

$$A_{3 \times 3} \quad \lambda_1 = 1, \lambda_2 = 2, \lambda_3 = 3 \quad \checkmark$$

$$\underline{x_1} \quad \underline{x_2} \quad \underline{x_3} \text{ are LI}$$

$$\underline{\text{LI}}: \text{ If } \sum_{i=1}^n \alpha_i x_i = 0 \Rightarrow \underline{\alpha_1 = 0}, \underline{\alpha_2 = 0}, \underline{\alpha_3 = 0} \text{ as the only solution.}$$

(λ, x) EV EVecr pair iff $Ax = \lambda x \quad x \neq 0$

Let A be a $n \times n$ matrix & $\lambda_1, \lambda_2, \dots, \lambda_n$ be its distinct eigenvalues. $\lambda_1 \neq \lambda_2 \neq \lambda_3 \neq \dots \neq \lambda_n$

Let x_1, x_2, \dots, x_n be the corr. eigenvectors

$$\therefore Ax_1 = \lambda_1 x_1; Ax_2 = \lambda_2 x_2; \dots Ax_n = \lambda_n x_n$$

$$P = \{ \overset{\neq 0}{x_1}, \overset{\neq 0}{x_2}, \dots, x_n \} \quad \text{is LI} \quad \text{then result is proved.}$$

$$P = \{ x_1, x_2, \dots, x_r \} \quad r < n \quad \text{is LI}$$

Recipe : $x_1 = \text{turmeric}$

$x_2 = \text{Salt}$

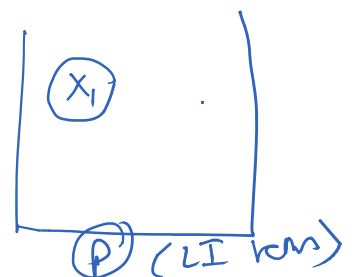
$x_3 = \text{Sambar powder}$

$x_4 = \text{garam masala powder}$

$x_5 = \text{Hing}$

$x_6 = \text{sugar}$

$x_7 = \text{Cinnamon}$



$$P = \{ \text{turmeric, Salt, Hing, Cinnamon} \} \text{ is LI}$$

$x_1 \neq x_i$

x_1, x_2, \dots, x_n as eigenvectors $x_i \neq 0$ to
 $P = \{x_1, x_2, \dots, x_r\}$ $r < n$ to be LI.

$$\rightarrow \boxed{x_{r+1} = \alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_r x_r} \quad (1)$$

$$\begin{aligned} A x_{r+1} &= A \alpha_1 x_1 + A \alpha_2 x_2 + \dots + A \alpha_r x_r \\ \lambda_{r+1} x_{r+1} &= \boxed{\alpha_1 \lambda_1 x_1} + \alpha_2 \lambda_2 x_2 + \dots + \alpha_r \lambda_r x_r \quad (2) \end{aligned}$$

Multiply (1) with λ_{r+1} throughout

$$\boxed{\lambda_{r+1} x_{r+1}} = \boxed{\alpha_1 \lambda_{r+1} x_1} + \alpha_2 \lambda_{r+1} x_2 + \dots + \alpha_r \lambda_{r+1} x_r \quad (3)$$

$$(2) - (3) \quad \boxed{0} = \underbrace{\alpha_1}_{\neq 0} x_1 \underbrace{(\lambda_1 - \lambda_{r+1})}_{\neq 0} + \dots + \alpha_r x_r \underbrace{(\lambda_r - \lambda_{r+1})}_{\neq 0}$$

$$\begin{aligned} \alpha_1 \underbrace{(\lambda_1 - \lambda_{r+1})}_{\neq 0} &= 0 & \Rightarrow \alpha_1 &= 0 \\ \alpha_2 \underbrace{(\lambda_2 - \lambda_{r+1})}_{\neq 0} &= 0 & \Rightarrow \alpha_2 &= 0 \\ &\vdots & & \\ \alpha_r \underbrace{(\lambda_r - \lambda_{r+1})}_{\neq 0} &= 0 & \Rightarrow \alpha_r &= 0 \end{aligned}$$

$\Rightarrow x_{r+1} = 0$, a contradiction because
 x_{r+1} being an eigenvector $\neq 0$

$x_1 = \text{turmeric}$, $x_2 = \text{Salt}$,
 $x_3 = \text{honey}$, $x_4 = \text{tham dhani}$

\dots $x_5 = \boxed{\text{Sambhar}}$

$P = \{x_1, x_2, x_3, x_4, \dots\}$

$$P = \{ \underline{x_1, x_2, x_3, x_4}, \}$$

$$\lambda_1 \neq \lambda_2, \dots \neq \lambda_n$$

$$P = \{x_1, x_2, \dots, x_n\} \subset \mathbb{R}^n$$

$A_{n \times n}$ eigenvalues
cor. ev

$$\boxed{\lambda_1, \lambda_2, \dots, \lambda_n}$$

$$x_1, x_2, \dots, x_n$$

$$\begin{matrix} 1, 2, 3, 6, 8 \\ 1 \\ 3 \end{matrix}$$

$$\therefore Ax_i = \lambda_i x_i \quad \forall i$$

$P_{n \times n}$ non-singular. P^{-1} exists $Q A Q^{-1}$

$$\hat{A}_{n \times n} = P^{-1} A P ; P^{-1} = Q, P = Q^{-1}$$

Theorem: Eigenvalues of \hat{A} are $\lambda_1, \lambda_2, \dots, \lambda_n$

If λ is an eigenvalue of A , then λ is an eigenvalue of \hat{A} .

