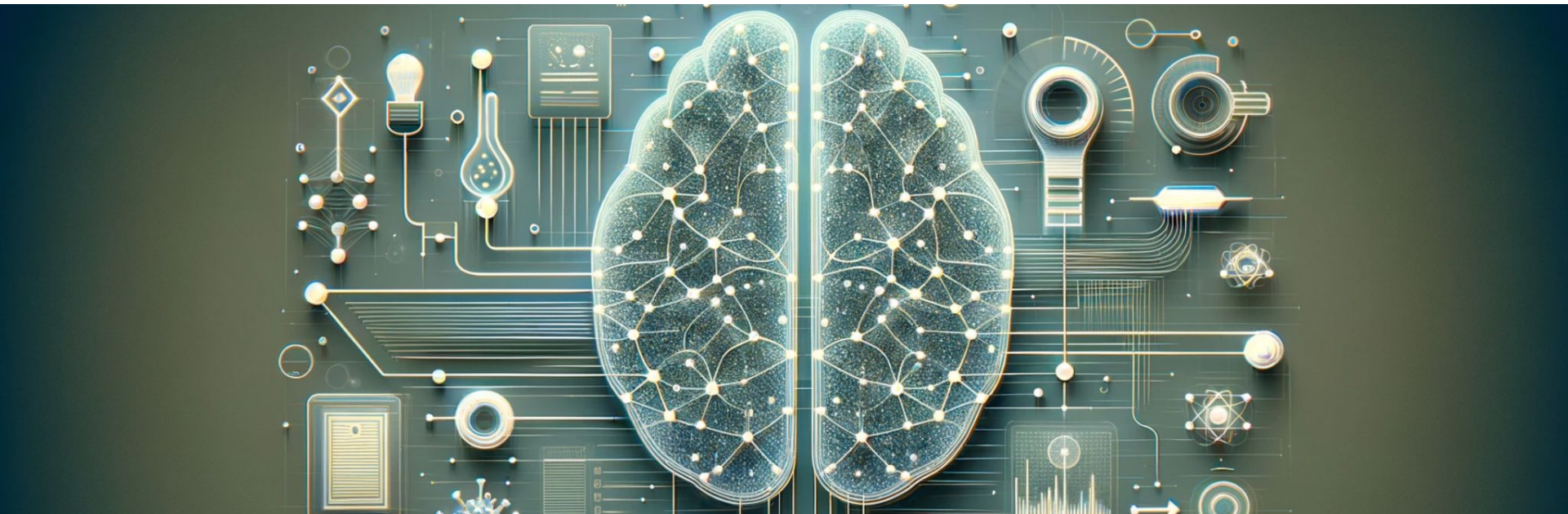


# CSE7850/CX4803 Machine Learning in Computational Biology



## Lecture 22: ML for Bioimaging Data

Yunan Luo

# Dall-E: text-to-image generation (available in ChatGPT)



You

A photo of an astronaut riding a horse



ChatGPT



How to build such a  
generative model?

# Two steps

## Step 1: connecting text and images

an armchair in the shape of an avocado



an illustration of a baby daikon radish in a tutu walking a dog



a professional high quality emoji of a Lovestruck cup of boba



# Two steps

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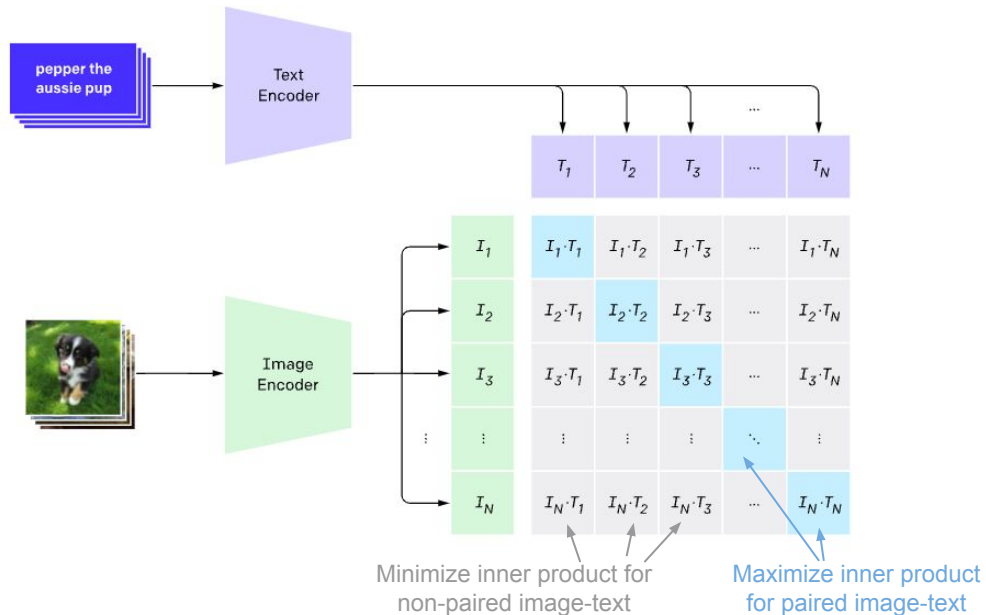
## Step 2: generate images



