

EMI and productivity

David Garcia and Segun Aroyehun

1: Scatter plots

```
library(dplyr)
library(lmtest)
library(sandwich)
library(tseries)
library(ggplot2)
library(ggrepel)
library(stargazer)
library(car)
library(interactions)
library(lsr)
output_path <- "output"

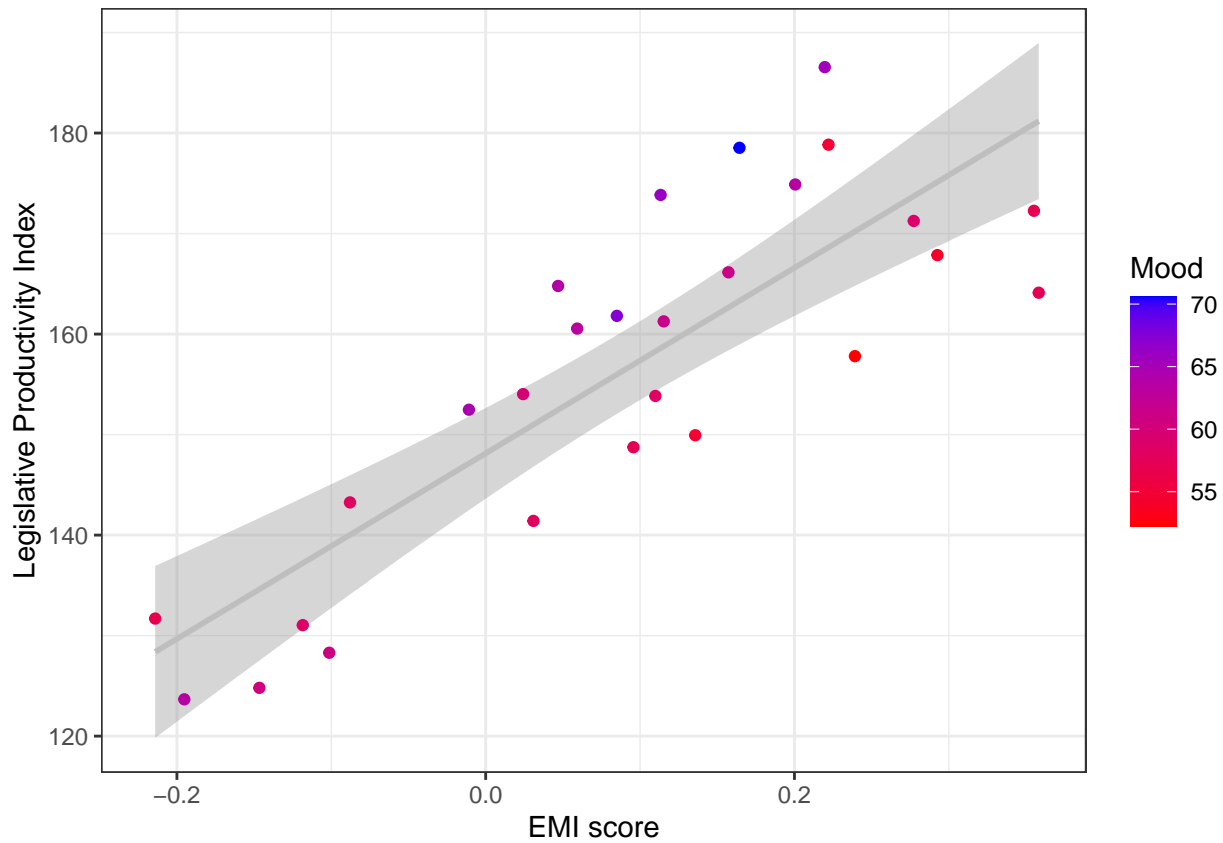
df <- read.csv("data/emi_congressw2v_prod_variables_public_laws.csv")
df_avg <- df %>% rowwise() %>% mutate(Avg_pol=mean(c(House_party.mean.diff.d1, Senate_party.mean.diff.d1)))
df_avg$EMI <- df_avg$evidence_minus_intuition_score

mood_df <- read.csv('data/mood_biannual.csv')
names(mood_df)[names(mood_df) == "FirstYear"] <- "starting_year"
df_avg %>% left_join(mood_df, by = "starting_year") -> df_plot

df_plot %>% filter(!is.na(Mood)) -> df_plot

ggplot(df_plot, aes(x=EMI, y=LPI, color=Mood)) + geom_smooth(method = "lm", color="gray") + geom_point()

## Warning: Removed 9 rows containing non-finite values (`stat_smooth()`).
## Warning: Removed 9 rows containing missing values (`geom_point()`).
```



```
ggsave(filename = file.path(output_path, "LPI_scatter.pdf"), width = 4, height = 3, dpi = 300, device =
```

