

Integrability and action-angle variables of post-Newtonian binary black holes

Sashwat Tanay
with Leo Stein, Gihyuk Cho*
& José T. Gálvez Gherzi†

Univ. of Mississippi, SNU (Seoul)*, UTEC (Lima)†

Northwestern University (Jul 2023)

Refs: [2012.06586](#), [2110.15351](#), [2210.01605](#), [2206.05799](#)

stanay@olemiss.edu

Plan of the talk

- Introduction and theory

Plan of the talk

- Introduction and theory
- 1.5PN: action-angles

Plan of the talk

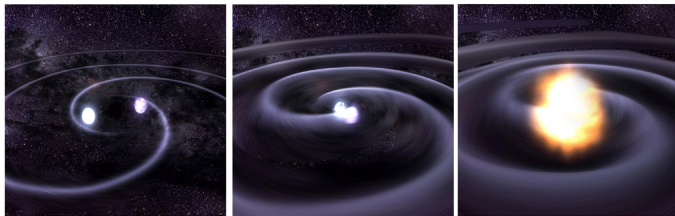
- Introduction and theory
- 1.5PN: action-angles
- 2PN: integrable or non-integrable?

Plan of the talk

- Introduction and theory
- 1.5PN: action-angles
- 2PN: integrable or non-integrable?
- Conclusions

Introduction and theory

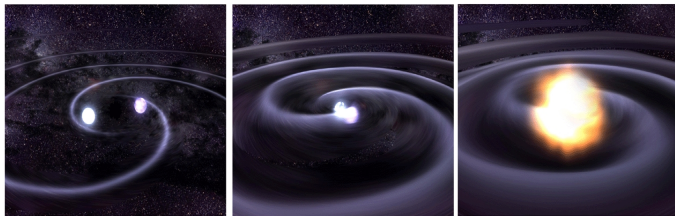
Gravitational waves from binary black holes



- **Stellar mass BBHs:** gravitational wave (GW) sources of LIGO and LISA.

Image credit: www.eoportal.org

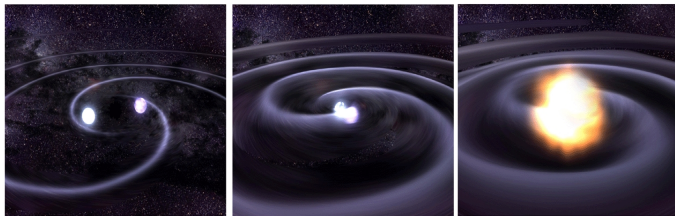
Gravitational waves from binary black holes



- **Stellar mass BBHs:** gravitational wave (GW) sources of LIGO and LISA.
- **Inspiral stage:** the longest-lived stage of BBH evolution.

Image credit: www.eoportal.org

Gravitational waves from binary black holes



- **Stellar mass BBHs:** gravitational wave (GW) sources of LIGO and LISA.
- **Inspiral stage:** the longest-lived stage of BBH evolution.
- Quadrupole formula \implies GWs are functions of **black hole trajectories** (*focus of the talk*).

Image credit: www.eoportal.org

Binary black-holes and post-Newtonian theory

- BBHs in inspiral stage are studied within post-Newtonian (PN) approximation.

Binary black-holes and post-Newtonian theory

- BBHs in inspiral stage are studied within post-Newtonian (PN) approximation.
- Applicable when black holes are far apart ($\frac{Gm}{c^2 R} \ll 1$) and move slowly ($v^2/c^2 \ll 1$).

Binary black-holes and post-Newtonian theory

- BBHs in inspiral stage are studied within post-Newtonian (PN) approximation.
- Applicable when black holes are far apart ($\frac{Gm}{c^2 R} \ll 1$) and move slowly ($v^2/c^2 \ll 1$).
- Quantities are expanded in the small parameter v^2/c^2 .

Binary black-holes and post-Newtonian theory

- BBHs in inspiral stage are studied within post-Newtonian (PN) approximation.
- Applicable when black holes are far apart ($\frac{Gm}{c^2 R} \ll 1$) and move slowly ($v^2/c^2 \ll 1$).
- Quantities are expanded in the small parameter v^2/c^2 .
- **Example:** schematic representation of Hamiltonian. Each factor of $1/c^2 \implies$ one PN order.

$$H = (\dots) + \frac{1}{c^2}(\dots) + \frac{1}{c^3}(\dots) + \frac{1}{c^4}(\dots)$$

0PN 1PN 1.5PN 2PN

Binary black-holes and post-Newtonian theory

- BBHs in inspiral stage are studied within post-Newtonian (PN) approximation.
- Applicable when black holes are far apart ($\frac{Gm}{c^2 R} \ll 1$) and move slowly ($v^2/c^2 \ll 1$).
- Quantities are expanded in the small parameter v^2/c^2 .
- **Example:** schematic representation of Hamiltonian. Each factor of $1/c^2 \implies$ one PN order.

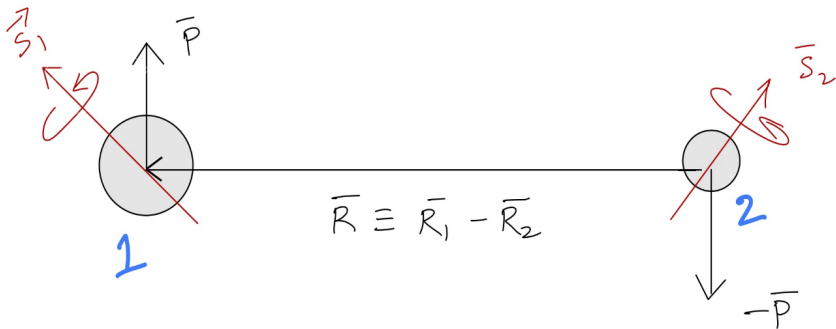
$$H = (\dots) + \frac{1}{c^2}(\dots) + \frac{1}{c^3}(\dots) + \frac{1}{c^4}(\dots)$$

0PN 1PN 1.5PN 2PN

- **Starting point:** 2PN Hamiltonian due to [\[Barker, O'Connell-1975\]](#)

Phase space of spinning PN BBHs

COM FRAME



$\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2$

Phase space of spinning PN BBHs

No. of phase space variables = 10

Phase space of spinning PN BBHs

No. of phase space variables = 10 (since $\dot{S}_1 = \dot{S}_2 = 0$):

Phase space of spinning PN BBHs

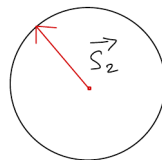
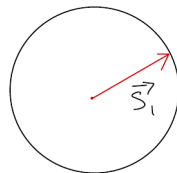
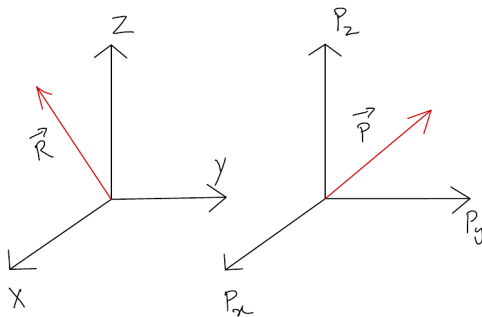
No. of phase space variables = 10 (since $\dot{S}_1 = \dot{S}_2 = 0$):

$X, Y, Z, \quad P_x, P_y, P_z, \quad S_{1\phi}, S_{1z}, \quad S_{2\phi}, S_{2z}$

Phase space of spinning PN BBHs

No. of phase space variables = 10 (since $\dot{S}_1 = \dot{S}_2 = 0$):

$X, Y, Z, \quad P_x, P_y, P_z, \quad S_{1\phi}, S_{1z}, \quad S_{2\phi}, S_{2z}$



$$\mathbb{R}^3 \otimes \mathbb{R}^3 \otimes S^2 \otimes S^2$$

2PN Hamiltonian

- With $m = m_1 + m_2$, $\mu := m_1 m_2 / m$ and $\vec{n} := \vec{R} / R$, the 2PN Hamiltonian becomes [\[Barker, O'Connell-1975\]](#)

