

Communication theory Assignment-1

Report and results for MATLAB questions:

A)

We have taken B_c to be a vector of length N and it consists of -1, 1 generated randomly.

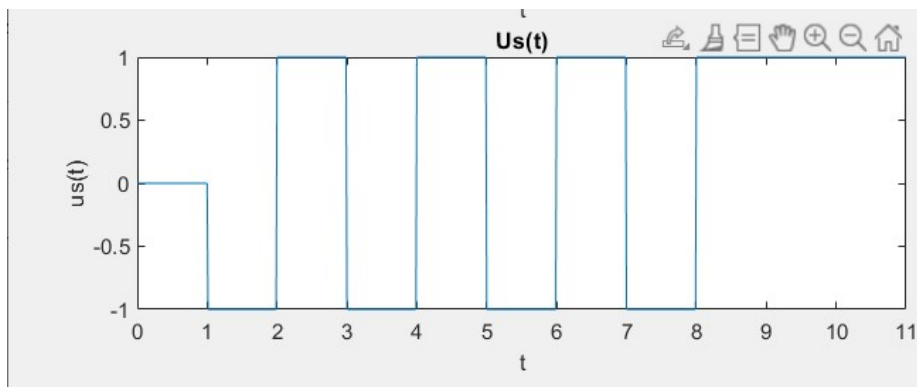
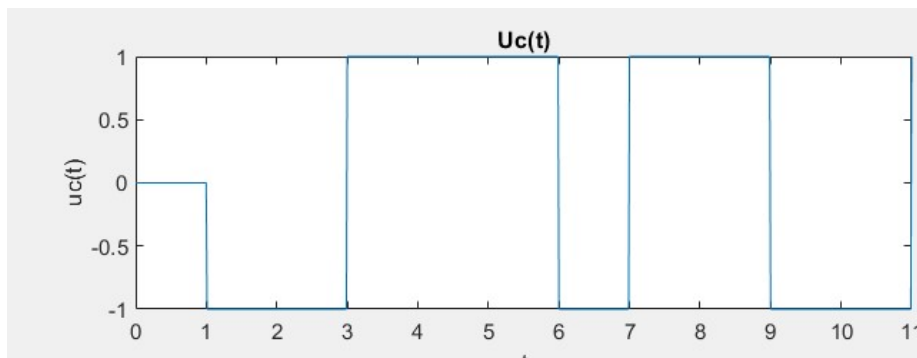
We need to plot $u_c(t)$ which is B_c multiplied with shifted rectangular pulses $p(t-n)$.

Parameters:

$N=10$

$F_s=80$ Hz

Plots:



Explanation:

Clearly, the above graph depicts $\{1, -1\}$ being multiplied with shifted rectangular pulses. We have taken the sampling frequency as 80 Hz (multiples of 20) so that the graph actually looks like a rectangular pulse. Note that even for lesser frequency also graph can be obtained.

B), C)

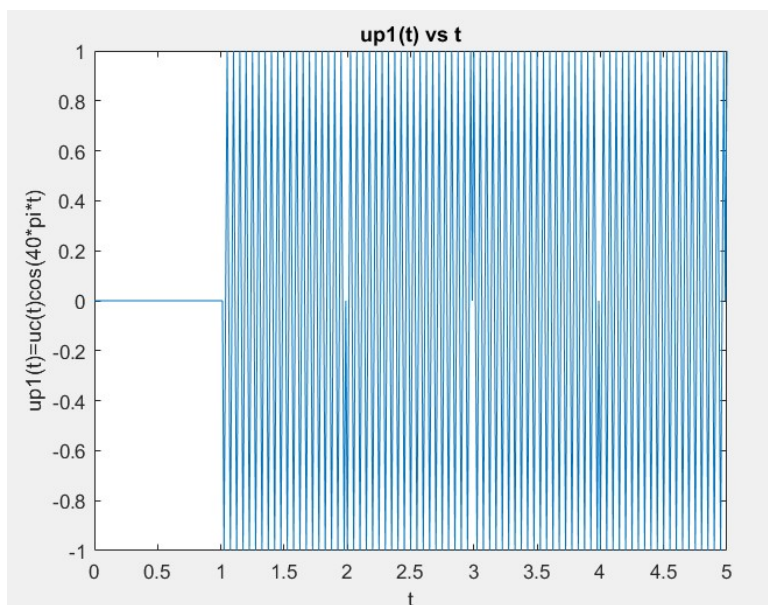
Here, we are required to upconvert the baseband form by multiplying $uc(t)$ with $\cos(40\pi t)$ to get passband signal. We are expected to take a proper sampling rate so that we don't get a distorted plot.