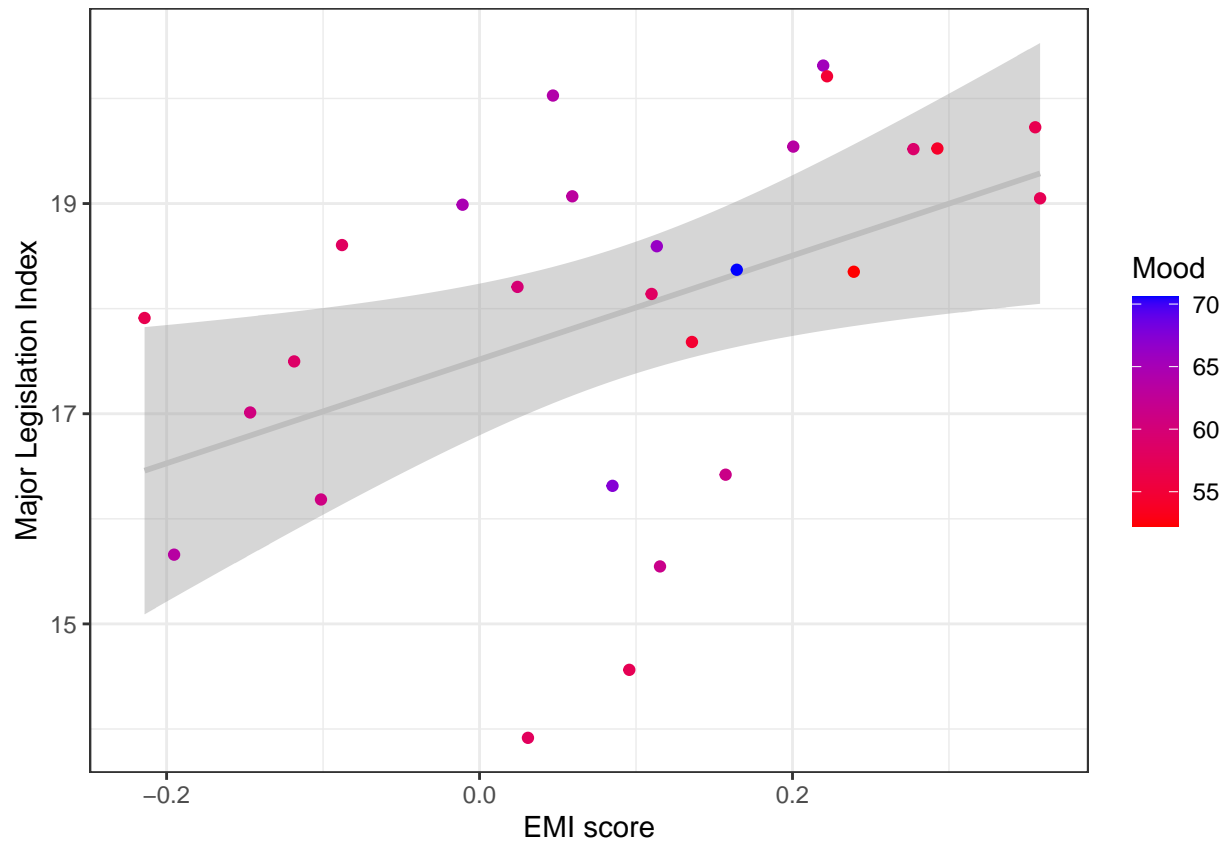
```
## Warning: Removed 9 rows containing non-finite values (`stat_smooth()`).
```

```
## Removed 9 rows containing missing values (`geom_point()`).
```

```
ggplot(df_plot, aes(x=EMI, y=MLI, color=Mood)) + geom_smooth(method = "lm", color="gray") + geom_point(
```

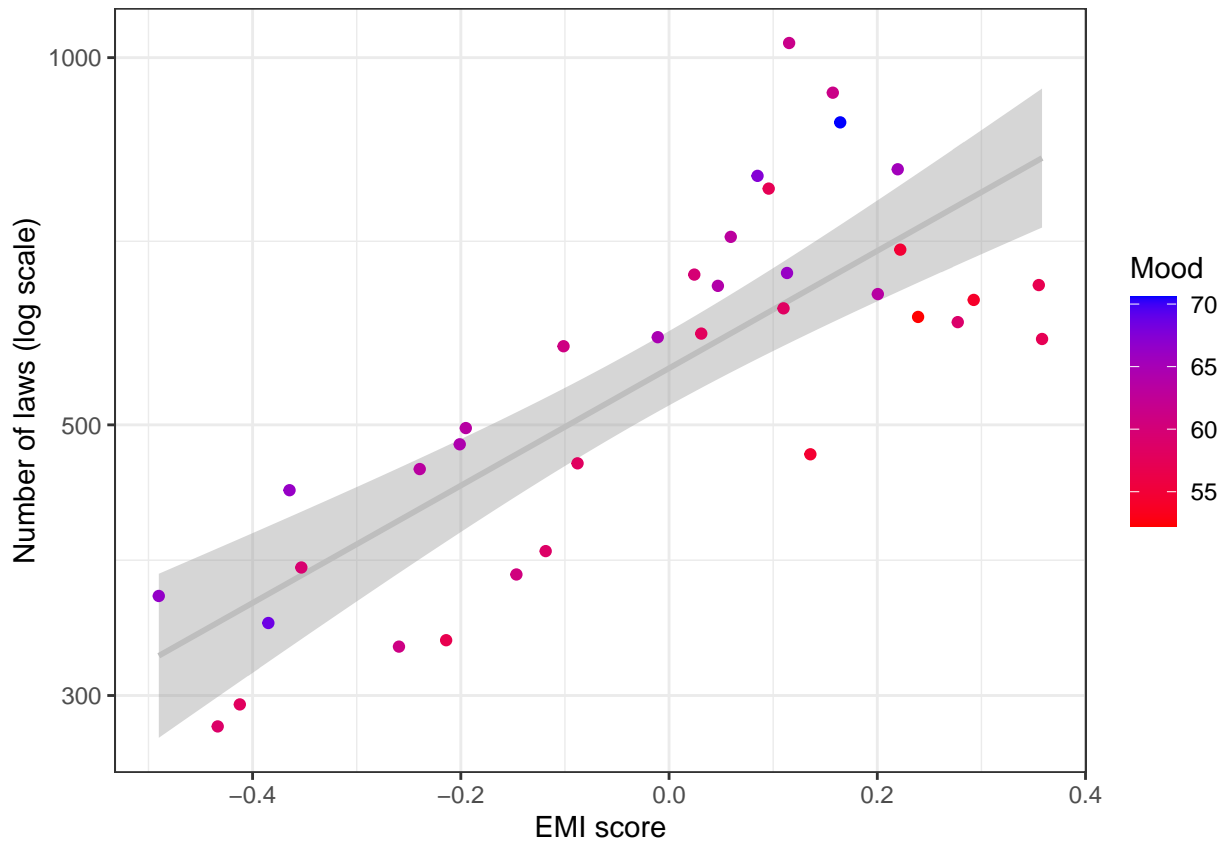
```
## Warning: Removed 9 rows containing non-finite values (`stat_smooth()`).
```

```
## Removed 9 rows containing missing values (`geom_point()`).
```



```
ggsave(filename = file.path(output_path, "MLI_scatter.pdf"), width = 4, height = 3, dpi = 300, device =

## Warning: Removed 9 rows containing non-finite values (`stat_smooth()`).
## Removed 9 rows containing missing values (`geom_point()`).
ggplot(df_plot, aes(x=EMI, y=nlaw, color=Mood)) + geom_smooth(method = "lm", color="gray") + geom_poin
```



```
ggsave(filename = file.path(output_path, "nlaw_scatter.pdf"), width = 4, height = 3, dpi = 300, device = "pdf")
```

