

# HW5\_P3

March 5, 2022

## 1 Problem 3

Cell 1 marks all the modified plotting functions that have been used for this problem. Cell 2 is the code for the problem, and has been well-documented. Running cell 3 displays all relevant plots and answers.

```
[1]: #####
# EE559 Hw5 Wk7, Prof. Jenkins, Spring 2022
# Created by Fernando V. Monteiro, TA
#####

import matplotlib.pyplot as plt
import numpy as np
import pandas as pd

def linear_decision_function(X, weight, labels):
    """
    Implements the perceptron decision function
    :param X: feature matrix of dimension  $N \times D$ 
    :param weight: weight vector of dimension  $1 \times D$ 
    :param labels: possible class assignments
    :return:
    """
    g_x = np.dot(X, weight)
    pred_label = np.zeros((X.shape[0], 1))
    pred_label[g_x > 0] = labels[0]
    pred_label[g_x < 0] = labels[1]
    return pred_label

def nonlinear_decision_function(X, weight, labels):
    """
    Implements a non linear decision function
    :param X: feature matrix of dimension  $N \times D$ 
    :param weight: weight vector of dimension  $1 \times D$ 
    :param labels: possible class assignments
    :return:
```

```

"""
    # Consider  $x_1x_2$  and  $x_1x_1$  as the most relevant features. Use this to
    ↪construct the
    # quadratic equation to fit the data.
    X = np.column_stack((np.multiply(X[:,0], X[:,1]), np.multiply(X[:,1], X[
    ↪:,1])))
    g_x = np.dot(X, weight)
    pred_label = np.zeros((X.shape[0], 1))
    pred_label[g_x > 0] = labels[0]
    pred_label[g_x < 0] = labels[1]
    return pred_label

def plot_perceptron_boundary(training, label_train, weight,
                             decision_function):
    """
    Plot the 2D decision boundaries of a linear classifier
    :param training: training data
    :param label_train: class labels correspond to training data
    :param weight: weights of a trained linear classifier. This
        must be a vector of dimensions (1, D)
    :param decision_function: a function that takes in a matrix with N
        samples and returns N predicted labels
    """

    if isinstance(training, pd.DataFrame):
        training = training.to_numpy()
    if isinstance(label_train, pd.DataFrame):
        label_train = label_train.to_numpy()

    # Total number of classes
    classes = np.unique(label_train)
    nclass = len(classes)

    class_names = []
    for c in classes:
        class_names.append('Class ' + str(int(c)))

    # Set the feature range for plotting
    max_x1 = np.ceil(np.max(training[:, 0])) + 1.0
    min_x1 = np.floor(np.min(training[:, 0])) - 1.0
    max_x2 = np.ceil(np.max(training[:, 1])) + 1.0
    min_x2 = np.floor(np.min(training[:, 1])) - 1.0

    xrange = (min_x1, max_x1)
    yrange = (min_x2, max_x2)

```

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# step size for how finely you want to visualize the decision boundary.
inc = 0.005

# generate grid coordinates. This will be the basis of the decision
# boundary visualization.
(x1, x2) = np.meshgrid(np.arange(xrange[0], xrange[1] + inc / 100, inc),
                        np.arange(yrange[0], yrange[1] + inc / 100, inc))

# size of the (x1, x2) image, which will also be the size of the
# decision boundary image that is used as the plot background.
image_size = x1.shape
# make (x1, x2) pairs as a bunch of row vectors.
grid_2d = np.hstack((x1.reshape(x1.shape[0] * x1.shape[1], 1, order='F'),
                     x2.reshape(x2.shape[0] * x2.shape[1], 1, order='F')))

# Labels for each (x1, x2) pair.
pred_label = decision_function(grid_2d, weight, classes)

# reshape the idx (which contains the class label) into an image.
decision_map = pred_label.reshape(image_size, order='F')

# create fig
fig, ax = plt.subplots()
# show the image, give each coordinate a color according to its class
# label
ax.imshow(decision_map, vmin=np.min(classes), vmax=9, cmap='Pastel1',
          extent=[xrange[0], xrange[1], yrange[0], yrange[1]],
          origin='lower')

# plot the class training data.
data_point_styles = ['rx', 'bo', 'g*']
for i in range(nclass):
    ax.plot(training[label_train == classes[i], 0],
            training[label_train == classes[i], 1],
            data_point_styles[int(classes[i]) - 1],
            label=class_names[i])

ax.legend()
ax.set_xlabel('Feature 1')
ax.set_ylabel('Feature 2')
plt.tight_layout()
plt.show()

return fig

```

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[4]: import os
import numpy as np
import pandas as pd

