Artificial Intelligence: Deep Learning

Mini project: Face Mask detection

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Individual report

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Introduction

In this mini project, I have developed a neural network which is able to detect if the person is wearing a face mask. This kind of system can be used in a place where one needs to have a face mask on.

I tried to make this solution in two different ways. First I tried by applying custom convnets with data augmentation and second I did it using pre-trained convnets. In a second solution, I just run the convolutional base over the dataset, recording the output to a Numpy array. I could not do it in another way, where we can add a dense layer on top to extend the model, because of the limited time frame I had and GPU requirements. We can also use data augmentation if we add a dense layer on the top. It helps us to reduce the overfitting and is very important while working with the small dataset.

Description

In my dataset, I have different images of people who're having and not having the masks on. Look at the screenshot below for the number of images available for different purposes.

```
In [4]: 1 print('total with mask training images:', len(os.listdir(train_withmask_dir)))
    total with mask training images: 682

In [5]: 1 print('total with mask validation images:', len(os.listdir(validation_withmask_dir)))
    total with mask validation images: 1386

In [6]: 1 print('total with mask test images:', len(os.listdir(test_withmask_dir)))
    total with mask test images: 700

In [7]: 1 print('total without mask training images:', len(os.listdir(train_withoutmask_dir)))
    total without mask training images: 712

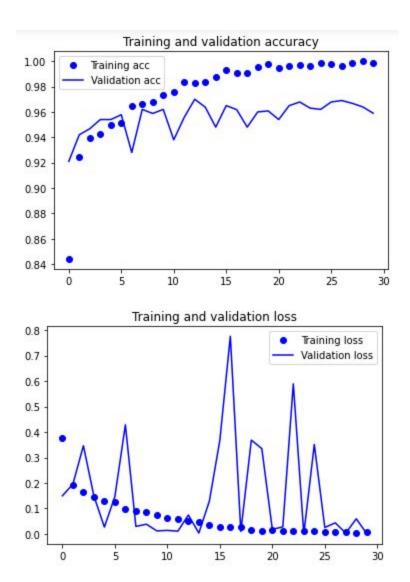
In [8]: 1 print('total without mask validation images:', len(os.listdir(validation_withoutmask_dir)))
    total without mask validation images: 1389

In [9]: 1 print('total without mask test images:', len(os.listdir(test_withoutmask_dir)))
    total without mask test images: 705
```

I've applied convnets to extract the feature map. I assigned different convolutional and pooling layers as you can see in the screenshot below.

Layer (type)	Output	Shape	Param #
conv2d_1 (Conv2D)	(None,	148, 148, 32)	896
max_pooling2d_1 (MaxPooling2	(None,	74, 74, 32)	0
conv2d_2 (Conv2D)	(None,	72, 72, 64)	18496
max_pooling2d_2 (MaxPooling2	(None,	36, 36, 64)	0
conv2d_3 (Conv2D)	(None,	34, 34, 128)	73856
max_pooling2d_3 (MaxPooling2	(None,	17, 17, 128)	0
conv2d_4 (Conv2D)	(None,	15, 15, 128)	147584
max_pooling2d_4 (MaxPooling2	(None,	7, 7, 128)	0
flatten_1 (Flatten)	(None,	6272)	0
dense_1 (Dense)	(None,	512)	3211776
dense_2 (Dense)	(None,	1)	513

From the summary, we can notice that the dimension of the model is decreasing when the depth is increasing and also have 3,453,121 trainable parameters. This is because in every layer it is collecting the features of the images and shrinking. It ended up with having a dimension of 7*7 with 128 depth in the very last pooling layer. Let's look at the generated plot from this result.



Having applied convnets with the different convolutional and pooling layers, our model is overfitted. This can be noticed by the lines of training and accuracy going two different directions. Overfitting has become the biggest problem in our model. This is mainly because our dataset is very small and we do not have any layer like "Dropout" to reduce overfitting.

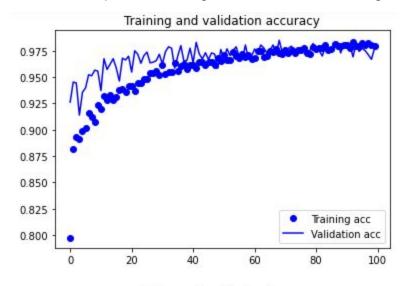
To overcome this problem we have used data augmentation which generates new samples from the existing samples and also applied "Dropout". It alters certain transitions of the original image and makes it different. Data augmentation is one of the most important techniques to overcome overfitting, especially working with small datasets. Because of data augmentation our network never experiences the same input

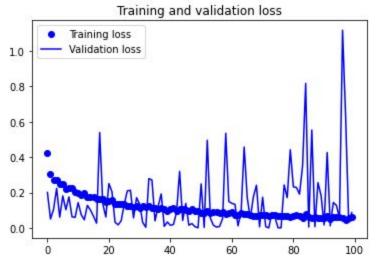
twice but inputs are mostly related because we are just remixing the same information. Let's look at the options below. I have applied for the ImageDataGenerator to perform the data augmentation.

```
train_datagen = ImageDataGenerator(
    rescale=1./255,
    rotation_range=40,
    width_shift_range=0.2,
    height_shift_range=0.2,
    shear_range=0.2,
    zoom_range=0.2,
    horizontal_flip=True,)
```

Each option changes the specific attribute of an image.

Let's see the plot after fitting the model with data augmentation and the dropout.





Now, we have achieved the accuracy of 98% after data augmentation.

Working with pre-trained convnet VGG16 vs Custom

VGG16 is a pre-trained convnet. We can use it in our project in two different ways. First we can just run the convolutional base over our dataset, second we can add a dense layer on top. The second one gives us the ability to use data augmentation.

Comparing customly created networks, using pre-trained convnet is faster. Also it provides better accuracy as it has been tested and developed given a long time.