2PN Hamiltonian

- With $m = m_1 + m_2$, $\mu := m_1 m_2 / m$ and $\vec{n} := \vec{R} / R$, the 2PN Hamiltonian becomes [\[Barker, O'Connell-1975\]](#)

$$H = \left(\frac{P^2}{2\mu} - \frac{Gm_1 m_2}{R} \right) + \frac{1}{c^2} F_1(R, \vec{P}) + \frac{1}{c^4} F_2(R, \vec{P}) \\ + \frac{1}{c^2} F_3 \left(\vec{S}_1 \cdot \vec{L}, \vec{S}_2 \cdot \vec{L} \right) + \frac{1}{c^4} F_4 \left(\vec{S}_1 \cdot \vec{n}, \vec{S}_2 \cdot \vec{n}, \vec{S}_1 \cdot \vec{S}_2 \right).$$

2PN Hamiltonian

- With $m = m_1 + m_2$, $\mu := m_1 m_2 / m$ and $\vec{n} := \vec{R} / R$, the 2PN Hamiltonian becomes [Barker, O'Connell-1975]

$$H = \left(\frac{P^2}{2\mu} - \frac{Gm_1 m_2}{R} \right) + \frac{1}{c^2} F_1(R, \vec{P}) + \frac{1}{c^4} F_2(R, \vec{P}) \\ + \frac{1}{c^2} F_3 \left(\vec{S}_1 \cdot \vec{L}, \vec{S}_2 \cdot \vec{L} \right) + \frac{1}{c^4} F_4 \left(\vec{S}_1 \cdot \vec{n}, \vec{S}_2 \cdot \vec{n}, \vec{S}_1 \cdot \vec{S}_2 \right).$$

- Evolution of $G(R^i, P^i, S_1^i, S_2^i)$ in terms of Poisson bracket (PB):
 $\dot{G} = \{G, H\}$. [Goldstein]

2PN Hamiltonian

- With $m = m_1 + m_2$, $\mu := m_1 m_2 / m$ and $\vec{n} := \vec{R} / R$, the 2PN Hamiltonian becomes [Barker, O'Connell-1975]

$$H = \left(\frac{P^2}{2\mu} - \frac{Gm_1 m_2}{R} \right) + \frac{1}{c^2} F_1(R, \vec{P}) + \frac{1}{c^4} F_2(R, \vec{P}) \\ + \frac{1}{c^2} F_3(\vec{S}_1 \cdot \vec{L}, \vec{S}_2 \cdot \vec{L}) + \frac{1}{c^4} F_4(\vec{S}_1 \cdot \vec{n}, \vec{S}_2 \cdot \vec{n}, \vec{S}_1 \cdot \vec{S}_2).$$

- Evolution of $G(R^i, P^i, S_1^i, S_2^i)$ in terms of Poisson bracket (PB):
 $\dot{G} = \{G, H\}$. [Goldstein]
- We can write any PB in terms of the **basic PBs**:
 $\{R^i, P^j\} = \delta^{ij}$ and $\{S_A^i, S_B^j\} = \epsilon^{ijk} S_A^k \delta_{AB}.$

2PN Hamiltonian

- With $m = m_1 + m_2$, $\mu := m_1 m_2 / m$ and $\vec{n} := \vec{R} / R$, the 2PN Hamiltonian becomes [Barker, O'Connell-1975]

$$H = \left(\frac{P^2}{2\mu} - \frac{Gm_1 m_2}{R} \right) + \frac{1}{c^2} F_1(R, \vec{P}) + \frac{1}{c^4} F_2(R, \vec{P}) \\ + \frac{1}{c^2} F_3(\vec{S}_1 \cdot \vec{L}, \vec{S}_2 \cdot \vec{L}) + \frac{1}{c^4} F_4(\vec{S}_1 \cdot \vec{n}, \vec{S}_2 \cdot \vec{n}, \vec{S}_1 \cdot \vec{S}_2).$$

- Evolution of $G(R^i, P^i, S_1^i, S_2^i)$ in terms of Poisson bracket (PB):
 $\dot{G} = \{G, H\}$. [Goldstein]
- We can write any PB in terms of the **basic PBs**:
 $\{R^i, P^j\} = \delta^{ij}$ and $\{S_A^i, S_B^j\} = \epsilon^{ijk} S_A^k \delta_{AB}$.
- H and $\{, \}$ determine EOMs.

2PN Hamiltonian

- With $m = m_1 + m_2$, $\mu := m_1 m_2 / m$ and $\vec{n} := \vec{R} / R$, the 2PN Hamiltonian becomes [Barker, O'Connell-1975]

$$H = \left(\frac{P^2}{2\mu} - \frac{Gm_1 m_2}{R} \right) + \frac{1}{c^2} F_1(R, \vec{P}) + \frac{1}{c^4} F_2(R, \vec{P}) \\ + \frac{1}{c^2} F_3(\vec{S}_1 \cdot \vec{L}, \vec{S}_2 \cdot \vec{L}) + \frac{1}{c^4} F_4(\vec{S}_1 \cdot \vec{n}, \vec{S}_2 \cdot \vec{n}, \vec{S}_1 \cdot \vec{S}_2).$$

- Evolution of $G(R^i, P^i, S_1^i, S_2^i)$ in terms of Poisson bracket (PB):
 $\dot{G} = \{G, H\}$. [Goldstein]
- We can write any PB in terms of the **basic PBs**:
 $\{R^i, P^j\} = \delta^{ij}$ and $\{S_A^i, S_B^j\} = \epsilon^{ijk} S_A^k \delta_{AB}$.
- H and $\{, \}$ determine EOMs.
- Lingo:** $\{F, G\} = 0 \sim F \text{ \& } G \text{ commute.}$

2PN Hamiltonian

- With $m = m_1 + m_2$, $\mu := m_1 m_2 / m$ and $\vec{n} := \vec{R} / R$, the 2PN Hamiltonian becomes [Barker, O'Connell-1975]

$$H = \left(\frac{P^2}{2\mu} - \frac{Gm_1 m_2}{R} \right) + \frac{1}{c^2} F_1(R, \vec{P}) + \frac{1}{c^4} F_2(R, \vec{P}) \\ + \frac{1}{c^2} F_3(\vec{S}_1 \cdot \vec{L}, \vec{S}_2 \cdot \vec{L}) + \frac{1}{c^4} F_4(\vec{S}_1 \cdot \vec{n}, \vec{S}_2 \cdot \vec{n}, \vec{S}_1 \cdot \vec{S}_2).$$

- Evolution of $G(R^i, P^i, S_1^i, S_2^i)$ in terms of Poisson bracket (PB):
 $\dot{G} = \{G, H\}$. [Goldstein]
- We can write any PB in terms of the **basic PBs**:
 $\{R^i, P^j\} = \delta^{ij}$ and $\{S_A^i, S_B^j\} = \epsilon^{ijk} S_A^k \delta_{AB}$.
- H and $\{, \}$ determine EOMs.
- Lingo:** $\{F, G\} = 0 \sim F \text{ \& } G \text{ commute.}$
- G is a constant $\iff \{G, H\} = 0$.

