# Sarvan Gill

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sarvangill.ca



### **University of British Columbia**

BASc Engineering Physics Average: 90.2%

2017 – Present Vancouver, BC

#### **2019 Trek Scholarship Recipient**

# **♦** Work Experience

**TRIUMF**Co-op Student

Vancouver, BC

- > Optimized reflector geometry on photomultiplier tubes for Hyper Kamiokande, JPN. (MATLAB/C++)
- > Designed a large permanent magnet spectrometer (up to 2 Tesla) for a new experiment in FERMILAB, USA. (COMSOL)
- > Ran large simulations using a local cluster and Compute Canda Servers
- > Presented at meetings on average three times a week

# **△** Projects

### **Machine Learning Robot Simulation**

Sept. 2019 - Present

- > A simulated robot competition where our robot must use computer vision to ticket illegally parked cars from license plate data
- > Simulated with ROS and trained with the use of Keras and TensorFlow

### **ENPH 253 Robot Competition**

May 2019 - Aug. 2019

- > A completely autonomous robot tasked with navigating to pillars of different heights, picking up stones on the pillars, returning home and placing the stones accurately in a tilted gauntlet.
- > Competed against 15 other robots and went undefeated
- > Programmed arm movements and navigation in C++
- > Designed with SOLIDWORKS
- > Built multiple H-Bridges and control circuits

Boggle Player November 2018

> Implemented a Graph ADT in Java to calculate the maxmimum score of a Boggle board game using a dictionary text file

### **♥**\$ Skills

**Languages** C++/C, Python, Java, MATLAB, HTML/CSS

**Software** Linux OS, ROS, SOLIDWORKS, COMSOL Multiphysics

Hardware Soldering, Hand/Power tools, Oscilloscope, Function Generator

### Extracurriculars

**Vaisakhi Parade** Volunteer for a local cultural event **Sports** Play recreational Ice Hockey and Water Polo