```
In[ • ]:= G = 6.67 \times 10^{-11};
                                 (*gravitational constant*)
M = 5.97219 \times 10^{24};
                                   (*mass of earth in kilograms*)
r0 = 12000 \times 10^3;
(*initial distance of the satellite from the centre of the Earth in metres*)
v0KmpHr = 19000;
(*initial speed of the satellite in km/hr fired horizontally ∗)
v0Mps = v0KmpHr - \frac{5}{18};
(*initial speed of the satellite in m/s fired horizontally *)
phid0 = \frac{\text{vOMps}}{\text{r0}};
 RE = 6378 \times 1000;
                                   (*radius of the Earth*)
 airDrag = 34;
                                   (*amount of air drag*)
tFin = 140000;
                                   (*how much time is to be simulated*)
StopCriterion = {WhenEvent[{r[t] < RE || t > tFin} , end = t;
      "StopIntegration "]};
sol = NDSolve \left[ \left\{ r[t] \times phi''[t] + 2r'[t] \times phi'[t] == 0 - airDrag phi'[t] \right\} \right],
       r''[t] - r[t] phi'[t]^2 = \frac{-(GM)}{r[t]^2}, r[0] = r0, phi[0] = \frac{\pi}{2}, r'[0] = 0,
       phi'[0] == phid0, StopCriterion \}, \{r, phi\}, \{t, \infty\}] # Quiet;
p1 = ParametricPlot [Evaluate [{r[t] Cos[phi[t]], r[t] Sin[phi[t]]} /. sol],
    {t, 0, end}, AspectRatio → 1, PlotStyle → Red, PlotRange → Full];
p2 = ParametricPlot [{ RE Cos[u], RE Sin[u]}, {u, 0, 2 Pi},
    PlotStyle → Blue, PlotRange → Full];
Show[p1, p2]
Show[p1, p2, PlotRange \rightarrow All]
```

- In[]:=
- In[]:=
- In[]:=