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{I}}, \vec{\theta})$

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{I}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{I}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]
- Hamilton's eqns. \implies

$$\dot{\mathcal{J}}_i = -\partial H / \partial \theta_i = 0 \quad \implies \mathcal{J}_i \text{ stay constant}$$

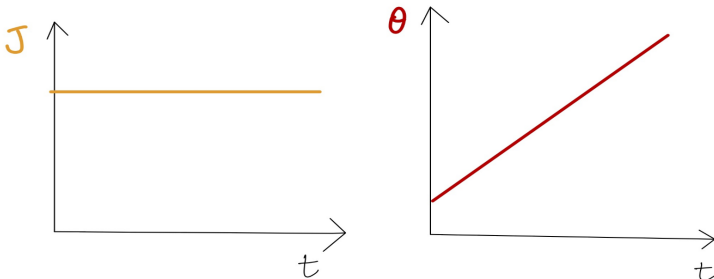
$$\dot{\theta}_i = \partial H / \partial \mathcal{J}_i \equiv \omega_i(\vec{\mathcal{J}}) \quad \implies \theta_i = \omega_i(\vec{\mathcal{J}})t$$

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]
- Hamilton's eqns. \implies

$$\dot{\mathcal{J}}_i = -\partial H / \partial \theta_i = 0 \quad \implies \mathcal{J}_i \text{ stay constant}$$

$$\dot{\theta}_i = \partial H / \partial \mathcal{J}_i \equiv \omega_i(\vec{\mathcal{J}}) \quad \implies \theta_i = \omega_i(\vec{\mathcal{J}})t$$



Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]
- Hamilton's eqns. \implies

$$\dot{\mathcal{J}}_i = -\partial H / \partial \theta_i = 0 \quad \implies \mathcal{J}_i \text{ stay constant}$$

$$\dot{\theta}_i = \partial H / \partial \mathcal{J}_i \equiv \omega_i(\vec{\mathcal{J}}) \quad \implies \theta_i = \omega_i(\vec{\mathcal{J}})t$$

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]
- Hamilton's eqns. \implies

$$\dot{\mathcal{J}}_i = -\partial H / \partial \theta_i = 0 \quad \implies \mathcal{J}_i \text{ stay constant}$$

$$\dot{\theta}_i = \partial H / \partial \mathcal{J}_i \equiv \omega_i(\vec{\mathcal{J}}) \quad \implies \theta_i = \omega_i(\vec{\mathcal{J}})t$$

- **Liouville-Arnold theorem:** $2n$ phase space variables & n commuting constants of motion \implies integrability. [V. I. Arnold]

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]
- Hamilton's eqns. \implies

$$\dot{\mathcal{J}}_i = -\partial H / \partial \theta_i = 0 \quad \implies \mathcal{J}_i \text{ stay constant}$$

$$\dot{\theta}_i = \partial H / \partial \mathcal{J}_i \equiv \omega_i(\vec{\mathcal{J}}) \quad \implies \theta_i = \omega_i(\vec{\mathcal{J}})t$$

- **Liouville-Arnold theorem:** $2n$ phase space variables & n commuting constants of motion \implies integrability. [V. I. Arnold]
- 10 phase-space variables \implies 5 commuting constants for integrability \rightarrow 5 actions & 5 angles (5+5=10).

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]
- Hamilton's eqns. \implies

$$\dot{\mathcal{J}}_i = -\partial H / \partial \theta_i = 0 \quad \implies \mathcal{J}_i \text{ stay constant}$$

$$\dot{\theta}_i = \partial H / \partial \mathcal{J}_i \equiv \omega_i(\vec{\mathcal{J}}) \quad \implies \theta_i = \omega_i(\vec{\mathcal{J}})t$$

- **Liouville-Arnold theorem:** $2n$ phase space variables & n commuting constants of motion \implies integrability. [V. I. Arnold]
- 10 phase-space variables \implies 5 commuting constants for integrability \rightarrow 5 actions & 5 angles (5+5=10).
- **Line of approach:**

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]
- Hamilton's eqns. \implies

$$\dot{\mathcal{J}}_i = -\partial H / \partial \theta_i = 0 \quad \implies \mathcal{J}_i \text{ stay constant}$$

$$\dot{\theta}_i = \partial H / \partial \mathcal{J}_i \equiv \omega_i(\vec{\mathcal{J}}) \quad \implies \theta_i = \omega_i(\vec{\mathcal{J}})t$$

- **Liouville-Arnold theorem:** $2n$ phase space variables & n commuting constants of motion \implies integrability. [V. I. Arnold]
- 10 phase-space variables \implies 5 commuting constants for integrability \rightarrow 5 actions & 5 angles (5+5=10).
- **Line of approach:** (1) prove integrability

Integrable systems and action-angles

- **Integrable system:** canonical transformation $(\vec{p}, \vec{q}) \leftrightarrow (\vec{\mathcal{J}}, \vec{\theta})$ exists such that $H = H(\vec{\mathcal{J}})$ and $\{\vec{p}, \vec{q}\}(\theta_i + 2\pi) = \{\vec{p}, \vec{q}\}(\theta_i)$.
- $\mathcal{J}_i = \text{action} \sim p$; $\theta_i = \text{angle} \sim q$ [Goldstein]
- Hamilton's eqns. \implies

$$\dot{\mathcal{J}}_i = -\partial H / \partial \theta_i = 0 \quad \implies \mathcal{J}_i \text{ stay constant}$$

$$\dot{\theta}_i = \partial H / \partial \mathcal{J}_i \equiv \omega_i(\vec{\mathcal{J}}) \quad \implies \theta_i = \omega_i(\vec{\mathcal{J}})t$$

- **Liouville-Arnold theorem:** $2n$ phase space variables & n commuting constants of motion \implies integrability. [V. I. Arnold]
- 10 phase-space variables \implies 5 commuting constants for integrability \rightarrow 5 actions & 5 angles (5+5=10).
- **Line of approach:** (1) prove integrability (2) find action-angles

Integrable systems are nice (and rare) systems!

- Integrable systems are not chaotic.

Integrable systems are nice (and rare) systems!

- Integrable systems are not chaotic. Can't have closed-form solutions for chaotic systems.

Integrable systems are nice (and rare) systems!

- Integrable systems are not chaotic. Can't have closed-form solutions for chaotic systems.
- Action-angles \rightarrow solution and frequencies.

Integrable systems are nice (and rare) systems!

- Integrable systems are not chaotic. Can't have closed-form solutions for chaotic systems.
- Action-angles \rightarrow solution and frequencies.
- Canonical perturbation theory: $(\vec{\mathcal{J}}_{\text{old}}, \vec{\theta}_{\text{old}}, \vec{\omega}_{\text{old}}) \rightarrow (\vec{\mathcal{J}}_{\text{new}}, \vec{\theta}_{\text{new}}, \vec{\omega}_{\text{new}})$.
[Goldstein]

Integrable systems are nice (and rare) systems!

- Integrable systems are not chaotic. Can't have closed-form solutions for chaotic systems.
- Action-angles \rightarrow solution and frequencies.
- Canonical perturbation theory: $(\vec{\mathcal{J}}_{\text{old}}, \vec{\theta}_{\text{old}}, \vec{\omega}_{\text{old}}) \rightarrow (\vec{\mathcal{J}}_{\text{new}}, \vec{\theta}_{\text{new}}, \vec{\omega}_{\text{new}})$.
[Goldstein]

It's nice to have integrable systems (they occur rarely),

Integrable systems are nice (and rare) systems!

- Integrable systems are not chaotic. Can't have closed-form solutions for chaotic systems.
- Action-angles \rightarrow solution and frequencies.
- Canonical perturbation theory: $(\vec{\mathcal{I}}_{\text{old}}, \vec{\theta}_{\text{old}}, \vec{\omega}_{\text{old}}) \rightarrow (\vec{\mathcal{I}}_{\text{new}}, \vec{\theta}_{\text{new}}, \vec{\omega}_{\text{new}})$.
[Goldstein]

It's nice to have integrable systems (they occur rarely), and extra nice to have action-angles.

1.5PN: action-angle variables

History of PN BBH action-angles

- **1609:** Kepler equation $l = u - e \sin u = nt$ gives the Newtonian angle variable.