Notebooks

Face mask detection - Custom convnets

```
In [1]: import keras
        keras. version
        Using TensorFlow backend.
Out[1]: '2.3.1'
In [2]: import os, shutil
In [3]: # The directory where we will
        # store our smaller dataset
        ### MODIFY THIS LINE SO IT FITS WITH YOUR FILES!!!!!
        ## IF YOUR NOTEBOOK IS IN THE SAME FOLDER AS THE DATASET, YOU CAN JUST
        USE RELATIVE PATHS
        base dir = 'dataset'
        # Directories for our training,
        # validation and test splits
        train dir = os.path.join(base dir, 'train')
        validation dir = os.path.join(base_dir, 'validation')
        test dir = os.path.join(base dir, 'test')
        # Directory with our training cat pictures
        train withmask dir = os.path.join(train dir, 'withmask')
        # Directory with our validation cat pictures
        validation withmask dir = os.path.join(validation dir, 'withmask')
        # Directory with our validation cat pictures
        test_withmask_dir = os.path.join(test_dir, 'withmask')
        # Directory with our training cat pictures
        train withoutmask dir = os.path.join(train dir, 'withoutmask')
        # Directory with our validation cat pictures
        validation withoutmask dir = os.path.join(validation dir, 'withoutmask
        # Directory with our validation cat pictures
        test withoutmask dir = os.path.join(test dir, 'withoutmask')
In [4]: print('total with mask training images:', len(os.listdir(train withmask
        dir)))
        total with mask training images: 682
In [5]: print('total with mask validation images:', len(os.listdir(validation w
        ithmask dir)))
        total with mask validation images: 1386
```

```
In [6]: print('total with mask test images:', len(os.listdir(test withmask di
         r)))
         total with mask test images: 700
In [7]: print('total without mask training images:', len(os.listdir(train without
         utmask dir)))
         total without mask training images: 712
In [8]: print('total without mask validation images:', len(os.listdir(validatio
         n_withoutmask_dir)))
         total without mask validation images: 1389
In [9]: print('total without mask test images:', len(os.listdir(test withoutmas
         k dir)))
         total without mask test images: 705
In [10]: from keras import layers
         from keras import models
         model = models.Sequential()
         model.add(layers.Conv2D(32, (3, 3), activation='relu',
                                 input_shape=(150, 150, 3)))
         model.add(layers.MaxPooling2D((2, 2)))
         model.add(layers.Conv2D(64, (3, 3), activation='relu'))
         model.add(layers.MaxPooling2D((2, 2)))
         model.add(layers.Conv2D(128, (3, 3), activation='relu'))
         model.add(layers.MaxPooling2D((2, 2)))
         model.add(layers.Conv2D(128, (3, 3), activation='relu'))
         model.add(layers.MaxPooling2D((2, 2)))
         model.add(layers.Flatten())
         model.add(layers.Dense(512, activation='relu'))
         model.add(layers.Dense(1, activation='sigmoid'))
```

```
In [11]: model.summary()
```

Model: "sequential_1"

Layer (type)	Output	Shape	Param #
conv2d_1 (Conv2D)	(None,	======================================	896
max_pooling2d_1 (MaxPooling2	(None,	74, 74, 32)	0
conv2d_2 (Conv2D)	(None,	72, 72, 64)	18496
max_pooling2d_2 (MaxPooling2	(None,	36, 36, 64)	0
conv2d_3 (Conv2D)	(None,	34, 34, 128)	73856
max_pooling2d_3 (MaxPooling2	(None,	17, 17, 128)	0
conv2d_4 (Conv2D)	(None,	15, 15, 128)	147584
max_pooling2d_4 (MaxPooling2	(None,	7, 7, 128)	0
flatten_1 (Flatten)	(None,	6272)	0
dense_1 (Dense)	(None,	512)	3211776
dense_2 (Dense)	(None,	1)	513
Total params: 3,453,121	_		_ _

Total params: 3,453,121 Trainable params: 3,453,121 Non-trainable params: 0

```
In [13]: from keras.preprocessing.image import ImageDataGenerator
         # All images will be rescaled by 1./255
         train datagen = ImageDataGenerator(rescale=1./255)
         test datagen = ImageDataGenerator(rescale=1./255)
         train generator = train datagen.flow from directory(
                 # This is the target directory
                 train dir,
                 # All images will be resized to 150x150
                 target size=(150, 150),
                 batch size=20,
                 # Since we use binary crossentropy loss, we need binary labels
                 class mode='binary')
         validation generator = test datagen.flow from directory(
                 validation dir,
                 target size=(150, 150),
                 batch size=20,
                 class mode='binary')
         Found 1394 images belonging to 2 classes.
         Found 2775 images belonging to 2 classes.
In [14]: for data batch, labels batch in train generator:
             print('data batch shape:', data batch.shape)
             print('labels batch shape:', labels batch.shape)
```

break

data batch shape: (20, 150, 150, 3)

labels batch shape: (20,)

