

Assembly - Arithmetic Instructions

The INC Instruction

The INC instruction is used for incrementing an operand by one. It works on a single operand that can be either in a register or in memory.

Syntax

The INC instruction has the following syntax –

INC destination

The operand destination could be an 8-bit, 16-bit or 32-bit operand.

Example

The DEC Instruction

The DEC instruction is used for decrementing an operand by one. It works on a single operand that can be either in a register or in memory.

Syntax

The DEC instruction has the following syntax –

DEC destination

The operand destination could be an 8-bit, 16-bit or 32-bit operand.

Example

```
segment .data
count dw 0
value db 15
```



```
segment .text
inc [count]
dec [value]

mov ebx, count
inc word [ebx]

mov esi, value
dec byte [esi]
```

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The ADD and SUB Instructions

The ADD and SUB instructions are used for performing simple addition/subtraction of binary data in byte, word and doubleword size, i.e., for adding or subtracting 8-bit, 16-bit or 32-bit operands, respectively.

Syntax

The ADD and SUB instructions have the following syntax –

```
ADD/SUB destination, source
```

The ADD/SUB instruction can take place between -

- Register to register
- Memory to register
- Register to memory
- Register to constant data
- Memory to constant data

However, like other instructions, memory-to-memory operations are not possible using ADD/SUB instructions. An ADD or SUB operation sets or clears the overflow and carry flags.

Example

The following example will ask two digits from the user, store the digits in the EAX and EBX register, respectively, add the values, store the result in a memory location 'res' and



finally display the result.

```
SYS_EXIT equ 1
SYS_READ equ 3
SYS_WRITE equ 4
STDIN
         equ 0
STD0UT
         equ 1
segment .data
   msg1 db "Enter a digit ", 0xA,0xD
   len1 equ $- msg1
   msg2 db "Please enter a second digit", 0xA,0xD
   len2 equ $- msg2
   msq3 db "The sum is: "
   len3 equ $- msg3
segment .bss
   num1 resb 2
   num2 resb 2
   res resb 1
section .text
   global _start    ;must be declared for using gcc
                    ;tell linker entry point
_start:
   mov eax, SYS_WRITE
   mov ebx, STDOUT
   mov ecx, msg1
   mov edx, len1
   int 0x80
   mov eax, SYS_READ
   mov ebx, STDIN
   mov ecx, num1
   mov edx, 2
   int 0x80
   mov eax, SYS_WRITE
   mov ebx, STDOUT
   mov ecx, msg2
   mov edx, len2
```



```
int 0x80
   mov eax, SYS_READ
   mov ebx, STDIN
   mov ecx, num2
   mov edx, 2
   int 0x80
   mov eax, SYS_WRITE
   mov ebx, STDOUT
   mov ecx, msg3
   mov edx, len3
   int 0x80
   ; moving the first number to eax register and second number to ebx
   ; and subtracting ascii '0' to convert it into a decimal number
   mov eax, [num1]
   sub eax, '0'
   mov ebx, [num2]
   sub ebx, '0'
   ; add eax and ebx
   add eax, ebx
   ; add '0' to to convert the sum from decimal to ASCII
   add eax, '0'
   ; storing the sum in memory location res
   mov [res], eax
   ; print the sum
   mov eax, SYS_WRITE
   mov ebx, STDOUT
   mov ecx, res
   mov edx, 1
   int 0x80
exit:
   mov eax, SYS_EXIT
   xor ebx, ebx
   int 0x80
```

When the above code is compiled and executed, it produces the following result –



```
Enter a digit:
3
Please enter a second digit:
4
The sum is:
7
```

The program with hardcoded variables -

```
section .text
                                                            Live Demo
  global _start    ;must be declared for using gcc
                   ;tell linker entry point
_start:
  mov eax, '3'
        eax, '0'
  sub
  mov ebx, '4'
  sub
          ebx, '0'
  add eax, ebx
  add eax, '0'
  mov [sum], eax
  mov ecx, msg
  mov edx, len
  mov ebx,1 ;file descriptor (stdout)
  mov eax,4 ;system call number (sys_write)
  int 0x80 ; call kernel
  mov ecx, sum
  mov edx, 1
  mov ebx,1 ;file descriptor (stdout)
  mov eax,4 ;system call number (sys_write)
  int 0x80 ; call kernel
  mov eax,1 ;system call number (sys_exit)
   int 0x80 ; call kernel
section .data
  msg db "The sum is:", 0xA,0xD
  len equ $ - msg
  segment .bss
  sum resb 1
```



When the above code is compiled and executed, it produces the following result -

The sum is:

7

The MUL/IMUL Instruction

There are two instructions for multiplying binary data. The MUL (Multiply) instruction handles unsigned data and the IMUL (Integer Multiply) handles signed data. Both instructions affect the Carry and Overflow flag.

Syntax

The syntax for the MUL/IMUL instructions is as follows -

MUL/IMUL multiplier

Multiplicand in both cases will be in an accumulator, depending upon the size of the multiplicand and the multiplier and the generated product is also stored in two registers depending upon the size of the operands. Following section explains MUL instructions with three different cases —

Sr.No.	Scenarios
1	When two bytes are multiplied – The multiplicand is in the AL register, and the multiplier is a byte in the memory or in another register. The product is in AX. High-order 8 bits of the product is stored in AH and the low-order 8 bits are stored in AL. AL χ 8 Bit Source = AH AL
2	When two one-word values are multiplied — The multiplicand should be in the AX register, and the multiplier is a word in memory or another register. For example, for an instruction like MUL DX, you must store the multiplier in DX and the multiplicand in AX. The resultant product is a doubleword, which will need two registers. The high-order (leftmost) portion gets stored in DX and the lower-order (rightmost) portion gets stored in AX.
3	When two doubleword values are multiplied — When two doubleword values are multiplied, the multiplicand should be in EAX and the multiplier is a doubleword value stored in memory or in another



register. The product generated is stored in the EDX:EAX registers, i.e., the high order 32 bits gets stored in the EDX register and the low order 32-bits are stored in the EAX register.

```
EAX X 32 Bit Source = EDX EAX
```

Example

```
MOV AL, 10
MOV DL, 25
MUL DL
...
MOV DL, 0FFH ; DL= -1
MOV AL, 0BEH ; AL = -66
IMUL DL
```

Example

The following example multiplies 3 with 2, and displays the result –

```
section .text
                                                              Live Demo
  global _start
                   ;must be declared for using gcc
_start:
                    ;tell linker entry point
       al,'3'
  mov
          al, '0'
   sub
       bl, '2'
  mov
           bl, '0'
   sub
  mul
       bl
  add al, '0'
        [res], al
  mov
  mov ecx, msg
       edx, len
  mov
       ebx,1 ;file descriptor (stdout)
  mov
       eax,4 ;system call number (sys_write)
  mov
   int
       08x0
              ;call kernel
       ecx, res
  mov
       edx, 1
  mov
```



```
mov ebx,1 ;file descriptor (stdout)
mov eax,4 ;system call number (sys_write)
int 0x80 ;call kernel

mov eax,1 ;system call number (sys_exit)
int 0x80 ;call kernel

section .data
msg db "The result is:", 0xA,0xD
len equ $- msg
segment .bss
res resb 1
```

When the above code is compiled and executed, it produces the following result –

```
The result is:
```

The DIV/IDIV Instructions

The division operation generates two elements - a **quotient** and a **remainder**. In case of multiplication, overflow does not occur because double-length registers are used to keep the product. However, in case of division, overflow may occur. The processor generates an interrupt if overflow occurs.

The DIV (Divide) instruction is used for unsigned data and the IDIV (Integer Divide) is used for signed data.

Syntax

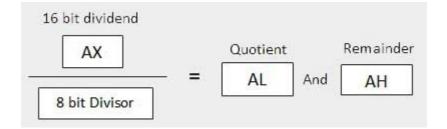
The format for the DIV/IDIV instruction -

```
DIV/IDIV divisor
```

The dividend is in an accumulator. Both the instructions can work with 8-bit, 16-bit or 32-bit operands. The operation affects all six status flags. Following section explains three cases of division with different operand size –

Sr.No.	Scenarios
1	When the divisor is 1 byte – The dividend is assumed to be in the AX register (16 bits). After division, the quotient goes to the AL register and the remainder goes to the AH register.

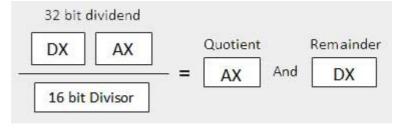




When the divisor is 1 word -

The dividend is assumed to be 32 bits long and in the DX:AX registers. The high-order 16 bits are in DX and the low-order 16 bits are in AX. After division, the 16-bit quotient goes to the AX register and the 16-bit remainder goes to the DX register.

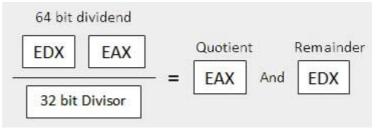
2



When the divisor is doubleword -

The dividend is assumed to be 64 bits long and in the EDX:EAX registers. The high-order 32 bits are in EDX and the low-order 32 bits are in EAX. After division, the 32-bit quotient goes to the EAX register and the 32-bit remainder goes to the EDX register.

3



Example

The following example divides 8 with 2. The **dividend 8** is stored in the **16-bit AX register** and the **divisor 2** is stored in the **8-bit BL register**.

```
section .text
global _start ; must be declared for using gcc

_start: ; tell linker entry point
mov ax,'8'
sub ax,'0'

mov bl, '2'
sub bl, '0'
```



```
div bl
  add ax, '0'
  mov [res], ax
  mov ecx, msg
  mov edx, len
  mov ebx,1 ;file descriptor (stdout)
  mov eax,4 ;system call number (sys_write)
  int 0x80 ; call kernel
  mov ecx, res
  mov edx, 1
  mov ebx,1 ;file descriptor (stdout)
  mov eax,4 ;system call number (sys_write)
  int 0x80 ; call kernel
  mov eax,1 ;system call number (sys_exit)
  int 0x80 ; call kernel
section .data
msg db "The result is:", 0xA,0xD
len equ $- msg
segment .bss
res resb 1
```

When the above code is compiled and executed, it produces the following result -

```
The result is:
4
```