# Step 1: Connecting text and images

CLIP (Contrastive Language–Image Pre-training)

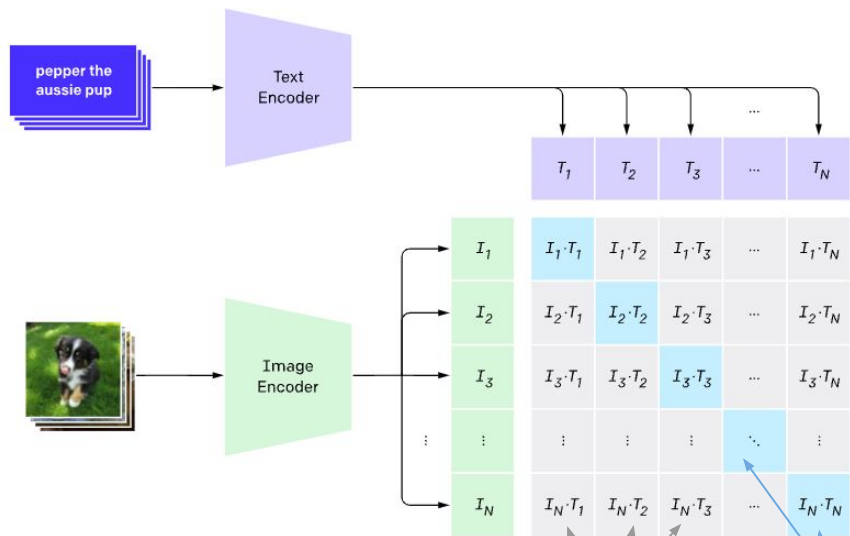
## 1. Contrastive pre-training



# Step 1: Connecting text and images

## CLIP (Contrastive Language–Image Pre-training)

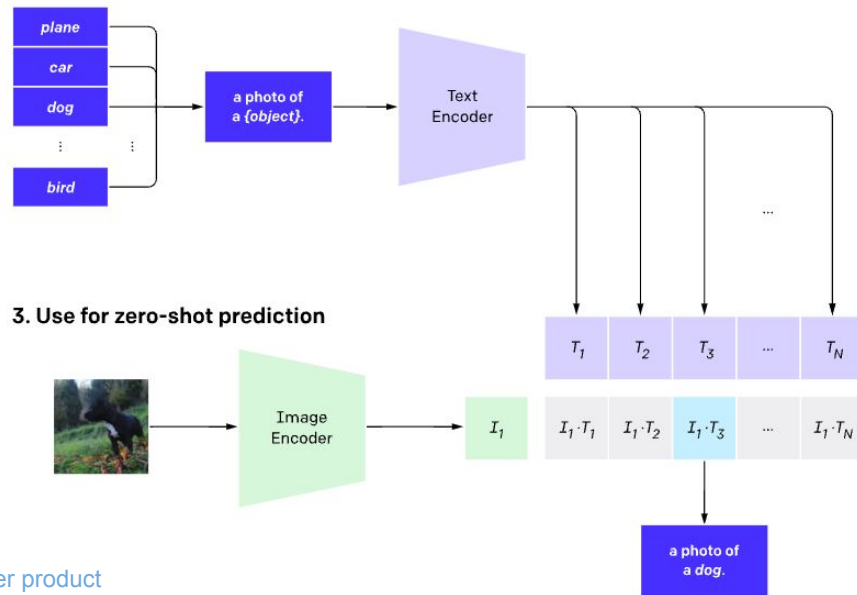
### 1. Contrastive pre-training



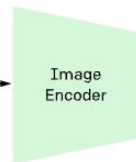
Minimize inner product for  
non-paired image-text

Maximize inner product  
for paired image-text

### 2. Create dataset classifier from label text



### 3. Use for zero-shot prediction



$I_1$

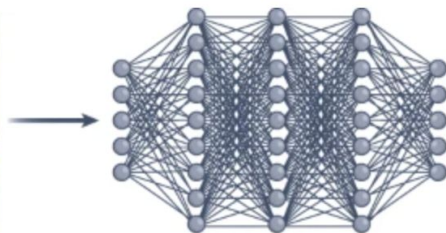
$I_1 \cdot T_1$   $I_1 \cdot T_2$   $I_1 \cdot T_3$  ...  $I_1 \cdot T_N$

a photo of  
a dog.

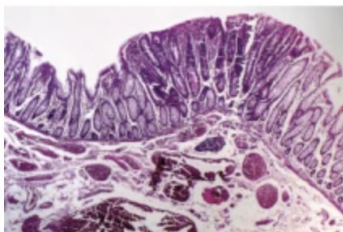
# Today's paper



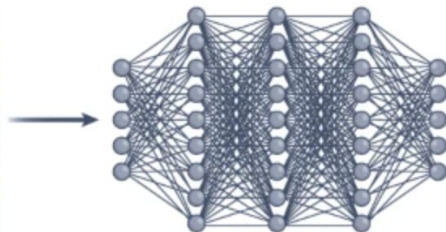
A natural image



CLIP zero-shot



A pathology image



PLIP zero-shot





# Today's paper

e

Small infiltrative-looking glands with crystalloid secretions are suspicious for prostatic adenocarcinoma.

Nevoid melanoma with atypism, poor maturation and dermal mitoses.

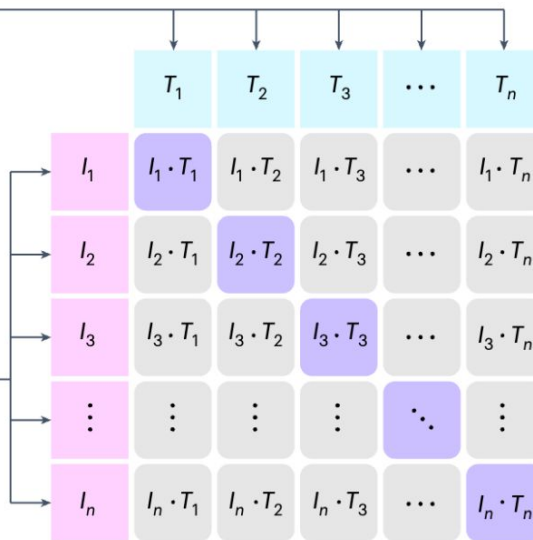
⋮

Herd of trichomonads set on a squamous epithelial cell.



Text encoder

Image encoder



# Today's paper

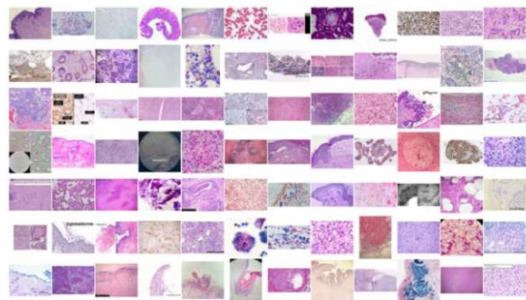
e

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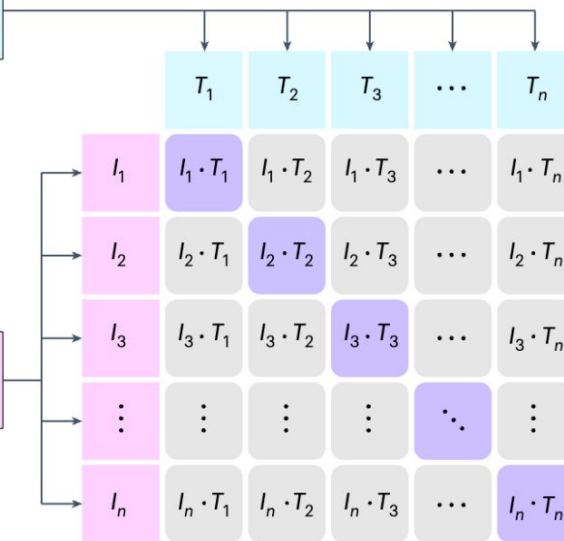
⋮

Herd of trichomonads set on a squamous epithelial cell.