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```
Epoch 1/30
34/100 [=======>.....] - ETA: 1:09 - loss: 0.5392 - acc: 0.7515
```

C:\Users\saroj\anaconda3\envs\AI_keras_env\lib\site-packages\PIL\Imag
e.py:961: UserWarning: Palette images with Transparency expressed in
bytes should be converted to RGBA images

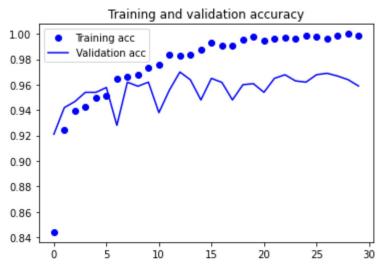
"Palette images with Transparency expressed in bytes should be "

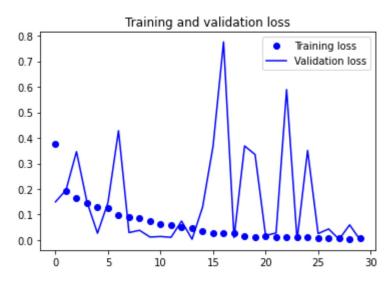
```
4 - acc: 0.8440 - val loss: 0.1498 - val acc: 0.9210
Epoch 2/30
1 - acc: 0.9245 - val loss: 0.1955 - val acc: 0.9420
Epoch 3/30
100/100 [=============== ] - 122s 1s/step - loss: 0.163
8 - acc: 0.9393 - val loss: 0.3463 - val acc: 0.9467
Epoch 4/30
100/100 [============== ] - 133s 1s/step - loss: 0.146
5 - acc: 0.9427 - val loss: 0.1489 - val acc: 0.9540
100/100 [============== ] - 229s 2s/step - loss: 0.129
8 - acc: 0.9493 - val loss: 0.0268 - val acc: 0.9540
Epoch 6/30
6 - acc: 0.9512 - val loss: 0.1472 - val acc: 0.9578
Epoch 7/30
100/100 [=============== ] - 248s 2s/step - loss: 0.098
6 - acc: 0.9644 - val loss: 0.4282 - val acc: 0.9280
Epoch 8/30
100/100 [============== ] - 200s 2s/step - loss: 0.088
8 - acc: 0.9659 - val loss: 0.0294 - val acc: 0.9620
Epoch 9/30
100/100 [============== ] - 225s 2s/step - loss: 0.086
9 - acc: 0.9678 - val loss: 0.0382 - val acc: 0.9588
Epoch 10/30
0 - acc: 0.9734 - val loss: 0.0119 - val acc: 0.9620
Epoch 11/30
100/100 [============== ] - 204s 2s/step - loss: 0.063
6 - acc: 0.9759 - val loss: 0.0140 - val acc: 0.9380
Epoch 12/30
100/100 [=============== ] - 216s 2s/step - loss: 0.058
4 - acc: 0.9835 - val loss: 0.0107 - val acc: 0.9558
Epoch 13/30
100/100 [============== ] - 213s 2s/step - loss: 0.049
3 - acc: 0.9824 - val loss: 0.0744 - val acc: 0.9700
Epoch 14/30
0 - acc: 0.9834 - val loss: 0.0035 - val acc: 0.9638
Epoch 15/30
```

```
In [16]: model.save('face_mask_1.h5')
```

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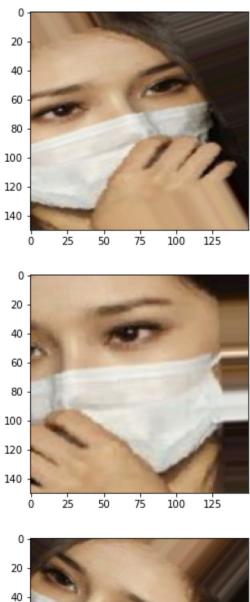
```
In [17]:
         import matplotlib.pyplot as plt
         acc = history.history['acc']
         val acc = history.history['val acc']
         loss = history.history['loss']
         val loss = history.history['val loss']
         epochs = range(len(acc))
         plt.plot(epochs, acc, 'bo', label='Training acc')
         plt.plot(epochs, val_acc, 'b', label='Validation acc')
         plt.title('Training and validation accuracy')
         plt.legend()
         plt.figure()
         plt.plot(epochs, loss, 'bo', label='Training loss')
         plt.plot(epochs, val loss, 'b', label='Validation loss')
         plt.title('Training and validation loss')
         plt.legend()
         plt.show()
```

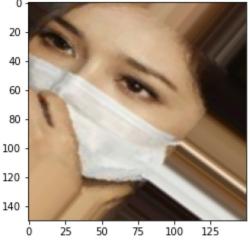




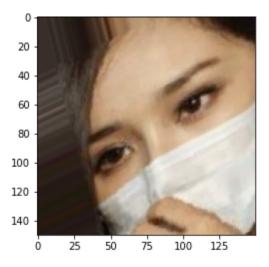
```
In [18]: datagen = ImageDataGenerator(
    rotation_range=40,
    width_shift_range=0.2,
    height_shift_range=0.2,
    shear_range=0.2,
    zoom_range=0.2,
    horizontal_flip=True,
    fill_mode='nearest')
```

```
In [19]: # This is module with image preprocessing utilities
         from keras.preprocessing import image
         fnames = [os.path.join(train withmask dir, fname) for fname in os.listd
         ir(train withmask dir)]
         # We pick one image to "augment"
         img path = fnames[3]
         # Read the image and resize it
         img = image.load img(img path, target size=(150, 150))
         # Convert it to a Numpy array with shape (150, 150, 3)
         x = image.img to array(img)
         # Reshape it to (1, 150, 150, 3)
         x = x.reshape((1,) + x.shape)
         # The .flow() command below generates batches of randomly transformed i
         # It will loop indefinitely, so we need to `break` the loop at some poi
         nt!
         i = 0
         for batch in datagen.flow(x, batch size=1):
             plt.figure(i)
             imgplot = plt.imshow(image.array to img(batch[0]))
             if i % 4 == 0:
                 break
         plt.show()
```





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```
model = models.Sequential()
In [20]:
         model.add(layers.Conv2D(32, (3, 3), activation='relu',
                                  input shape=(150, 150, 3)))
         model.add(layers.MaxPooling2D((2, 2)))
         model.add(layers.Conv2D(64, (3, 3), activation='relu'))
         model.add(layers.MaxPooling2D((2, 2)))
         model.add(layers.Conv2D(128, (3, 3), activation='relu'))
         model.add(layers.MaxPooling2D((2, 2)))
         model.add(layers.Conv2D(128, (3, 3), activation='relu'))
         model.add(layers.MaxPooling2D((2, 2)))
         model.add(layers.Flatten())
         model.add(layers.Dropout(0.5))
         model.add(layers.Dense(512, activation='relu'))
         model.add(layers.Dense(1, activation='sigmoid'))
         model.compile(loss='binary crossentropy',
                       optimizer=optimizers.RMSprop(lr=1e-4),
                       metrics=['acc'])
```

```
In [21]: train datagen = ImageDataGenerator(
            rescale=1./255,
             rotation range=40,
             width shift range=0.2,
             height shift range=0.2,
             shear range=0.2,
             zoom range=0.2,
             horizontal flip=True,)
         # Note that the validation data should not be augmented!
         test datagen = ImageDataGenerator(rescale=1./255)
         train generator = train datagen.flow from directory(
                 # This is the target directory
                 train dir,
                 # All images will be resized to 150x150
                 target size=(150, 150),
                 batch size=32,
                 # Since we use binary crossentropy loss, we need binary labels
                 class mode='binary')
         validation generator = test datagen.flow from directory(
                 validation dir,
                 target size=(150, 150),
                 batch size=32,
                 class mode='binary')
         history = model.fit generator(
               train generator,
               steps per epoch=100,
               epochs=100,
               validation data=validation generator,
               validation steps=50)
```