```

```

import matplotlib.pyplot as plt
from sklearn.linear_model import Perceptron

np.random.seed(0)

ROOTDIR = './data/h5w7_pr3_python_files/'
FILENAME = 'h5w7_data.csv'

class NonLinearMapping:

    def __init__(self, filepath):
        self.filepath = filepath

    def _get_features(self, path):
        """ Obtain the feature matrix and the corresponding labels.

        Parameters
        -----
        path : str
            Path to the dataset.

        Returns
        -----
        x : ndarray
            Feature matrix of dimension  $N \times D$ .
        y : ndarray
            Labels of dimension  $N \times 1$ .
        """
        df = pd.read_csv(path, header = None)[1 : ]
        x, y = df.iloc[:, :-1].values.astype(float), \
            df.iloc[:, -1].values.astype(float)
        return x, y

    def _plot_feature_space(self, x, y):
        """
        Visualize the original feature space.

        Parameters
        -----
        x : ndarray
            Feature matrix of dimension  $N \times D$ .
        y : ndarray
            Labels of dimension  $N \times 1$ .

        Returns

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```

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None
"""

#inspired from the utility function given above

class_names = ['Class ' + str(int(c)) for c in np.unique(y)]
classes = np.unique(y)
style = ['rx', 'bo']
for idx in range(len(classes)):
    plt.plot(x[y == classes[idx], 0],
             x[y == classes[idx], 1],
             style[idx],
             label = class_names[idx])
plt.legend(loc = 'upper right')
plt.xlabel('Feature 1')
plt.ylabel('Feature 2')
plt.title('Feature space (non-augmented)')
plt.tight_layout()
plt.show()

def _feature_space_expansion(self, x):
    """
    Expand the feature space using the feature vectors.
    [x1, x2] -> [x1, x2, x1x2, x1x1, x2x2]

    Parameters
    -----
    x : ndarray
        Feature matrix of dimension N x D.

    Returns
    -----
    expanded_x : ndarray
        Expanded feature matrix of dimension N x (D + 3).
    """

    x1x2 = np.multiply(x[:, 0], x[:, 1]).reshape(-1, 1)
    x1x1 = np.multiply(x[:, 0], x[:, 0]).reshape(-1, 1)
    x2x2 = np.multiply(x[:, 1], x[:, 1]).reshape(-1, 1)
    expanded_x = np.hstack((x, x1x2, x1x1, x2x2))
    return expanded_x

def _runner(self):
    """