4 $P^{-1} = \begin{bmatrix} 3 & -1 \\ 2 & -6 \end{bmatrix}$ Proof: $(\lambda, x) \rightarrow$ pair of A

$$\Rightarrow Ax = \lambda x \quad (x \neq 0)$$

$$A \hat{I} x = \lambda x \quad \hat{I} \text{ is the identity matrix}$$

$$A P P^{-1} x = \lambda x$$

$$P^{-1} A P P^{-1} x = P^{-1} \lambda x$$

$$\hat{A} (P^{-1} x) = \lambda (P^{-1} x)$$

λ is an eigenvalue of \hat{A} ? Yes

$$\boxed{\lambda_1 = 2}, x_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$P^{-1} A P$$

λ is an eigenvalue of \tilde{A} ? Yes
 $P^{-1}x$ is the corr. eigenvector

~~A~~ For any general matrix

$\lambda_1, \lambda_2, \dots, \lambda_n$ eigenvalues

x_1, x_2, \dots, x_n are LI eigenvectors

$$P = \begin{bmatrix} \uparrow & \uparrow & & \uparrow \\ x_1 & x_2 & \dots & x_n \\ \downarrow & \downarrow & & \downarrow \end{bmatrix} \quad \det(P) \neq 0$$

P is invertible

$$P^{-1}AP = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

$A_{n \times n}$ $\lambda_1, \lambda_2, \dots, \lambda_n$ eigenvalues
 x_1, x_2, \dots, x_n eigenvectors

$$Ax_i = \lambda_i x_i$$

$$1 \leq i \leq n \quad \checkmark$$

$$\begin{cases} Ax_1 = \lambda_1 x_1 \\ Ax_2 = \lambda_2 x_2 \\ \vdots \\ Ax_n = \lambda_n x_n \end{cases}$$

$$A \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \begin{bmatrix} \lambda_1 & \dots & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

$$A \begin{bmatrix} \uparrow & \uparrow & & \uparrow \\ x_1 & x_2 & \dots & x_n \\ \downarrow & \downarrow & & \downarrow \end{bmatrix} = \begin{bmatrix} \uparrow & \uparrow & & \uparrow \\ x_1 & x_2 & \dots & x_n \\ \downarrow & \downarrow & & \downarrow \end{bmatrix} \begin{bmatrix} \lambda_1 & \dots & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

$$2n^3 M, 2n^2/(n-1) A$$

$$A \rightarrow \text{E.V.} \rightarrow \text{E.V.s} \rightarrow P \rightarrow P^T \rightarrow \text{Ske}$$

$$P^{-1}AP = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}$$

$$P^{-1}AP \cdot P^TAP = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}$$

$$P^{-1}A^2P = \begin{pmatrix} \lambda_1^2 & & 0 \\ & \ddots & \\ 0 & & \lambda_n^2 \end{pmatrix}$$

$$P^{-1}A^kP = \begin{pmatrix} \lambda_1^k & & 0 \\ & \ddots & \\ 0 & & \lambda_n^k \end{pmatrix}, \quad k \in \mathbb{N}.$$

$$A^{28}$$

$$P^{-1}A^{28}P = \begin{pmatrix} \lambda_1^{28} & & \\ & \ddots & \\ & & \lambda_n^{28} \end{pmatrix}$$

$$A^{28} = P \begin{pmatrix} \lambda_1^{28} & & \\ & \ddots & \\ & & \lambda_n^{28} \end{pmatrix} P^{-1}$$

$$P^{-1}AP \cdot P^{-1}AP \cdot P^{-1}AP \cdot P^{-1}AP$$

$$= P^{-1}A^4P = \begin{pmatrix} \lambda_1^4 & & 0 \\ & \ddots & \\ 0 & & \lambda_n^4 \end{pmatrix}$$

$$A_{n \times n} \quad (\lambda_1, x_1) \dots (\lambda_n, x_n)$$

$$Ax_1 = \lambda_1 \underline{x_1}, \quad Ax_2 = \lambda_2 \underline{x_2} \dots Ax_n = \lambda_n \underline{x_n}$$

x_1, x_2, \dots, x_n are LI
 \mathbb{R}^n

x_0 as an initial approximation.

$$x_0 = c_1 x_1 + \dots + c_n x_n$$

λ_1 d.e.v

$$Ax_0 = A c_1 x_1 + \dots + A c_n x_n \\ = c_1 \lambda_1 x_1 + \dots + c_n \lambda_n x_n$$

$$A^2 x_0 = A \cdot c_1 \lambda_1 x_1 + \dots + A c_n \lambda_n x_n \\ = c_1 \lambda_1^2 x_1 + \dots + c_n \lambda_n^2 x_n$$

$$\underline{\underline{A^k x_0}} = \underline{\underline{c_1 \lambda_1^k x_1 + c_2 \lambda_2^k x_2 + \dots + c_n \lambda_n^k x_n}} \\ = c_1 \lambda_1^k \left[\underbrace{x_1}_{(0.1)^{25}} + \underbrace{\frac{c_2}{c_1} \left(\frac{\lambda_2}{\lambda_1} \right)^k}_{(0.88)} x_2 + \dots + \frac{c_n}{c_1} \left(\frac{\lambda_n}{\lambda_1} \right)^k x_n \right]$$

$$k=25$$

$$\frac{\lambda_2}{\lambda_1} = (0.1)$$