow diagram for this approach

Objectives

• Study the performance a state-of-the-art CNN model, namely VGG16 [2], on LivDet-2011 [1] dataset

 Compare the performance of 2 shallow CNN models with that of the VGG16 [2] model on the same dataset

Dataset used

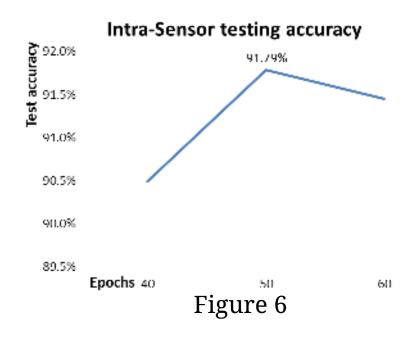
• LivDet-2011 Dataset [1] has been used to train the models

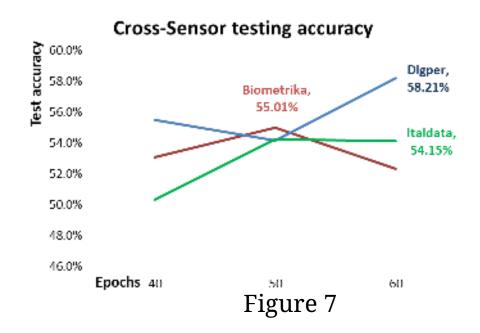
 Contains roughly 16000 fingerprint images from 4 sensors – Biometrika, Italdata, Digper and Sagem

 4000 from each sensor, equally divided into training and testing

Exploring VGG16 Model

- Training a pre-trained VGG16 [2] model on LivDet 2011
 (Sagem sensor) dataset [1]
- Model accuracy peaks at around 50 epochs of training





Exploring shallow CNN architectures

Shallow CNN on LivDet-2011 Dataset (Sagem Sensor) [1]

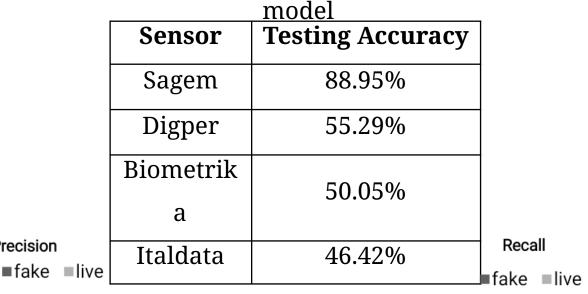
- 8 layers
- 2 convolution layers, 2 max-pooling layers, 2 dense layers, 1 flatten layer and a final Softmax layer

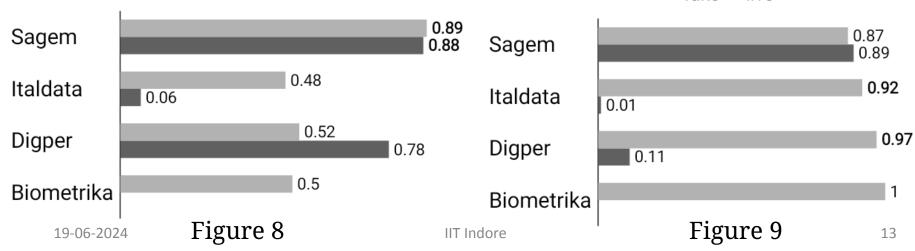
Shallow CNN on LivDet-2011 Dataset (Digper Sensor) [1]

- 9 layers
- 2 convolution layers, 2 max-pooling layers, 3 dense layers, 1 flatten layer and a last Softmax layer

Shallow CNN (Sagem Sensor)