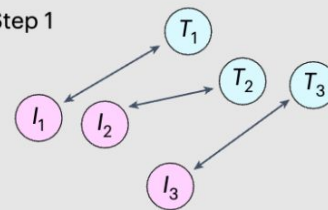
Text encoder

Image encoder



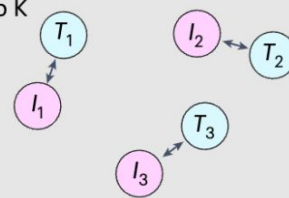
f

Step 1

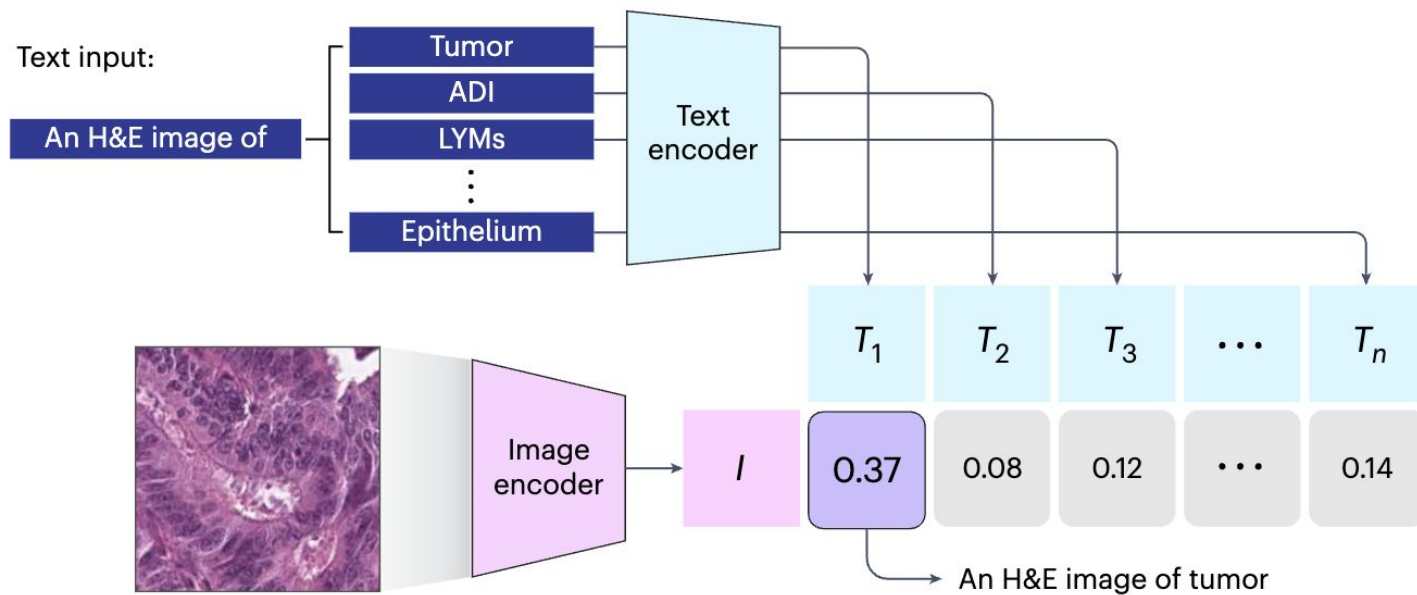


Training

Step K



# Today's paper



# Two steps

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## Step 2: generate images



## Step 2: generate images

an armchair in the shape of an avocado



DALL-E (2021)



DALL-E (2023)

# Diffusion Models

Ho et al. Denoising diffusion probabilistic models (DDPM), Neurips 2020.

Song et al. Score-based generative modeling through stochastic differential equations, ICLR 2021.

Bao et al. Analytic-DPM: an Analytic Estimate of the Optimal Reverse Variance in Diffusion Probabilistic Models, ICLR 2022.

Bao et al. Estimating the Optimal Covariance with Imperfect Mean in Diffusion Probabilistic Models, ICML 2022.

Rombach et al. High-resolution image synthesis with latent diffusion models. CVPR, 2022.

# Text-to-image generation

## Input

An astronaut riding a horse in photorealistic style.