Parameters:

$N=4$

$F_s=80$ Hz

Plots:



Explanation:

The above plot depicts the passband signal of $uc(t)$. One cannot exactly tell what $uc(t)$ after the upconversion happens by looking at $up1(t)$. However, we find that the recognition when we have a **phase change** i.e. from -1 to 1 or 1 to -1, we notice a gap in the graph that is caused due to the change in phase of $uc(t)$. So the name Binary Shift Keying(BPSK) is justified. Also the amplitude is 1 as expected.

Regarding the frequency, we need to be careful that when we take lesser frequencies, we get a bad graph (ie phase shift is not clear) and the sampling frequency needs to be slowly increased in multiples of 20Hz and when we get the expected graph we can stop.

D)

Here, we need to add the other upconverted component, and finally we generate the complete passband signal $u_p(t) = u_c(t)\cos 40\pi t - u_s(t)\sin 40\pi t$.

Parameters:

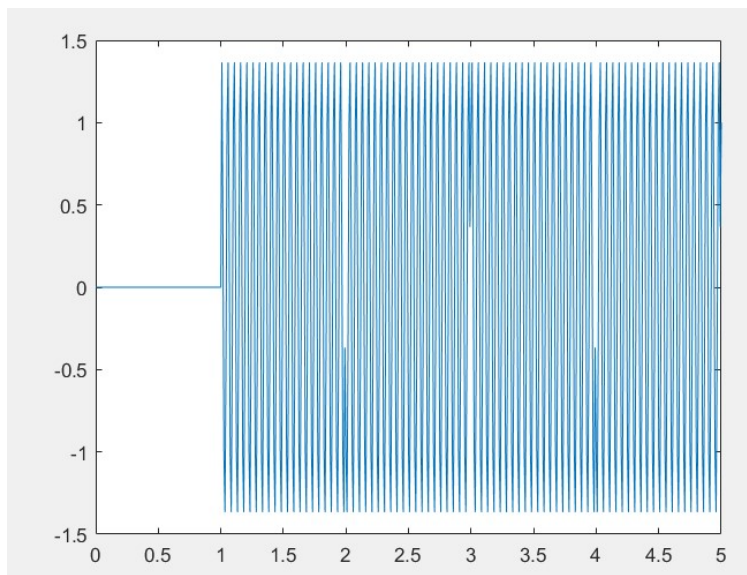
$N=4$

$F_s=120$ Hz

Plots:

X-axis- Time

Y-axis- $u_p(t)$



Explanation:

Here, we have finally got the passband signal $u_p(t)$. It is impossible to tell what $u_c(t)$ and $u_s(t)$ are from looking at the plots. Here, we notice that there is a **phase shift** whenever either **$B_c(n)$ changes or $B_s(n)$ changes**. Since there are 4 such possible cases, we say that this is QPSK. Also since we get a combination of sin and cos, the maximum value of their sum $\sqrt{2}$ is the amplitude expected.

With regard to the sampling frequency, 80Hz is not sufficient to prevent the distortion of shapes we increase it to 120Hz so that the graph is neatly formed and looks nice. Any higher values are also fine as long as we clearly are able to observe the change in phase.

E)

Here, we need to downconvert the signal by multiplying the signal with $\cos(2\pi f_c t + \theta)$ and $\sin(2\pi f_c t + \theta)$, and then pass it through a low pass filter $l(0, 0, 25)$. We take phase to be 0.