```

*Runner module for the class.*

*Parameters*

-----

*None*

*Returns*

-----

*None*

"""

```
# 3(a)
print('3(a)')
# Load the data
x, y = self._get_features(self.filepath)
# Plot the feature space (non-augmented)
self._plot_feature_space(x, y)

# 3(b)
print('3(b)')
# Fit the perceptron model
model = Perceptron(fit_intercept = False).fit(x, y)
# Obtain weights
perceptron_weights = model.coef_[0]
print(f'Classification score on the feature space: {model.score(x, y)}')

# 3(c)
print('3(c)')
# Plot the decision boundary
plot_perceptron_boundary(
    x, y, perceptron_weights, linear_decision_function
)

# 3(d)
print('3(d)')
# Quadratic feature expansion
expanded_x = self._feature_space_expansion(x)
# Fit the perceptron model
model.fit(expanded_x, y)
# Obtain weights
weights_newspace = model.coef_[0]
# Classification accuracy
score_newspace = model.score(expanded_x, y)
print('Weight vector in the new feature space:', weights_newspace)
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    print(f'Classification score on the expanded feature space:␣
→{score_newspace}')

    # 3(e)
    print('3(e)')
    # Obtain absolute weights of the expanded feature space
    abs_weights = np.abs(weights_newspace)
    # Get locations of the sorted absolute weights
    indices_locs = np.flip(np.argsort(abs_weights))
    # Consider relevant features according to the weights
    relevant_feat_1, relevant_feat_2 = expanded_x[:, indices_locs[0]].
→reshape(-1, 1), \
                                expanded_x[:, indices_locs[1]].
→reshape(-1, 1)
    # New feature space (2 dims) of relevant features
    phi_X_best = np.hstack((relevant_feat_1, relevant_feat_2))
    # Weights of the relevant features
    weights_best_2 = np.array([abs_weights[indices_locs[0]],␣
→abs_weights[indices_locs[1]]])
    # Plot the decision boundary
    plot_perceptron_boundary(
        phi_X_best, y, weights_best_2, linear_decision_function
    )

    # 3(f)
    # Nonlinear mapping (decision boundary)
    print('3(f)')
    plot_perceptron_boundary(
        x, y, perceptron_weights, nonlinear_decision_function
    )

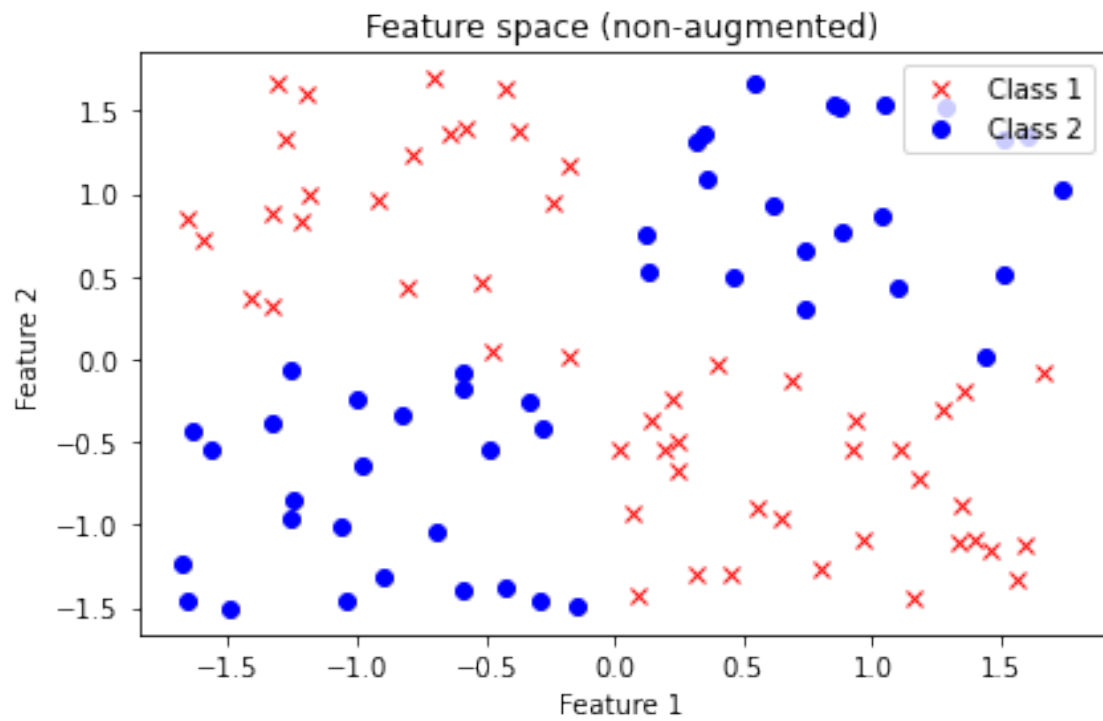
```

```

[5]: if __name__ == '__main__':
    filepath = os.path.join(ROOTDIR, FILENAME)
    hw = NonLinearMapping(filepath)
    hw._runner()

```

3(a)

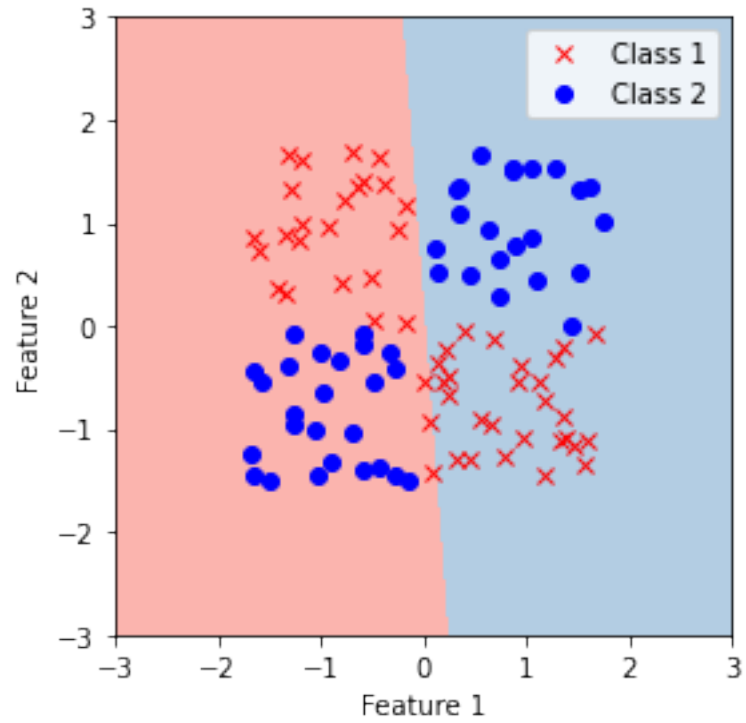


3(b)

Classification score on the feature space: 0.53

3(c)