2: Models including mood

```
df <- read.csv("data/emi_congressw2v_prod_variables_public_laws.csv")

df_avg <- df %>% rowwise() %>% mutate(Avg_pol=mean(c(House_party.mean.diff.d1, Senate_party.mean.diff.d1)))

df_avg$MLI <- scale(df_avg$MLI)
df_avg$MLIpre <- lag(df_avg$MLI)
df_avg$LPI <- scale(df_avg$LPI)
df_avg$LPIpre <- lag(df_avg$LPI)
df_avg$lognlaw <- scale(log(df_avg$count))
df_avg$lognlawpre <- lag(df_avg$lognlaw)

df_avg$controlDif <- df_avg$party_control!=lag(df_avg$party_control)
df_avg$controlDif <- df_avg$party_control!=lag(df_avg$party_control)
df_avg$EMI <- scale(df_avg$evidence_minus_intuition_score)
df_avg$Pol <- scale(df_avg$Avg_pol)
df_avg$logpatents <- scale(log(df_avg$number_of_patents))

mood_df <- read.csv('data/mood_biannual.csv')
names(mood_df)[names(mood_df) == "FirstYear"] <- "starting_year"

df_avg %>% left_join(mood_df, by = "starting_year") -> df_avg_mood
```

```

df_avg_mood$MLIpre <- lag(df_avg_mood$MLI)
df_avg_mood$LPIpre <- lag(df_avg_mood$LPI)
df_avg_mood$lognlawpre <- lag(df_avg_mood$lognlaw)
df_avg_mood$controlDif <- df_avg_mood$party_control!=lag(df_avg_mood$party_control)
df_avg_mood$controlDif <- df_avg_mood$party_control!=lag(df_avg_mood$party_control)

df_avg_mood %>% filter(LastYear>=1949) -> df_avg_mood #one session before mood data starts

df_avg_mood$MLI <- scale(df_avg_mood$MLI)
df_avg_mood$LPI <- scale(df_avg_mood$LPI)
df_avg_mood$lognlaw <- scale(log(df_avg_mood$count))

df_avg_mood$MLIpre <- scale(df_avg_mood$MLIpre)
df_avg_mood$LPIpre <- scale(df_avg_mood$LPIpre)
df_avg_mood$lognlawpre <- scale(df_avg_mood$lognlawpre)

df_avg_mood$EMI <- scale(df_avg_mood$evidence_minus_intuition_score)
df_avg_mood$Pol <- scale(df_avg_mood$Avg_pol)
df_avg_mood$logpatents <- scale(log(df_avg_mood$number_of_patents))
df_avg_mood$Mood <- scale(df_avg_mood$Mood)

attach(df_avg_mood)

model_mli0 <- lm(MLI~MLIpre+Pol+party_control+controlDif+Mood)
etaSquared(model_mli0)

##               eta.sq eta.sq.part
## MLIpre          0.808378529  0.81637089
## Pol             0.032738306  0.15257658
## party_control  0.005064057  0.02709567
## controlDif     0.007241234  0.03829870
## Mood           0.028794833  0.13671060

model_mli0_coefs <- coeftest(model_mli0, vcov=vcovHAC(model_mli0))
model_mli <- lm(MLI~MLIpre+EMI*Pol+party_control+controlDif+Mood)
vif(model_mli)

##          MLIpre          EMI          Pol party_control  controlDif
##      2.078284      6.334590      4.680607      1.194112      1.170732
##          Mood          EMI:Pol
##      1.206852      2.322269

model_mli_coefs <- coeftest(model_mli, vcov=vcovHAC(model_mli))
model_mli_coefs

##
## t test of coefficients:
##
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  -0.135679   0.159269  -0.8519  0.404889
## MLIpre        0.768745   0.072478  10.6066 2.021e-09 ***
## EMI           0.669028   0.253970   2.6343  0.016343 *
## Pol           0.211636   0.237671   0.8905  0.384357
## party_control -0.084345   0.187283  -0.4504  0.657548

```

```

## controlDifTRUE      0.266026    0.194546    1.3674    0.187454
## Mood                0.236889    0.082201    2.8818    0.009552 **
## EMI:Pol             0.232486    0.297494    0.7815    0.444149
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

adf.test(residuals(model_mli))

##
## Augmented Dickey-Fuller Test
##
## data:  residuals(model_mli)
## Dickey-Fuller = -2.8176, Lag order = 2, p-value = 0.2603
## alternative hypothesis: stationary

kpss.test(residuals(model_mli))

## Warning in kpss.test(residuals(model_mli)): p-value greater than printed p-value
##
## KPSS Test for Level Stationarity
##
## data:  residuals(model_mli)
## KPSS Level = 0.062135, Truncation lag parameter = 2, p-value = 0.1

jarque.bera.test(residuals(model_mli))

##
## Jarque Bera Test
##
## data:  residuals(model_mli)
## X-squared = 0.94254, df = 2, p-value = 0.6242

model_lpi0 <- lm(LPI~LPIpre+Pol+party_control+controlDif+Mood)
etaSquared(model_lpi0)

##                eta.sq eta.sq.part
## LPIpre          0.271513405  0.65881342
## Pol             0.040244786  0.22252359
## party_control   0.004309374  0.02973605
## controlDif      0.010229684  0.06781759
## Mood            0.028231226  0.16720429

model_lpi0_coefs <- coeftest(model_lpi0, vcov=vcovHAC(model_lpi0))
model_lpi <- lm(LPI~LPIpre+EMI*Pol+party_control+controlDif+Mood)
vif(model_lpi)

##          LPIpre          EMI          Pol party_control    controlDif
##      3.281626      5.969536      2.624503      1.188459      1.168623
##          Mood      EMI:Pol
##      1.327453      2.328786

model_lpi_coefs <- coeftest(model_lpi, vcov=vcovHAC(model_lpi))
model_lpi_coefs

##
## t test of coefficients:
##
##              Estimate Std. Error t value Pr(>|t|)

```

```
## (Intercept)      -0.425279    0.129835 -3.2755 0.0039786 **
## LPIpre           0.444191    0.075341  5.8957 1.121e-05 ***
## EMI              0.827706    0.205655  4.0247 0.0007241 ***
## Pol             -0.137315    0.160821 -0.8538 0.4038303
## party_controlUNI -0.065400    0.138079 -0.4736 0.6411494
## controlDifTRUE   0.294248    0.140824  2.0895 0.0503518 .
## Mood            0.298359    0.068927  4.3286 0.0003620 ***
## EMI:Pol          0.129086    0.246394  0.5239 0.6064038
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

adf.test(residuals(model_lpi))

##
## Augmented Dickey-Fuller Test
##
## data: residuals(model_lpi)
## Dickey-Fuller = -3.4675, Lag order = 2, p-value = 0.06793
## alternative hypothesis: stationary

kpss.test(residuals(model_lpi))

## Warning in kpss.test(residuals(model_lpi)): p-value greater than printed p-value
##
## KPSS Test for Level Stationarity
##
## data: residuals(model_lpi)
## KPSS Level = 0.054263, Truncation lag parameter = 2, p-value = 0.1

jarque.bera.test(residuals(model_lpi))

##
## Jarque Bera Test
##
## data: residuals(model_lpi)
## X-squared = 0.22468, df = 2, p-value = 0.8937

model_nlaws0 <- lm(lognlaw~lognlawpre+Pol+party_control+controlDif+Mood)
etaSquared(model_nlaws0)

##
##          eta.sq  eta.sq.part
## lognlawpre 0.0096487085 0.0569943969
## Pol        0.2002032412 0.5563569345
## party_control 0.0019253622 0.0119166649
## controlDif  0.0000307087 0.0001923209
## Mood        0.0913819077 0.3640344660

model_nlaws0_coefs <- coeftest(model_nlaws0, vcov=vcovHAC(model_nlaws0))
model_nlaws <- lm(lognlaw~lognlawpre+EMI+Pol+party_control+controlDif+Mood)
vif(model_nlaws)

##      lognlawpre      EMI      Pol party_control      controlDif
##      6.255830      6.159443    12.986386      1.160240      1.144889
##      Mood
##      1.563108

model_nlaws <- lm(lognlaw~lognlawpre+EMI*Pol+party_control+controlDif+Mood)
model_nlaws_coefs <- coeftest(model_nlaws, vcov=vcovHAC(model_nlaws))
```

```
model_nlaws_coefs
```

```
##
## t test of coefficients:
##
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept)   0.0057518  0.1247802  0.0461 0.963561
## lognlawpre   -0.2061457  0.1571212 -1.3120 0.200170
## EMI           0.2698952  0.1580621  1.7075 0.098791 .
## Pol          -0.8918055  0.2642280 -3.3751 0.002178 **
## party_controlUNI -0.0618383  0.2021352 -0.3059 0.761924
## controlDifTRUE   0.0518599  0.1524204  0.3402 0.736213
## Mood           0.3937340  0.0791867  4.9722 2.992e-05 ***
## EMI:Pol         0.0024512  0.0976903  0.0251 0.980160
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
adf.test(residuals(model_nlaws))
```

```
##
## Augmented Dickey-Fuller Test
##
## data: residuals(model_nlaws)
## Dickey-Fuller = -3.8164, Lag order = 3, p-value = 0.03057
## alternative hypothesis: stationary
```

```
kpss.test(residuals(model_nlaws))
```

```
## Warning in kpss.test(residuals(model_nlaws)): p-value greater than printed
## p-value
```

```
##
## KPSS Test for Level Stationarity
##
## data: residuals(model_nlaws)
## KPSS Level = 0.05562, Truncation lag parameter = 3, p-value = 0.1
```

```
jarque.bera.test(residuals(model_nlaws))
```

```
##
## Jarque Bera Test
##
## data: residuals(model_nlaws)
## X-squared = 1.1435, df = 2, p-value = 0.5645
```

```
stargazer(model_mli,model_lpi, model_nlaws,type = "latex", digits = 2, df = F,
           se=list(model_mli_coefs[,2], model_lpi_coefs[,2], model_nlaws_coefs[,2]),
           p=list(model_mli_coefs[,4], model_lpi_coefs[,4], model_nlaws_coefs[,4]),
           out="output/EMI-Prod-Mood-LM.tex")
```

```
##
## % Table created by stargazer v.5.2.3 by Marek Hlavac, Social Policy Institute. E-mail: marek.hlavac@sp.i.cas.cz
## % Date and time: Wed, Mar 27, 2024 - 12:20:55
## \begin{table}[!htbp] \centering
##   \caption{}
##   \label{}
##   \begin{tabular}{@{\extracolsep{5pt}}lccc}
```



```

## \[-1.8ex]\hline
## \hline \[-1.8ex]
## & \multicolumn{3}{c}{\textit{Dependent variable:}} \\\
## \cline{2-4}
## \[-1.8ex] & MLI & LPI & lognlaw \\\
## \[-1.8ex] & (1) & (2) & (3)\\
## \hline \[-1.8ex]
## MLipre & 0.77$^{***}$ & & \\\
## & (0.07) & & \\\
## & & & \\\
## LPIpre & & 0.44$^{***}$ & \\\
## & & (0.08) & \\\
## & & & \\\
## lognlawpre & & & $-0.21 \\\
## & & & (0.16) \\\
## & & & \\\
## EMI & 0.67$^{**}$ & 0.83$^{***}$ & 0.27$^{*}$ \\\
## & (0.25) & (0.21) & (0.16) \\\
## & & & \\\
## Pol & 0.21 & $-0.14 & $-0.89$^{***}$ \\\
## & (0.24) & (0.16) & (0.26) \\\
## & & & \\\
## party\_controlUNI & $-0.08 & $-0.07 & $-0.06 \\\
## & (0.19) & (0.14) & (0.20) \\\
## & & & \\\
## controlDif & 0.27 & 0.29$^{*}$ & 0.05 \\\
## & (0.19) & (0.14) & (0.15) \\\
## & & & \\\
## Mood & 0.24$^{***}$ & 0.30$^{***}$ & 0.39$^{***}$ \\\
## & (0.08) & (0.07) & (0.08) \\\
## & & & \\\
## EMI:Pol & 0.23 & 0.13 & 0.002 \\\
## & (0.30) & (0.25) & (0.10) \\\
## & & & \\\
## Constant & $-0.14 & $-0.43$^{***}$ & 0.01 \\\
## & (0.16) & (0.13) & (0.12) \\\
## & & & \\\
## \hline \[-1.8ex]
## Observations & 27 & 27 & 36 \\\
## R$^2$ & 0.85 & 0.92 & 0.85 \\\
## Adjusted R$^2$ & 0.80 & 0.89 & 0.82 \\\
## Residual Std. Error & 0.45 & 0.33 & 0.43 \\\
## F Statistic & 15.45$^{***}$ & 30.91$^{***}$ & 23.06$^{***}$ \\\
## \hline
## \hline \[-1.8ex]
## \textit{Note:} & \multicolumn{3}{r}{$^{*}$p<$0.1; $^{**}$p<$0.05; $^{***}$p<$0.01} \\\
## \end{tabular}
## \end{table}

```

```

stargazer(model_mli,model_lpi, model_nlaws,type = "text", digits = 2, df = F,
          se=list(model_mli_coefs[,2], model_lpi_coefs[,2], model_nlaws_coefs[,2]),
          p=list(model_mli_coefs[,4], model_lpi_coefs[,4], model_nlaws_coefs[,4]),
          out="output/EMI-Prod-Mood-LM.txt")

```

```
##
```

```

## =====
##                               Dependent variable:
##                               -----
##                               MLI      LPI      lognlaw
##                               (1)      (2)      (3)
##                               -----
## MLipre      0.77***
##              (0.07)
##
## LPipre      0.44***
##              (0.08)
##
## lognlawpre      -0.21
##                  (0.16)
##
## EMI      0.67**      0.83***      0.27*
##           (0.25)      (0.21)      (0.16)
##
## Pol      0.21      -0.14      -0.89***
##           (0.24)      (0.16)      (0.26)
##
## party_controlUNI      -0.08      -0.07      -0.06
##                       (0.19)      (0.14)      (0.20)
##
## controlDif      0.27      0.29*      0.05
##                  (0.19)      (0.14)      (0.15)
##
## Mood      0.24***      0.30***      0.39***
##            (0.08)      (0.07)      (0.08)
##
## EMI:Pol      0.23      0.13      0.002
##              (0.30)      (0.25)      (0.10)
##
## Constant      -0.14      -0.43***      0.01
##                (0.16)      (0.13)      (0.12)
##
## -----
## Observations      27      27      36
## R2      0.85      0.92      0.85
## Adjusted R2      0.80      0.89      0.82
## Residual Std. Error      0.45      0.33      0.43
## F Statistic      15.45***      30.91***      23.06***
## =====
## Note:      *p<0.1; **p<0.05; ***p<0.01

```

```

stargazer(model_mli0, model_mli, model_lpi0, model_lpi, model_nlaws0, model_nlaws, type = "latex", digits = 3,
          se=list(model_mli0_coefs[,2], model_mli_coefs[,2], model_lpi0_coefs[,2], model_lpi_coefs[,2]),
          p=list(model_mli0_coefs[,4], model_mli_coefs[,4], model_lpi0_coefs[,4], model_lpi_coefs[,4]),
          out="output/EMI-Prod-Mood-LM-ext.tex")

```

```

##
## % Table created by stargazer v.5.2.3 by Marek Hlavac, Social Policy Institute. E-mail: marek.hlavac@sps.muni.cz
## % Date and time: Wed, Mar 27, 2024 - 12:20:55
## \begin{table}[!htbp] \centering
##   \caption{}

```

```

## \label{}
## \begin{tabular}{@{\extracolsep{5pt}}lcccccc}
## \[-1.8ex\]\hline
## \hline \[-1.8ex\]
## & \multicolumn{6}{c}{\textit{Dependent variable:}} \\
## \cline{2-7}
## \[-1.8ex\] & \multicolumn{2}{c}{MLI} & \multicolumn{2}{c}{LPI} & \multicolumn{2}{c}{lognlaw} \\
## \[-1.8ex\] & (1) & (2) & (3) & (4) & (5) & (6) \\
## \hline \[-1.8ex\]
## MLIpre & 0.95$^{***}$ & 0.77$^{***}$ & & & & \\
## & (0.06) & (0.07) & & & & \\
## & & & & & & \\
## EMI & 0.67$^{**}$ & 0.83$^{***}$ & 0.27$^{*}$ & & & \\
## & (0.25) & (0.21) & (0.16) & & & \\
## & & & & & & \\
## LPIpre & 0.75$^{***}$ & 0.44$^{***}$ & & & & \\
## & (0.09) & (0.08) & & & & \\
## & & & & & & \\
## lognlawpre & & & & $-0.24 & $-0.21 \\
## & & & & (0.15) & (0.16) \\
## & & & & & & \\
## Pol & $-0.31$^{***}$ & 0.21 & $-0.45$^{*}$ & $-0.14 & $-1.16$^{***}$ & $-0.89$^{***}$ \\
## & (0.08) & (0.24) & (0.16) & (0.16) & (0.14) & (0.26) \\
## & & & & & & \\
## party\_controlUNI & $-0.16 & $-0.08 & $-0.14 & $-0.07 & $-0.10 & $-0.06 \\
## & (0.17) & (0.19) & (0.14) & (0.14) & (0.20) & (0.20) \\
## & & & & & & \\
## controlDif & 0.19 & 0.27 & 0.23 & 0.29$^{*}$ & 0.01 & 0.05 \\
## & (0.20) & (0.19) & (0.18) & (0.14) & (0.16) & (0.15) \\
## & & & & & & \\
## Mood & 0.17$^{**}$ & 0.24$^{***}$ & 0.17$^{**}$ & 0.30$^{***}$ & 0.37$^{***}$ & 0.39$^{***}$ \\
## & (0.08) & (0.08) & (0.06) & (0.07) & (0.09) & (0.08) \\
## & & & & & & \\
## EMI:Pol & 0.23 & 0.13 & 0.002 \\
## & (0.30) & (0.25) & (0.10) \\
## & & & & & & \\
## Constant & $-0.16 & $-0.14 & $-0.25$^{*}$ & $-0.43$^{***}$ & 0.03 & 0.01 \\
## & (0.12) & (0.16) & (0.11) & (0.13) & (0.09) & (0.12) \\
## & & & & & & \\
## \hline \[-1.8ex\]
## Observations & 27 & 27 & 27 & 27 & 36 & 36 \\
## R$^2$ & 0.82 & 0.85 & 0.86 & 0.92 & 0.84 & 0.85 \\
## Adjusted R$^2$ & 0.77 & 0.80 & 0.83 & 0.89 & 0.81 & 0.82 \\
## Residual Std. Error & 0.47 & 0.45 & 0.42 & 0.33 & 0.43 & 0.43 \\
## F Statistic & 18.90$^{***}$ & 15.45$^{***}$ & 25.67$^{***}$ & 30.91$^{***}$ & 31.58$^{***}$ & 23.06$^{***}$ \\
## \hline
## \hline \[-1.8ex\]
## \textit{Note:} & \multicolumn{6}{r}{$^{*}$p<$0.1; $^{**}$p<$0.05; $^{***}$p<$0.01} \\
## \end{tabular}
## \end{table}

```

```

stargazer(model_mli0, model_mli, model_lpi0, model_lpi, model_nlaws0, model_nlaws, type = "text", digits
          se=list(model_mli0_coefs[,2], model_mli_coefs[,2], model_lpi0_coefs[,2], model_lpi_coefs[,2],
          p=list(model_mli0_coefs[,4], model_mli_coefs[,4], model_lpi0_coefs[,4], model_lpi_coefs[,4],

```

```
out="output/EMI-Prod-Mood-LM-ext.txt")
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               MLI          LPI          lognlaw
##                               (1)         (2)         (3)         (4)         (5)         (6)
##                               -----
## MLipre          0.95***  0.77***
##                               (0.06)  (0.07)
##
## EMI              0.67**      0.83***      0.27*
##                               (0.25)      (0.21)      (0.16)
##
## LPIpre              0.75***  0.44***
##                               (0.09)  (0.08)
##
## lognlawpre              -0.24  -0.21
##                               (0.15)  (0.16)
##
## Pol              -0.31***  0.21  -0.45**  -0.14  -1.16*** -0.89***
##                               (0.08)  (0.24)  (0.16)  (0.16)  (0.14)  (0.26)
##
## party_controlUNI  -0.16  -0.08  -0.14  -0.07  -0.10  -0.06
##                               (0.17)  (0.19)  (0.14)  (0.14)  (0.20)  (0.20)
##
## controlDif        0.19  0.27  0.23  0.29*  0.01  0.05
##                               (0.20)  (0.19)  (0.18)  (0.14)  (0.16)  (0.15)
##
## Mood              0.17**  0.24***  0.17**  0.30***  0.37***  0.39***
##                               (0.08)  (0.08)  (0.06)  (0.07)  (0.09)  (0.08)
##
## EMI:Pol              0.23      0.13      0.002
##                               (0.30)      (0.25)      (0.10)
##
## Constant          -0.16  -0.14  -0.25**  -0.43***  0.03  0.01
##                               (0.12)  (0.16)  (0.11)  (0.13)  (0.09)  (0.12)
##
## -----
## Observations          27      27      27      27      36      36
## R2                    0.82      0.85      0.86      0.92      0.84      0.85
## Adjusted R2           0.77      0.80      0.83      0.89      0.81      0.82
## Residual Std. Error    0.47      0.45      0.42      0.33      0.43      0.43
## F Statistic           18.90***  15.45***  25.67***  30.91***  31.58***  23.06***
## =====
## Note:                  *p<0.1; **p<0.05; ***p<0.01
```

3: MLI models with patents

```
df <- read.csv("data/emi_congressw2v_prod_variables_public_laws.csv")
attach(df_avg)
```

```

model_mli0 <- lm(MLI~MLIpre+Pol+logpatents+party_control+controlDif)
model_mli0_coefs <- coeftest(model_mli0, vcov=vcovHAC(model_mli0))
model_mli0_coefs

##
## t test of coefficients:
##
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)   -0.018147   0.050406  -0.3600 0.720197
## MLIpre         0.672853   0.094005   7.1576 1.9e-09 ***
## Pol           -0.194202   0.068747  -2.8249 0.006542 **
## logpatents     0.276589   0.114696   2.4115 0.019192 *
## party_controlUNI 0.071211   0.071376   0.9977 0.322722
## controlDifTRUE  0.095482   0.076728   1.2444 0.218528
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

model_mli <- lm(MLI~MLIpre+EMI+Pol+logpatents+party_control+controlDif)
vif(model_mli)

##          MLIpre          EMI          Pol    logpatents party_control
##      9.426628      1.596349      3.181818      5.379051      1.204671
##      controlDif
##      1.094396

model_mli <- lm(MLI~MLIpre+EMI*Pol+logpatents+party_control+controlDif)
model_mli_coefs <- coeftest(model_mli, vcov=vcovHAC(model_mli))
model_mli_coefs

##
## t test of coefficients:
##
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)   -0.058277   0.056239  -1.0362 0.304715
## MLIpre         0.588313   0.083092   7.0802 3.052e-09 ***
## EMI            0.109546   0.048499   2.2587 0.027962 *
## Pol           -0.197662   0.071641  -2.7591 0.007897 **
## logpatents     0.367314   0.104140   3.5271 0.000866 ***
## party_controlUNI 0.101495   0.068182   1.4886 0.142414
## controlDifTRUE  0.108690   0.076561   1.4197 0.161456
## EMI:Pol        -0.020009   0.086607  -0.2310 0.818160
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

adf.test(residuals(model_mli))

##
## Augmented Dickey-Fuller Test
##
## data: residuals(model_mli)
## Dickey-Fuller = -4.0324, Lag order = 3, p-value = 0.01411
## alternative hypothesis: stationary

kpss.test(residuals(model_mli))

## Warning in kpss.test(residuals(model_mli)): p-value greater than printed p-value

```

```
##
## KPSS Test for Level Stationarity
##
## data: residuals(model_mli)
## KPSS Level = 0.054298, Truncation lag parameter = 3, p-value = 0.1
jarque.bera.test(residuals(model_mli)) #slight skewness in residuals - solved by HAC standard errors

##
## Jarque Bera Test
##
## data: residuals(model_mli)
## X-squared = 10.974, df = 2, p-value = 0.00414
set.seed(1985)
library(boot)
bootf <- function(df, indices)
{
  model_mli <- lm(MLI~MLIpre+EMI+Pol+logpatents+party_control+controlDif, data=df, subset=indices)
  return(model_mli$coefficients[3])
}
boots <- boot(df_avg, bootf, R=10000)
quantile(boots$t, p=c(0.025, 0.5, 0.975)) # to verify, we perform a bootstrapping test, low part of CI

##      2.5%      50%      97.5%
## 0.02585457 0.11960447 0.21402484
```

4: LPI and nlaws models with patents

```
model_lpi0 <- lm(LPI~LPIpre+Pol+logpatents+party_control+controlDif)
model_lpi0_coefs <- coeftest(model_lpi0, vcov=vcovHAC(model_lpi0))
model_lpi0_coefs

##
## t test of coefficients:
##
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)   -0.079888   0.046180  -1.7299  0.089153 .
## LPIpre         0.625272   0.109246   5.7235 4.263e-07 ***
## Pol           -0.294853   0.108469  -2.7183  0.008718 **
## logpatents     0.179419   0.086898   2.0647  0.043592 *
## party_control  0.141299   0.067478   2.0940  0.040797 *
## controlDifTRUE 0.035849   0.069488   0.5159  0.607952
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

model_lpi <- lm(LPI~LPIpre+EMI+Pol+logpatents+party_control+controlDif)
vif(model_lpi)

##      LPIpre      EMI      Pol      logpatents party_control
## 12.734637    1.481295    7.673421    3.551798      1.218801
##      controlDif
##      1.144974

model_lpi <- lm(LPI~LPIpre+EMI*Pol+logpatents+party_control+controlDif)
model_lpi_coefs <- coeftest(model_lpi, vcov=vcovHAC(model_lpi))
```

```
model_lpi_coefs
```

```
##
## t test of coefficients:
##
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept) -0.1111911  0.0468135 -2.3752  0.021120 *
## LPIpre      0.5822219  0.1068017  5.4514 1.271e-06 ***
## EMI         0.0728561  0.0510916  1.4260  0.159627
## Pol        -0.3055842  0.1112943 -2.7457  0.008184 **
## logpatents  0.2174967  0.0843501  2.5785  0.012682 *
## party_controlUNI 0.1691191  0.0669214  2.5271  0.014461 *
## controlDifTRUE 0.0433164  0.0705149  0.6143  0.541605
## EMI:Pol      0.0032665  0.0811126  0.0403  0.968025
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
adf.test(residuals(model_lpi))
```

```
##
## Augmented Dickey-Fuller Test
##
## data: residuals(model_lpi)
## Dickey-Fuller = -3.2196, Lag order = 3, p-value = 0.09268
## alternative hypothesis: stationary
```

```
kpss.test(residuals(model_lpi))
```

```
## Warning in kpss.test(residuals(model_lpi)): p-value greater than printed p-value
```

```
##
## KPSS Test for Level Stationarity
##
## data: residuals(model_lpi)
## KPSS Level = 0.071217, Truncation lag parameter = 3, p-value = 0.1
```

```
jarque.bera.test(residuals(model_lpi))
```

```
##
## Jarque Bera Test
##
## data: residuals(model_lpi)
## X-squared = 2.2169, df = 2, p-value = 0.3301
```

```
model_nlaws0 <- lm(lognlaw~lognlawpre+Pol+logpatents+party_control+controlDif)
model_nlaws0_coefs <- coeftest(model_nlaws0, vcov=vcovHAC(model_nlaws0))
model_nlaws0_coefs
```

```
##
## t test of coefficients:
##
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept) -0.021181  0.109402 -0.1936  0.8470972
## lognlawpre   0.327938  0.119670  2.7403  0.0079448 **
## Pol         -0.433469  0.112297 -3.8600  0.0002665 ***
## logpatents  -0.102152  0.077354 -1.3206  0.1913439
## party_controlUNI 0.233465  0.150917  1.5470  0.1267989
```

```
## controlDifTRUE -0.254417 0.165221 -1.5399 0.1285243
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

model_nlaws <- lm(lognlaw~lognlawpre+EMI+Pol+logpatents+party_control+controlDif)
vif(model_nlaws)

##      lognlawpre          EMI          Pol      logpatents party_control
##      2.213807      2.271791      2.649096      1.606919      1.196803
##      controlDif
##      1.105261

model_nlaws <- lm(lognlaw~lognlawpre+EMI*Pol+logpatents+party_control+controlDif)
model_nlaws_coefs <- coeftest(model_nlaws, vcov=vcovHAC(model_nlaws))
model_nlaws_coefs

##
## t test of coefficients:
##
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)   -0.063844  0.133514  -0.4782 0.634203
## lognlawpre     0.323999  0.123855   2.6160 0.011161 *
## EMI            0.049058  0.102349   0.4793 0.633393
## Pol           -0.410465  0.133755  -3.0688 0.003186 **
## logpatents    -0.114012  0.116266  -0.9806 0.330594
## party_control  0.254166  0.161605   1.5728 0.120863
## controlDifTRUE -0.250502  0.163899  -1.5284 0.131500
## EMI:Pol       -0.052713  0.102184  -0.5159 0.607788
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

adf.test(residuals(model_nlaws))

## Warning in adf.test(residuals(model_nlaws)): p-value smaller than printed
## p-value

##
## Augmented Dickey-Fuller Test
##
## data: residuals(model_nlaws)
## Dickey-Fuller = -4.3042, Lag order = 4, p-value = 0.01
## alternative hypothesis: stationary

kpss.test(residuals(model_nlaws))

## Warning in kpss.test(residuals(model_nlaws)): p-value greater than printed
## p-value

##
## KPSS Test for Level Stationarity
##
## data: residuals(model_nlaws)
## KPSS Level = 0.039311, Truncation lag parameter = 3, p-value = 0.1

jarque.bera.test(residuals(model_nlaws))

##
## Jarque Bera Test
##
```



```

## data: residuals(model_nlaws)
## X-squared = 1.2794, df = 2, p-value = 0.5275

stargazer(model_mli0, model_mli, model_lpi0, model_lpi, model_nlaws0, model_nlaws, type = "latex", digits = 4,
  se=list(model_mli0_coefs[,2], model_mli_coefs[,2], model_lpi0_coefs[,2], model_lpi_coefs[,2],
  p=list(model_mli0_coefs[,4], model_mli_coefs[,4], model_lpi0_coefs[,4], model_lpi_coefs[,4]),
  out="output/EMI-Prod-LM.tex")

##
## % Table created by stargazer v.5.2.3 by Marek Hlavac, Social Policy Institute. E-mail: marek.hlavac@sps.muni.cz
## % Date and time: Wed, Mar 27, 2024 - 12:21:07
## \begin{table}[!htbp] \centering
##   \caption{}
##   \label{}
##   \begin{tabular}{@{\extracolsep{5pt}}lcccccc}
##     \hline
##     \hline \hline
##     & \multicolumn{6}{c}{\textit{Dependent variable:}} & \hline
##     \cline{2-7}
##     \hline & \multicolumn{2}{c}{MLI} & \multicolumn{2}{c}{LPI} & \multicolumn{2}{c}{lognlaw} & \hline
##     \hline & (1) & (2) & (3) & (4) & (5) & (6) & \hline
##     \hline
##     MLIpre & 0.67$^{***}$ & 0.59$^{***}$ & & & & & \hline
##     & (0.09) & (0.08) & & & & & \hline
##     & & & & & & & \hline
##     EMI & 0.11$^{**}$ & 0.07 & 0.05 & & & & \hline
##     & (0.05) & (0.05) & (0.10) & & & & \hline
##     & & & & & & & \hline
##     LPIpre & 0.63$^{***}$ & 0.58$^{***}$ & & & & & \hline
##     & (0.11) & (0.11) & & & & & \hline
##     & & & & & & & \hline
##     lognlawpre & 0.33$^{***}$ & 0.32$^{**}$ & & & & & \hline
##     & (0.12) & (0.12) & & & & & \hline
##     & & & & & & & \hline
##     Pol & -$0.19$^{***}$ & -$0.20$^{***}$ & -$0.29$^{***}$ & -$0.31$^{***}$ & -$0.43$^{***}$ & -$0.43$^{***}$ & \hline
##     & (0.07) & (0.07) & (0.11) & (0.11) & (0.11) & (0.13) & \hline
##     & & & & & & & \hline
##     logpatents & 0.28$^{**}$ & 0.37$^{***}$ & 0.18$^{**}$ & 0.22$^{**}$ & -$0.10 & -$0.11 & \hline
##     & (0.11) & (0.10) & (0.09) & (0.08) & (0.08) & (0.12) & \hline
##     & & & & & & & \hline
##     party\controlUNI & 0.07 & 0.10 & 0.14$^{**}$ & 0.17$^{**}$ & 0.23 & 0.25 & \hline
##     & (0.07) & (0.07) & (0.07) & (0.07) & (0.15) & (0.16) & \hline
##     & & & & & & & \hline
##     controlDif & 0.10 & 0.11 & 0.04 & 0.04 & -$0.25 & -$0.25 & \hline
##     & (0.08) & (0.08) & (0.07) & (0.07) & (0.17) & (0.16) & \hline
##     & & & & & & & \hline
##     EMI:Pol & -$0.02 & 0.003 & & -$0.05 & & & \hline
##     & (0.09) & (0.08) & & (0.10) & & & \hline
##     & & & & & & & \hline
##     Constant & -$0.02 & -$0.06 & -$0.08$^{*}$ & -$0.11$^{**}$ & -$0.02 & -$0.06 & \hline
##     & (0.05) & (0.06) & (0.05) & (0.05) & (0.11) & (0.13) & \hline
##     & & & & & & & \hline
##     \hline \hline
##     Observations & 62 & 62 & 62 & 62 & 70 & 70 & \hline
##     R$^2$ & 0.94 & 0.94 & 0.94 & 0.95 & 0.63 & 0.63 & \hline