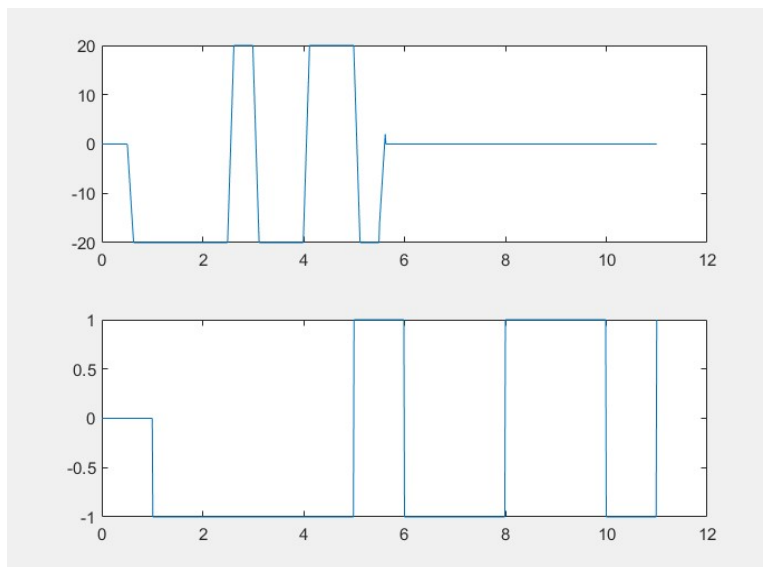
Parameters:

$N=10$

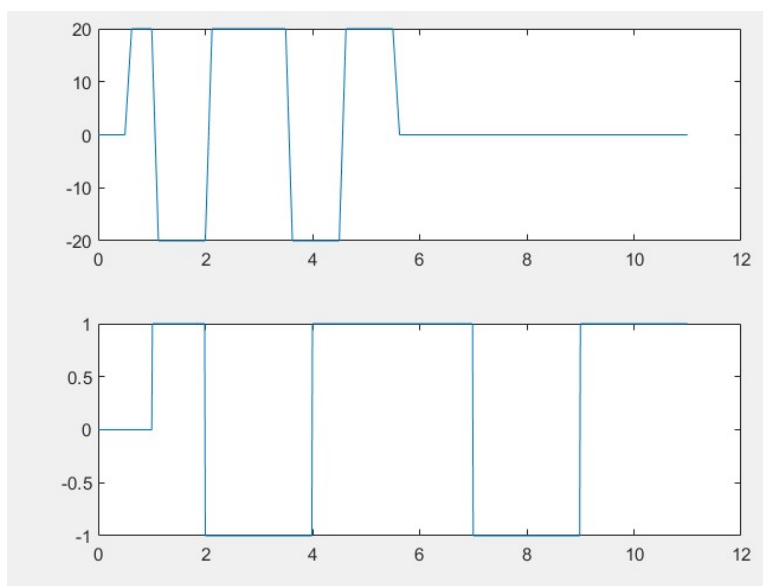
$F_s=80$ Hz

Plots:

$V_c(t)$ -1st subplot; $U_c(t)$ -2nd subplot



$V_s(t)$ -1st subplot vs $U_s(t)$ -2nd subplot



Explanation:

Clearly we notice that in both the cases, the V_c , V_s obtained are similar to the actual waveform but are scaled. The scaling in x axis is due to defining new time variable for convolution.

We can see that we **can actually identify** what bit is sent using our eyeballs and the chance of error is almost 0.

F)

Here, we need to downconvert the signal by multiplying the signal with $\cos(2\pi f_c t + \theta)$ and $\sin(2\pi f_c t + \theta)$, and then pass it through a low pass filter $I(0, 0, 25)$. We take phase with which we multiply the values to be $\pi/4$.

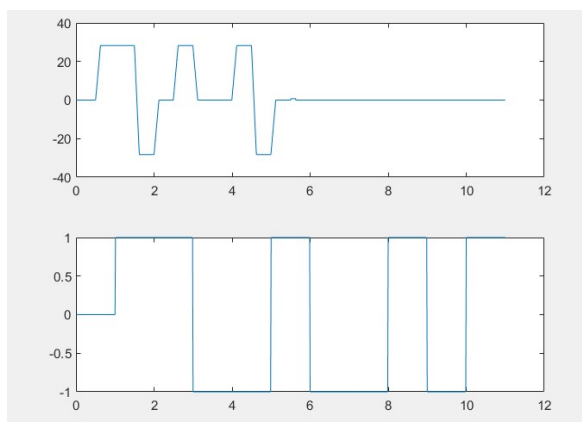
Parameters:

$N=10$

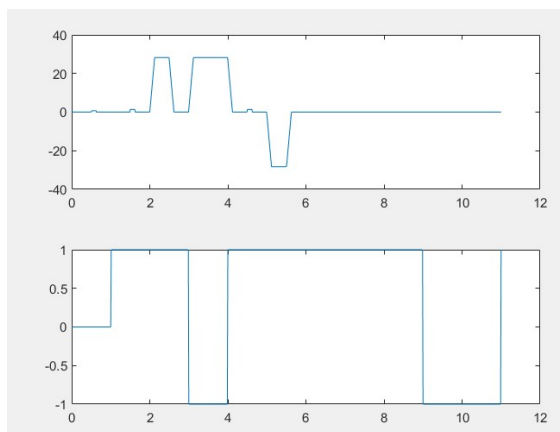
$F_s=80$ Hz

Plots:

$V_c(t)$ -1st subplot; $U_c(t)$ -2nd subplot



$V_s(t)$ -1st subplot; $V_c(t)$ -2nd subplot



Explanation:

Clearly we notice that in both the cases, the V_c , V_s obtained are different from each other. The scaling in x axis is due to defining new time variable for convolution.

We **cannot actually identify** what bit is sent using our eyeballs and the chance of error is extremely high because of the initial phase in the value of u_c and u_s .

G)

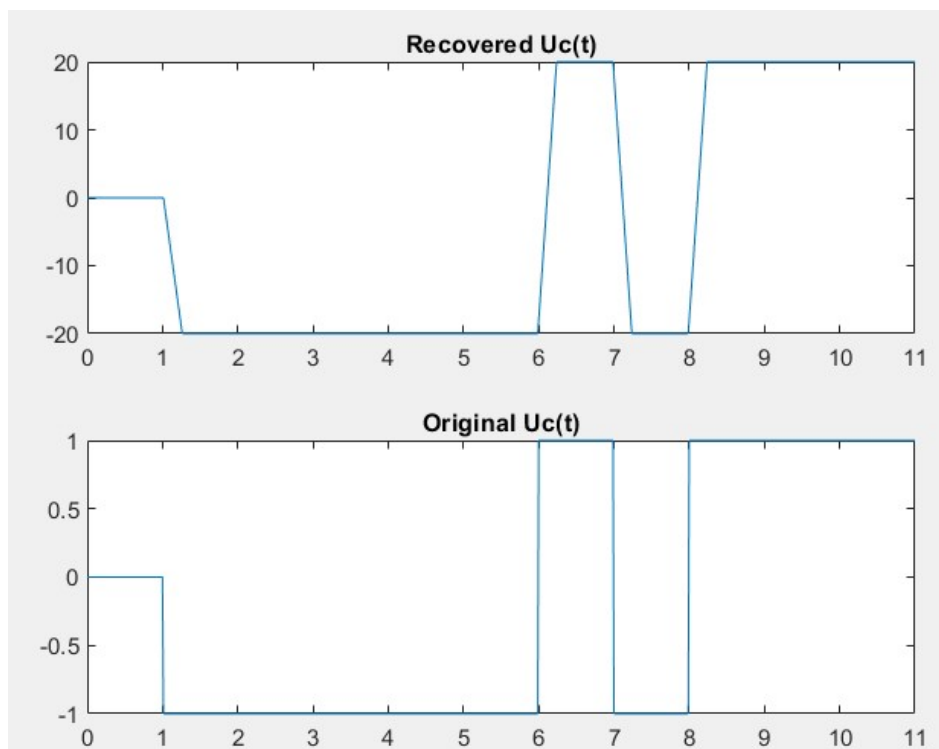
Here, we need to downconvert the signal by multiplying the signal with $\cos(2\pi f_c t + \theta)$ and $\sin(2\pi f_c t + \theta)$, and then pass it through a low pass filter $I(0, 0.25)$. We take phase with which we multiply the values to be $\pi/4$. After that we manipulate the components using certain formula to get $u_c(t)$ and $u_s(t)$