History of PN BBH action-angles

- **1609:** Kepler equation $l = u - e \sin u = nt$ gives the Newtonian angle variable.
- **1850-1920:** Delaunay & Sommerfeld contributed to the Newtonian action-angles.

History of PN BBH action-angles

- **1609:** Kepler equation $l = u - e \sin u = nt$ gives the Newtonian angle variable.
- **1850-1920:** Delaunay & Sommerfeld contributed to the Newtonian action-angles.
- **1966:** 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).

History of PN BBH action-angles

- **1609:** Kepler equation $l = u - e \sin u = nt$ gives the Newtonian angle variable.
- **1850-1920:** Delaunay & Sommerfeld contributed to the Newtonian action-angles.
- **1966:** 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- **1985:** Damour & Deruelle: full solution and angle variable at 1PN.

History of PN BBH action-angles

- **1609:** Kepler equation $l = u - e \sin u = nt$ gives the Newtonian angle variable.
- **1850-1920:** Delaunay & Sommerfeld contributed to the Newtonian action-angles.
- **1966:** 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- **1985:** Damour & Deruelle: full solution and angle variable at 1PN.
- **1988:** Damour & Schafer: 2PN action (spin terms ignored; they enter at 1.5PN)

History of PN BBH action-angles

- **1609:** Kepler equation $l = u - e \sin u = nt$ gives the Newtonian angle variable.
- **1850-1920:** Delaunay & Sommerfeld contributed to the Newtonian action-angles.
- **1966:** 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- **1985:** Damour & Deruelle: full solution and angle variable at 1PN.
- **1988:** Damour & Schafer: 2PN action (spin terms ignored; they enter at 1.5PN)
- **1999:** Damour et. al: 3PN action variables (spin terms ignored)

History of PN BBH action-angles

- **1609:** Kepler equation $l = u - e \sin u = nt$ gives the Newtonian angle variable.
- **1850-1920:** Delaunay & Sommerfeld contributed to the Newtonian action-angles.
- **1966:** 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- **1985:** Damour & Deruelle: full solution and angle variable at 1PN.
- **1988:** Damour & Schafer: 2PN action (spin terms ignored; they enter at 1.5PN)
- **1999:** Damour et. al: 3PN action variables (spin terms ignored)
- **2001:** 5 commuting constants were given by Damour at 1.5PN:
 $H^{1.5\text{PN}}, J^2, J_z, L^2, \vec{S}_{\text{eff}} \cdot \vec{L}$ [[gr-qc:0103018](#)].

History of PN BBH action-angles

- **1609:** Kepler equation $l = u - e \sin u = nt$ gives the Newtonian angle variable.
- **1850-1920:** Delaunay & Sommerfeld contributed to the Newtonian action-angles.
- **1966:** 1.5PN Hamiltonian given in Barker et. al (1966). (55 years-old!)
- **1985:** Damour & Deruelle: full solution and angle variable at 1PN
- **1988:** Damour & Schafer: 2PN action (spin terms ignored; they enter at 1.5PN)
- **1999:** Damour et. al: 3PN action variables (spin terms ignored)
- **2001:** 5 commuting constants were given by Damour at 1.5PN:
 $H^{1.5\text{PN}}, J^2, J_z, L^2, \vec{S}_{\text{eff}} \cdot \vec{L}$ [gr-qc:0103018].

RESULTS: action-angles & the solution at 1.5PN

- Spins enter at 1.5PN. 1.5PN Hamiltonian given in [\[Barker et. al \(1966\).\]](#)

RESULTS: action-angles & the solution at 1.5PN

- Spins enter at 1.5PN. 1.5PN Hamiltonian given in [\[Barker et. al \(1966\).\]](#)

$$H = \underbrace{\left(\frac{P^2}{2\mu} - \frac{Gm_1 m_2}{R} \right)}_{\text{Newtonian}} + \frac{1}{c^2} F_1(\vec{R}, \vec{P}) + \frac{1}{c^3} F_2(\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2)$$

RESULTS: action-angles & the solution at 1.5PN

- Spins enter at 1.5PN. 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).

RESULTS: action-angles & the solution at 1.5PN

- Spins enter at 1.5PN. 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- We present **all 5 actions & frequencies** of the most general 1.5PN BBH [[2012.06586](#), [2110.15351](#), [2210.01605](#)].

RESULTS: action-angles & the solution at 1.5PN

- Spins enter at 1.5PN. 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- We present **all 5 actions & frequencies** of the most general 1.5PN BBH [\[2012.06586, 2110.15351, 2210.01605\]](#). Orbital-precession enters at 1.5PN.

RESULTS: action-angles & the solution at 1.5PN

- Spins enter at 1.5PN. 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- We present **all 5 actions & frequencies** of the most general 1.5PN BBH [\[2012.06586, 2110.15351, 2210.01605\]](#). Orbital-precession enters at 1.5PN.
- We give a method to construct $\{\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2\}$ as functions of $(\vec{J}, \vec{\theta})$

RESULTS: action-angles & the solution at 1.5PN

- Spins enter at 1.5PN. 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- We present **all 5 actions & frequencies** of the most general 1.5PN BBH [\[2012.06586, 2110.15351, 2210.01605\]](#). Orbital-precession enters at 1.5PN.
- We give a method to construct $\{\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2\}$ as functions of $(\vec{J}, \vec{\theta})$ thereby constructing the solution.

RESULTS: action-angles & the solution at 1.5PN

- Spins enter at 1.5PN. 1.5PN Hamiltonian given in [Barker et. al \(1966\)](#).
- We present **all 5 actions & frequencies** of the most general 1.5PN BBH [\[2012.06586, 2110.15351, 2210.01605\]](#). Orbital-precession enters at 1.5PN.
- We give a method to construct $\{\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2\}$ as functions of $(\vec{J}, \vec{\theta})$ thereby constructing the solution.
- Necessary concepts laid out in [Goldstein, Jose-Saletan, V. I. Arnold, Fasano-Marmi](#).

RESULTS: action expressions

- $m \equiv m_1 + m_2, \quad \mu \equiv m_1 m_2 / m, \quad \nu \equiv \mu / m, \quad \vec{L} \equiv \vec{R} \times \vec{P},$
 $\sigma_1 \equiv (2 + 3m_2/m_1), \quad \sigma_2 \equiv (2 + 3m_1/m_2), \quad \vec{S}_{\text{eff}} \equiv \sigma_1 \vec{S}_1 + \sigma_2 \vec{S}_2,$
 $\vec{J} = \vec{L} + \vec{S}_1 + \vec{S}_2.$

RESULTS: action expressions

- $m \equiv m_1 + m_2, \quad \mu \equiv m_1 m_2 / m, \quad \nu \equiv \mu / m, \quad \vec{L} \equiv \vec{R} \times \vec{P},$
 $\sigma_1 \equiv (2 + 3m_2 / m_1), \quad \sigma_2 \equiv (2 + 3m_1 / m_2), \quad \vec{S}_{\text{eff}} \equiv \sigma_1 \vec{S}_1 + \sigma_2 \vec{S}_2,$
 $\vec{J} = \vec{L} + \vec{S}_1 + \vec{S}_2.$
- $\mathcal{J}_1 = L, \quad \mathcal{J}_2 = J, \quad \mathcal{J}_3 = J_z.$

RESULTS: action expressions

- $m \equiv m_1 + m_2, \quad \mu \equiv m_1 m_2 / m, \quad \nu \equiv \mu / m, \quad \vec{L} \equiv \vec{R} \times \vec{P},$
 $\sigma_1 \equiv (2 + 3m_2/m_1), \quad \sigma_2 \equiv (2 + 3m_1/m_2), \quad \vec{S}_{\text{eff}} \equiv \sigma_1 \vec{S}_1 + \sigma_2 \vec{S}_2,$
 $\vec{J} = \vec{L} + \vec{S}_1 + \vec{S}_2.$
- $\mathcal{J}_1 = L, \quad \mathcal{J}_2 = J, \quad \mathcal{J}_3 = J_z.$
- $\mathcal{J}_4 = -\mathcal{J}_1 + \frac{Gm\mu^{3/2}}{\sqrt{-2H}} - \frac{G^2 m \mu^3}{c^2 \mathcal{J}_1^3} (\vec{S}_{\text{eff}} \cdot \vec{L}) + \frac{Gm}{c^2} \left(\frac{3Gm\mu^2}{\mathcal{J}_1} + \frac{\sqrt{-H} \mu^{1/2} (-15 + \nu)}{4\sqrt{2}} \right).$

RESULTS: action expressions

- $m \equiv m_1 + m_2$, $\mu \equiv m_1 m_2 / m$, $\nu \equiv \mu / m$, $\vec{L} \equiv \vec{R} \times \vec{P}$,
 $\sigma_1 \equiv (2 + 3m_2/m_1)$, $\sigma_2 \equiv (2 + 3m_1/m_2)$, $\vec{S}_{\text{eff}} \equiv \sigma_1 \vec{S}_1 + \sigma_2 \vec{S}_2$,
 $\vec{J} = \vec{L} + \vec{S}_1 + \vec{S}_2$.
- $\mathcal{J}_1 = L$, $\mathcal{J}_2 = J$, $\mathcal{J}_3 = J_z$.
- $\mathcal{J}_4 = -\mathcal{J}_1 + \frac{Gm\mu^{3/2}}{\sqrt{-2H}} - \frac{G^2 m \mu^3}{c^2 \mathcal{J}_1^3} (\vec{S}_{\text{eff}} \cdot \vec{L}) + \frac{Gm}{c^2} \left(\frac{3Gm\mu^2}{\mathcal{J}_1} + \frac{\sqrt{-H} \mu^{1/2} (-15 + \nu)}{4\sqrt{2}} \right)$.
- \mathcal{J}_5 is very lengthy.

$$J = JdJ^{1/2}; L = LdL^{1/2}; S1 = S1dS1^{1/2}; S2 = S2dS2^{1/2};$$

$$\Delta 1 = \frac{\left(\frac{(J^2 - L^2 - S1^2 - S2^2)}{2} - \frac{SeffdL}{\sigma 2} \right)}{\sigma 1 - \sigma 2};$$

$$\Delta 2 = \frac{\left(\frac{(J^2 - L^2 - S1^2 - S2^2)}{2} - \frac{SeffdL}{\sigma 1} \right)}{\sigma 1 - \sigma 2};$$

$$\sigma 2 = 1 + \frac{9}{16 \times (-1 + \sigma 1)};$$

$$\sigma 1 = \left(1 + \frac{3}{4} \frac{m2}{m1} \right); \quad \sigma 2 = \left(1 + \frac{3}{4} \frac{m1}{m2} \right);$$

$$Seff = \delta 1 S1 + \delta 2 S2$$

$$\text{cubic} = L^2 S1^2 S2^2 - 2 \sigma 1 \sigma 2 (\sigma 1 - \sigma 2) f (f - \Delta 1) (f - \Delta 2) - \\ L^2 (\sigma 1 - \sigma 2)^2 f^2 - S2^2 \sigma 2^2 (f - \Delta 1)^2 - S1^2 \sigma 1^2 (f - \Delta 2)^2 ;$$

$$\text{cubic} = \text{Collect}[\text{cubic} // \text{Expand} // \text{Simplify}, f] ;$$

$$\text{cubSol1} = ((\text{Solve}[\text{cubic} == 0, f])[1]);$$

$$\text{cubSol2} = ((\text{Solve}[\text{cubic} == 0, f])[2]);$$

$$\text{cubSol3} = ((\text{Solve}[\text{cubic} == 0, f])[3]);$$

$$f3 = f /. \text{cubSol1} ;$$

$$f1 = f /. \text{cubSol2} ;$$

$$f2 = f /. \text{cubSol3} ; \quad (*\text{The three roots of the cubic}*)$$

$$A = 2 \sigma 1 \sigma 2 (\sigma 2 - \sigma 1) ;$$

$$\beta = ((f2 - f1) / (f3 - f1))^{1/2};$$

$$B1 = \frac{1}{2} ((\text{SeffdL} + L^2 (\sigma 1 + \sigma 2)) (J + L) + L (\sigma 1 S1^2 + \sigma 2 S2^2 + (\sigma 1 + \sigma 2) (\Delta 2 \sigma 1 - \Delta 1 \sigma 2))) ;$$

$$B2 = \frac{1}{2} ((\text{SeffdL} + L^2 (\sigma 1 + \sigma 2)) (J - L) - L (\sigma 1 S1^2 + \sigma 2 S2^2 + (\sigma 1 + \sigma 2) (\Delta 2 \sigma 1 - \Delta 1 \sigma 2))) ;$$

$$D1 = L (L + J) + \Delta 2 \sigma 1 - \Delta 1 \sigma 2;$$

$$D2 = L (L - J) + \Delta 2 \sigma 1 - \Delta 1 \sigma 2;$$

$$B1S = \frac{1}{2} (-L^2 S1 \sigma 1 + J S1^2 \sigma 1 - S1^3 \sigma 1 - S1 \Delta 2 \sigma 1^2 + J^2 S1 \sigma 2 - \\ 2 J S1^2 \sigma 2 + S1^3 \sigma 2 - J \Delta 1 \sigma 1 \sigma 2 + 2 S1 \Delta 1 \sigma 1 \sigma 2 + J \Delta 1 \sigma 2^2 - S1 \Delta 1 \sigma 2^2) ;$$

$$B2S = \frac{1}{2} (L^2 S1 \sigma 1 + J S1^2 \sigma 1 + S1^3 \sigma 1 + S1 \Delta 2 \sigma 1^2 - J^2 S1 \sigma 2 - 2 J S1^2 \sigma 2 - \\ S1^3 \sigma 2 - J \Delta 1 \sigma 1 \sigma 2 - 2 S1 \Delta 1 \sigma 1 \sigma 2 + J \Delta 1 \sigma 2^2 + S1 \Delta 1 \sigma 2^2) ;$$

$$D1S = -J S1 + S1^2 - \Delta 1 \sigma 2;$$

$$D2S = (J S1 + S1^2 - \Delta 1 \sigma 2);$$

$$\alpha 1 = \frac{(\sigma 1 - \sigma 2) (f2 - f1)}{D1 - f1 (\sigma 1 - \sigma 2)} ;$$

$$\alpha_2 = \frac{(\sigma_1 - \sigma_2)(f_2 - f_1)}{D_2 - f_1(\sigma_1 - \sigma_2)} ;$$

$$\alpha_{1S} = \frac{(-\sigma_1)(f_2 - f_1)}{D_{1S} + f_1 \sigma_1} ;$$

$$\alpha_{2S} = \frac{(-\sigma_1)(f_2 - f_1)}{D_{2S} + f_1 \sigma_1} ;$$

$$\Delta Y = \text{EllipticK}[\beta^2] ;$$

$$\Delta \lambda_1 = \frac{4 \Delta Y}{(A(f_3 - f_1))^{1/2}} ;$$

$$\Delta \lambda_2 = \left(\frac{-1}{2 J d J^{1/2}} \right) \left(\frac{4}{(A(f_3 - f_1))^{1/2}} \right) \left(\frac{B_1 \text{EllipticPi}[\alpha_1, \beta^2]}{D_1 - f_1(\sigma_1 - \sigma_2)} + \frac{B_2 \text{EllipticPi}[\alpha_2, \beta^2]}{D_2 - f_1(\sigma_1 - \sigma_2)} \right) ;$$

$$\Delta \lambda_3 = \left(\frac{-1}{2 L d L^{1/2}} \right) \left(\left(\frac{4}{(A(f_3 - f_1))^{1/2}} \right) \left(\frac{B_1 \text{EllipticPi}[\alpha_1, \beta^2]}{D_1 - f_1(\sigma_1 - \sigma_2)} - \frac{B_2 \text{EllipticPi}[\alpha_2, \beta^2]}{D_2 - f_1(\sigma_1 - \sigma_2)} \right) - \right. \\ \left. (\text{SeffdL} + (\Delta_1 - \Delta_2) \sigma_1 \sigma_2 + L d L (\sigma_1 + \sigma_2)) \frac{\Delta \lambda_1}{L d L^{1/2}} \right) ;$$

$$\Delta \lambda_4 = \left(\frac{-1}{2 S_1 d S_1^{1/2}} \right) \left(\left(\frac{4}{(A(f_3 - f_1))^{1/2}} \right) \left(- \frac{B_{1S} \text{EllipticPi}[\alpha_{1S}, \beta^2]}{D_{1S} + f_1 \sigma_1} + \frac{B_{2S} \text{EllipticPi}[\alpha_{2S}, \beta^2]}{D_{2S} + f_1 \sigma_1} \right) + \right. \\ \left. S_1 d S_1^{1/2} (\sigma_2 - \sigma_1) \Delta \lambda_1 \right) ;$$

$$\Delta \lambda_5 = \Delta \lambda_4 /. \sigma_1 \rightarrow \sigma_2 /. S_1 d S_1 \rightarrow S_1 D S_1 /. S_2 d S_2 \rightarrow S_2 D S_2 /. S_1 D S_1 \rightarrow S_2 d S_2 /. S_2 D S_2 \rightarrow S_1 d S_1 ;$$

$$J_5 = \frac{1}{\pi} (\text{SeffdL} \Delta \lambda_1 + J^2 \Delta \lambda_2 + L^2 \Delta \lambda_3 + S_1^2 \Delta \lambda_4 + S_2 \Delta \lambda_5) ;$$

Mathematical ingredients of the action-angle recipe

Mathematical ingredients of the action-angle recipe

- Used complex analysis, symplectic differential geometry & topology,

Mathematical ingredients of the action-angle recipe

- Used complex analysis, symplectic differential geometry & topology, and invented *unmeasurable, fictitious* variables...

Mathematical ingredients of the action-angle recipe

- Used complex analysis, symplectic differential geometry & topology, and invented *unmeasurable, fictitious* variables...
- ...albeit the problem statement is a simple coupled ODE system $\dot{G} = \{G, H\}$. Solution is easy to check too.

Mathematical ingredients of the action-angle recipe

- Used complex analysis, symplectic differential geometry & topology, and invented *unmeasurable, fictitious* variables...
- ...albeit the problem statement is a simple coupled ODE system $\dot{G} = \{G, H\}$. Solution is easy to check too.
- We have all seen this before (in spirit)!

Mathematical ingredients of the action-angle recipe

- Used complex analysis, symplectic differential geometry & topology, and invented *unmeasurable, fictitious* variables...
- ...albeit the problem statement is a simple coupled ODE system $\dot{G} = \{G, H\}$. Solution is easy to check too.
- We have all seen this before (in spirit)!

$$\int_0^\infty \frac{dx}{1+x^n} = \frac{\pi/n}{\sin(\pi/n)}$$

Arfken-Weber 7 ed., Chapter 11 (Complex Variable Theory), Prob. 11.8.22

Mathematical ingredients of the action-angle recipe

- Used complex analysis, symplectic differential geometry & topology, and invented *unmeasurable, fictitious* variables...
- ...albeit the problem statement is a simple coupled ODE system $\dot{G} = \{G, H\}$. Solution is easy to check too.
- We have all seen this before (in spirit)!
$$\int_0^\infty \frac{dx}{1+x^n} = \frac{\pi/n}{\sin(\pi/n)}$$

Arfken-Weber 7 ed., Chapter 11 (Complex Variable Theory), Prob. 11.8.22
- LHS and RHS are built out of reals, but we need complex variables (extra variables) to prove it.

Mathematical ingredients of the action-angle recipe

- Used complex analysis, symplectic differential geometry & topology, and invented *unmeasurable, fictitious* variables...
- ...albeit the problem statement is a simple coupled ODE system $\dot{G} = \{G, H\}$. Solution is easy to check too.

- We have all seen this before (in spirit)!

$$\int_0^\infty \frac{dx}{1+x^n} = \frac{\pi/n}{\sin(\pi/n)}$$

Arfken-Weber 7 ed., Chapter 11 (Complex Variable Theory), Prob. 11.8.22

- LHS and RHS are built out of reals, but we need complex variables (extra variables) to prove it.
- **Other examples:** Radius of convergence of Taylor series, Fermat's last theorem.

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$,

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have
$$\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$$
Can't be integrated!

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have
$$\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$$
Can't be integrated!
- Invent fictitious variables: $\vec{r}_1 \times \vec{p}_1 = \vec{S}_1$; $\vec{r}_2 \times \vec{p}_2 = \vec{S}_2$.

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have
$$\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$$
Can't be integrated!
- Invent **fictitious** variables: $\vec{r}_1 \times \vec{p}_1 = \vec{S}_1$; $\vec{r}_2 \times \vec{p}_2 = \vec{S}_2$.
- Hamiltonian is $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ with $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i$.

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have
$$\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$$
Can't be integrated!
- Invent **fictitious** variables: $\vec{r}_1 \times \vec{p}_1 = \vec{S}_1$; $\vec{r}_2 \times \vec{p}_2 = \vec{S}_2$.
- Hamiltonian is $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ with $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i$.
- \mathcal{J}_5 becomes $\oint (\vec{P} \cdot d\vec{R} + \vec{p}_1 \cdot d\vec{r}_1 + \vec{p}_2 \cdot d\vec{r}_2)$.

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have

$$\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$$
Can't be integrated!
- Invent **fictitious** variables: $\vec{r}_1 \times \vec{p}_1 = \vec{S}_1$; $\vec{r}_2 \times \vec{p}_2 = \vec{S}_2$.
- Hamiltonian is $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ with $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i$.
- \mathcal{J}_5 becomes $\oint (\vec{P} \cdot d\vec{R} + \vec{p}_1 \cdot d\vec{r}_1 + \vec{p}_2 \cdot d\vec{r}_2)$. Can be integrated.

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have
$$\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$$
Can't be integrated!
- Invent **fictitious** variables: $\vec{r}_1 \times \vec{p}_1 = \vec{S}_1$; $\vec{r}_2 \times \vec{p}_2 = \vec{S}_2$.
- Hamiltonian is $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ with $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i$.
- \mathcal{J}_5 becomes $\oint (\vec{P} \cdot d\vec{R} + \vec{p}_1 \cdot d\vec{r}_1 + \vec{p}_2 \cdot d\vec{r}_2)$. Can be integrated.
- **Justification:** $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i \implies \{S_\phi, S_z\} = 1$.

Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have $\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$ Can't be integrated!
- Invent **fictitious** variables: $\vec{r}_1 \times \vec{p}_1 = \vec{S}_1$; $\vec{r}_2 \times \vec{p}_2 = \vec{S}_2$.
- Hamiltonian is $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ with $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i$.
- \mathcal{J}_5 becomes $\oint (\vec{P} \cdot d\vec{R} + \vec{p}_1 \cdot d\vec{r}_1 + \vec{p}_2 \cdot d\vec{r}_2)$. Can be integrated.
- **Justification:** $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i \implies \{S_\phi, S_z\} = 1$. EOMs are the same in the 2 pictures: $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ vs $H(\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2)$.

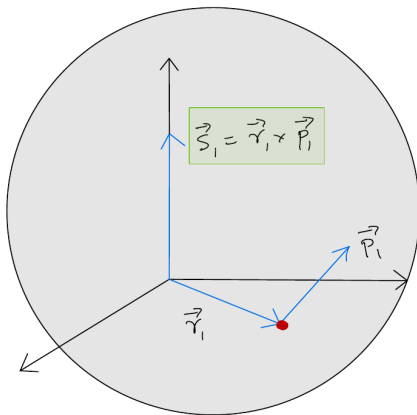
Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have $\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$ Can't be integrated!
- Invent **fictitious** variables: $\vec{r}_1 \times \vec{p}_1 = \vec{S}_1$; $\vec{r}_2 \times \vec{p}_2 = \vec{S}_2$.
- Hamiltonian is $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ with $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i$.
- \mathcal{J}_5 becomes $\oint (\vec{P} \cdot d\vec{R} + \vec{p}_1 \cdot d\vec{r}_1 + \vec{p}_2 \cdot d\vec{r}_2)$. Can be integrated.
- **Justification:** $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i \implies \{S_\phi, S_z\} = 1$. EOMs are the same in the 2 pictures: $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ vs $H(\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2)$.
- **Sanity check:** \mathcal{J}_5 depends only on $(\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2)$.

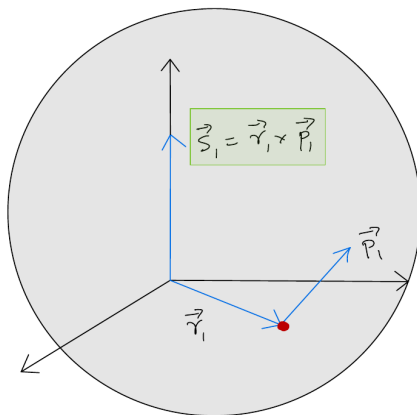
Technical details: fictitious variables

- With $\mathcal{J} \equiv \oint P_i dQ^i$ and $\{R_i, P^j\} = \delta_i^j$ and $\{S_\phi, S_z\} = 1$, we have $\mathcal{J}_5 = \oint (\vec{P} \cdot d\vec{R} + S_z^A dS_{A\phi})$ Can't be integrated!
- Invent **fictitious** variables: $\vec{r}_1 \times \vec{p}_1 = \vec{S}_1$; $\vec{r}_2 \times \vec{p}_2 = \vec{S}_2$.
- Hamiltonian is $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ with $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i$.
- \mathcal{J}_5 becomes $\oint (\vec{P} \cdot d\vec{R} + \vec{p}_1 \cdot d\vec{r}_1 + \vec{p}_2 \cdot d\vec{r}_2)$. Can be integrated.
- **Justification:** $\{r_i^A, p_j^B\} = \delta_B^A \delta_j^i \implies \{S_\phi, S_z\} = 1$. EOMs are the same in the 2 pictures: $H(\vec{R}, \vec{P}, \vec{r}_1, \vec{p}_1, \vec{r}_2, \vec{p}_2)$ vs $H(\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2)$.
- **Sanity check:** \mathcal{J}_5 depends only on $(\vec{R}, \vec{P}, \vec{S}_1, \vec{S}_2)$.
- **Numerical check:** matches with numerical solution
[\[github.com/sashwattanay/BBH-PN-Toolkit\]](https://github.com/sashwattanay/BBH-PN-Toolkit).

A pictorial mnemonic for fictitious variables



A pictorial mnemonic for fictitious variables



Essentially, trade the spherical manifold in favor of a Cartesian manifold.

2PN: Integrable or non-integrable?

History: are PN BBHs chaotic or integrable?

- **2001:** 5 commuting constants were found by Damour at 1.5PN [[gr-qc:0103018](#)].

History: are PN BBHs chaotic or integrable?

- **2001:** 5 commuting constants were found by Damour at 1.5PN [[gr-qc:0103018](#)].
- **2000-2005:** Heated debate on chaotic nature of 2PN BBHs (via numerical simulations)

History: are PN BBHs chaotic or integrable?

- **2001:** 5 commuting constants were found by Damour at 1.5PN [[gr-qc:0103018](#)].
- **2000-2005:** Heated debate on chaotic nature of 2PN BBHs (via numerical simulations) and the detectability prospects of GWs

History: are PN BBHs chaotic or integrable?

- **2001:** 5 commuting constants were found by Damour at 1.5PN [[gr-qc:0103018](#)].
- **2000-2005:** Heated debate on chaotic nature of 2PN BBHs (via numerical simulations) and the detectability prospects of GWs
 - **Chaos:** N. Cornish, J. Levin
 - **No chaos:** F. Rasio, J. Schnittman, A. Gopakumar, C. Konigsdorffer
 - **On the fence:** A. Buonanno, M. Hartl

History: are PN BBHs chaotic or integrable?

- **2001:** 5 commuting constants were found by Damour at 1.5PN [[gr-qc:0103018](#)].
- **2000-2005:** Heated debate on chaotic nature of 2PN BBHs (via numerical simulations) and the detectability prospects of GWs
 - **Chaos:** N. Cornish, J. Levin
 - **No chaos:** F. Rasio, J. Schnittman, A. Gopakumar, C. Konigsdorffer
 - **On the fence:** A. Buonanno, M. Hartl
- **Simmering tension:** *"However the above analysis was strongly criticized in Ref. [9]..."* [[gr-qc:0511009](#)]

History: are PN BBHs chaotic or integrable?

- **2001:** 5 commuting constants were found by Damour at 1.5PN [[gr-qc:0103018](#)].
- **2000-2005:** Heated debate on chaotic nature of 2PN BBHs (via numerical simulations) and the detectability prospects of GWs
 - **Chaos:** N. Cornish, J. Levin
 - **No chaos:** F. Rasio, J. Schnittman, A. Gopakumar, C. Konigsdorffer
 - **On the fence:** A. Buonanno, M. Hartl
- **Simmering tension:** *"However the above analysis was strongly criticized in Ref. [9]..."* [[gr-qc:0511009](#)]
- See the Introduction of [[gr-qc:0511009](#)] and [[2012.06586](#)] for details.

RESULTS: integrable or non-integrable at the 2PN?

- Commuting constants of motion at 1.5PN: $H^{1.5\text{PN}}, J^2, J_z, L^2, \vec{S}_{\text{eff}} \cdot \vec{L}$.

RESULTS: integrable or non-integrable at the 2PN?

- Commuting constants of motion at 1.5PN: $H^{1.5\text{PN}}, J^2, J_z, L^2, \vec{S}_{\text{eff}} \cdot \vec{L}$.
- Commuting constants of motion at 2PN: $H^{2\text{PN}}, J_z, J^2, \cancel{L^2}, \cancel{\vec{S}_{\text{eff}} \cdot \vec{L}}$.

RESULTS: integrable or non-integrable at the 2PN?

- Commuting constants of motion at 1.5PN: $H^{1.5\text{PN}}, J^2, J_z, L^2, \vec{S}_{\text{eff}} \cdot \vec{L}$.
- Commuting constants of motion at 2PN: $H^{2\text{PN}}, J_z, J^2, \cancel{L^2}, \cancel{\vec{S}_{\text{eff}} \cdot \vec{L}}$.
- **Result:** found corrections to $\vec{S}_{\text{eff}} \cdot \vec{L}$ and L^2 to render them commuting constants

RESULTS: integrable or non-integrable at the 2PN?

- Commuting constants of motion at 1.5PN: $H^{1.5\text{PN}}, J^2, J_z, L^2, \vec{S}_{\text{eff}} \cdot \vec{L}$.
- Commuting constants of motion at 2PN: $H^{2\text{PN}}, J_z, J^2, \cancel{L^2}, \cancel{\vec{S}_{\text{eff}} \cdot \vec{L}}$.
- **Result:** found corrections to $\vec{S}_{\text{eff}} \cdot \vec{L}$ and L^2 to render them commuting constants \implies 2PN integrability [\[2012.06586\]](#).

RESULTS: integrable or non-integrable at the 2PN?

- Commuting constants of motion at 1.5PN: $H^{1.5\text{PN}}, J^2, J_z, L^2, \vec{S}_{\text{eff}} \cdot \vec{L}$.
- Commuting constants of motion at 2PN: $H^{2\text{PN}}, J_z, J^2, \cancel{L^2}, \cancel{\vec{S}_{\text{eff}} \cdot \vec{L}}$.
- **Result:** found corrections to $\vec{S}_{\text{eff}} \cdot \vec{L}$ and L^2 to render them commuting constants \implies 2PN integrability [\[2012.06586\]](#).
- They are not exact commuting constants; only in the PN perturbative sense.

RESULTS: integrable or non-integrable at the 2PN?

- Commuting constants of motion at 1.5PN: $H^{1.5\text{PN}}, J^2, J_z, L^2, \vec{S}_{\text{eff}} \cdot \vec{L}$.
- Commuting constants of motion at 2PN: $H^{2\text{PN}}, J_z, J^2, \cancel{L^2}, \cancel{\vec{S}_{\text{eff}} \cdot \vec{L}}$.
- **Result:** found corrections to $\vec{S}_{\text{eff}} \cdot \vec{L}$ and L^2 to render them commuting constants \implies 2PN integrability [\[2012.06586\]](#).
- They are not exact commuting constants; only in the PN perturbative sense.
- The non-exact nature of integrability \implies the tension b/w the two camps.

The fourth commuting constant of motion

With the definitions:

$$\sigma_1 := (2 + 3m_2/m_1)$$

$$\sigma_2 := (2 + 3m_1/m_2)$$

$$\vec{S}_{\text{eff}} := \sigma_1 \vec{S}_1 + \sigma_2 \vec{S}_2$$

$$\vec{L} := \vec{R} \times \vec{P}$$

$$\epsilon := 1/c^2$$

The fourth commuting constant of motion

With the definitions:

$$\sigma_1 := (2 + 3m_2/m_1)$$

$$\sigma_2 := (2 + 3m_1/m_2)$$

$$\vec{S}_{\text{eff}} := \sigma_1 \vec{S}_1 + \sigma_2 \vec{S}_2$$

$$\vec{L} := \vec{R} \times \vec{P}$$

$$\epsilon := 1/c^2$$

The 4th commuting constant is

The fourth commuting constant of motion

With the definitions:

$$\sigma_1 := (2 + 3m_2/m_1)$$

$$\sigma_2 := (2 + 3m_1/m_2)$$

$$\vec{S}_{\text{eff}} := \sigma_1 \vec{S}_1 + \sigma_2 \vec{S}_2$$

$$\vec{L} := \vec{R} \times \vec{P}$$

$$\epsilon := 1/c^2$$

The 4th commuting constant is

$$\begin{aligned} L^2 - \epsilon & \left[\frac{(m_2 P^i S_{1i} + m_1 P^i S_{2i})^2}{m_1^2 m_2^2} + \frac{2G(m_2 R^i S_{1i} + m_1 R^i S_{2i})^2}{(m_1 + m_2)(R^i R_i)^{3/2}} \right. \\ & \left. + \left(\frac{P^i P_i}{m_1 m_2} - \frac{2Gm_1 m_2}{(m_1 + m_2)\sqrt{R^i R_i}} \right) S_{1a} S_2^a \right]. \end{aligned}$$

And the 5th commuting constant is ...

And the 5th commuting constant is ...

$$\begin{aligned}
 \vec{S}_{\text{eff}} \cdot \vec{L} &+ \frac{1}{2} (S_1^a S_{2a}) + \frac{\epsilon (P^a S_{1a})^2}{m_1^2} + \frac{3m_2 \epsilon (P^a S_{1a})^2}{4m_1^3} - \frac{2Gm_2^2 \epsilon (R^a S_{1a})^2}{(m_1 + m_2) (R_a R^a)^{3/2}} \\
 &- \frac{3Gm_2^3 \epsilon (R^a S_{1a})^2}{2m_1 (m_1 + m_2) (R_a R^a)^{3/2}} + \frac{3\epsilon (P^a S_{1a}) (P^a S_{2a})}{4m_1^2} \\
 &+ \frac{3\epsilon (P^a S_{1a}) (P^a S_{2a})}{4m_2^2} + \frac{2\epsilon (P^a S_{1a}) (P^a S_{2a})}{m_1 m_2} + \frac{3m_1 \epsilon (P^a S_{2a})^2}{4m_2^3} \\
 &+ \frac{\epsilon (P^a S_{2a})^2}{m_2^2} - \frac{3Gm_1^2 \epsilon (R^a S_{1a}) (R^a S_{2a})}{2(m_1 + m_2) (R_a R^a)^{3/2}} \\
 &- \frac{4Gm_1 m_2 \epsilon (R^a S_{1a}) (R^a S_{2a})}{(m_1 + m_2) (R_a R^a)^{3/2}} - \frac{3Gm_2^2 \epsilon (R^a S_{1a}) (R^a S_{2a})}{2(m_1 + m_2) (R_a R^a)^{3/2}} \\
 &- \frac{2Gm_1^2 \epsilon (R^a S_{2a})^2}{(m_1 + m_2) (R_a R^a)^{3/2}} - \frac{3Gm_1^3 \epsilon (R^a S_{2a})^2}{2m_2 (m_1 + m_2) (R_a R^a)^{3/2}}.
 \end{aligned}$$

Conclusions

Summary

For a BBH with arbitrary masses, spins and eccentricity,

Summary

For a BBH with arbitrary masses, spins and eccentricity,

- **1.5PN:** Found all the actions and frequencies and constructed the action-angle based solution.

Summary

For a BBH with arbitrary masses, spins and eccentricity,

- **1.5PN:** Found all the actions and frequencies and constructed the action-angle based solution.
- **2PN:** Found 2 new (PN perturbative) constants of motion, thereby establishing the integrable nature of the BBH.

Summary

For a BBH with arbitrary masses, spins and eccentricity,

- **1.5PN:** Found all the actions and frequencies and constructed the action-angle based solution.
- **2PN:** Found 2 new (PN perturbative) constants of motion, thereby establishing the integrable nature of the BBH.

Afterthoughts: (1) Nature is complex; elaborate math unavoidable

Summary

For a BBH with arbitrary masses, spins and eccentricity,

- **1.5PN:** Found all the actions and frequencies and constructed the action-angle based solution.
- **2PN:** Found 2 new (PN perturbative) constants of motion, thereby establishing the integrable nature of the BBH.

Afterthoughts: (1) Nature is complex; elaborate math unavoidable
(2) Using classical mechanics to do GW research.

Future avenues

- Find action-angles at 2PN using canonical pert. theory. Add 2.5PN radiation reaction.

Future avenues

- Find action-angles at 2PN using canonical pert. theory. Add 2.5PN radiation reaction.
- Prove integrability at 3PN.

Future avenues

- Find action-angles at 2PN using canonical pert. theory. Add 2.5PN radiation reaction.
- Prove integrability at 3PN.
- Compute EMRI action-angles (with Vojtěch Witzany).

Future avenues

- Find action-angles at 2PN using canonical pert. theory. Add 2.5PN radiation reaction.
- Prove integrability at 3PN.
- Compute EMRI action-angles (with Vojtěch Witzany).
- Redo EOB for spinning systems by matching PN and EMRI action angles.



Thank you!
Questions?

Refs:

- Papers: [2012.06586](#), [2110.15351](#), [2210.01605](#), [2110.09608](#).
- Lecture notes: [2206.05799](#)
- Mathematica package:
github.com/sashwattanay/BBH-PN-Toolkit