```

```

## Adjusted R2 & 0.93 & 0.93 & 0.94 & 0.94 & 0.60 & 0.59 \\
## Residual Std. Error & 0.26 & 0.25 & 0.24 & 0.24 & 0.63 & 0.64 \\
## F Statistic & 167.22*** & 125.51*** & 186.41*** & 133.02*** & 21.39*** & 14
## \hline
## \hline \\[-1.8ex]
## \textit{Note:} & \multicolumn{6}{r}{*p<0.1; **p<0.05; ***p<0.01} \\
## \end{tabular}
## \end{table}

stargazer(model_mli0, model_mli, model_lpi0, model_lpi, model_nlaws0, model_nlaws, type = "text", digits
se=list(model_mli0_coefs[,2], model_mli_coefs[,2], model_lpi0_coefs[,2], model_lpi_coefs[,2],
p=list(model_mli0_coefs[,4], model_mli_coefs[,4], model_lpi0_coefs[,4], model_lpi_coefs[,4],
out="output/EMI-Prod-LM.txt")

```

```

##
## =====
##                               Dependent variable:
##                               -----
##                               MLI          LPI          lognlaw
##                               (1)         (2)         (3)         (4)         (5)         (6)
##                               -----
## MLIpre          0.67***    0.59***
##                  (0.09)    (0.08)
##
## EMI              0.11**          0.07          0.05
##                  (0.05)          (0.05)          (0.10)
##
## LPIpre              0.63***    0.58***
##                  (0.11)    (0.11)
##
## lognlawpre              0.33***    0.32**
##                  (0.12)    (0.12)
##
## Pol              -0.19***    -0.20***    -0.29***    -0.31***    -0.43***    -0.41***
##                  (0.07)    (0.07)    (0.11)    (0.11)    (0.11)    (0.13)
##
## logpatents        0.28**     0.37***     0.18**     0.22**     -0.10     -0.11
##                  (0.11)    (0.10)    (0.09)    (0.08)    (0.08)    (0.12)
##
## party_controlUNI    0.07      0.10      0.14**     0.17**     0.23      0.25
##                  (0.07)    (0.07)    (0.07)    (0.07)    (0.15)    (0.16)
##
## controlDif         0.10      0.11      0.04      0.04      -0.25     -0.25
##                  (0.08)    (0.08)    (0.07)    (0.07)    (0.17)    (0.16)
##
## EMI:Pol              -0.02          0.003          -0.05
##                  (0.09)          (0.08)          (0.10)
##
## Constant          -0.02     -0.06     -0.08*     -0.11**     -0.02     -0.06
##                  (0.05)    (0.06)    (0.05)    (0.05)    (0.11)    (0.13)
##
## -----
## Observations          62      62      62      62      70      70
## R2                    0.94     0.94     0.94     0.95     0.63     0.63
## Adjusted R2          0.93     0.93     0.94     0.94     0.60     0.59

```

```

## Residual Std. Error    0.26      0.25      0.24      0.24      0.63      0.64
## F Statistic           167.22*** 125.51*** 186.41*** 133.02*** 21.39*** 14.98***
## =====
## Note:                                     *p<0.1; **p<0.05; ***p<0.01

```