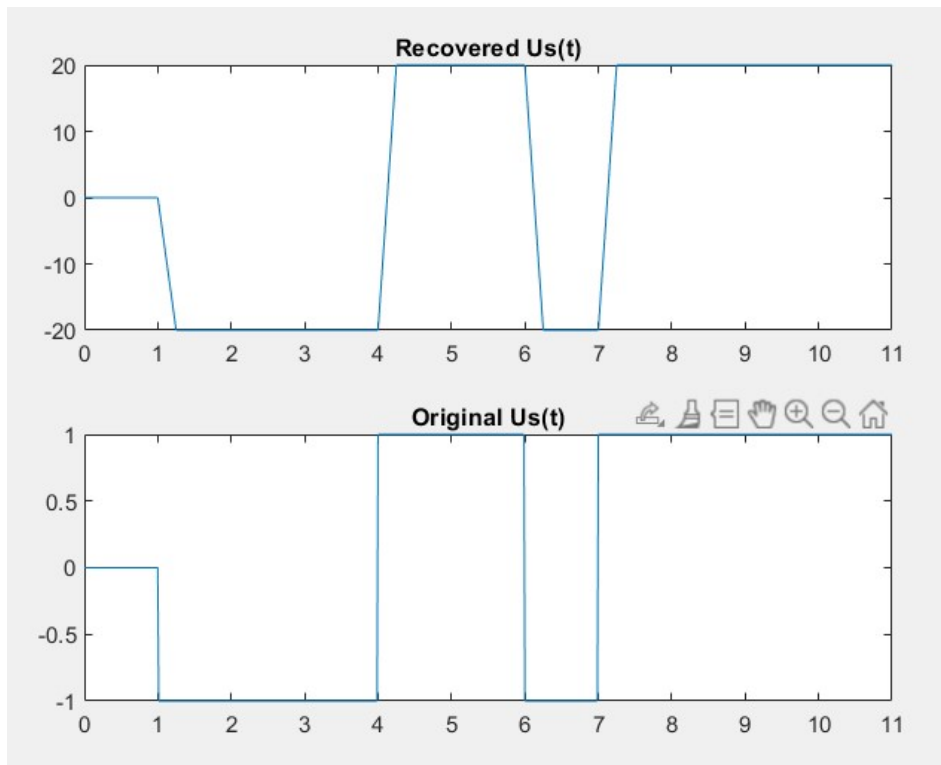
Parameters:

$N=10$

$F_s=80$ Hz

Plots:





Explanation:

We are able to recover $u_c(t)$ and $u_s(t)$ from $v_c(t)$ and $v_s(t)$ by using the following formula

$$u_s(t) = v_c(t) \cdot \cos(\theta) - v_s(t) \cdot \sin(\theta);$$

$$u_c(t) = v_c(t) \cdot \sin(\theta) + v_s(t) \cdot \cos(\theta);$$

We can simply derive this formula from the basic formulas we know during the process of downconversion.

Clearly we can observe that we are able to arrive at the initial signal and be able to tell the values of B_c and B_s clearly by looking at the following graph. So this process can be applied when we downconvert with a nonzero phase.