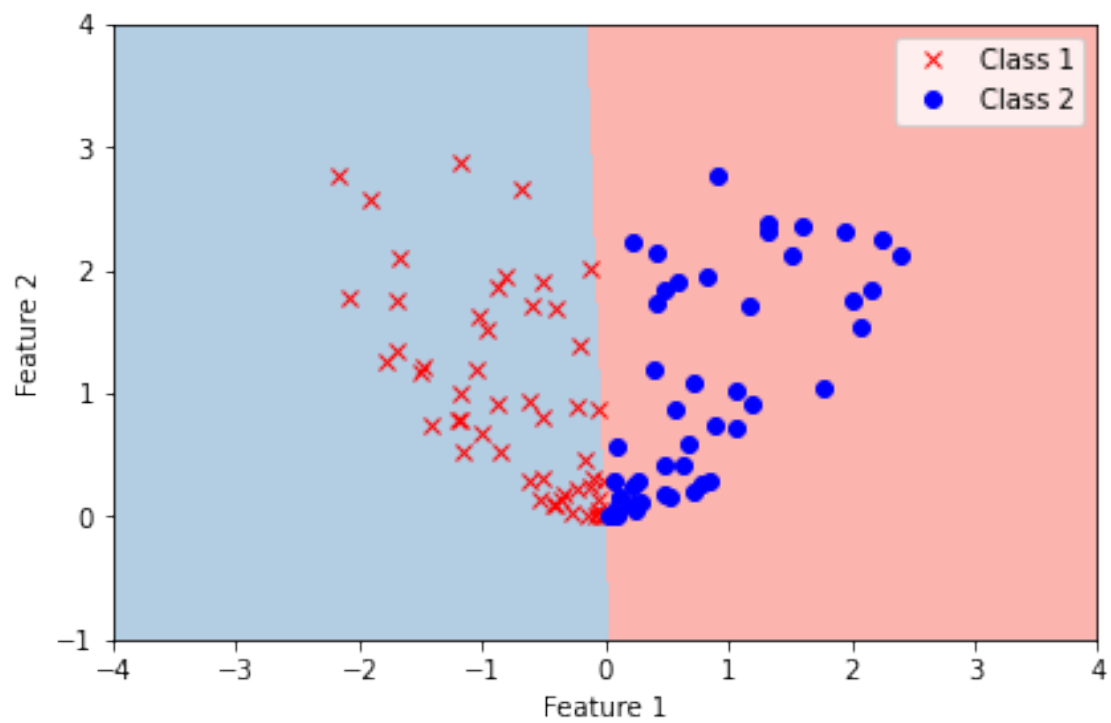


3(d)

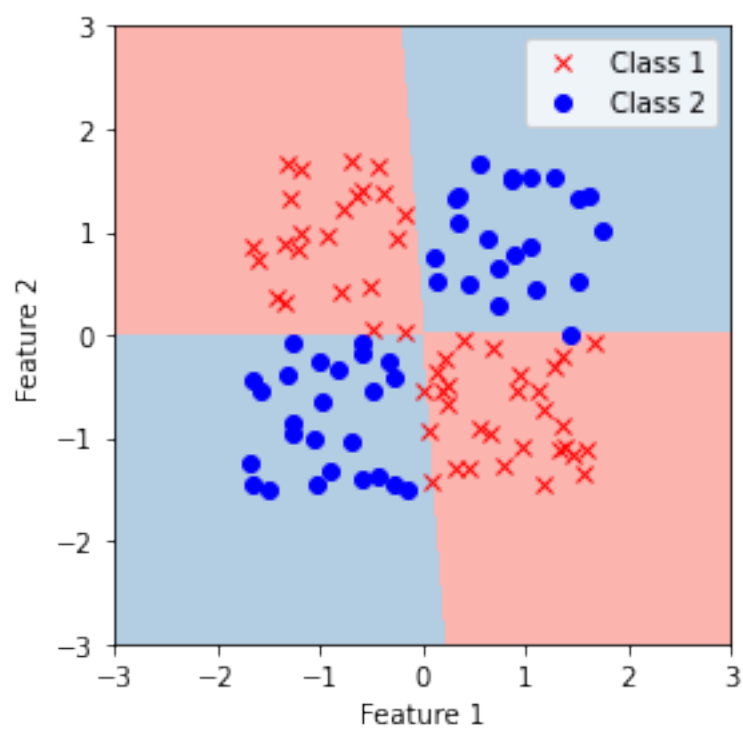
Weight vector in the new feature space:  $[-0.10562188 \ -0.14390327 \ 7.616127 \ 0.05743614 \ -0.28634851]$

Classification score on the expanded feature space: 1.0

3(e)



3(f)



[ ]: