

```
const int pir =4;
2
   const int temp = A0;
3
   int led =6;
4
5
   int motor =7;
   int buzzer =8;
6
7
8
   void setup()
9
10
      Serial.begin(9600);
11
      pinMode (pir, INPUT);
12
      pinMode (temp, INPUT);
13
      pinMode (led, OUTPUT);
14
      pinMode (motor, OUTPUT);
15
      pinMode (buzzer, OUTPUT);
16
17
18
    void loop()
19
       int pirval = digitalRead(pir);
20
       int tempval = analogRead(temp);
       if (pirval == HIGH)
         digitalWrite (led, HIGH);
       else
```

```
void loop()
18
19
       int pirval = digitalRead(pir);
20
       int tempval = analogRead(temp);
21
       if (pirval == HIGH)
22
23
24
         digitalWrite (led, HIGH);
25
26
       else
27
28
         digitalWrite (led, LOW);
 29
 30
       if (tempval>=200)
31
 32
         digitalWrite (motor, HIGH);
 33
         digitalWrite (buzzer, HIGH);
 34
 35
       else
          digitalWrite (motor, LOW);
          digitalWrite (buzzer, LOW);
```