C:\Users\saroj\anaconda3\envs\AI_keras_env\lib\site-packages\PIL\Imag
e.py:961: UserWarning: Palette images with Transparency expressed in
bytes should be converted to RGBA images

"Palette images with Transparency expressed in bytes should be "

```
5 - acc: 0.7973 - val loss: 0.2011 - val acc: 0.9262
Epoch 2/100
6 - acc: 0.8821 - val loss: 0.0512 - val acc: 0.9453
Epoch 3/100
8 - acc: 0.8933 - val loss: 0.1059 - val acc: 0.9444
Epoch 4/100
100/100 [============== ] - 232s 2s/step - loss: 0.272
6 - acc: 0.8911 - val loss: 0.2245 - val acc: 0.9139
Epoch 5/100
2 - acc: 0.8989 - val loss: 0.0616 - val acc: 0.9356
Epoch 6/100
2 - acc: 0.9013 - val loss: 0.1820 - val acc: 0.9397
Epoch 7/100
100/100 [============== ] - 238s 2s/step - loss: 0.222
8 - acc: 0.9155 - val loss: 0.1035 - val acc: 0.9522
Epoch 8/100
100/100 [=============== ] - 218s 2s/step - loss: 0.228
0 - acc: 0.9120 - val loss: 0.1763 - val acc: 0.9513
Epoch 9/100
100/100 [============== ] - 212s 2s/step - loss: 0.227
9 - acc: 0.9075 - val loss: 0.0636 - val acc: 0.9566
Epoch 10/100
3 - acc: 0.9237 - val loss: 0.0600 - val acc: 0.9556
Epoch 11/100
4 - acc: 0.9199 - val loss: 0.1439 - val acc: 0.9371
Epoch 12/100
100/100 [============== ] - 220s 2s/step - loss: 0.186
3 - acc: 0.9316 - val loss: 0.0751 - val acc: 0.9675
Epoch 13/100
100/100 [============== ] - 216s 2s/step - loss: 0.196
1 - acc: 0.9281 - val loss: 0.0466 - val acc: 0.9573
Epoch 14/100
100/100 [============== ] - 216s 2s/step - loss: 0.173
4 - acc: 0.9332 - val loss: 0.1285 - val acc: 0.9623
Epoch 15/100
100/100 [============== ] - 218s 2s/step - loss: 0.173
6 - acc: 0.9284 - val loss: 0.1017 - val_acc: 0.9675
Epoch 16/100
7 - acc: 0.9313 - val loss: 0.0667 - val acc: 0.9585
Epoch 17/100
100/100 [============= ] - 215s 2s/step - loss: 0.160
7 - acc: 0.9379 - val loss: 0.0276 - val acc: 0.9463
Epoch 18/100
6 - acc: 0.9392 - val loss: 0.5395 - val acc: 0.9679
Epoch 19/100
100/100 [============== ] - 219s 2s/step - loss: 0.164
8 - acc: 0.9357 - val loss: 0.1376 - val acc: 0.9663
```

```
Epoch 20/100
0 - acc: 0.9420 - val loss: 0.0625 - val acc: 0.9698
Epoch 21/100
100/100 [============== ] - 220s 2s/step - loss: 0.151
2 - acc: 0.9417 - val loss: 0.2514 - val acc: 0.9547
Epoch 22/100
100/100 [============== ] - 217s 2s/step - loss: 0.159
5 - acc: 0.9373 - val loss: 0.2049 - val acc: 0.9750
Epoch 23/100
0 - acc: 0.9448 - val loss: 0.0329 - val acc: 0.9717
Epoch 24/100
2 - acc: 0.9443 - val loss: 0.0180 - val acc: 0.9631
Epoch 25/100
100/100 [=============== ] - 216s 2s/step - loss: 0.134
5 - acc: 0.9485 - val loss: 0.0414 - val acc: 0.9705
Epoch 26/100
0 - acc: 0.9481 - val loss: 0.1365 - val acc: 0.9737
Epoch 27/100
3 - acc: 0.9543 - val loss: 0.2103 - val acc: 0.9635
Epoch 28/100
3 - acc: 0.9541 - val loss: 0.2135 - val acc: 0.9642
Epoch 29/100
100/100 [============== ] - 211s 2s/step - loss: 0.120
0 - acc: 0.9562 - val loss: 0.0574 - val acc: 0.9656
Epoch 30/100
3 - acc: 0.9521 - val loss: 0.1715 - val acc: 0.9717
Epoch 31/100
0 - acc: 0.9611 - val loss: 0.1350 - val acc: 0.9625
Epoch 32/100
100/100 [============== ] - 213s 2s/step - loss: 0.124
1 - acc: 0.9529 - val loss: 0.0314 - val acc: 0.9742
Epoch 33/100
100/100 [============== ] - 213s 2s/step - loss: 0.122
6 - acc: 0.9547 - val loss: 0.0045 - val acc: 0.9787
Epoch 34/100
7 - acc: 0.9552 - val loss: 0.2791 - val acc: 0.9774
Epoch 35/100
100/100 [============= ] - 214s 2s/step - loss: 0.114
4 - acc: 0.9630 - val loss: 0.2716 - val acc: 0.9585
Epoch 36/100
100/100 [============== ] - 212s 2s/step - loss: 0.112
7 - acc: 0.9562 - val loss: 0.0406 - val acc: 0.9700
Epoch 37/100
100/100 [============== ] - 226s 2s/step - loss: 0.109
7 - acc: 0.9609 - val loss: 0.1216 - val acc: 0.9799
Epoch 38/100
100/100 [============== ] - 212s 2s/step - loss: 0.116
```