## Output

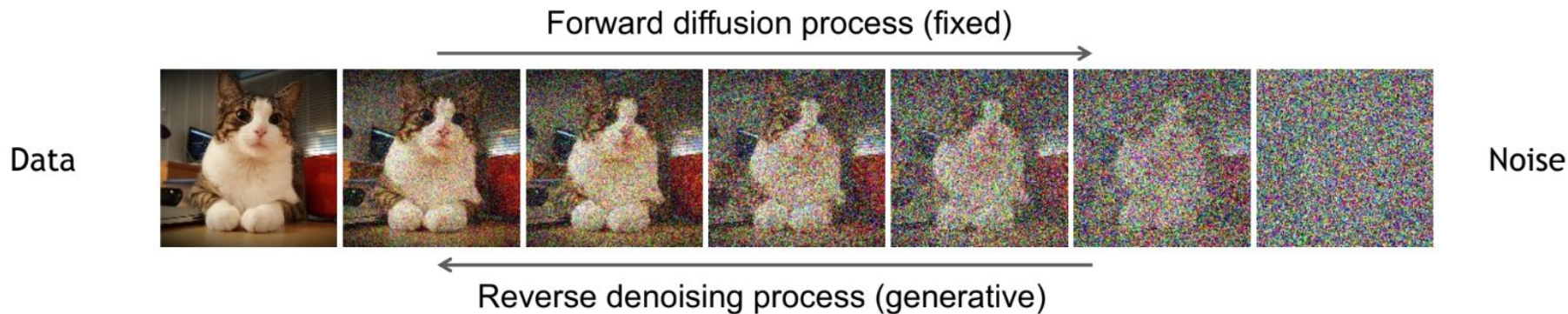




# Diffusion models

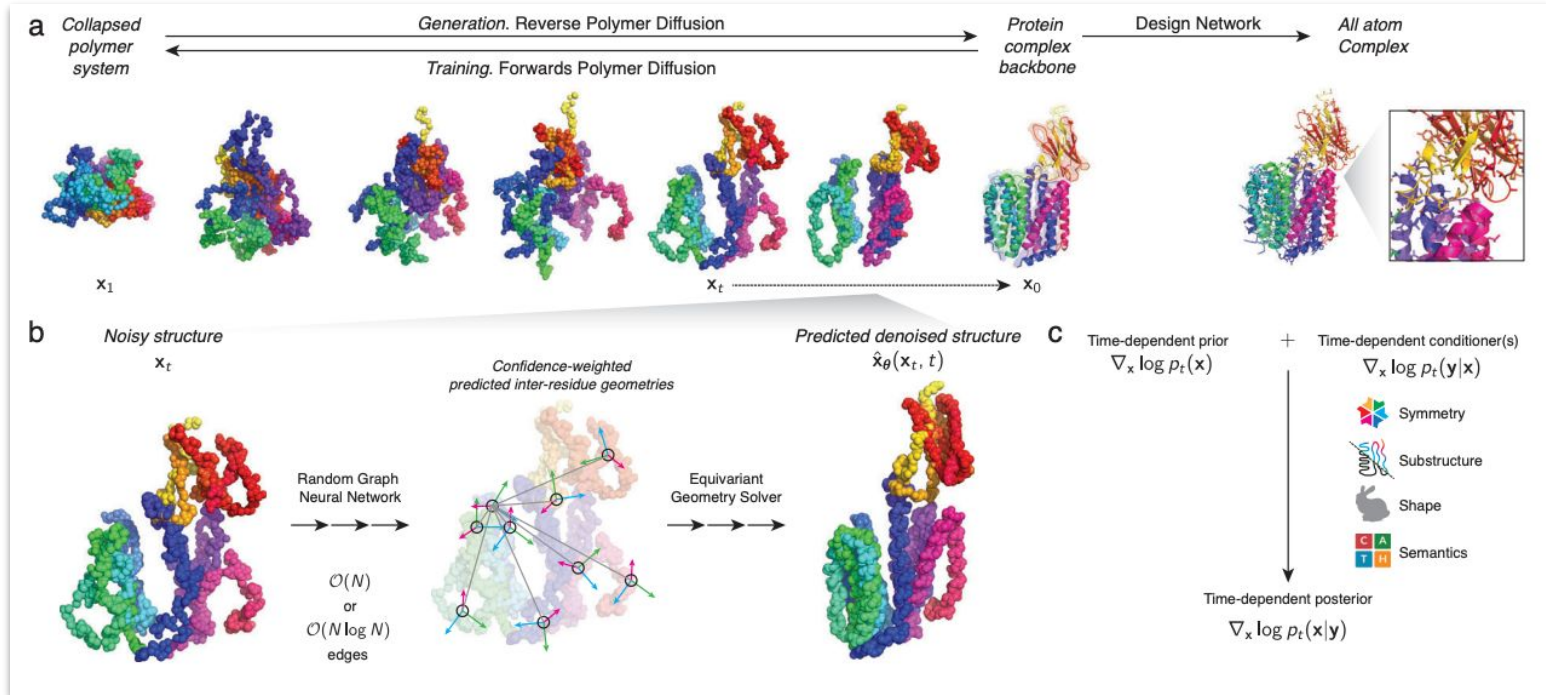
Denoising diffusion models consist of two processes:

- Forward diffusion process that gradually adds noise to input
- Reverse denoising process that learns to generate data by denoising



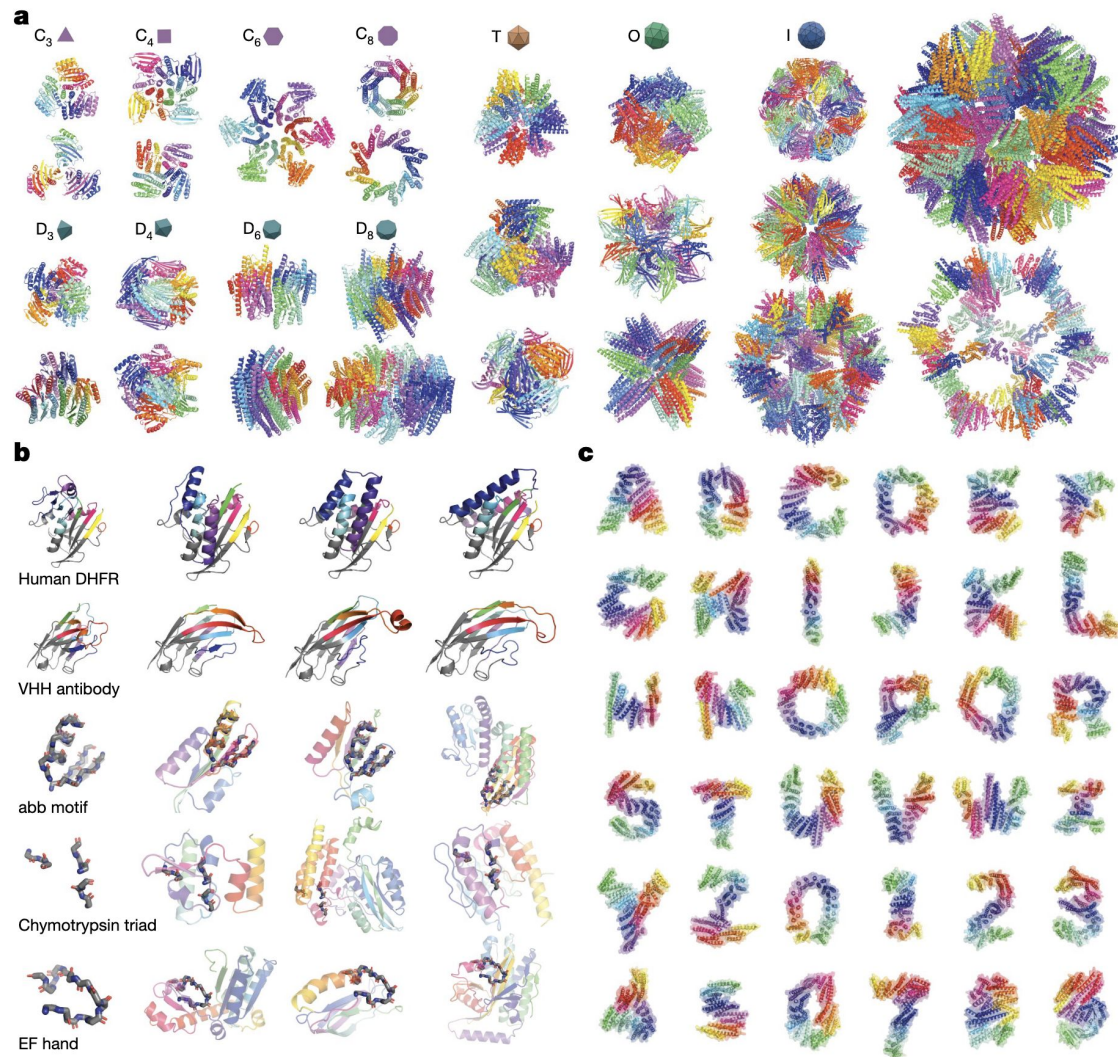
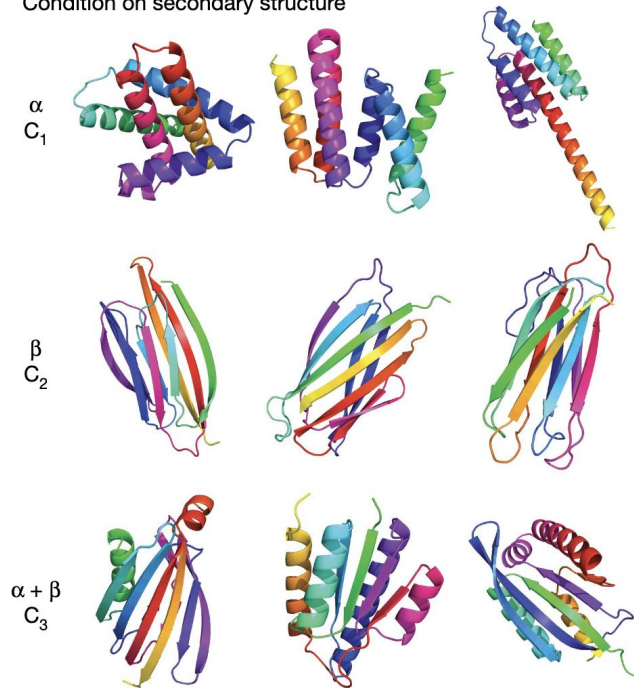


# Application: Protein Design

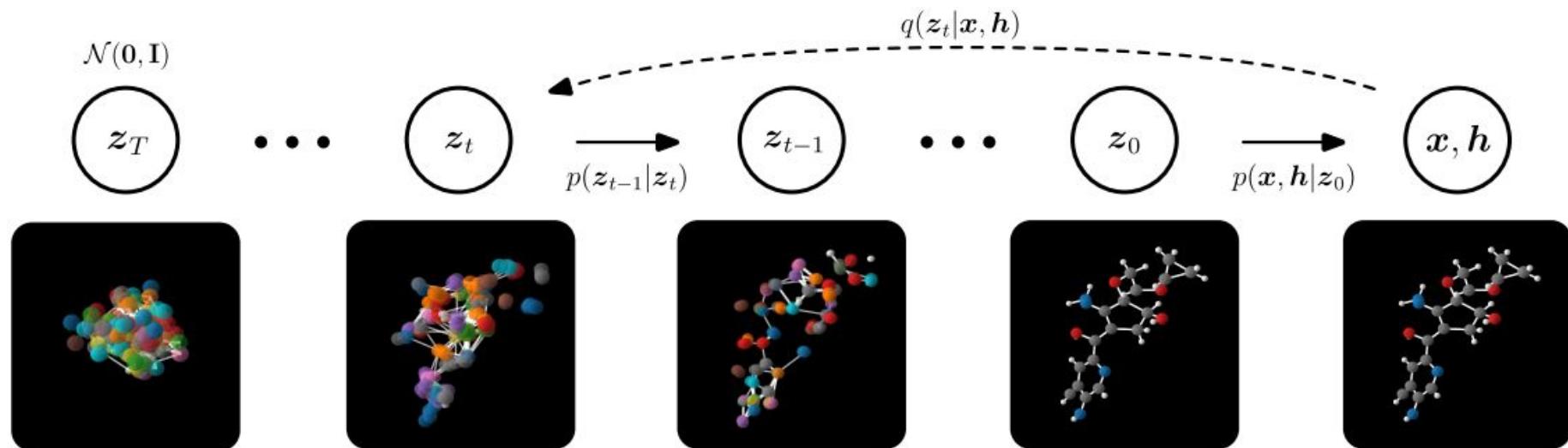


# Paper #2 last lecture

Condition on secondary structure



# Application: Drug Design

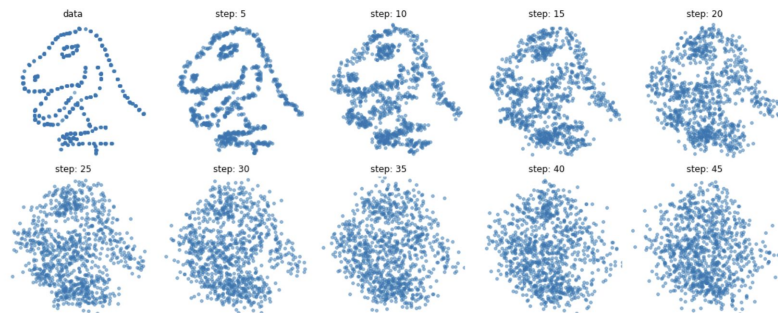


# Simple code demo

<https://github.com/tanelp/tiny-diffusion>

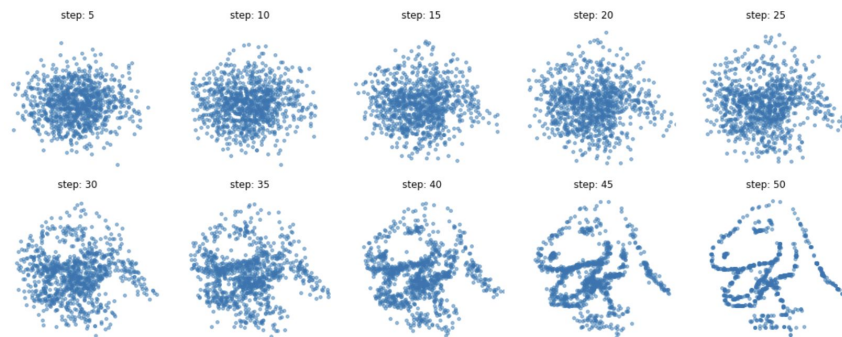
## Forward process

A visualization of the forward diffusion process being applied to a dataset of one thousand 2D points. Note that the dinosaur is not a single training example, it represents each 2D point in the dataset.



## Reverse process

This illustration shows how the reverse process recovers the distribution of the training data.

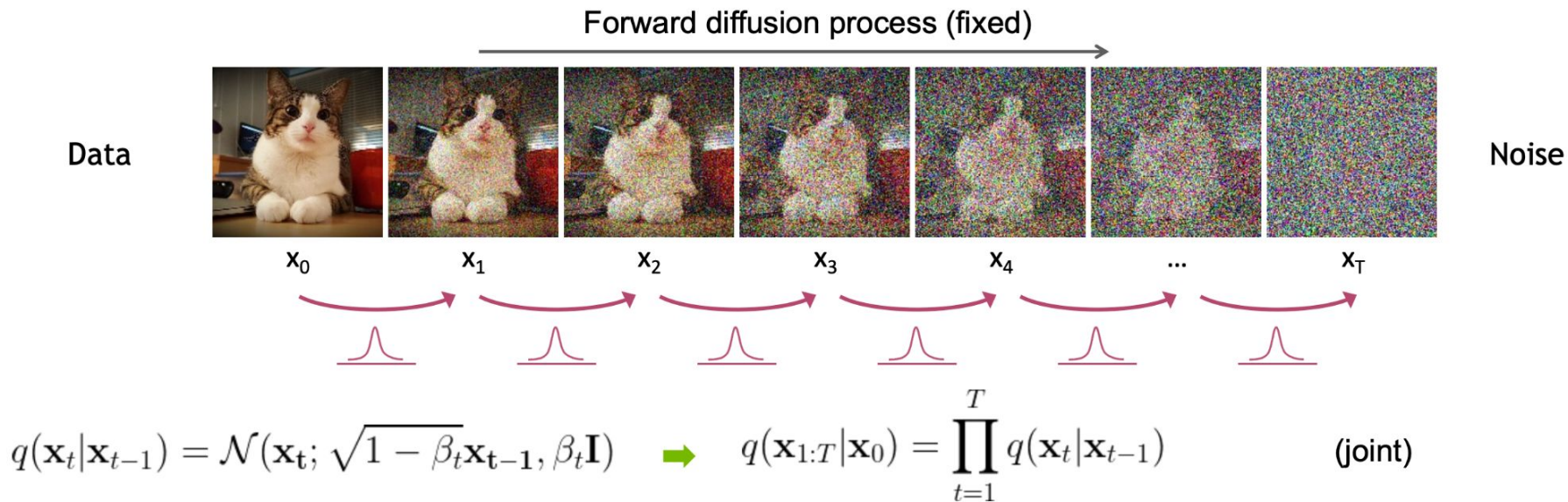




# Forward Diffusion Process

```
def add_noise(self, x_start, x_noise, timesteps):  
    s1 = self.sqrt_alphas_cumprod[timesteps]  
    s2 = self.sqrt_one_minus_alphas_cumprod[timesteps]  
  
    s1 = s1.reshape(-1, 1)  
    s2 = s2.reshape(-1, 1)  
  
    return s1 * x_start + s2 * x_noise
```

The formal definition of the forward process in T steps:



# Reverse Denoising Process

Formal definition of forward and reverse processes in T steps:

```
def step(self, model_output, timestep, sample):  
    t = timestep  
    pred_original_sample = self.reconstruct_x0(sample, t, model_output)  
    pred_prev_sample = self.q_posterior(pred_original_sample, sample, t)  
  
    variance = 0  
    if t > 0:  
        noise = torch.randn_like(model_output)  
        variance = (self.get_variance(t) ** 0.5) * noise  
  
    pred_prev_sample = pred_prev_sample + variance  
  
    return pred_prev_sample
```