Table 1: Testing accuracy of this





Precision

Shallow CNN on LivDet-2011 Dataset (Sagem Sensor) using Adam optimizer

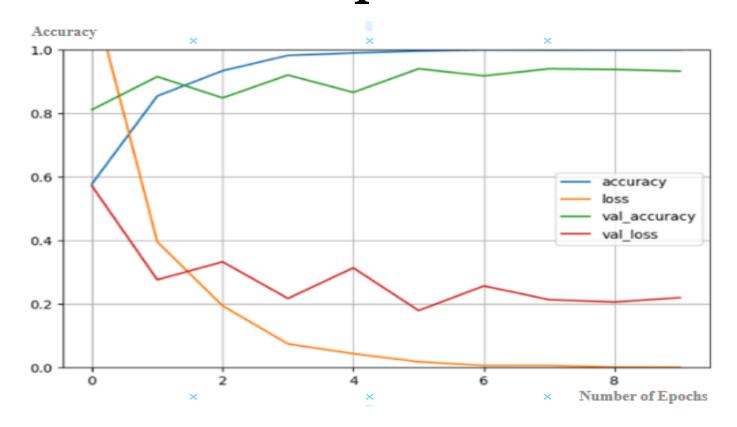


Figure 10 : Accuracy and loss curve using Adam optimizer

Shallow CNN on LivDet-2011 Dataset (Sagem Sensor) using SGD optimizer

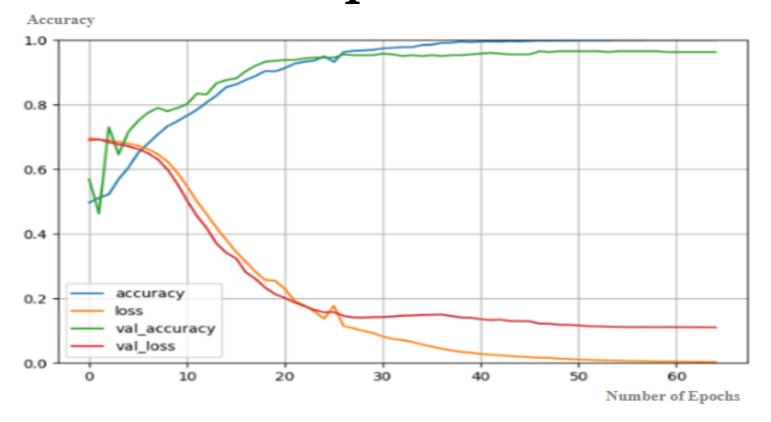
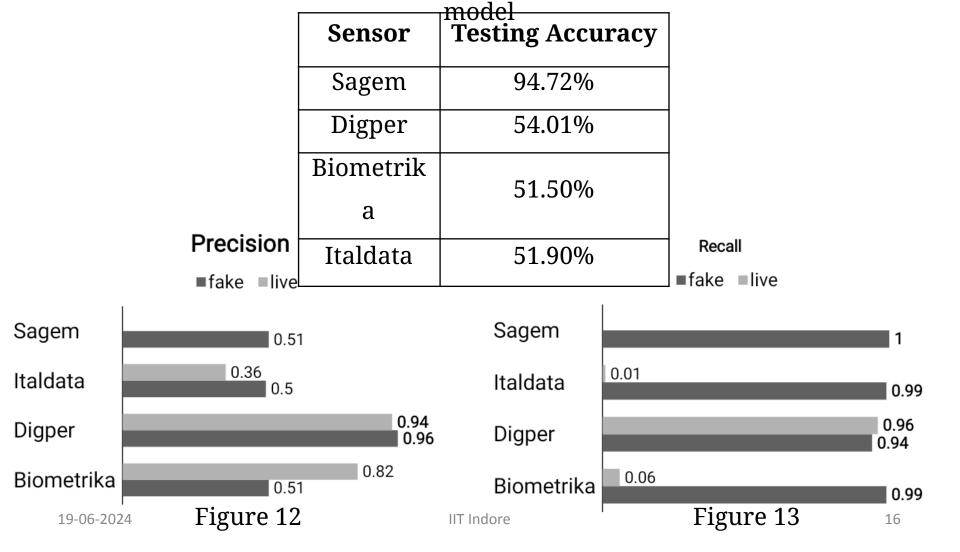


Figure 11 : Accuracy and loss curve using SGD optimizer

Shallow CNN (Digper Sensor)

Table 2: Testing accuracy of this



Shallow CNN on LivDet-2011 Dataset (Digper Sensor) using Adam optimizer

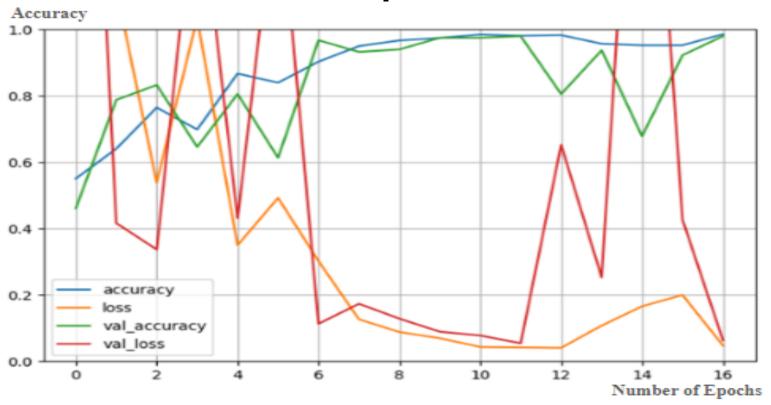


Figure 14 : Accuracy and loss curve using Adam optimizer

Observations

- VGG16 model (Sagem sensor) shows intra-sensor testing accuracy of 91.79%, cross sensor testing accuracy of 58%.
- Shallow CNN network (Digper sensor) exceeds this intrasensor testing accuracy, attaining 94.72%
- Shallow CNN network (Sagem sensor) attains a comparable cross-sensor accuracy 55.29%
- Both shallow networks exhibit high recall values, specially the one trained on Digper sensor data.
- Both shallow networks took up to 70% less time to train

Conclusion

- The observations suggest potential effectiveness of shallow CNN models over deep architecture models
- If used collectively in form of Ensemble
 Classifiers they might prove to be more efficient as well as more practical

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References

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References

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Appendix