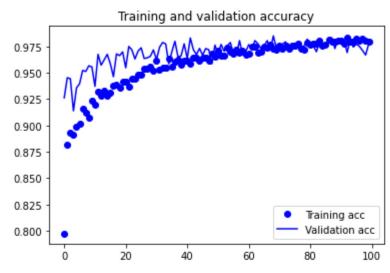
```
1 - acc: 0.9625 - val loss: 0.1928 - val acc: 0.9650
Epoch 39/100
100/100 [============= ] - 210s 2s/step - loss: 0.107
4 - acc: 0.9574 - val loss: 0.0093 - val acc: 0.9661
Epoch 40/100
2 - acc: 0.9617 - val loss: 0.0342 - val acc: 0.9775
Epoch 41/100
100/100 [============== ] - 216s 2s/step - loss: 0.109
3 - acc: 0.9619 - val loss: 0.0156 - val acc: 0.9635
Epoch 42/100
1 - acc: 0.9584 - val loss: 0.0202 - val acc: 0.9830
Epoch 43/100
5 - acc: 0.9639 - val loss: 0.0888 - val acc: 0.9719
Epoch 44/100
100/100 [============== ] - 213s 2s/step - loss: 0.105
3 - acc: 0.9644 - val loss: 0.3201 - val acc: 0.9673
Epoch 45/100
3 - acc: 0.9612 - val loss: 0.0425 - val acc: 0.9731
Epoch 46/100
100/100 [============== ] - 211s 2s/step - loss: 0.104
3 - acc: 0.9647 - val loss: 0.1395 - val acc: 0.9667
Epoch 47/100
100/100 [============== ] - 208s 2s/step - loss: 0.095
8 - acc: 0.9645 - val loss: 0.0163 - val acc: 0.9730
Epoch 48/100
9 - acc: 0.9612 - val loss: 0.0253 - val acc: 0.9719
Epoch 49/100
100/100 [============== ] - 210s 2s/step - loss: 0.094
0 - acc: 0.9680 - val loss: 0.0078 - val acc: 0.9585
Epoch 50/100
5 - acc: 0.9650 - val loss: 0.0012 - val acc: 0.9762
Epoch 51/100
100/100 [============= ] - 209s 2s/step - loss: 0.084
8 - acc: 0.9708 - val loss: 0.2496 - val acc: 0.9679
Epoch 52/100
0 - acc: 0.9658 - val loss: 0.0037 - val acc: 0.9769
Epoch 53/100
100/100 [============== ] - 211s 2s/step - loss: 0.094
1 - acc: 0.9660 - val loss: 0.4959 - val acc: 0.9705
Epoch 54/100
100/100 [============== ] - 220s 2s/step - loss: 0.082
9 - acc: 0.9737 - val loss: 0.0561 - val acc: 0.9755
Epoch 55/100
100/100 [============= ] - 212s 2s/step - loss: 0.088
8 - acc: 0.9697 - val loss: 0.0158 - val acc: 0.9787
Epoch 56/100
100/100 [============= ] - 209s 2s/step - loss: 0.088
7 - acc: 0.9682 - val loss: 0.0056 - val acc: 0.9686
Epoch 57/100
```

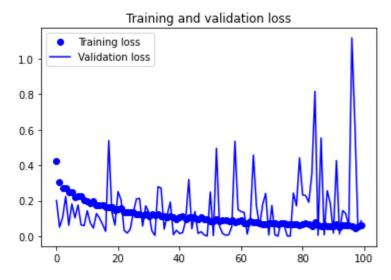
```
100/100 [============= ] - 210s 2s/step - loss: 0.087
9 - acc: 0.9715 - val loss: 0.0087 - val acc: 0.9669
Epoch 58/100
8 - acc: 0.9691 - val loss: 0.0549 - val acc: 0.9805
Epoch 59/100
100/100 [=============== ] - 215s 2s/step - loss: 0.078
3 - acc: 0.9712 - val loss: 0.5352 - val acc: 0.9669
Epoch 60/100
1 - acc: 0.9674 - val loss: 0.1503 - val acc: 0.9698
Epoch 61/100
100/100 [============== ] - 211s 2s/step - loss: 0.090
4 - acc: 0.9683 - val loss: 0.1392 - val acc: 0.9767
Epoch 62/100
100/100 [=============== ] - 214s 2s/step - loss: 0.073
0 - acc: 0.9751 - val loss: 0.1342 - val acc: 0.9725
Epoch 63/100
100/100 [============== ] - 213s 2s/step - loss: 0.073
5 - acc: 0.9751 - val loss: 0.0123 - val acc: 0.9805
Epoch 64/100
4 - acc: 0.9687 - val loss: 0.0922 - val acc: 0.9775
Epoch 65/100
6 - acc: 0.9699 - val loss: 0.4577 - val acc: 0.9730
Epoch 66/100
100/100 [============== ] - 210s 2s/step - loss: 0.077
4 - acc: 0.9750 - val loss: 0.1701 - val acc: 0.9756
Epoch 67/100
0 - acc: 0.9741 - val loss: 0.0562 - val acc: 0.9805
Epoch 68/100
100/100 [============== ] - 208s 2s/step - loss: 0.069
8 - acc: 0.9763 - val loss: 0.1772 - val acc: 0.9717
Epoch 69/100
100/100 [============== ] - 210s 2s/step - loss: 0.066
2 - acc: 0.9732 - val loss: 0.2420 - val acc: 0.9850
Epoch 70/100
100/100 [============= ] - 215s 2s/step - loss: 0.074
9 - acc: 0.9719 - val loss: 0.0070 - val acc: 0.9730
Epoch 71/100
6 - acc: 0.9753 - val loss: 0.1743 - val acc: 0.9744
Epoch 72/100
100/100 [============== ] - 211s 2s/step - loss: 0.075
9 - acc: 0.9729 - val loss: 0.0082 - val acc: 0.9774
Epoch 73/100
100/100 [============== ] - 208s 2s/step - loss: 0.069
8 - acc: 0.9754 - val loss: 8.3167e-04 - val acc: 0.9794
Epoch 74/100
100/100 [=============== ] - 215s 2s/step - loss: 0.073
3 - acc: 0.9732 - val loss: 0.0875 - val acc: 0.9705
Epoch 75/100
9 - acc: 0.9757 - val loss: 0.0629 - val acc: 0.9736
```

```
Epoch 76/100
100/100 [============== ] - 210s 2s/step - loss: 0.067
1 - acc: 0.9760 - val loss: 0.0018 - val acc: 0.9781
Epoch 77/100
100/100 [============== ] - 211s 2s/step - loss: 0.069
2 - acc: 0.9772 - val loss: 0.0014 - val acc: 0.9767
Epoch 78/100
100/100 [============== ] - 210s 2s/step - loss: 0.070
4 - acc: 0.9729 - val loss: 0.2435 - val acc: 0.9744
Epoch 79/100
100/100 [============== ] - 213s 2s/step - loss: 0.070
7 - acc: 0.9716 - val loss: 0.1716 - val acc: 0.9755
Epoch 80/100
100/100 [============== ] - 209s 2s/step - loss: 0.064
0 - acc: 0.9782 - val loss: 0.4422 - val acc: 0.9819
Epoch 81/100
100/100 [=============== ] - 214s 2s/step - loss: 0.067
2 - acc: 0.9764 - val loss: 0.2328 - val acc: 0.9755
Epoch 82/100
5 - acc: 0.9779 - val loss: 0.2294 - val acc: 0.9755
Epoch 83/100
100/100 [================ ] - 207s 2s/step - loss: 0.066
4 - acc: 0.9776 - val loss: 0.1915 - val acc: 0.9700
Epoch 84/100
7 - acc: 0.9807 - val loss: 0.3512 - val acc: 0.9793
Epoch 85/100
```

In [22]: model.save('face_mask_2.h5')

```
In [23]:
         acc = history.history['acc']
         val acc = history.history['val acc']
         loss = history.history['loss']
         val loss = history.history['val loss']
         epochs = range(len(acc))
         plt.plot(epochs, acc, 'bo', label='Training acc')
         plt.plot(epochs, val_acc, 'b', label='Validation acc')
         plt.title('Training and validation accuracy')
         plt.legend()
         plt.figure()
         plt.plot(epochs, loss, 'bo', label='Training loss')
         plt.plot(epochs, val loss, 'b', label='Validation loss')
         plt.title('Training and validation loss')
         plt.legend()
         plt.show()
```





```
In [24]: # We pick one image to "augment"
    img_path = 'manwithmask.jpg'

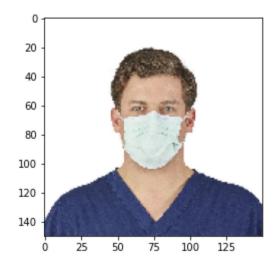
# Read the image and resize it
    img = image.load_img(img_path, target_size=(150, 150))

# Convert it to a Numpy array with shape (150, 150, 3)
    x = image.img_to_array(img)

# Reshape it to (1, 150, 150, 3)
    x = x.reshape((1,) + x.shape)
    prediction = model.predict(x)
    item = prediction.item()
```

```
In [25]: plt.imshow(img)
   (item)
```

Out[25]: 0.0



```
In [26]: # We pick one image to "augment"
    img_path = 'manwithoutmask.jpg'

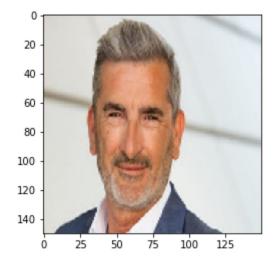
# Read the image and resize it
    img = image.load_img(img_path, target_size=(150, 150))

# Convert it to a Numpy array with shape (150, 150, 3)
    x = image.img_to_array(img)

# Reshape it to (1, 150, 150, 3)
    x = x.reshape((1,) + x.shape)
    prediction = model.predict(x)
    item = prediction.item()
```

```
In [27]: plt.imshow(img)
   (item)
```

Out[27]: 1.0



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Face mask detection - VGG16 (Without data augmentation)

```
In [11]: import keras
   keras.__version__
Out[11]: '2.3.1'
```

Let's instantiate the VGG16 model:

Let's look at the details of an architechture of VGG16 convolutional base.

In [12]: conv_base.summary()

Model: "vgg16"

Layer (type)	Output Shape	Param #
input_2 (InputLayer)	(None, 150, 150, 3)	0
block1_conv1 (Conv2D)	(None, 150, 150, 64)	1792
block1_conv2 (Conv2D)	(None, 150, 150, 64)	36928
block1_pool (MaxPooling2D)	(None, 75, 75, 64)	0
block2_conv1 (Conv2D)	(None, 75, 75, 128)	73856
block2_conv2 (Conv2D)	(None, 75, 75, 128)	147584
block2_pool (MaxPooling2D)	(None, 37, 37, 128)	0
block3_conv1 (Conv2D)	(None, 37, 37, 256)	295168
block3_conv2 (Conv2D)	(None, 37, 37, 256)	590080
block3_conv3 (Conv2D)	(None, 37, 37, 256)	590080
block3_pool (MaxPooling2D)	(None, 18, 18, 256)	0
block4_conv1 (Conv2D)	(None, 18, 18, 512)	1180160
block4_conv2 (Conv2D)	(None, 18, 18, 512)	2359808
block4_conv3 (Conv2D)	(None, 18, 18, 512)	2359808
block4_pool (MaxPooling2D)	(None, 9, 9, 512)	0
block5_conv1 (Conv2D)	(None, 9, 9, 512)	2359808
block5_conv2 (Conv2D)	(None, 9, 9, 512)	2359808
block5_conv3 (Conv2D)	(None, 9, 9, 512)	2359808
block5_pool (MaxPooling2D)	(None, 4, 4, 512)	0
Total params: 14,714,688	==================================	

Total params: 14,714,688
Trainable params: 14,714,688

Non-trainable params: 0

Let's extract images as Numphy Arrays as well as their labels

```
In [13]: import os
         import numpy as np
         from keras.preprocessing.image import ImageDataGenerator
         ## YOUR OWN DIRECTORY!
         base dir = 'dataset'
         train dir = os.path.join(base dir, 'train')
         validation dir = os.path.join(base dir, 'validation')
         test dir = os.path.join(base dir, 'test')
         datagen = ImageDataGenerator(rescale=1./255)
         batch size = 20
         def extract features(directory, sample count):
             features = np.zeros(shape=(sample count, 4, 4, 512))
             labels = np.zeros(shape=(sample count))
             generator = datagen.flow from directory(
                 directory,
                 target_size=(150, 150),
                 batch size=batch size,
                 class mode='binary')
             for inputs batch, labels batch in generator:
                 features batch = conv base.predict(inputs batch)
                 features[i * batch size : (i + 1) * batch size] = features batc
                 labels[i * batch size : (i + 1) * batch size] = labels batch
                 i += 1
                 if i * batch size >= sample count:
                      # Note that since generators yield data indefinitely in a l
         oop,
                     # we must `break` after every image has been seen once.
                     break
             return features, labels
         train features, train labels = extract features(train dir, 2700)
         validation features, validation labels = extract features(validation di
         r, 1350)
         test features, test labels = extract features(test dir, 1350)
         Found 2700 images belonging to 2 classes.
         Found 1350 images belonging to 2 classes.
         Found 1350 images belonging to 2 classes.
```

The extracted features are currently of shape (samples, 4, 4, 512) so, we much flatten them.

```
In [14]: train_features = np.reshape(train_features, (2700, 4 * 4 * 512))
    validation_features = np.reshape(validation_features, (1350, 4 * 4 * 51
    2))
    test_features = np.reshape(test_features, (1350, 4 * 4 * 512))
```

Let's define our densely connected classifier and triain it on data and labels that we just recorded.

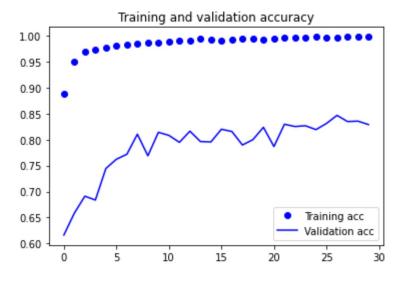
```
Train on 2700 samples, validate on 1350 samples
Epoch 1/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.31
21 - acc: 0.8885 - val loss: 0.6637 - val acc: 0.6163
Epoch 2/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.13
94 - acc: 0.9507 - val loss: 0.6497 - val acc: 0.6585
Epoch 3/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.09
45 - acc: 0.9689 - val loss: 0.6341 - val acc: 0.6911
Epoch 4/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.07
77 - acc: 0.9741 - val loss: 0.6767 - val acc: 0.6837
Epoch 5/30
2700/2700 [============== ] - 6s 2ms/step - loss: 0.06
47 - acc: 0.9778 - val loss: 0.5161 - val acc: 0.7444
Epoch 6/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.05
67 - acc: 0.9815 - val loss: 0.4893 - val acc: 0.7622
Epoch 7/30
2700/2700 [==============] - 5s 2ms/step - loss: 0.05
16 - acc: 0.9819 - val loss: 0.4814 - val acc: 0.7719
Epoch 8/30
2700/2700 [===============] - 5s 2ms/step - loss: 0.04
56 - acc: 0.9852 - val loss: 0.4073 - val acc: 0.8104
Epoch 9/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.04
22 - acc: 0.9874 - val loss: 0.4959 - val acc: 0.7689
Epoch 10/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.03
80 - acc: 0.9870 - val loss: 0.4089 - val acc: 0.8141
Epoch 11/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.03
55 - acc: 0.9878 - val loss: 0.4242 - val acc: 0.8081
Epoch 12/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.03
35 - acc: 0.9896 - val loss: 0.4618 - val acc: 0.7948
Epoch 13/30
2700/2700 [=============== ] - 5s 2ms/step - loss: 0.02
95 - acc: 0.9900 - val loss: 0.4180 - val acc: 0.8163
Epoch 14/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.02
38 - acc: 0.9937 - val loss: 0.4675 - val acc: 0.7963
Epoch 15/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.02
60 - acc: 0.9922 - val loss: 0.4753 - val acc: 0.7956
Epoch 16/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.02
69 - acc: 0.9911 - val loss: 0.4236 - val acc: 0.8200
Epoch 17/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.02
16 - acc: 0.9930 - val loss: 0.4394 - val acc: 0.8156
2700/2700 [============== ] - 5s 2ms/step - loss: 0.02
16 - acc: 0.9948 - val loss: 0.4935 - val acc: 0.7896
Epoch 19/30
```

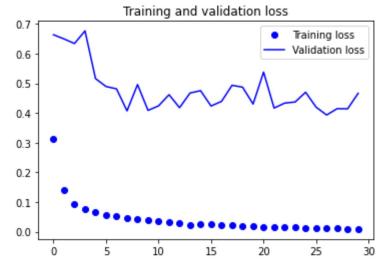
```
2700/2700 [=============== ] - 5s 2ms/step - loss: 0.01
86 - acc: 0.9952 - val loss: 0.4870 - val acc: 0.8000
Epoch 20/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.02
02 - acc: 0.9933 - val loss: 0.4304 - val acc: 0.8237
Epoch 21/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.01
62 - acc: 0.9948 - val loss: 0.5379 - val acc: 0.7867
Epoch 22/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.01
55 - acc: 0.9963 - val loss: 0.4167 - val acc: 0.8296
Epoch 23/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.01
54 - acc: 0.9970 - val loss: 0.4335 - val acc: 0.8252
Epoch 24/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.01
53 - acc: 0.9963 - val loss: 0.4372 - val acc: 0.8267
Epoch 25/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.01
27 - acc: 0.9974 - val loss: 0.4700 - val acc: 0.8193
Epoch 26/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.01
32 - acc: 0.9967 - val loss: 0.4197 - val acc: 0.8311
Epoch 27/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.01
35 - acc: 0.9959 - val loss: 0.3934 - val acc: 0.8467
Epoch 28/30
2700/2700 [============= ] - 5s 2ms/step - loss: 0.01
14 - acc: 0.9974 - val loss: 0.4147 - val acc: 0.8348
Epoch 29/30
2700/2700 [============== ] - 5s 2ms/step - loss: 0.01
03 - acc: 0.9978 - val loss: 0.4143 - val acc: 0.8356
Epoch 30/30
2700/2700 [=============== ] - 5s 2ms/step - loss: 0.00
93 - acc: 0.9978 - val loss: 0.4664 - val acc: 0.8289
```

Let's look at the plot for loss and accuracy during the plotting.

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```
In [16]:
         import matplotlib.pyplot as plt
         acc = history.history['acc']
         val acc = history.history['val acc']
         loss = history.history['loss']
         val loss = history.history['val loss']
         epochs = range(len(acc))
         plt.plot(epochs, acc, 'bo', label='Training acc')
         plt.plot(epochs, val_acc, 'b', label='Validation acc')
         plt.title('Training and validation accuracy')
         plt.legend()
         plt.figure()
         plt.plot(epochs, loss, 'bo', label='Training loss')
         plt.plot(epochs, val loss, 'b', label='Validation loss')
         plt.title('Training and validation loss')
         plt.legend()
         plt.show()
```





We reached validation accuracy around 85%. However, we can also some overfitting. This is because we cannot add data augmentation in this technique to reduce overfitting. Technique to reduce overfitting is very important while we work with small datasets.

Let's save the model

```
In [17]: model.save('face_mask_3.h5')
```

This is the end of this notebook

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Real Time detection

1 of 2

```
In [3]: import cv2
        import numpy as np
        from PIL import Image
        from keras import models
        #Load the saved model
        model = models.load model('face mask 2.h5')
        video = cv2.VideoCapture(1)
        labels dict={0:'with mask',1:'without mask'}
        color dict=\{0: (0,255,0), 1: (0,0,255)\}
        while True:
                , frame = video.read()
                #Convert the captured frame into RGB
                im = Image.fromarray(frame, 'RGB')
                #Resizing into 128x128 because we trained the model with this i
        mage size.
                im = im.resize((150, 150))
                img array = np.array(im)
                #Our keras model used a 4D tensor, (images x height x width x c
        hannel)
                #So changing dimension 128x128x3 into 1x128x128x3
                img array = np.expand dims(img array, axis=0)
                #Calling the predict method on model to predict 'me' on the ima
        ge
                prediction = int(model.predict(img array)[0][0])
                luna = str(model.predict proba(img array))
                #if prediction is 0, which means I am missing on the image, the
        n show the frame in gray color.
                if prediction == 0:
                         cv2.putText(frame, 'Mask! Probability:' + luna, (50, 5
        0), cv2.FONT HERSHEY SIMPLEX, 1, (0, 255, 255), 2, cv2.LINE 4)
                if prediction == 1:
                         cv2.putText(frame, 'No mask! Probability:' + luna, (5
        0, 50), cv2.FONT HERSHEY SIMPLEX, 1, (0, 255, 255), 2, cv2.LINE 4)
                cv2.imshow("Capturing", frame)
                key=cv2.waitKey(1)
                if key == ord('q'):
                        break
        video.release()
        cv2.destroyAllWindows()
```

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Conclusion

It has been fun working with CNN to determine if the person is wearing a facemask. There are multiple ways we can choose to implement an idea. Performing without a pre-trained convnets is time consuming where we have to spend a lot of time to find out what works the best. But on the other hand if we are working with a small dataset, we still need to apply data augmentation even if we have a pre-trained network. It takes a lot of time and GPU.

Convolutional and pooling layers are very important to generate a feature map. It gathers important features from the input and shrinks the dimension. Which progressively transforms the image from human readable to non-readable.